

The Meßthaler-Wulff Project

Julia Meßthaler

Blazingly fast code for finding all crystals (subsets of a graph) that can be constructed using only transformations that locally minimize surface energy.

The Problem

Let G be some graph and $C_0 \subset G$ a crystal. Furthermore let $\eta : G \rightarrow \wp(G)$ denote the neighbors of a given node and $C_1 := G \setminus C_0$. Then we can define the surface energy of the crystal C_0 as

$$\xi_{C_0} := \sum_{n \in C_0} l_n^1$$

where l_n^i denotes the forwards/backwards loneliness of the node n and is itself defined as

$$l_n^i := \#\{n_0 \in \eta(n) \mid n_0 \in C_i\}$$

The idea now is to find optimal ξ_{C_0} by doing locally minimizing transformations. We call a node n optimal in forwards mode if for the specific C_0 there is no node n_0 such that $l_{n_0}^1 < l_n^1$. The same definition can be applied to backwards mode, for this however we use l_n^0 .

A locally optimal addition is now simply a node with optimal l_n^1 and a locally optimal removal is a node with optimal l_n^0 .

Our goal in this project is to explore what crystals we can construct by only using such locally optimal transformations.

The Additive Simulation

This class encapsulates a current state representing a crystal and methods to find out what locally optimal transformations can be applied or to apply said transformations. It is optimized to be able to support $O(1)$ operations. A simplified definition of an additive simulation instance is $S_A = (\xi_C, B_0, B_1)$ where ξ_{C_0} is the energy of the current crystal and B_i are the boundaries, defined as follows:

$$B_i = \{n \in C_i \mid l_n^{1-i} > 0\}$$

The boundaries are represented by `PriorityStack` instances and support the following operations:

- Getting the loneliness for a node
- Setting the loneliness for a node
- Unsetting the loneliness for a node, effectively removing it from the boundary
- Getting the nodes that have minimal loneliness

In its essence `PriorityStack` is an implementation of a priority queue optimized for this specific use-case.

S_A now basically only has to support one operation: Moving a node from one boundary to the other.

Let n be the affected node and m the mode¹. If $m = 1$ the energy becomes

$$\begin{aligned}\xi'_{C_0} &= \xi_{C_0} + l_n^1 - l_n^0 \\ &= \xi_{C_0} + l_n^1 - (\#\eta(n) - l_n^1) \\ &= \xi_{C_0} + 2l_n^1 - \#\eta(n)\end{aligned}$$

Since backwards and forwards are inverse for $m = 0$ the energy must be

$$\begin{aligned}\xi'_{C_0} &= \xi_{C_0} - l_n^1 + l_n^0 \\ &= \xi_{C_0} + l_n^0 - (\#\eta(n) - l_n^0) \\ &= \xi_{C_0} + 2l_n^0 - \#\eta(n)\end{aligned}$$

¹This is 0 for backwards and 1 for forwards