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The Detailed Proof of The 2-Ray Ground Reflection Model "Supplemented By: MATLAB Codes & graphs"

### 1. The 2-Ray Ground Reflection Model

This model takes into account a line-of-sight and a ground reflection. It is a good approximation for propagation over a smooth well-reflecting terrain, as modeled by the plane-earth model, with:

$$p_R = \frac{\lambda^2}{(4\pi d)^2} \left[ 2\sin\frac{2\pi}{\lambda} \frac{h_T h_R}{d} \right]^2 G_T p_T G_R$$

# 2. The MATLAB Code & Graphs Representing The 2-Ray Ground Reflection Model

# The code:

#### Firstly: Pathloss Vs Distance:

```
%-----WIRELESS COMMUNICATIONS
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%--Title: The 2-Ray Ground Reflection Model MATLAB Codes & graphs
lambda = 0.3;
ht100=100;
ht30=30;
ht2=2;
hr=2;
axis=[];
p100=[];
p30 = [];
p2 = [];
pfsl=[];
for i=1000:5000
 d=10^{(i/1000)};
 axis = [axis d];
 fspower = (lambda/(4*3.1415*d))^2;
 power100 = fspower * 4 *(sin(2*3.1415*hr*ht100/(lambda*d)))^2;
 power30 = fspower* 4 *(\sin(2*3.1415*hr*ht30/(lambda*d)))^2;
 power2 = fspower * 4 *(\sin(2*3.1415*hr*ht2/(lambda*d)))^2;
 p100 = [p100, 10*log10(power100)];
 p30 = [p30, 10*log10(power30)];
 p2 = [p2, 10*log10(power2)];
pfsl=[pfsl, 10*log10(fspower)];
end
text('FontSize', 18)
```

```
semilogx(axis,p100, 'g-',axis,p30, 'b-',axis,p2, 'r-',axis,pfsl,'y-')

xlabel('distance in m');
ylabel('pathloss');
text(1000,-66,'blue : hr=30m');
text(1000,-74,'red : hr=2m');
text(1000,-58,'red : hr=100m');
text(1000,-50,'yellow: free space');

text(50,-180,'lambda = 0.30 m');
text(50,-190,'hr = 2 m');
```

#### Secondly: Power vs Distance:

Here are the keys from the configuration relevant for positioning the hosts:

```
*.*.mobility.initFromDisplayString = false
*.*.mobility.typename = "StationaryMobility"
*.*.mobility.initialY = 200m
*.*.mobility.initialZ = 2m

*.source.mobility.initialX = 0m
*.destination.mobility.initialX = ${distance=0..50 step 0.25, 51..100 step 1, 105..200 step 5, 220..1000 step 20}m.
```

The other variable in the parameter study is the path loss type, which takes on the following values:

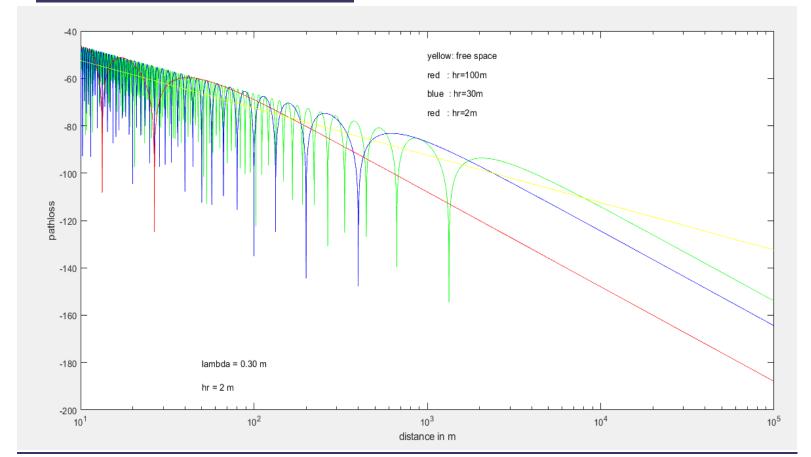
FreeSpacePathLoss, TwoRayGroundReflection, TwoRayInterference, RicianFading, LogNormalShadowing

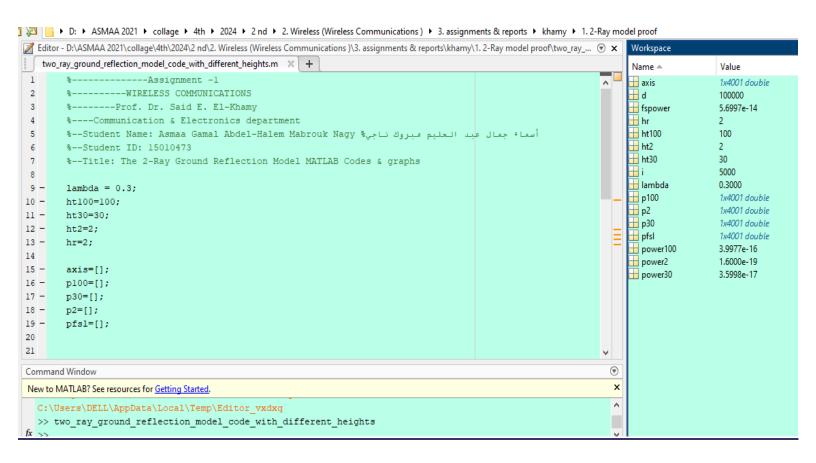
The source host will transmit with the default power of 20mW. We will record the power of the received transmission, using the receptionPower statistic. The receptionPower statistic is declared in the NED file, and it uses the receptionMinSignalPower signal of the radio medium module as input:

```
@statistic[receptionPower](source="receptionMinSignalPower(radioMedium.signalArrivalStarted)";
record=last);
```

#### **The MATLAB Results Graphs:**

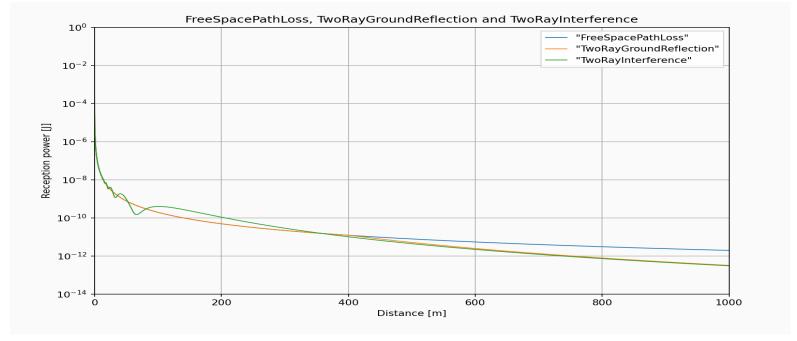
# • Firstly: Pathloss Vs Distance:



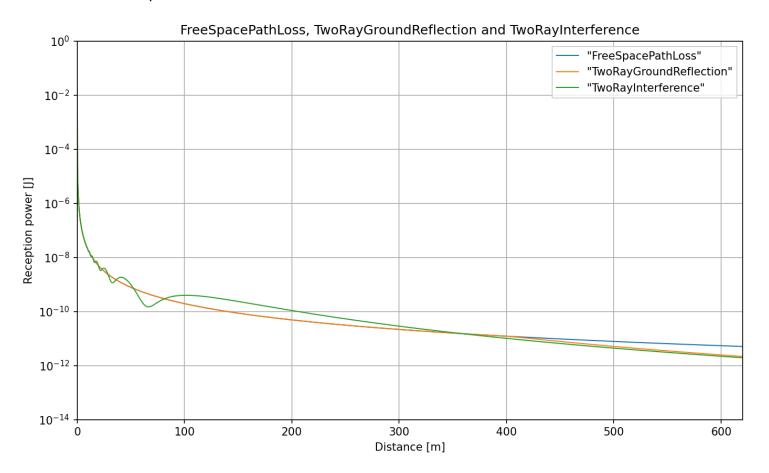


#### Secondly: Power vs Distance:

The power of the received signal vs. distance, using  $\underline{\mathtt{FreeSpacePathLoss}}$ ,  $\underline{\mathtt{TwoRayGroundReflection}}$ , and  $\underline{\mathtt{TwoRayInterference}}$  path loss module types, is displayed on the following plot:

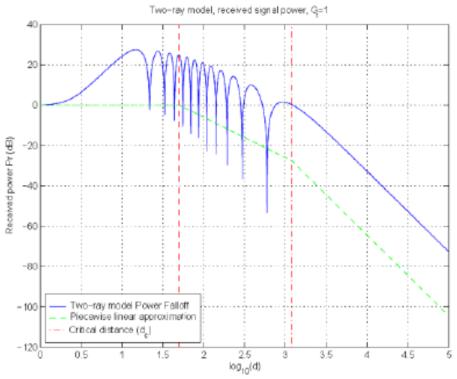


Here is the same plot zoomed in:



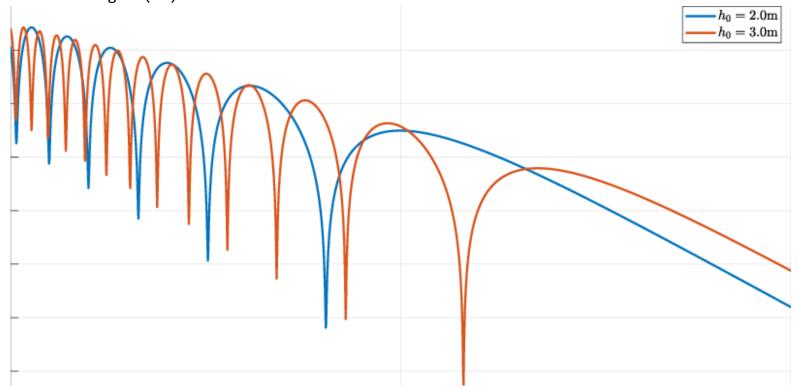
It is apparent that the two-ray ground reflection model yields the same values as the free space path loss model, up until the cross-over distance. After that point, the two curves diverge. The power of the two-ray interference model fluctuates in the near-field and converges to the two-ray ground reflection model in the far- field. Thus the two-ray interference model can be used for more realistic two-ray propagation simulations.

Then, the Received Power versus Distance for Two-Ray Model only can be shown as:



## The conclusion:

Two-ray model showing that received power is affected by both the link distance and the antenna height (h0) relative to the reflective surface:



Here in the above MATLAB sketch, We focus our attention on links of short-to-medium-range distances with antenna heights near-to-the-water-surface.

According to the below equation:

$$|E_{TOT}(d)| = 2 \frac{E_0 d_0}{d} \sin\left(\frac{\theta_{\Delta}}{2}\right)$$

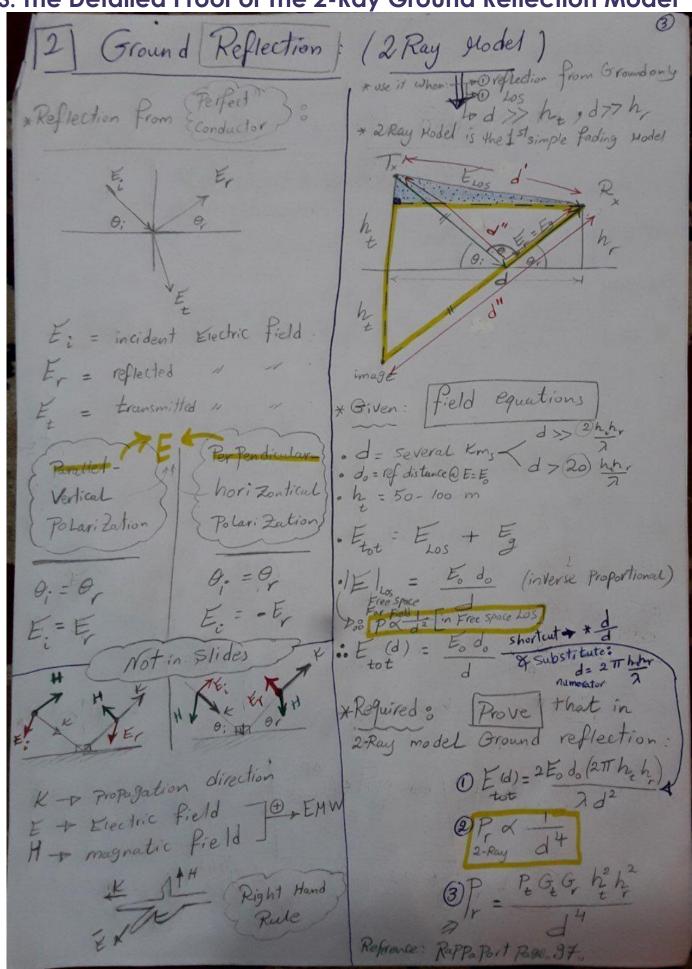
Where:

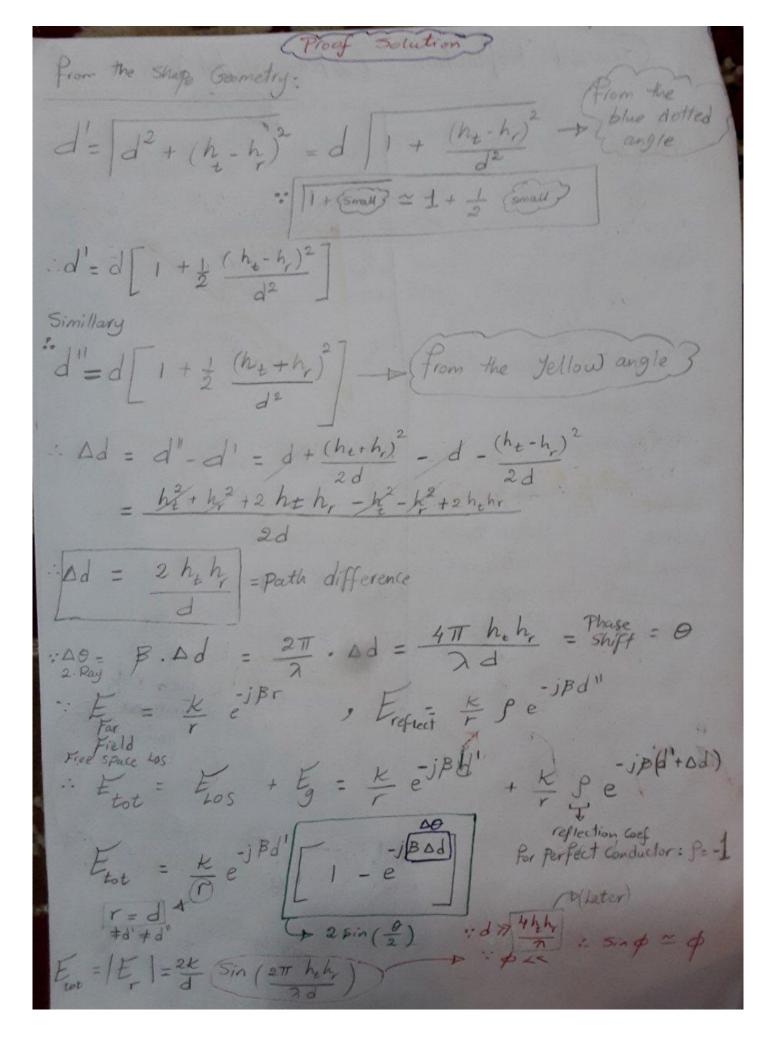
$$\frac{\theta_{\Delta}}{2} \approx \frac{2\pi h_t h_r}{\lambda d} < 0.3 \text{ rad}$$

Which implies that:

$$d > \frac{20\pi h_t h_r}{3\lambda} \approx \frac{20h_t h_r}{\lambda}$$

3. The Detailed Proof of The 2-Ray Ground Reflection Model





2 Ray Model - Ground Reflection EX 1 2 Ray PX 14 for const related to E Far field  $= |E(d)| = 2\pi 2 |K| h_t h_r$   $= |E_r| = 2E_0 d (2\pi h_t h_r)$   $= |E_r| = 2E_0 d (2\pi h_t h_r)$  $\left\| \frac{E_{tot}}{E_d} \right\| = \frac{4 \pi h_h}{7 l^2}$ · Pr x | Etot | 2 00 Pr x | Et | - Pr x of 4 : P= Pt Gt Gr 72 free (4T) d2 to where assume assume lest  $\frac{P_r}{2Ray} = \frac{P_t G_t G_r \lambda^2}{4\pi)^2} \cdot \left| \frac{E_{tot}}{E_d} \right|^2$ Ground Reflection  $(4\pi)^2$  $= \frac{P_{t} G_{t} G_{r} \lambda^{2}}{(4\pi)^{2}} \frac{(4\pi)^{2} h_{r}^{2}}{\lambda^{2} h_{r}^{4}}$ Pr = Pr Ge Gr he h

