## **CHAPTER TWO**

# Simple Sorting and Searching Algorithms

# 1. Simple Searching Algorithms

- Searching is a process of finding an element in a list of items or determining that the item is not in the list.
- The process of finding the location of an element within the data structure is called Searching.
  - Locate an element x in a list of distinct elements a1,a2,...an or determine that it is not in the list.
  - The solution to this search problem is the location of the item in the list that equals x and is 0 if x is not in the list.
- There are two simple Searching algorithms:
  - A. Linear (Sequential) Search
  - **B.** Binary Search

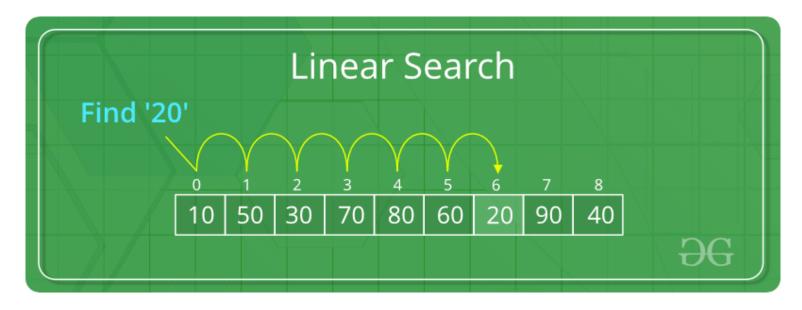
## A. Linear Searching

- Linear search is a very simple search algorithm.
- This algorithm can be implemented on the unsorted list.
- In this type of search, a sequential search is made over all items one by one.
  - Every item is checked and if a match is found then that particular item is returned, otherwise the search continues till the end of the data collection.
  - It compares the element to be searched with all the elements in an array, if the match is found, then it returns the index of the element else it returns -1.



## A. Linear Searching: How it works

- In a linear search, we start with top (beginning) of the list and compare the element at top with the key.
- If we have a match, the search terminates, and the index number is returned.
- If not, we go on the next element in the list.
- If we reach the end of the list without finding a match, we return -1.



## A. Linear Searching: Algorithm

```
Linear Search (Array A, Value x)
   Step 1: Set i to 1
   Step 2: if i > n then go to step 7
   Step 3: if A[i] = x then go to step 6
   Step 4: Set i to i + 1
   Step 5: Go to Step 2
   Step 6: Print Element x Found at index i and go to step 8
   Step 7: Print element not found
   Step 8: Exit
```

# A. Linear Searching: Pseudocode

```
procedure linear_search (list, value)
 for each item in the list
   if match item == value
     return the item's location
   else
      return the item is not found
   end if
 end for
end procedure
```

## A. Linear Searching: Implementation

```
int linearSearch(int a[], int n, int val)
for (int i = 0; i < n; i++)
    if (a[i] == val)
    return i;
   return -1;
```

## A. Linear Searching: Complexity Analysis

- In Linear search,
  - the best case occurs when the element we are looking is located at the first position of the array.
  - the worst case occurs when the element we are looking is present at the end of the array or not present in the given array.

Case	<b>Time Complexity</b>
<b>Best Case</b>	<b>O</b> (1)
<b>Average Case</b>	O(n)
<b>Worst Case</b>	O(n)

 However, the time complexity of linear search is O(n) because every element in the array is compared only once.

# **B.** Binary Searching

- A Binary search algorithm is the simplest algorithm that searches the element very quickly.
- This search algorithm works on the principle of divide and conquer approach.
- It is used to search the element from the sorted list.
  - The elements must be stored in sequential order or the sorted manner to implement the binary algorithm.
  - Binary search cannot be implemented if the elements are stored in a random manner.
- It is used to find the middle element of the list.

## **B. Binary Searching: How it works?**

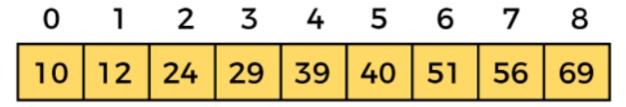
- In a binary search, we look for the key in the middle of the list. If we get a match, the search is over.
- If the key is greater than the element in the middle of the list, we make the top (upper) half the list to search.
- If the key is smaller, we make the bottom (lower) half the list to search.
- Repeat the above three steps until one element remains.
- If this element matches return the index of the element, else return -1 index. (-1 shows that the key is not in the list).

## **B. Binary Searching: Algorithm**

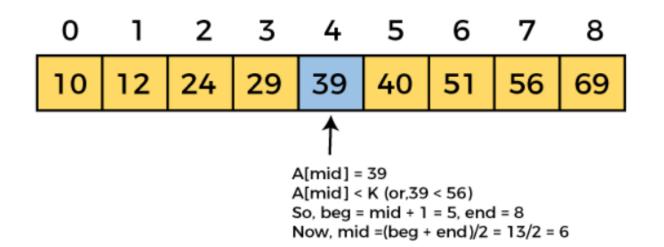
```
Binary_Search(a, lower_bound, upper_bound, val)
Step 1: set beg = lower_bound, end = upper_bound, pos = - 1
Step 2: repeat steps 3 and 4 while beg <=end
Step 3: set mid = (beg + end)/2
Step 4: if a[mid] = val
                                'a' is the given array
         set pos = mid
                                 'lower_bound' is the index of the first array element
         print pos
                                 'upper_bound' is the index of the last array element
         go to step 6
                                 'val' is the value to search
     else if a[mid] > val
         set end = mid - 1
     else
         set beg = mid + 1
    [end of if]
  [end of loop]
Step 5: if pos = -1
         print "value is not present in the array"
      [end of if]
Step 6: exit
```

## **B.** Binary Searching: Example 1

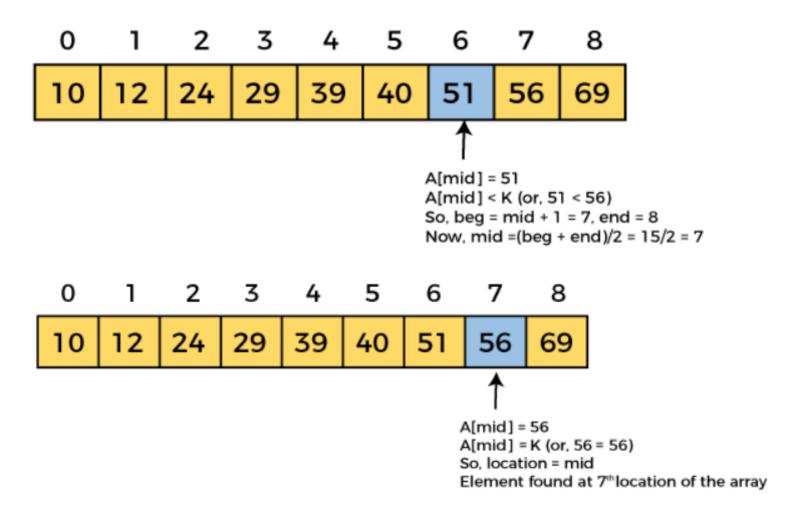
Let the elements of array are



- Let the element to search is, K = 56
- Calculate the mid of the array :- mid = (beg + end)/2mid = (0 + 8)/2 = 4. So, 4 is the mid of the array.

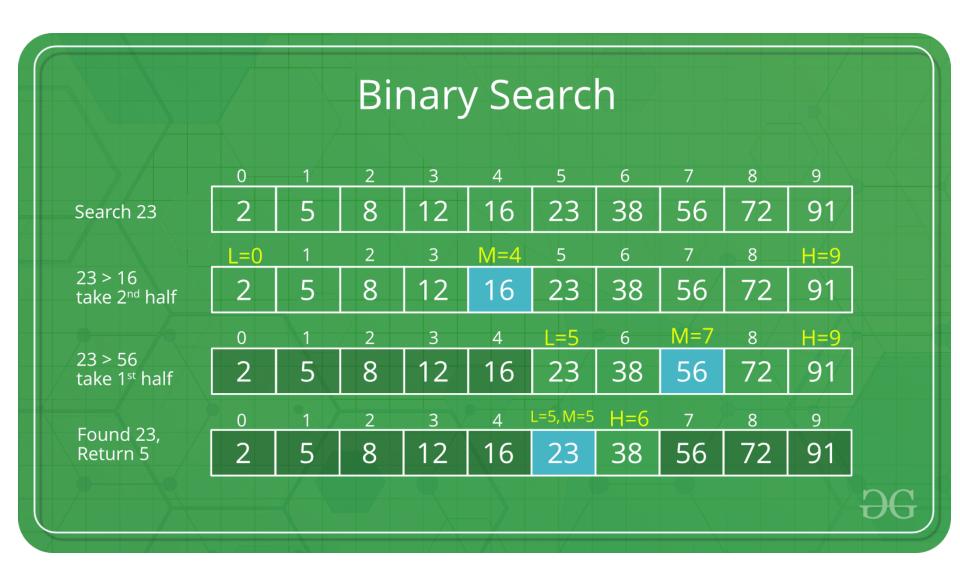


## **B.** Binary Searching: Example 1



- Now, the element to search is found.
- So algorithm will return the index of the element matched.

## **B.** Binary Searching: Example 2



## **B. Binary Searching: Implementation**

```
int binarySearch(int a[], int beg, int end, int val) {
  int mid;
  if(end \ge beg) 
     mid = (beg + end)/2;
/* if the item to be searched is present at middle */
     if(a[mid] == val) {
        return mid;
/* if the item to be searched is smaller than middle, then it can only be in left subarray */
     else if(a[mid] < val) {
        return binarySearch(a, mid+1, end, val);
 /* if the item to be searched is greater than middle, then it can only be in right subarray */
   else {
        return binarySearch(a, beg, mid-1, val);
  return -1;
```

## **B.** Binary Searching: Complexity Analysis

- In Binary search,
  - the best case occurs when the element to search is found in first comparison,
    - i.e., when the first middle element itself is the element to be searched.
  - the worst case occurs, when we must keep reducing the search space till it has only one element.

Case	<b>Time Complexity</b>
<b>Best Case</b>	<b>O</b> (1)
<b>Average Case</b>	O(logn)
<b>Worst Case</b>	O(logn)

Therefore, the time complexity of binary search algorithm

is O(logn).

# 2. Simple Sorting Algorithms

- Sorting algorithms are used to rearrange the elements in an array or a given data structure either in an ascending or descending order.
- It is a process of reordering a list of items in either increasing or decreasing order.
- The comparison operator decides the new order of the elements.

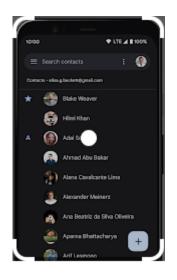
## Why do we need a sorting algorithm?

- Sorting is the most important operation performed by computers.
- Sorting is the first step in more complex algorithms.
- An efficient sorting algorithm is required for optimizing the efficiency of other algorithms like binary search algorithm.
  - a binary search algorithm requires an array to be sorted in a particular order, mainly in ascending order.
- It produces information in a sorted order, which is a human-readable format.
- Searching a particular element in a sorted list is faster than the unsorted list.

## **Example:** Sorting in real-life scenarios

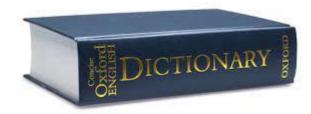
#### Telephone Directory

■ The telephone directory stores the telephone numbers of people sorted by their names, so that the names can be searched easily.



#### Dictionary

■ The dictionary stores words in an alphabetical order so that searching of any word becomes easy.



## **Properties of sorting algorithms**

- A. In-place Sorting and Not in-place Sorting
- **B.** Stable and Not Stable Sorting
- C. Adaptive and Non-Adaptive Sorting

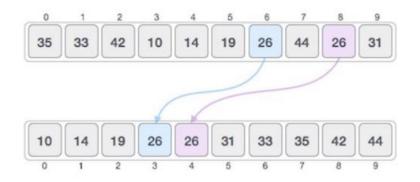
## A. In-place Sorting vs Not-in-place Sorting

- Sorting algorithms may require some extra space for comparison and temporary storage of few data elements.
- In-place Sorting:
  - These algorithms do not require any extra space and sorting is said to happen in-place, or for example, within the array itself.
  - Example: Bubble sort algorithm
- Not in-place Sorting:
  - These algorithms require extra space which is more than or equal to the elements being sorted.
  - Example: Merge-sort algorithm

## **B.** Stable vs Not Stable Sorting

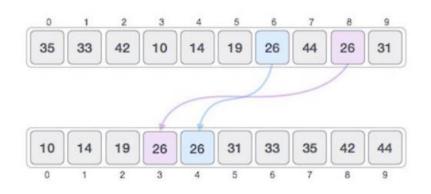
## Stable Sorting:

• If a sorting algorithm, after sorting the contents, does not change the sequence of similar content in which they appear, it is called stable sorting.



#### Not-Stable Sorting:

• If a sorting algorithm, after sorting the contents, changes the sequence of similar content in which they appear, it is called unstable sorting.



## C. Adaptive vs Non-Adaptive Sorting

#### Adaptive Sorting:

- A sorting algorithm is said to be adaptive, if it takes advantage of already 'sorted' elements in the list that is to be sorted.
  - i.e., while sorting if the source list has some element already sorted, adaptive algorithms will take this into account and will not try to re-order them.

### Non-Adaptive Sorting:

- A non-adaptive algorithm is one which does not take into account the elements which are already sorted.
- They try to force every single element to be re-ordered to confirm their sortedness.

# **Simple Sorting Algorithms**

- Simple sorting algorithms include:
  - A. Bubble Sorting
  - **B.** Selection Sorting
  - C. Insertion Sorting

## A. Bubble Sort

- It is a simple sorting algorithm that compares two adjacent elements and swaps them if they are not in the intended order.
  - It works on the repeatedly swapping of adjacent elements if they are not in the intended order.
- It is not suitable for large data sets as its average and worst-case complexity are of  $O(n^2)$ , where n is a number of items.
- Bubble sort is majorly used where
  - complexity does not matter
  - simple and short code is preferred

#### A. Bubble Sort: How it works?

- 1. Compare each element (except the last one) with its neighbor to the right.
  - If they are out of order, swap them
  - This puts the largest element at the very end
  - The last element is now in the correct and final place
- 2. Compare each element (except the last two) with its neighbor to the right.
  - If they are out of order, swap them
  - This puts the second largest element before last
  - The last two elements are now in their correct and final places
- 3. Continue as above until you have no unsorted elements on the left.

## A. Bubble Sort: Algorithm

• In the algorithm given below, suppose arr is an array of n elements. The assumed swap function in the algorithm will swap the values of given array elements.

```
begin BubbleSort(arr)
 for all array elements
   if arr[i] > arr[i+1]
     swap(arr[i], arr[i+1])
   end if
 end for
 return arr
end BubbleSort
```

• Let the elements of array are - 13 32 26 35 10

#### **First Iteration:**

• Sorting will start from the initial two elements. Let compare them to check which is greater.

Here, 32 is greater than 13 (32 > 13), so it is already sorted.
 Now, compare 32 with 26.

 Here, 26 is smaller than 36. So, swapping is required. After swapping new array will look like –

Now, compare 32 and 35.

13 26 32 35 10

- Here, 35 is greater than 32. So, there is no swapping required as they are already sorted.
- Now, the comparison will be in between 35 and 10.

• Here, 10 is smaller than 35 that are not sorted. So, swapping is required. Now, we reach at the end of the array. After first pass, the array will be –

Now, move to the second iteration.

#### **Second Iteration:**

• The same process will be followed for second iteration.

• Here, 10 is smaller than 32. So, swapping is required. After swapping, the array will be -

Now, move to the third iteration.

#### **Third Iteration:**

The same process will be followed for third iteration.

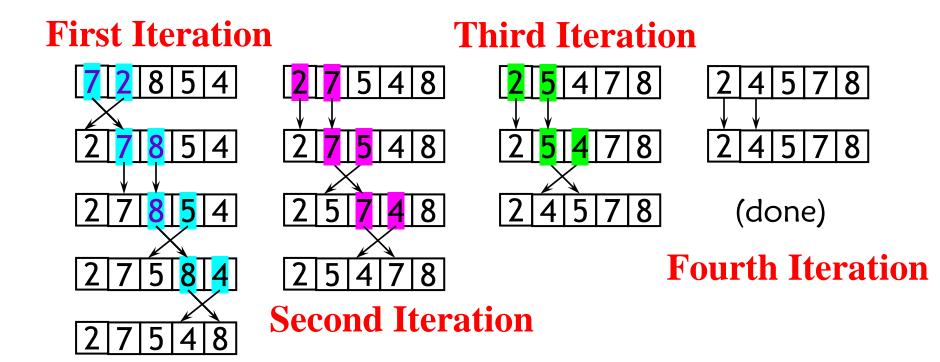
• Here, 10 is smaller than 26. So, swapping is required. After swapping, the array will be -

Now, move to the fourth iteration.

#### **Fourth Iteration:**

• Similarly, after the fourth iteration, the array will be -

• Hence, there is no swapping required, so the array is completely sorted.



## A. Bubble Sort: Implementation

```
void bubble(int a[], int n) {
int i, j, temp;
 for(i = 0; i < n; i++)
   for(j = i+1; j < n; j++)
       if(a[j] < a[i])
          temp = a[i];
          a[i] = a[j];
          a[j] = temp;
```

```
int main()
  int i, j,temp;
  int a[5] = \{45, 1, 32, 13, 26\};
  int n = sizeof(a)/sizeof(a[0]);
  cout<<"Before sorting:- \n";</pre>
  print(a, n);
  bubble(a, n);
  cout<<''\nAfter sorting:- \n'';</pre>
  print(a, n);
return 0;
```

## A. Bubble Sort: Complexity Analysis

- In bubble sort algorithm,
  - the best case time complexity occurs when there is no sorting required
    - i.e. the array is already sorted.
  - the worst case time complexity occurs when the array elements are required to be sorted in reverse order.

Case	<b>Time Complexity</b>
<b>Best Case</b>	O(n)
<b>Average Case</b>	$O(n^2)$
<b>Worst Case</b>	$O(n^2)$

• Therefore, the time complexity of a bubble sort algorithm is  $O(n^2)$ .

## **B. Selection Sort**

- Selection sort is a sorting algorithm that selects the smallest element from an unsorted list in each iteration and places that element at the beginning of the unsorted list.
  - i.e., the smallest value among the unsorted elements of the array is selected in every pass and inserted to its appropriate position into the array.
- It is the simplest algorithm.
- It is an in-place comparison sorting algorithm.

#### **B. Selection Sort: How it works?**

- In this algorithm, the array is divided into two parts: sorted part and unsorted part.
  - Initially, the sorted part of the array is empty, and unsorted part is the given array.
  - Sorted part is placed at the left, while the unsorted part is placed at the right.
- In selection sort, the first smallest element is selected from the unsorted array and placed at the first position.
- After that second smallest element is selected and placed in the second position.
- The process continues until the array is entirely sorted.

### **B. Selection Sort: Algorithm**

```
SELECTION SORT(arr, n)
   Step 1: Repeat Steps 2 and 3 for i = 0 to n-1
   Step 2: CALL SMALLEST(arr, i, n, pos)
   Step 3: SWAP arr[i] with arr[pos]
   [END OF LOOP]
   Step 4: EXIT
                SMALLEST (arr, i, n, pos)
                   Step 1: [INITIALIZE] SET SMALL = arr[i]
                   Step 2: [INITIALIZE] SET pos = i
                   Step 3: Repeat for j = i+1 to n
                   if (SMALL > arr[j])
                      SET SMALL = arr[j]
                   SET pos = j
                   [END OF if]
                   [END OF LOOP]
                  Step 4: RETURN pos
```

- Selection sort is generally used when
  - A small array is to be sorted
  - Swapping cost doesn't matter
  - It is compulsory to check all elements

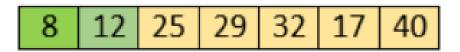
#### Example 1:

- Let the elements of array are 12 29 25 8 32 17 40
- Now, for the first position in the sorted array, the entire array is to be scanned sequentially.
- At present, 12 is stored at the first position, after searching the entire array, it is found that 8 is the smallest value.

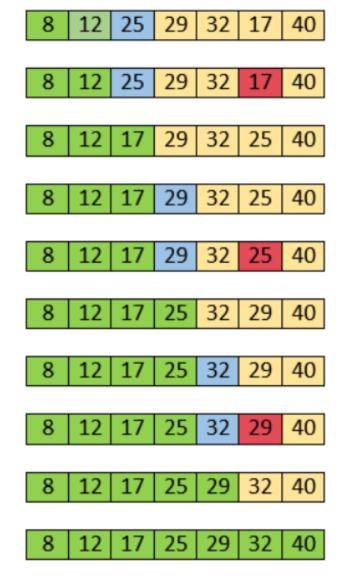
• So, swap 12 with 8. After the first iteration, 8 will appear at the first position in the sorted array.

- For the second position, where 29 is stored presently, we again sequentially scan the rest of the items of unsorted array.
- After scanning, we find that 12 is the second lowest element in the array that should be appeared at second position.

- Now, swap 29 with 12.
- After the second iteration, 12 will appear at the second position in the sorted array.
- So, after two iterations, the two smallest values are placed at the beginning in a sorted way.

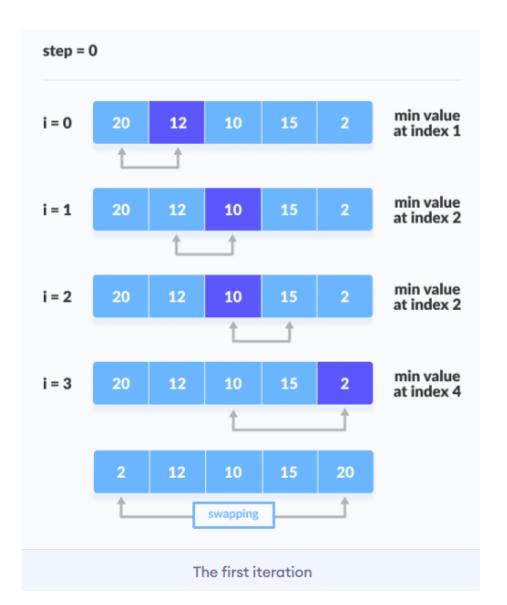


- The same process is applied to the rest of the array elements.
- Now, we are showing a pictorial representation of the entire sorting process.

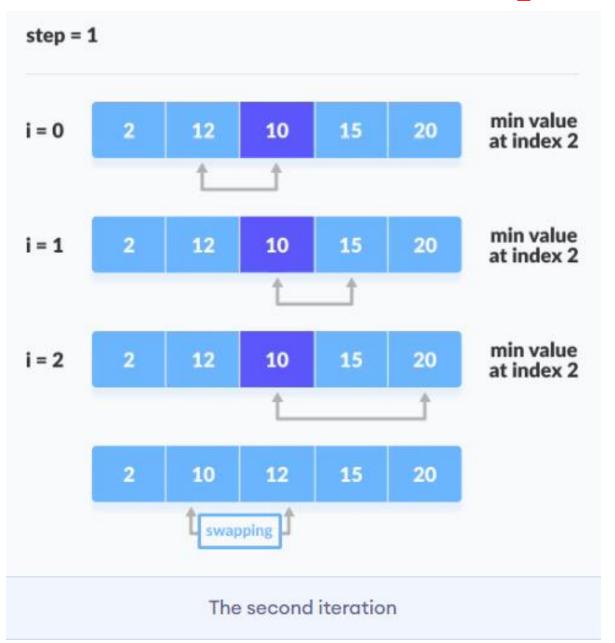


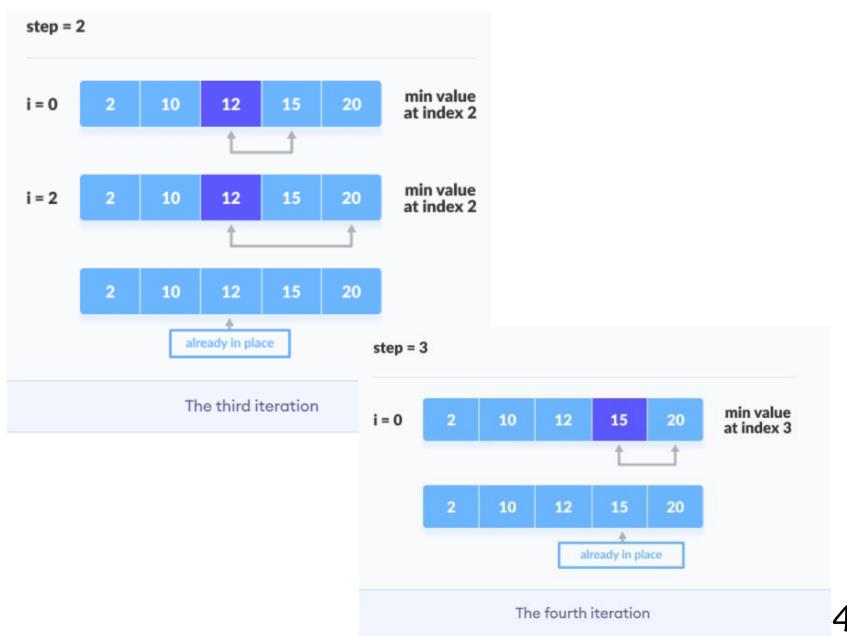
• Now, the array is completely sorted.

Let the elements of array are –









# **B. Selection Sort: Implementation**

```
void selection(int arr[], int n)
   int i, j, small;
   for (i = 0; i < n-1; i++)// One by one move boundary of unsorted subarray
      small = i; //minimum element in unsorted array
                                                 int main()
      for (j = i+1; j < n; j++)
                                                    int a[] = \{ 80, 10, 29, 11, 8, 30, 15 \};
      if (arr[j] < arr[small])</pre>
                                                    int n = sizeof(a) / sizeof(a[0]);
         small = j;
                                                    cout<< "before sorted:- "<<endl;</pre>
// Swap the minimum element with the first element
                                                   printArr(a, n);
                                                    selection(a, n);
   int temp = arr[small];
                                                    cout<< "after sorted"<<endl;</pre>
   arr[small] = arr[i];
                                                    printArr(a, n);
   arr[i] = temp;
                                                    return 0;
```

### **B. Selection Sort: Complexity Analysis**

- In Selection sort algorithm,
  - the best case time complexity occurs when there is no sorting required,
    - i.e. the array is already sorted.
  - the worst case time complexity occurs when the array elements are required to be sorted in reverse order.
    - That means suppose you have to sort the array elements in ascending order, but its elements are in descending order.

Case	<b>Time Complexity</b>
<b>Best Case</b>	$O(n^2)$
<b>Average Case</b>	$O(n^2)$
<b>Worst Case</b>	$O(n^2)$

• Overall algorithm complexity is O(n<sup>2</sup>)

### C. Insertion Sort

- Insertion sort is a sorting algorithm that places an unsorted element at its suitable place in each iteration.
- The idea behind the insertion sort is that first take one element, iterate it through the sorted array.
- It is simple to use.
- It is not appropriate for large data sets as the time complexity of insertion sort in the average case and worst case is  $O(n^2)$ , where n is the number of items.
- Insertion sort is less efficient than the other sorting algorithms like heap sort, quick sort, merge sort, etc.

#### C. Insertion Sort: How it works?

- Insertion sort algorithm somewhat resembles Selection Sort and Bubble sort.
- Array is imaginary divided into two parts sorted and unsorted.
- At the beginning, sorted part contains first element of the array and unsorted one contains the rest.
- At every step, algorithm takes first element in the unsorted part and inserts it to the right place of the sorted one.
- When unsorted part becomes empty, algorithm stops.
- It is reasonable to use binary search algorithm to find a proper place for insertion.
- Insertion sort works by inserting item into its proper place in the list.

#### C. Insertion Sort: How it works?

- Insertion sort works similarly as we sort cards in our hand in a card game.
  - We assume that the first card is already sorted then, we select an unsorted card.
  - If the unsorted card is greater than the card in hand, it is placed on the right otherwise, to the left.
  - In the same way, other unsorted cards are taken and put in their right place.
  - This process is repeated until all the cards are in the correct sequence.
- A similar approach is used by insertion sort.
- Insertion sort is over twice as fast as the bubble sort and is just as easy to implement as the selection sort.

### C. Insertion Sort: Algorithm

- **Step 1** If the element is the first element, assume that it is already sorted. Return 1.
- Step 2 Pick the next element and store it separately in a key.
- Step 3 Now, compare the key with all elements in the sorted array.
- Step 4 If the element in the sorted array is smaller than the current element, then move to the next element. Else, shift greater elements in the array towards the right.
- **Step 5 Insert the value.**
- **Step 6 Repeat until the array is sorted.**

Let the elements of array are –

• Initially, the first two elements are compared in insertion sort.

- Here, 31 is greater than 12.
  - That means both elements are already in ascending order.
  - So, for now, 12 is stored in a sorted sub-array.

Now, two elements in the sorted array are 12 and 25.
 Move forward to the next elements that are 31 and 8.

Both 31 and 8 are not sorted. So, swap them.

After swapping, elements 25 and 8 are unsorted.

So, swap them.

Now, elements 12 and 8 are unsorted.

So, swap them too.

Now, the sorted array has three items that are 8, 12 and 25. Move to the next items that are 31 and 32.

• Hence, they are already sorted. Now, the sorted array includes 8, 12, 25 and 31.

Move to the next elements that are 32 and 17.

• 17 is smaller than 32. So, swap them.

Swapping makes 31 and 17 unsorted. So, swap them too.

• Now, swapping makes 25 and 17 unsorted. So, perform swapping again.

Now, the array is completely sorted.

## C. Insertion Sort: Implementation

```
void insert(int a[], int n) /* function to sort an array with insertion sort */
   int i, j, temp;
   for (i = 1; i < n; i++)
      temp = a[i];
     j = i - 1;
      while(j \ge 0 \&\& temp \le a[j]) /* Move the elements greater than temp to
one position ahead from their current position*/
                                               int main() {
                                                 int a[] = \{ 89, 45, 35, 8, 12, 2 \};
         a[j+1] = a[j];
                                                 int n = sizeof(a) / sizeof(a[0]);
         j = j-1;
                                                 cout<<"Before sorting: "<<endl;</pre>
                                                 printArr(a, n);
      a[j+1] = temp;
                                                 insert(a, n);
                                                 cout<<"\nAfter sorting: "<<endl;</pre>
                                                 printArr(a, n);
                                                  return 0;
```

### C. Insertion Sort: Complexity Analysis

- In Insertion sort algorithm,
  - the best case time complexity occurs when there is no sorting required,
    - i.e. the array is already sorted.
  - the worst case time complexity occurs when the array elements are required to be sorted in reverse order.
    - That means suppose you have to sort the array elements in ascending order, but its elements are in descending order.

Case	<b>Time Complexity</b>
<b>Best Case</b>	O(n)
<b>Average Case</b>	$O(n^2)$
<b>Worst Case</b>	$O(n^2)$

• Overall algorithm complexity is  $O(n^2)$ 

# **Thank You**

**Question?**