

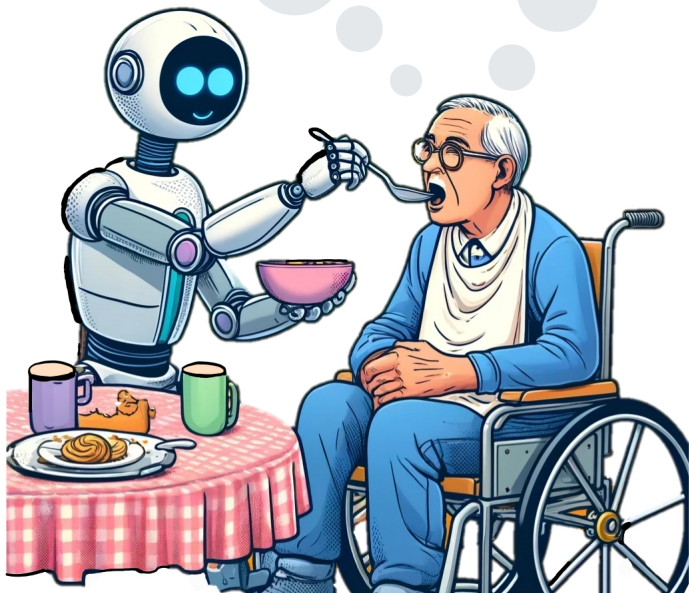
Challenges

Task Reward

Need to feed
the food.

Preference Reward

Could robot be
more gentler?



Motivation

Motion Anticipation

Where
would the user
go next?

Utility Inference

Should I feed
more gently?

