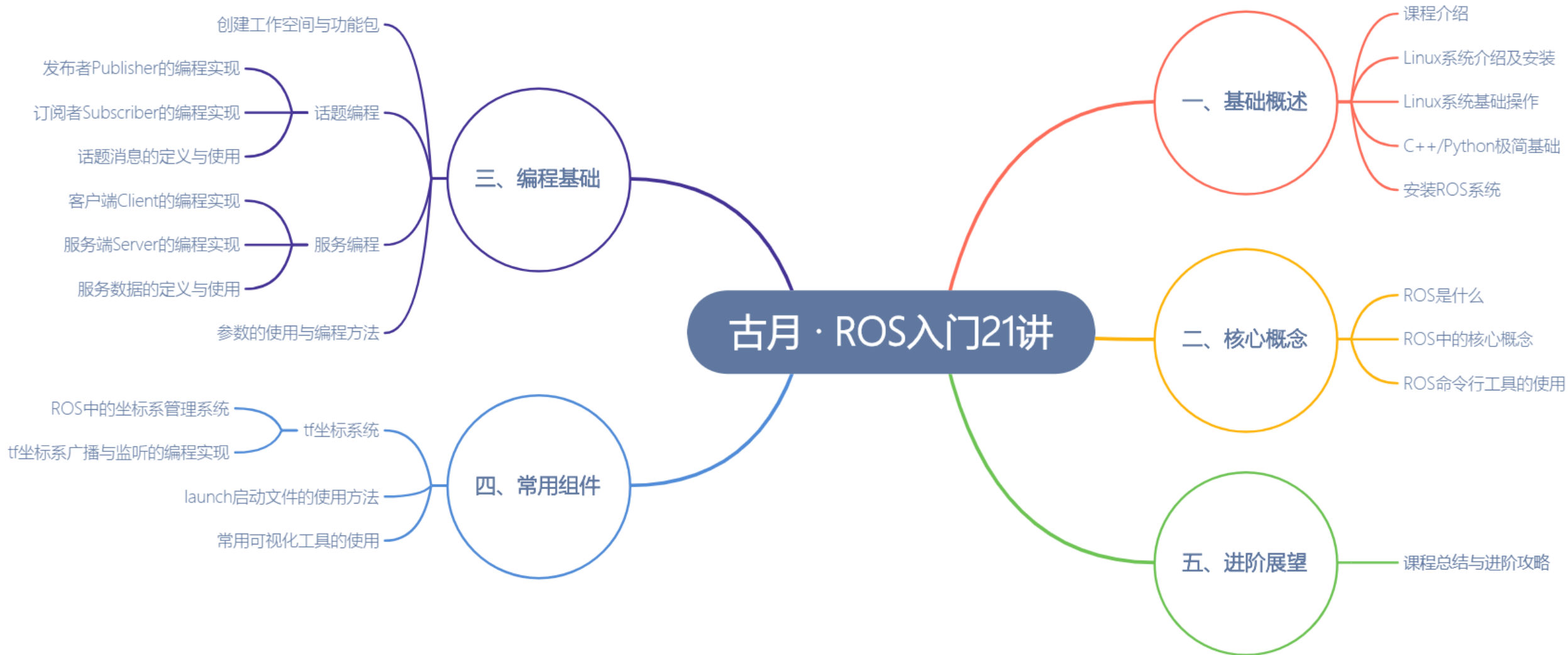


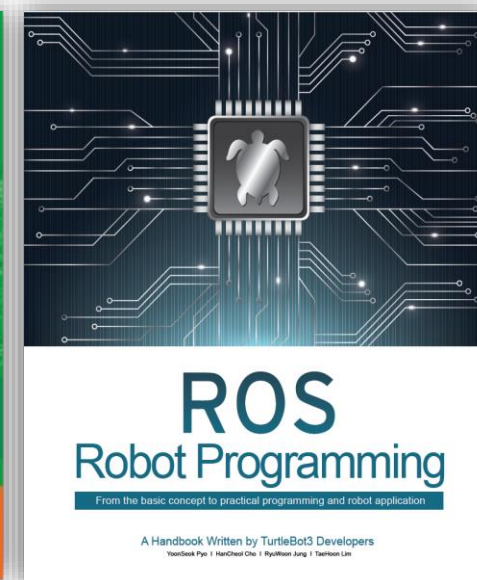
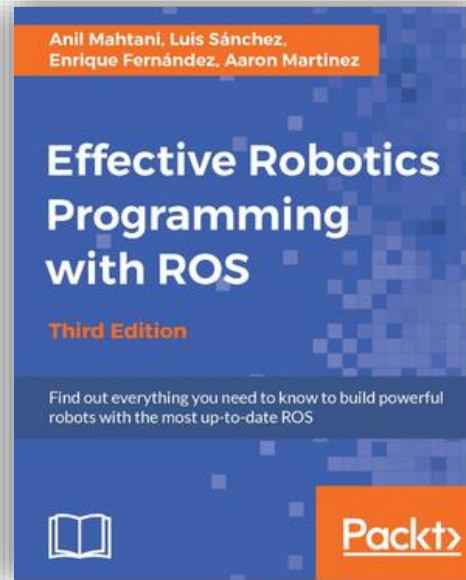
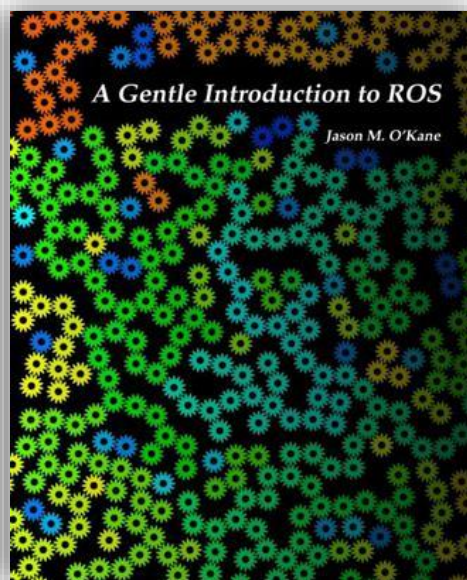
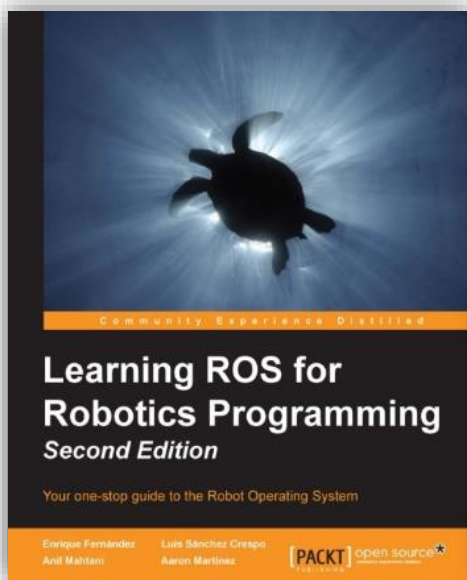
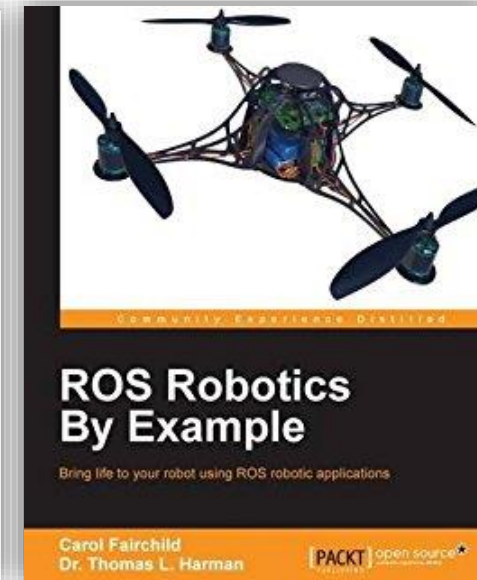
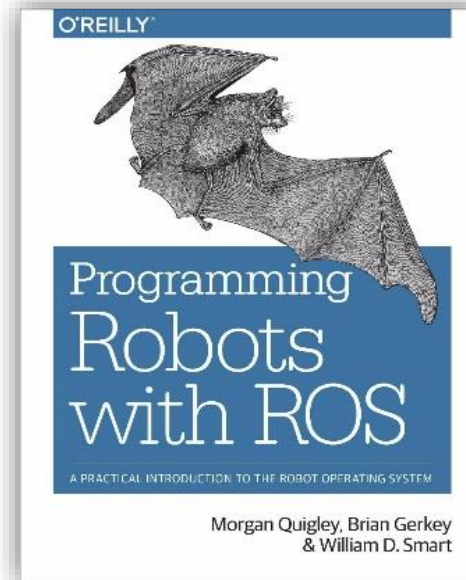
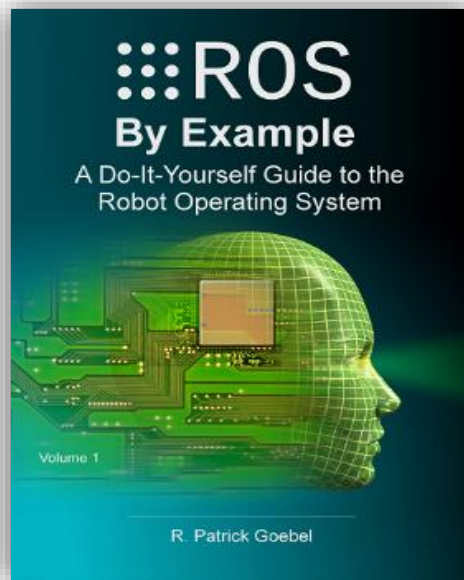
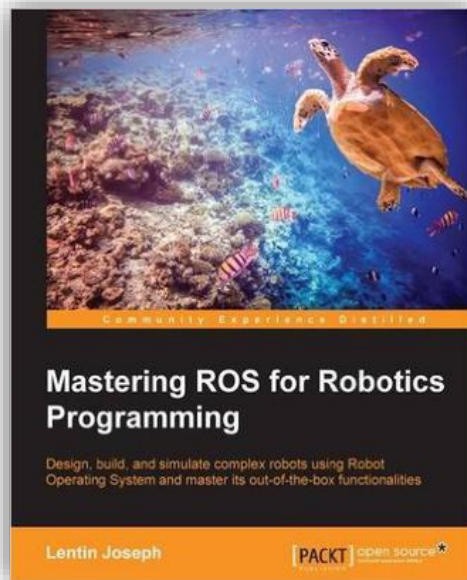
ROS入门
21讲

学完21讲，该学什么

主讲人：古月



• 找一本教程，系统学习



- 找一个项目，小试牛刀

Original TurtleBot
(Discontinued)



TurtleBot 2 Family



TurtleBot 2



TurtleBot 2i



TurtleBot 2e

TurtleBot 3 Family



Burger



Waffle

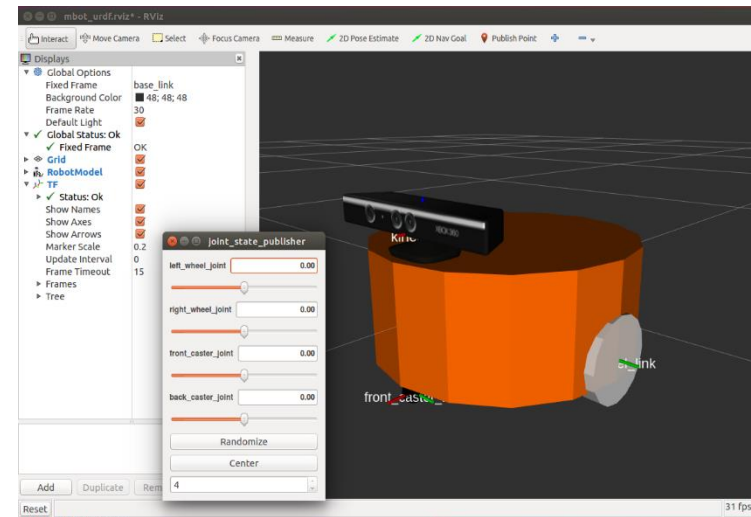


Waffle Pi

<https://wiki.ros.org/Robots/TurtleBot>



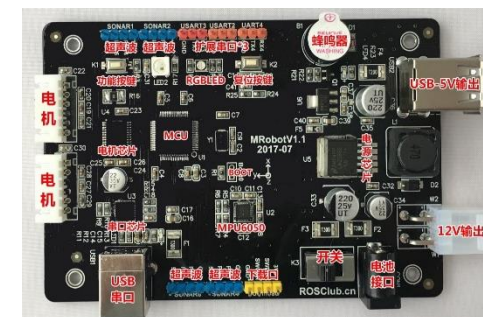
<http://wiki.ros.org/Robots/Husky>



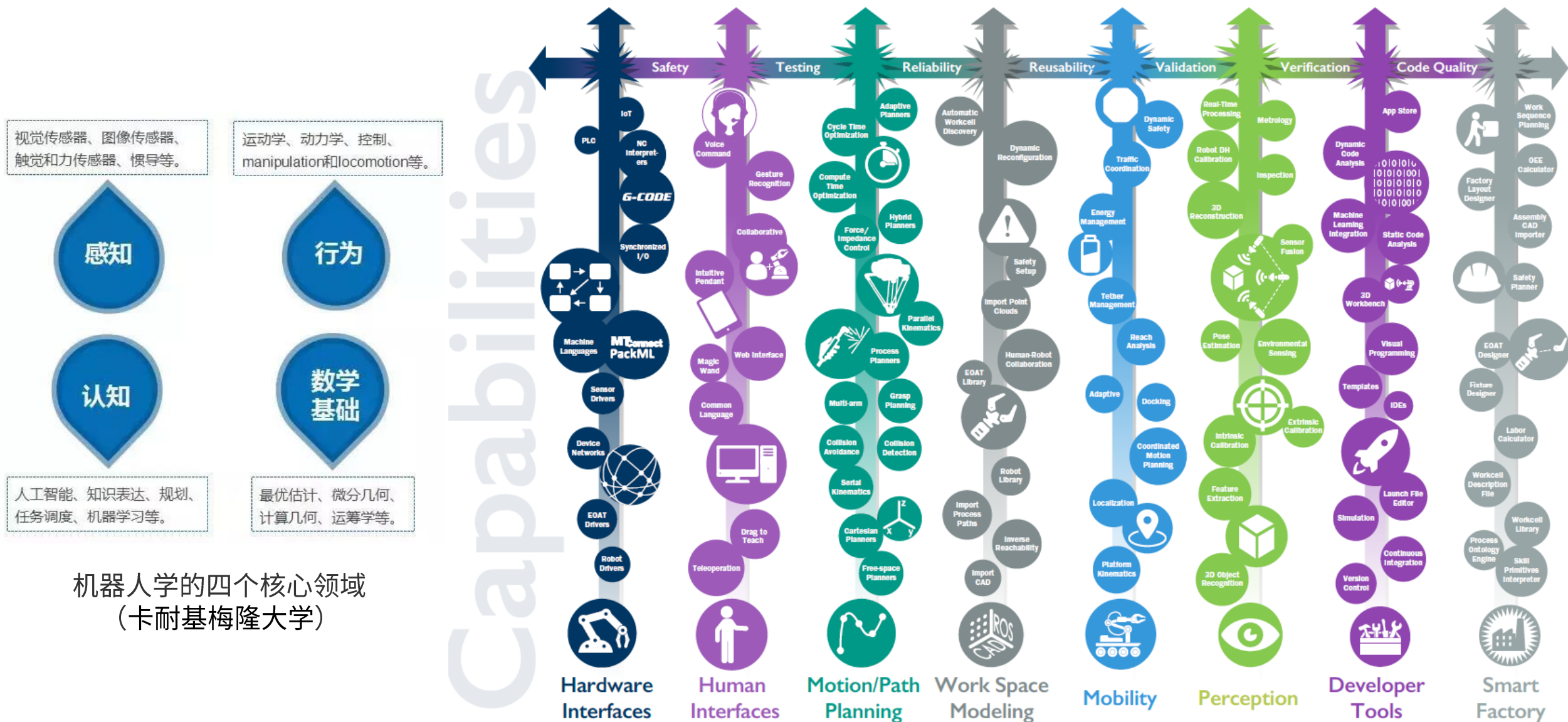
一起从零手写URDF模型



找一款硬件，上手实验



• 找一个方向，深入学习



- 如何学习ROS:

<https://mp.weixin.qq.com/s/uYvGuiG-TlOalWUynR2Nzg>

- 一起从零手写URDF模型:

https://class.guyuehome.com/detail/p_5e1eea4fe1e5c_lgm126Xn/6

- 如何从Solidworks导出URDF模型

https://class.guyuehome.com/detail/p_5e32dce7906e0_6TqS7BwX/6

- 如何在Gazebo中实现移动机器人仿真:

https://class.guyuehome.com/detail/p_5eb2366befe4a_E4rbNmXt/6

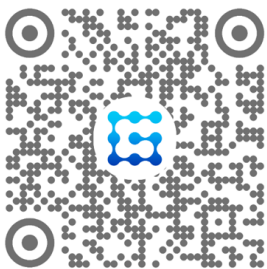
- MoveIt可视化配置及仿真指南

https://class.guyuehome.com/detail/p_5e71966b3fdfd_g4DpRGg9/6

感谢观看

怕什么真理无穷，进一寸有一寸的欢喜

更多精彩，欢迎关注



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