

Setup Raspberry Pi:
Used Canakit Raspberry Pi 4
Straightforward setup - connected to room WiFi

Setting up sensors:
<https://learn.adafruit.com/adxl343-breakout-learning-guide/assembly>
Pre-solder:

Installed Azure CLI:
<https://docs.microsoft.com/en-us/cli/azure/install-azure-cli-macos>

Followed this to get raspberry pi set up as a device
<https://docs.microsoft.com/en-us/azure/iot-hub/iot-hub-raspberry-pi-kit-node-get-started>

But, stopped at section which sends message using node js
Instead, used the python SDK:

<https://github.com/Azure/azure-iot-sdk-python>

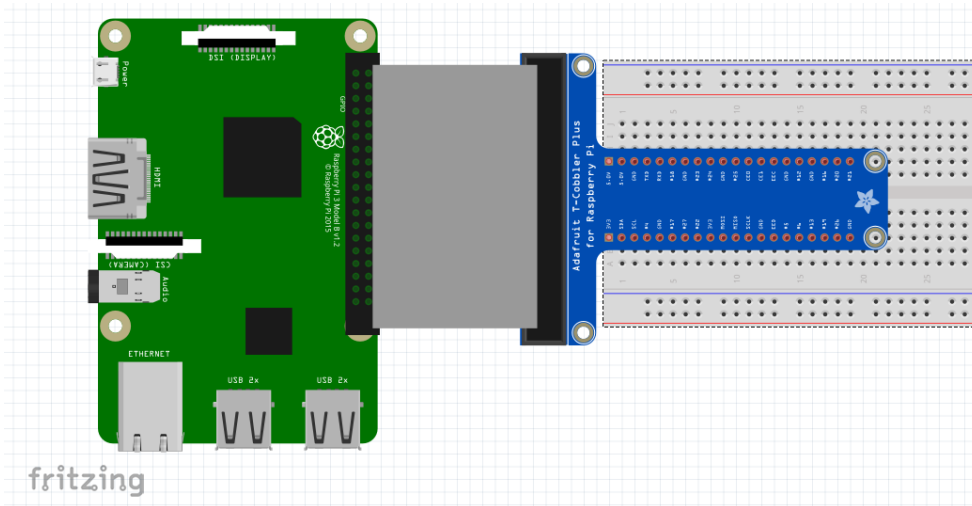
Sent dummy message from Pi to Azure:
Quick start guide here:
<https://github.com/Azure/azure-iot-sdk-python/tree/main/azure-iot-device/samples>

Basic order of guides:

1. [Install and use IoT explorer](#)
2. <https://docs.microsoft.com/en-us/cli/azure/install-azure-cli-macos>
3. [Send telemetry using SDK](#) (only for setting up iot hub, device registration)
4. But, use python SDK on the Pi: <https://github.com/Azure/azure-iot-sdk-python>
5. [Manage cloud device messaging with Azure IoT Tools for VS Code](#) Use VSCode extension to easily view messages / manage devices
6. <https://learn.adafruit.com/adxl343-breakout-learning-guide/circuitpython> Set up sensor and read data in python

Setting up the Raspberry Pi

1. <https://mikefrobbins.com/2020/01/22/initial-setup-of-a-canakit-raspberry-pi-4-4gb-starter-kit/> - Great guide to get the Pi4 setup and connected to a monitor
2. Connect the adafruit T-cobbler to the Pi and the breadboard



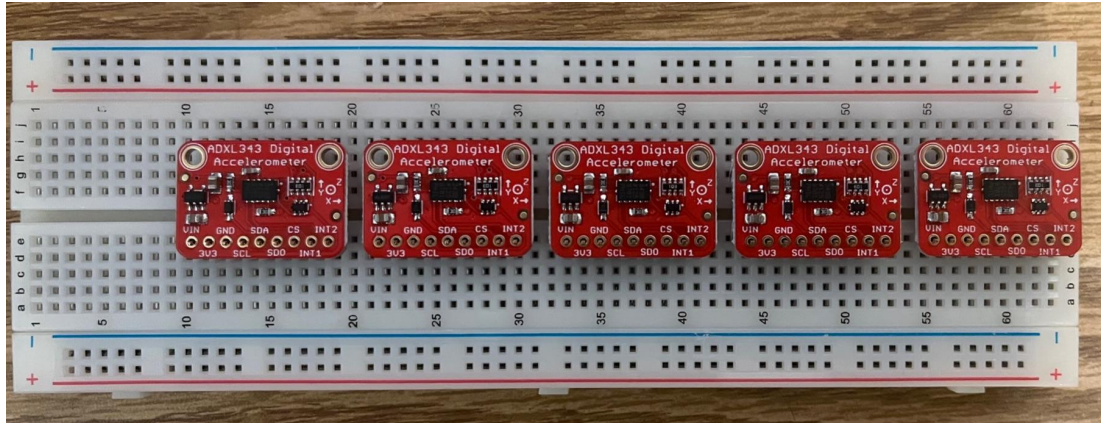
This will make wiring easier because the pins will be clearly labelled

3. Install an IDE like <https://thonny.org>

Connecting multiple sensors

1. Solder the sensors

(<https://learn.adafruit.com/adxl343-breakout-learning-guide/assembly>) for all 5



2. Install necessary CircuitPython (version of micropython that is able to interface with hardware)
<https://learn.adafruit.com/circuitpython-on-raspberrypi-linux/installing-circuitpython-on-raspberrypi>
3. Enable 2 more I2C buses
4. Add 1K8 pullup resistors to the new I2C ports
5. Connect the sensors:
 - a. For every I2C bus, connect two sensors, one of which has the SDO port wired to HIGH to use an alternate address
6. Run "test.py" file - see all 5 sensor readings show up

Communicating with Azure

1. [Install and use IoT explorer](#)
2. <https://docs.microsoft.com/en-us/cli/azure/install-azure-cli-macos>
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^TODO combine together, include python scripts that merges previous step and the following:

Visualizing as a graph:

1. Send telemetry using PNP conventions using code here:
https://github.com/Azure/azure-iot-sdk-python/blob/main/azure-iot-device/samples/pnp/sample_thermostat.py
2. Read from iot hub and display in node using this guide
<https://docs.microsoft.com/en-us/azure/iot-hub/iot-hub-live-data-visualization-in-web-apps> and my modified code.