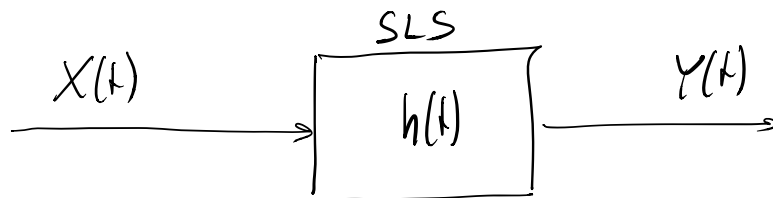


ESERCIZIO - 18/07/2017

$$X(t)$$

$$S_X(f) = \frac{\sigma_X^2}{2B} \text{rect}\left(\frac{f}{2B}\right)$$



$$h(t) = \frac{1}{2} \delta(t) + \delta(t-T) + \delta(t-2T)$$

- 1) Calcolare $S_Y(f)$
- 2) Disegnare il grafico di $S_Y(f)$ per $B = \frac{1}{2T}$
- 3) Calcolare $R_Y(\tau)$
- 4) Disegnare il grafico di $R_Y(\tau)$ per $B = \frac{1}{2T}$

Soluzione

$$1) \text{ Due strade } \begin{cases} \nearrow S_X(f) \Rightarrow R_X(\tau) \Rightarrow R_Y(\tau) = R_X(\tau) \otimes h(\tau) \otimes h(\tau) \\ \searrow h(t) \Rightarrow H(f) \Rightarrow S_Y(f) = S_X(f) |H(f)|^2 \end{cases}$$

$$S_Y(f) \stackrel{||}{=} \text{TCF}[R_Y(\tau)]$$

• I strada

$$R_X(\tau) = \text{ATCF}[S_X(f)] = \text{ATCF}\left[\frac{\sigma_X^2}{2B} \text{rect}\left(\frac{f}{2B}\right)\right]$$

$$= \sigma_X^2 \text{sinc}(2BT)$$

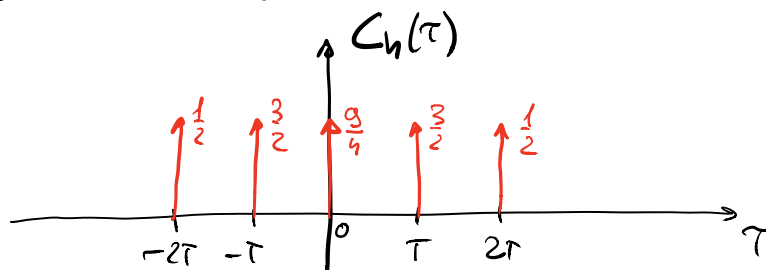
$$R_Y(\tau) = R_X(\tau) \otimes \underbrace{h(\tau) \otimes h(-\tau)}_{C_h(\tau) = \int_{-\infty}^{+\infty} h(t) h(t-\tau) dt}$$

$$h(t) = \frac{1}{2} \delta(t) + \delta(t-T) + \delta(t-2T)$$

$$h(-t) = \frac{1}{2} \delta(t) + \delta(t+T) + \delta(t+2T)$$

$$\begin{aligned} h(t) \otimes h(-t) &= \frac{1}{4} \delta(t) + \frac{1}{2} \delta(t+T) + \frac{1}{2} \delta(t+2T) + \\ &+ \frac{1}{2} \delta(t-T) + \delta(t) + \delta(t+T) + \\ &+ \frac{1}{2} \delta(t-2T) + \delta(t-T) + \delta(t) \end{aligned}$$

$$\begin{aligned} &= \frac{9}{4} \delta(t) + \frac{3}{2} \delta(t+T) + \frac{1}{2} \delta(t+2T) + \\ &+ \frac{3}{2} \delta(t-T) + \frac{1}{2} \delta(t-2T) \end{aligned}$$



$$R_Y(\tau) = R_X(\tau) \otimes C_h(\tau)$$

$$= \frac{1}{2} R_X(\tau-2T) + \frac{3}{2} R_X(\tau-T) + \frac{9}{4} R_X(\tau) + \frac{3}{2} R_X(\tau+T) + \frac{1}{2} R_X(\tau+2T)$$

$$R_Y(\tau) = \sigma_x^2 \left[\frac{1}{2} \text{sinc}[2B(\tau+2T)] + \frac{3}{2} \text{sinc}[2B(\tau+T)] + \right. \\ \left. + \frac{9}{4} \text{sinc}[2B\tau] + \frac{3}{2} \text{sinc}[2B(\tau-T)] + \frac{1}{2} \text{sinc}[2B(\tau-2T)] \right]$$

$$S_Y(f) = \frac{\sigma_x^2}{2B} \text{rect}\left(\frac{f}{2B}\right) \left[\frac{1}{2} e^{j2\pi f 2T} + \frac{3}{2} e^{j\pi f T} + \frac{9}{4} + \frac{3}{2} e^{-j2\pi f T} + \frac{1}{2} e^{-j2\pi f 2T} \right]$$

ricordo seno
il coseno!

$$= \frac{\sigma_x^2}{2B} \text{rect}\left(\frac{f}{2B}\right) \left[\frac{9}{4} \cos(4\pi f T) + 3 \cos(2\pi f T) \right]$$

• II° strada

$$h(t) = \frac{1}{2} \delta(t) + \delta(t-T) + \delta(t-2T)$$

$$H(f) = \frac{1}{2} + e^{-j2\pi f T} + e^{-j4\pi f T}$$

$$|H(f)|^2 = H(f) H^*(f) =$$

$$= \left(\frac{1}{2} + e^{-j2\pi f T} + e^{-j4\pi f T} \right) \left(\frac{1}{2} + e^{j2\pi f T} + e^{j4\pi f T} \right)$$

$$= \frac{1}{4} + \frac{1}{2} e^{j2\pi f T} + \frac{1}{2} e^{j4\pi f T} + \frac{1}{2} e^{-j2\pi f T} + 1 + e^{j2\pi f T} + \\ + \frac{1}{2} e^{-j4\pi f T} + e^{-j2\pi f T} + 1$$

$$= \frac{9}{4} + \frac{3}{2} e^{j2\pi fT} + \frac{1}{2} e^{j4\pi fT} + \frac{3}{2} e^{-j2\pi fT} + \frac{1}{2} e^{-j4\pi fT}$$

$$= \frac{9}{4} + 3 \cos(2\pi fT) + \cos(4\pi fT)$$

$$S_Y(f) = S_X(f) |H(f)|^2$$

$$= \frac{\sigma_x^2}{2B} \text{rect}\left(\frac{f}{2B}\right) \left[\frac{9}{4} + 3 \cos(2\pi fT) + \cos(4\pi fT) \right]$$

$$R_Y(\tau) = \text{ATCF}[S_Y(f)]$$

$$= \frac{9}{4} \sigma_x^2 \text{sinc}(2B\tau) + \frac{3}{2} \left[\sigma_x^2 \text{sinc}[2B(\tau - T)] + \sigma_x^2 \text{sinc}[2B(\tau + T)] \right] + \frac{1}{2} \left[\sigma_x^2 \text{sinc}[2B(\tau - 2T)] + \sigma_x^2 \text{sinc}[2B(\tau + 2T)] \right]$$

⇒ Si ottengono gli stessi risultati.

