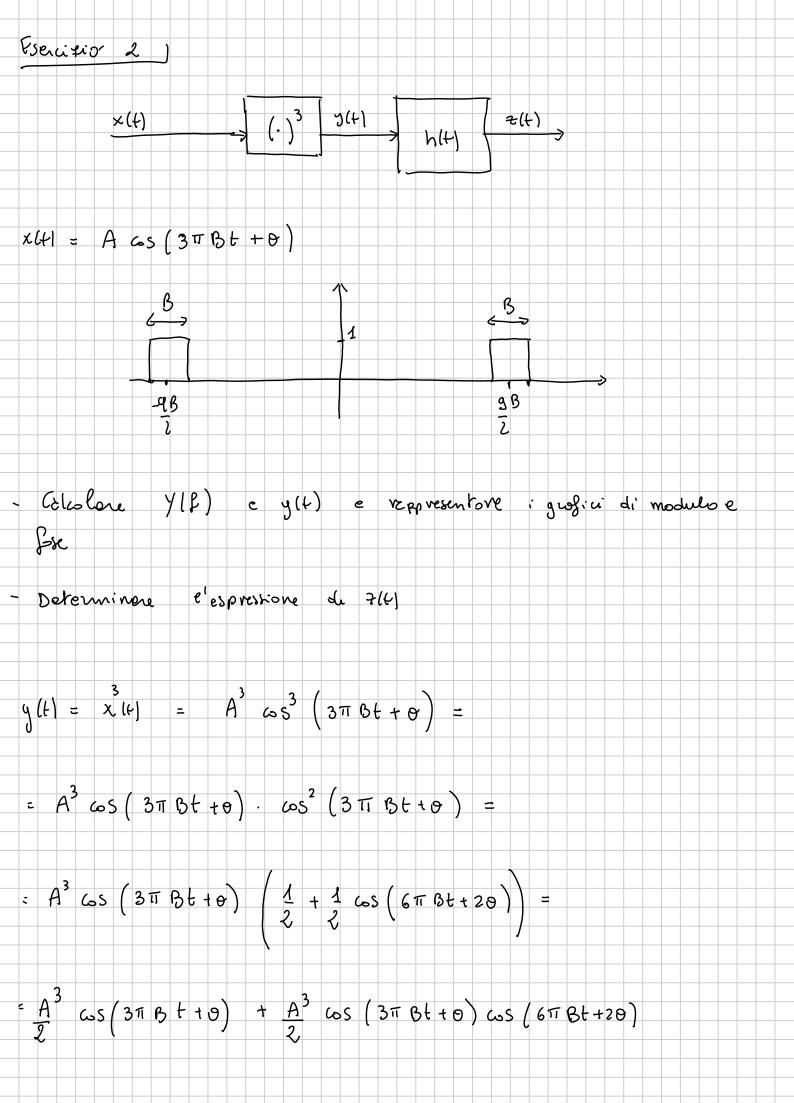
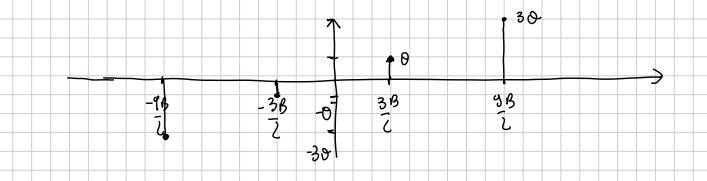


$$\begin{array}{c} \gamma(\ell) = S\left(\beta + \beta + \beta\right) - S\left(\beta - (\beta + \beta)\right) - \\ - \frac{1}{8} \text{ vect } \left(\frac{\beta + (\beta + \beta)}{8}\right) + \frac{1}{6} \text{ vect } \left(\frac{\ell - (\beta + \beta)}{8}\right) \\ y(\ell) = -2i \text{ sin } \left(2\pi (\beta + \beta) + \right) - \text{ sinc } (\pm \beta) \in \\ - 2i \text{ sin } \left(2\pi t \left(\beta + \beta\right)\right) + \text{ sinc } (\pm \beta) \left(\frac{1}{6}\right) + \frac{1}{6} + \frac{$$



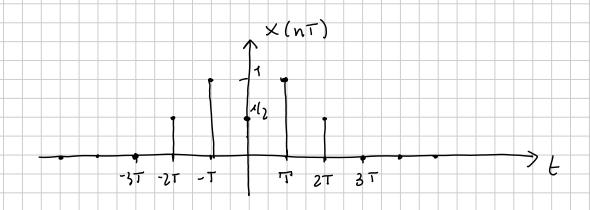


$$2(f) = \frac{A^{3}}{8} \left( 5 \left( f - \frac{93}{2} \right) e^{\frac{130}{2}} + 5 \left( f + \frac{36}{2} \right) e^{-\frac{130}{2}} \right)$$

$$\frac{7(t)}{4} = A^3 \cos \left(2\pi 98t + 39\right)$$

## Esercito 31

Si colcoli la Trosformora Discuta di Fourier (TDF), X(f) della seopuenze in figura.



$$x[n] = 1 S[n] + 1 S[n-1] + 1 S[n+1] + 1 S[n-2] + 1 S[n+2]$$

Teone mo del zirondo

$$= 1 + 2 \cos \left(2787\right) + \cos \left(27827\right)$$

$$ComP(TINO) 13 - APRILE 2010 \)

Fraction 401

Sia dato il sistema

$$y[t] = \left[ x(t) \right] + \left[ x(a) \text{ old} \right]$$

Sile SE il sistema & :

$$- \text{LineAre}, \text{Stanionario}, \text{ Con Methoria , stangliz, causalz}$$

$$- \text{LineAre}$$

$$x[t] = 3 \times x[t] + 5 \times x[t]$$

$$T[x[t]] = \left[ 3 \times x[t] + 5 \times x[t] + \left[ (3 \times x[t] + 5 \times x[t]) \text{ old} \right] \neq \left[ (3 \times x[t] + 5 \times x[t]) \text{ old} \right]$$

And if  $x = 3 \times x[t] + 5 \times x[t] + 5 \times x[t] = 3 \times x[t] + 5 \times x[t] = 3 \times x[t] + 5 \times x[t] = 3 \times x[t] = 3 \times x[t] + 5 \times x[t] = 3 \times x[t] =$$$

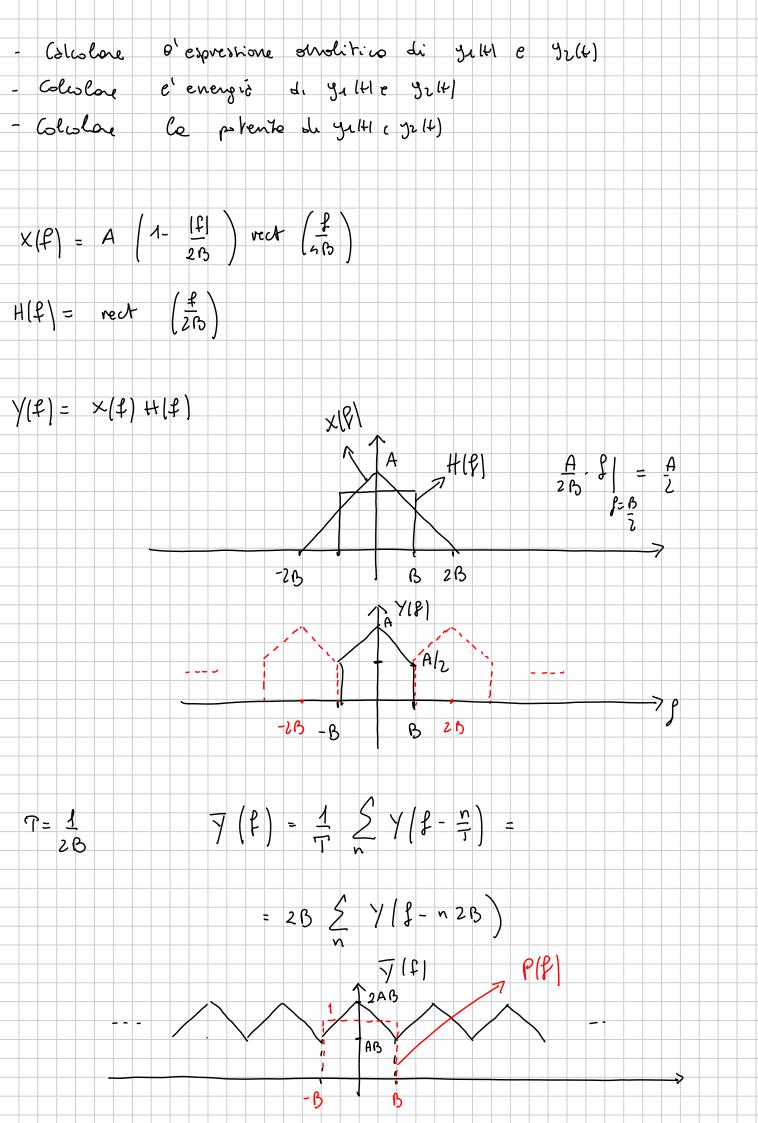
- ST ATIONAMO x(+-t,) => y(+t.) a-t= a'  $T(x(t-t_s)) = |x(t-t_s)| + |x(d-t_s)| dd$ = |x(t-t-)| + (x(d'))dd' t-t0 y (t-ts)= |x(t-ts)|+ (x(d) dd NON & STATIONARIO MEMONIA Il sistema ho memoria perché é usuira dipensie de voloni precedentia t. - CAUSALE Se b < t Il sistemo et course perut dipende sels do istonti precedenti at.

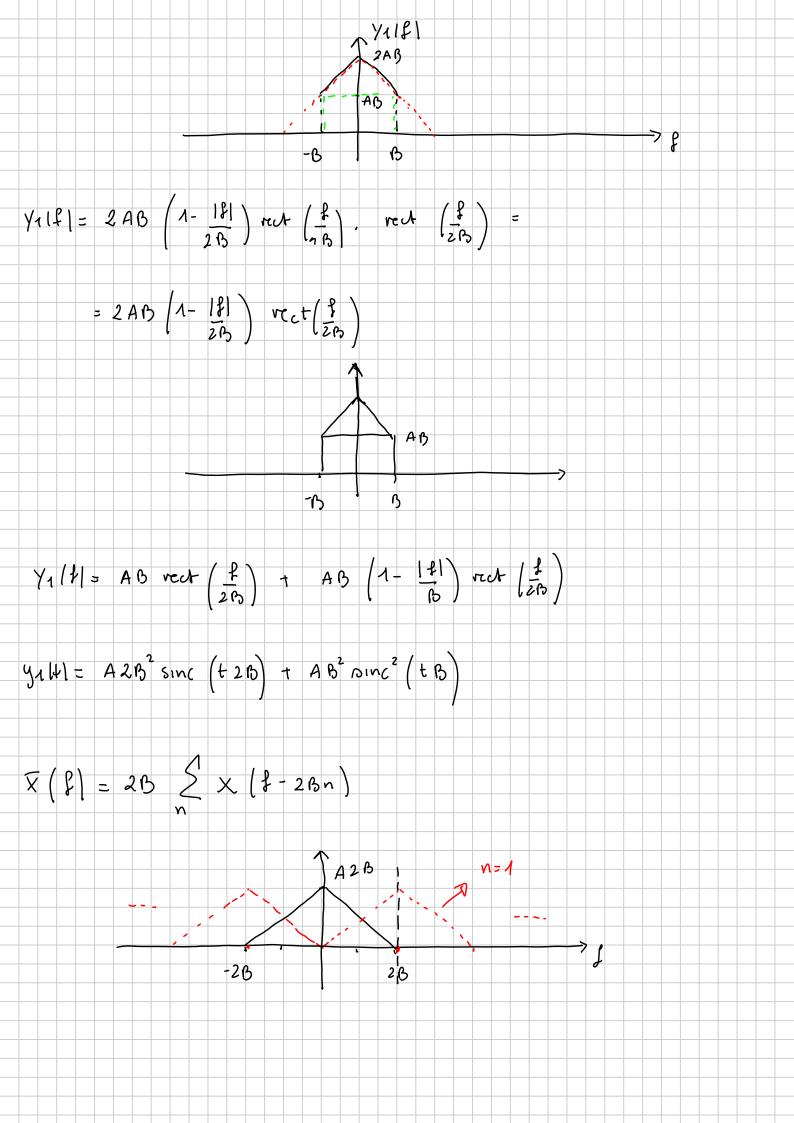
- STABILITA

$$|X(t)| < tM$$

per ognit

 $g(t) = |x(t)| + \int x(a) da$ 
 $|x(t)| = |x(t)| + \int x(a) da$ 
 $|x(t)| + \int |x(t)| + \int x(a) da$ 
 $|x(t)| + \int |x(t)| + \int |x(t)| da$ 
 $|x(t)| + \int |x(t)| da$ 
 $|x(t)$ 





Eyz = 
$$\begin{pmatrix} 1 & 4 & 1 \\ 1 & 4 & 1 \\ 1 & 4 & 4 \end{pmatrix}$$
 =  $\begin{pmatrix} 4 & 4 & 6 \\ 4 & 4 & 6 \end{pmatrix}$  of =  $4 & 4 & 6 \end{pmatrix}$  =  $8 & 4 & 6 \end{pmatrix}$ 

Salt e Juth some segnal and energy Jinita e openal house patente nulla

Ry1 = Ry2 = 0

Esercitio 3)

X(t) > 9 y(t)

W(t) =  $\sum_{n=-\infty}^{\infty} \cot\left(\frac{t-2T_n}{T/2}\right)$ 

W(t) =  $\cos\left(\frac{T_nt}{T}\right)$ 

(Alcolare

Xn , X(t))

Finery is a present of y(t)

Finery is a present of y(t)

$$X_{0}(t) = \operatorname{rect}\left(\frac{t}{\tau_{12}}\right)$$

$$X(t) = \sum_{n} X_{n} \left(t - nzT\right)$$

$$X(t) = \sum_{n} X_{n} \left(t - nzT\right)$$

$$Y(t) = X(t) \cdot W(t)$$

$$Y(t) = X(t) \cdot W(t)$$

$$Y(t) = X(t) \cdot W(t)$$

$$Y(t) = \sum_{n} Y_{n} \left(t - nT_{n}\right)$$

$$Y_{n} = \frac{1}{T_{0}} Y_{n} \left(\frac{n}{T_{0}}\right)$$

$$X_{n} = \frac{1}{T_{0}} X_{n} \left(\frac{n}{T_{0}}\right)$$

$$X_{n} = \frac{1}{T_{0}} X_{n} \left(\frac{n}{T_{0}}\right)$$

$$X_{n} = \frac{1}{T_{0}} \frac{1}{T_{0}} X_{n} \left(\frac{n}{T_{0}}\right)$$

$$S_{S}(t) = C_{S}(t) + T_{D}$$

$$W_{O}(t) = C_{O}(t) + T_{D}$$

$$W_{O}(t) = C_{O}(t) + T_{D}$$

$$W_{O}(t) = X_{O}(t) + W_{O}(t) = C_{O}(t) + T_{D}$$

$$W_{O}(t) = X_{O}(t) + W_{O}(t) = C_{O}(t) + T_{D}$$

$$W_{O}(t) = X_{O}(t) + W_{O}(t) = C_{O}(t) + T_{D}$$

$$W_{O}(t) = X_{O}(t) + W_{O}(t) = C_{O}(t) + T_{D}$$

$$W_{O}(t) = X_{O}(t) + W_{O}(t) = C_{O}(t) + T_{D}$$

$$W_{O}(t) = X_{O}(t) + W_{O}(t) + T_{D}(t) +$$

