

Homework 2 - Theoretical part

Solutions

1. Solution to Q1

$$\begin{aligned} \text{bias} &= \mathbb{E}[h_D(x')] - f(x') \\ \text{variance} &= \mathbb{E}[(h_D(x') - \mathbb{E}[h_D(x')])^2] \end{aligned}$$

$$\begin{aligned} \mathbb{E}[(h_D(x') - y')^2] &= \mathbb{E}[(h_D(x') - (f(x') + \epsilon))^2] \\ &= \mathbb{E}[(h_D(x') - (f(x') + \epsilon) + \mathbb{E}[h_D(x')] - \mathbb{E}[h_D(x')])^2] \\ &= \mathbb{E}[((h_D(x') - \mathbb{E}[h_D(x')]) + \mathbb{E}[h_D(x')] - (f(x') + \epsilon))^2] \\ &= \mathbb{E}[(h_D(x') - \mathbb{E}[h_D(x')])^2] + \mathbb{E}[(\mathbb{E}[h_D(x')] - (f(x') + \epsilon))^2] + 2\mathbb{E}[h_D(x') - \mathbb{E}[h_D(x')]] \mathbb{E}[(\mathbb{E}[h_D(x')] - (f(x') + \epsilon))] \\ &= \mathbb{E}[(h_D(x') - \mathbb{E}[h_D(x')])^2] + \mathbb{E}[(\mathbb{E}[h_D(x')] - f(x'))^2] + \mathbb{E}[\epsilon^2] \\ &\quad + 2\mathbb{E}[h_D(x') - \mathbb{E}[h_D(x')]] \mathbb{E}[(\mathbb{E}[h_D(x')] - f(x'))] \\ &\quad + 2\mathbb{E}[h_D(x') - \mathbb{E}[h_D(x')]] \mathbb{E}[\epsilon] \\ &\quad + 2\mathbb{E}[\mathbb{E}[h_D(x')] - f(x')] \mathbb{E}[\epsilon] \end{aligned}$$

Using $\mathbb{E}[\epsilon] = 0$

Using $\mathbb{E}[x - \mathbb{E}[x]] = 0$

$$\begin{aligned} \mathbb{E}[(h_D(x') - y')^2] &= \mathbb{E}[(h_D(x') - \mathbb{E}[h_D(x')])^2] + \mathbb{E}[(\mathbb{E}[h_D(x')] - f(x'))^2] + \mathbb{E}[\epsilon^2] \\ &= \text{Var}(h_D(x')) + \text{Bias}(h_D(x'))^2 + \mathbb{E}[\epsilon^2] \\ &= \text{Variance} + \text{Bias}^2 + \mathbb{E}[\epsilon^2] \end{aligned}$$

2. Solution to Q2

(a) The answer is Yes.

$$f(x) = \lfloor x \rfloor \% 2$$

(b) The answer is yes.

$$f(x_1, x_2) = x_1 * x_2$$

(c) Yes, it can be possible.

$$f(x_1, x_2) = \sqrt{x_1^2 + x_2^2}, f(y_1, y_2) = \sqrt{y_1^2 + y_2^2}$$

$$\phi(x) = \lfloor (\sqrt{x_1^2 + x_2^2}) \rfloor \% 2$$

The kernel is :

$$K(x, y) = \phi(x) * \phi(y) = \lfloor (\sqrt{x_1^2 + x_2^2}) \rfloor \% 2 * \lfloor (\sqrt{y_1^2 + y_2^2}) \rfloor \% 2$$

3. Solutions to Q3

(a)

$$f(x) = \log(x^4) \sin(x^3)$$

Applying the Product rule we get

$$\frac{d}{dx}[f(x)g(x)] = f(x)g'(x) + f'(x)g(x)$$

$$\frac{d}{dx}(\log(x^4)\sin(x^3)) = \log(x^4)\cos(x^3)(3x^2) + \frac{1}{x^4}(\sin(x^3))(4x^3)$$

$$f'(x) = (12x^2)\log(x)\cos(x^3) + \frac{4}{x}\sin(x^3)$$

(b)

$$f(x) = \exp\left(\frac{-1}{2\sigma}(x - \mu)^2\right)$$

Applying the Product rule we get

$$\frac{d}{dx}[f(x)g(x)] = f(x)g'(x) + f'(x)g(x)$$

$$\frac{d}{dx}\left(\exp\left(\frac{-1}{2\sigma}(x - \mu)^2\right)\right) = \left(\exp\left(\frac{-1}{2\sigma}(x - \mu)^2\right)\right)\left(\left(\frac{-1}{2\sigma}\right)(2)(x - \mu)\right)$$

$$f'(x) = f(x)\left(\frac{-1}{\sigma}(x - \mu)\right)$$

(c)

$$f_1(x) = \sin(x_1)\cos(x_2), x \in \mathbb{R}^2$$

$$f_2(x, y) = x^T y, x, y \in \mathbb{R}^n$$

$$f_3(x) = xx^T, x \in \mathbb{R}^n$$

i. f_1

$$\frac{\partial f_1}{\partial x_1} = \cos(x_1)\cos(x_2)$$

$$\frac{\partial f_1}{\partial x_2} = -\sin(x_1)\sin(x_2)$$

$$J = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \end{bmatrix} = [\cos(x_1)\cos(x_2) - \sin(x_1)\sin(x_2)] \in \mathbb{R}^{1 \times 2}$$

ii. f_2

$$\frac{\partial f_2}{\partial x} = \begin{bmatrix} \frac{\partial f_2}{\partial x_1} & \dots & \frac{\partial f_2}{\partial x_n} \end{bmatrix} = [y_1 \dots y_n] = y^T \in \mathbb{R}^n$$

$$\frac{\partial f_2}{\partial y} = \begin{bmatrix} \frac{\partial f_2}{\partial y_1} & \dots & \frac{\partial f_2}{\partial y_n} \end{bmatrix} = [x_1 \dots x_n] = x^T \in \mathbb{R}^n$$

$$J = \begin{bmatrix} \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix} = [y^T x^T] \in \mathbb{R}^{1 \times 2n}$$

iii. f_3

$$xx^T = \begin{bmatrix} x_1 x^T \\ x_2 x^T \\ \vdots \\ x_n x^T \end{bmatrix} = \begin{bmatrix} xx_1 & xx_2 & \dots & xx_n \end{bmatrix} \in \mathbb{R}^{n \times n}$$

$$\frac{\partial f_3}{\partial x_1} = \begin{bmatrix} x^T \\ 0_n^T \\ \vdots \\ 0_n^T \end{bmatrix} + \begin{bmatrix} x & 0_n & \dots & 0_n \end{bmatrix} \in \mathbb{R}^{n \times n}$$

$$\frac{\partial f_3}{\partial x_i} = \begin{bmatrix} 0_{(i-1) \times n} \\ x^T \\ \vdots \\ 0_{(n-1+1) \times n} \end{bmatrix} \begin{bmatrix} 0_{(i-1) \times n} & x^T & \dots & 0_{(n-i+1) \times n} \end{bmatrix} \in \mathbb{R}^{n \times n}$$

We need to concatenate the results to get the final results.

$$J = \begin{bmatrix} \frac{\partial f_3}{\partial x_1} & \dots & \frac{\partial f_3}{\partial x_n} \end{bmatrix} \in \mathbb{R}^{(n \times n) \times n}$$

(d) i.

$$f(z) = \exp\left(-\frac{1}{2}z\right)$$

$$z = g(y) = y^T S^{-1}y$$

$$y = h(x) = x - \mu$$

$$\frac{df}{dx} = \frac{\partial f}{\partial z} \frac{\partial g}{\partial y} \frac{\partial h}{\partial x} \in \mathbb{R}^{1 \times D}$$

$$\frac{\partial f}{\partial z} = -\frac{1}{2} \exp\left(-\frac{1}{2}z\right) \in \mathbb{R}^{1 \times 1}$$

$$\frac{\partial g}{\partial y} = 2y^T S^{-1} \in \mathbb{R}^{1 \times D}$$

$$\frac{\partial h}{\partial x} = I_D \in \mathbb{R}^{D \times D}$$

so that

$$\frac{df}{dx} = -\exp\left(-\frac{1}{2}(x - \mu)^T S^{-1}(x - \mu)\right) (x - \mu)^T S^{-1}$$

ii.

$$f(x) = \text{tr}(xx^T + \sigma I)$$

Here $x \in \mathbb{R}^D$ and $tr(A)$ is the trace of A.

We define $X = xx^T$

Trace sums up all the diagonal elements, such that

$$\frac{\partial}{\partial x_j} (tr(X + \sigma^2 I)) = \sum_{i=1}^D \frac{\partial X_{ii} + \sigma^2}{\partial x_j} = 2x_j$$

for $j = 1, \dots, D$. We can conclude that

$$\frac{\partial}{\partial x_j} (tr(xx^T + \sigma^2 I)) = 2x^T \in \mathbb{R}^{1 \times D}$$

iii.

$$f = \tanh(z)$$

Here $f \in \mathbb{R}^M$.

$$z = Ax + b$$

Here $x \in \mathbb{R}^N$, $A \in \mathbb{R}^{M \times N}$, $b \in \mathbb{R}^M$.

Here, \tanh is applied to every component of x .

$$\frac{\partial f}{\partial z} = \text{diag}(1 - \tanh^2(z)) \in \mathbb{R}^{M \times M}$$

$$\frac{\partial z}{\partial x} = \frac{\partial Ax}{\partial x} = A \in \mathbb{R}^{M \times N}$$

$$\frac{\partial f}{\partial x} \in \mathbb{R}^{M \times N}$$

Overall derivative is an $M \times N$ matrix.

4. Solutions to Q5

$$(a) R_{\text{emp}}(h) = \frac{1}{n} \sum_{i=1}^n (h(x) - y^2)$$

$$R(f) = \mathbb{E}_{p(x,y)} (h(x) - y^2)$$

(b)

$$\mathbb{E}_{D \sim p} [\text{error}_{LOO}] = \mathbb{E}_{\substack{D' \sim p \\ (x,y) \sim p}} [(y - h_{D'}(x))^2]$$

$$\mathbb{E}_{D \sim p} [\text{error}_{LOO}] = \mathbb{E}_{D' \sim p} \left[\frac{1}{n} \sum_{i=1}^n \ell(h_{D \setminus i}(x_i), y_i) \right]$$

$$\mathbb{E}_{D \sim p} [\text{error}_{LOO}] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}_{D \sim p} [\ell(h_{D \setminus i}(x_i), y_i)]$$

$$\mathbb{E}_{D \sim p} [\text{error}_{LOO}] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}_{\substack{D' \sim p \\ (x,y) \sim p}} [\ell(h_{D'}(x), y)]$$

$$\mathbb{E}_{D \sim p} [\text{error}_{LOO}] = \mathbb{E}_{\substack{D' \sim p, \\ (x, y) \sim p}} \left[(y - h_{D'}(x))^2 \right]$$

error_{LOO} is an (almost) unbiased estimator of the risk of $h_{D'}$ because D' contains $(n-1)$ samples. D contains n samples and n is very large.

- (c) For n observations and d weights, complexity of Matrix Multiplication of $X^T X$ is $\mathcal{O}(d^2 n)$ and the matrix inverse complexity is $\mathcal{O}(d^3)$.

Total complexity = $(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$ is $\mathcal{O}(d^2 n) + \mathcal{O}(d^3)$.

- (d)

$$\text{error}_{LOO} = \frac{1}{n} \sum_{i=1}^n (y_i - [(\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{X}_{-i}^T \mathbf{y}_{-i}]^T \mathbf{x}_i)^2$$

Total complexity = $\mathcal{O}(d^2 n^2) + \mathcal{O}(d^3 n)$.

- (e) From the previous question we have the

$$\text{error}_{LOO} = \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i)^2$$

We are putting this value in the given equation we get

$$\begin{aligned} (y_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i)^2 &= \left(\frac{y_i - \mathbf{w}^{*\top} \mathbf{x}_i}{1 - \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i} \right)^2 \\ y_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i &= \frac{y_i - \mathbf{w}^{*\top} \mathbf{x}_i}{1 - \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i} \\ \left(y_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i \right) \left(1 - \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \right) &= y_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i \\ &= y_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i - y_i \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i + \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \end{aligned} \quad (1)$$

Now $\mathbf{X}_{-i}^T \mathbf{X}_{-i} = (\mathbf{X}_i^T \mathbf{X}_i) - \mathbf{x}_i \mathbf{x}_i^T$ or $\mathbf{X}^T \mathbf{X} = \mathbf{X}_{-i}^T \mathbf{X}_{-i} + \mathbf{x}_i \mathbf{x}_i^T$

By putting this value we get

$$\begin{aligned} &\mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \\ &= \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \\ (y_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}_{-i}^T \mathbf{X}_{-i})^{-1} \mathbf{x}_i) \left(1 - \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \right) &= y_i - y_i \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i - \mathbf{y}_{-i}^T \mathbf{X}_{-i} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \\ &= y_i - (y_i \mathbf{x}_i^T + \mathbf{y}_{-i}^T \mathbf{X}_{-i}) (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \\ &= y_i - (\mathbf{y}^T \mathbf{X}) (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i \\ &= y_i - \mathbf{w}^{*\top} \mathbf{x}_i \end{aligned}$$

Hence proved.

As we know that combining w^* and $(\mathbf{X}^\top \mathbf{X})^{-1}$ the complexity is $\mathcal{O}(d^2 n) + \mathcal{O}(d^3)$.

$$4) f^*(u) = \begin{cases} 1 & \eta(u) \geq 1/2 \\ 0 & \text{otherwise} \end{cases} \quad \eta(u) = P(Y=1 | X=u)$$

a)

$$\begin{aligned} R(f) &= E_{(u,y) \sim p} [l(f(u), y)] \\ &= E_{(u,y) \sim p} [11(f(u) \neq y)] \\ &= 0 * P_{(u,y) \sim p}(f(u) = y) + \\ &\quad 1 * P_{(u,y) \sim p}(f(u) \neq y) \\ &= P_{(u,y) \sim p}(f(u) \neq y) \end{aligned}$$

b)

$$\begin{aligned} P(g(u) = y | X = u) &= P(g(u) = 1, y = 1 | X = u) \\ &\quad + P(g(u) = 0, y = 0 | X = u) \\ &= P(g(u) = 1 | X = u) * P(y = 1 | X = u) + P(g(u) = 0 | X = u) * \\ &\quad P(y = 0 | X = u) \quad [\text{Since } y \text{ \& } g \text{ are independent}] \\ P(g(u) = 1 | X = u) &= 11(g(u) = 1) \quad \left[\begin{array}{l} \text{Since } g(u) \text{ is} \\ \text{deterministic} \\ \text{given } u \end{array} \right] \\ P(g(u) = 0 | X = u) &= 11(g(u) = 0) \\ \text{we know, } \eta(u) &= P(Y=1 | X=u) \\ \therefore P(Y=0 | X=u) &= 1 - \eta(u) \end{aligned}$$

$$P(g(u) = y | X = u) \\ = \mathbb{1}(g(u) = 1) \eta(u) + \mathbb{1}(g(u) = 0)(1 - \eta(u))$$

$$P(g(u) \neq y | X = u) = 1 - P(g(u) = y | X = u) \\ = 1 - [\mathbb{1}(g(u) = 1) \eta(u) + \mathbb{1}(g(u) = 0)(1 - \eta(u))]$$

c)

$$P(g(u) \neq y | X = u) - P(f^*(u) \neq y | X = u) \\ = [\mathbb{1}(f^*(u) = 1) \eta(u) + \mathbb{1}(f^*(u) = 0)(1 - \eta(u))] \\ - [\mathbb{1}(g(u) = 1) \eta(u) + \mathbb{1}(g(u) = 0)(1 - \eta(u))]$$

we know, $\mathbb{1}(f^*(u) = 0) = 1 - \mathbb{1}(f^*(u) = 1)$
 $\mathbb{1}(g(u) = 0) = 1 - \mathbb{1}(g(u) = 1)$

$$= [\mathbb{1}(f^*(u) = 1) \eta(u) + (1 - \mathbb{1}(f^*(u) = 1))(1 - \eta(u))] \\ - [\mathbb{1}(g(u) = 1) \eta(u) + (1 - \mathbb{1}(g(u) = 1))(1 - \eta(u))] \\ = \eta(u) (\mathbb{1}(f^*(u) = 1) - \mathbb{1}(g(u) = 1)) + \\ (1 - \eta(u)) (\mathbb{1}(g(u) = 1) - \mathbb{1}(f^*(u) = 1)) \\ = (2\eta(u) - 1) (\mathbb{1}(f^*(u) = 1) - \mathbb{1}(g(u) = 1))$$

$$d) i) \text{ if } \eta(u) \geq \frac{1}{2} \Rightarrow (2\eta(u) - 1) \geq 0$$

$$\text{and } \mathbb{1}(f^*(u)=1) = 1$$

$$\Rightarrow \mathbb{1}(f^*(u)=1) - \mathbb{1}(g(u)=1) = 1 - \mathbb{1}(g(u)=1) \geq 0$$

$$\therefore (2\eta(u) - 1)(\mathbb{1}(f^*(u)=1) - \mathbb{1}(g(u)=1)) \geq 0$$

$$ii) \text{ if } \eta(u) < \frac{1}{2} \Rightarrow (2\eta(u) - 1) < 0$$

$$\text{and } \mathbb{1}(f^*(u)=1) = 0$$

$$\Rightarrow \mathbb{1}(f^*(u)=1) - \mathbb{1}(g(u)=1) = 0 - \mathbb{1}(g(u)=1) \leq 0$$

$$\therefore (2\eta(u) - 1)(\mathbb{1}(f^*(u)=1) - \mathbb{1}(g(u)=1)) \geq 0$$

Hence for both cases we get the desired result

$$e) \text{ T.P } R(g) \geq R(f^*)$$

from (c) & (d),

$$P(g(u) \neq y | X=u) - P(f^*(u) \neq y | X=u)$$

$$\Rightarrow P(g(u) \neq y | X=u) \geq P(f^*(u) \neq y | X=u) \geq 0$$

$$P(g(u) \neq y) = \int_u P(g(u) \neq y | x=u) p(x=u) du$$

$$P(f^*(u) \neq y) = \int_u P(f^*(u) \neq y | x=u) p(x=u) du$$

we have,

$$P(g(u) \neq y | x=u) \geq P(f^*(u) \neq y | x=u)$$

$$\Rightarrow \int_u P(g(u) \neq y | x=u) p(x=u) du \geq \int_u P(f^*(u) \neq y | x=u) p(x=u) du$$

$$\Rightarrow P(g(u) \neq y) \geq P(f^*(u) \neq y)$$

$$\Rightarrow R(g) \geq R(f^*)$$
