# Greenstand Duplicate Detection and Update Feature

Problem Space and System Architecture

## Data Point Capture



#### **Data Properties**

- Image
- Timestamp
- GPS Coordinate
- GPS Accuracy
- Device id
- Planter identifier

#### **Data Facts**

- Very dense GPS locations
- GPS accuracy is not good enough for unique identification

### Problem Space

- Detect when the same picture has been submitted multiple times
- Detect when the same tree has been captured multiple times
- Connect multiple captures of the same tree across moderately distant timestamps

#### Same Image Submitted Multiple Times

- Images will never be exactly the same, but sometimes 'cheaters' will take the same picture multiple times
- We need to detect and flag these so they are not counted as separate trees
- Double counting in this case would mostly apply to a single individual

# Detect when the same tree has been captured multiple times

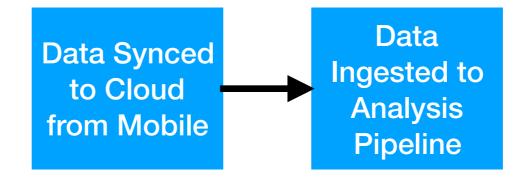
- Sometimes a tree will be captured from multiple vantage points. It should not be counted more than once.
- In this case multiple planters could try to capture the same tree.
- This scenario applies to tree captures that have nearby timestamps.

# Connect multiple captures of the same tree across moderately distant timestamps

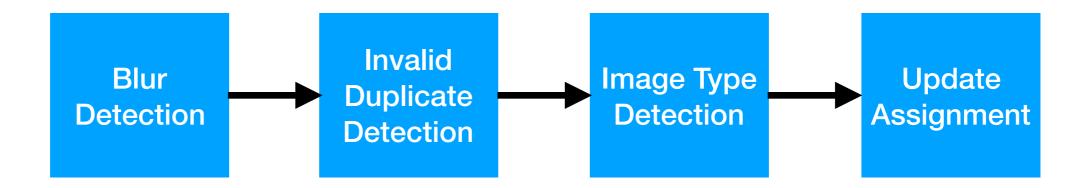
- For tree updates, additional tree captures are valid.
  These captures do not have nearby timestamps, they represent updated status about the tree.
- We need to make the best possible guess to connect new tree captures with the past captures.
- Trees grow over time and captures are not taken from the same heading, making this a difficult problem.

### Data Ingestion Pipeline

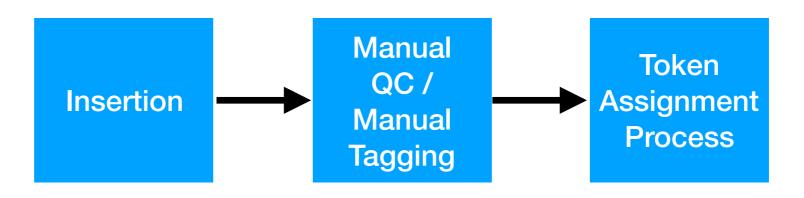
**Data Sync** 



**Data Analysis** 



**Data Approval** 



# Some Ideas for the Update Feature

- Improve GPS using Kalman Filter
- Force user behaviors
- Probabilistically assign multiple matches, with a match score, for manual QC
- Use proximity of multiple trees to design a 'solver'.