An Implementation of Database on LNC Controller

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ME 7007: Software and Hardware System Development under Industry 4.0

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June 18, 2019



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Introduction

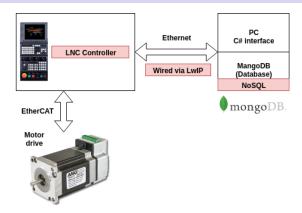


Figure 1: Framwork of experiment

Primary Scenario

Outline of experiment environment

- Setting up GUI for controller in C# (provided by LNC Tech.)
- Connecting to controller via wired Ethernet.
- Uploading G-code for controller in C# via File Transfer Protocol.
- Starting up motor drive by running uploaded G-code.
- Receiving encoder data and sending to server (.py) via socket.
- Listening to any client to be connected.
- Creating MongoClient, connecting to server and receiving data simutaneously.
- Storing data into database and collection.



Hardware

LNC controller



- ► 10.4" TFT LCD.
- Control 9+6 axis.
- Support MII/RTEX/ EtherCAT communication protocol.
- ► High-speed, high- precision and wiring saving.
- Provides interpolations to satisfy the requirements of high level of turn-milling.
- Various intelligent functions.
- Particle-button and support USB drive.

A mechanism for allowing communication between processes where running on same/different computers connected on a network.



Widely used applications:

- Instant messaging and chat.
- Real-time analytics by pushing data to clients that get represented as real-time counters, charts or log.
- Documentation collaboration.

Software

MongoDB



- Easy to install and set up.
- ▶ A BSON (a JSON-like format) to store data.
- Easy to map the document objects to application code.
- Highly scalable and available, and includes support for out-of-the-box replication.
- Support MapReduce operations for condensing a large volume of data into useful aggregated results.
- Free and open source.

Software

MongoDB - NoSQL

- Flexible data models (Schema Free)
 - NoSQL databases more relaxed in structure of data
- Clusters of cheap commodity servers to manage the data and transaction volumes
- NoSQL are still implementing their basic feature set

Why MongoDB?

- Simple queries
- Functionality provided applicable to most web applications
- Easy and fast integration of data
- Not well suited for heavy and complex transactions systems

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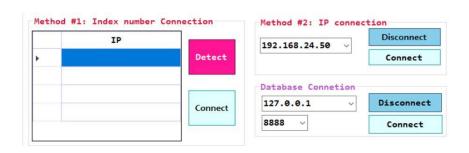
Ethernet Connection

TCPIP connection between LNC controller to PC.



Ethernet Connection

TCPIP connection between LNC controller to PC.



Data Extraction

- Extract data (eg. coordinates, loading, error) stored in R values.
- Get polling of the mirror memory for important R values.

```
private void ReadPos()
{
    for (int i = 0; i < 6; i++)
    {
        Pos_MAC[i] = scif_dll.scif_ReadR(scif_dll.R_AXIS_R_INT_MACHINE_POS + Convert.ToUInt32(i));
        Pos_ABS[i] = scif_dll.scif_ReadR(scif_dll.R_AXIS_R_INT_POS_ABSOLUTE + Convert.ToUInt32(i));
        Load[i] = scif_dll.scif_ReadR(scif_dll.R_LOAD + Convert.ToUInt32(i));
    }
}</pre>
```

Data Extraction

- Extract data (eg. coordinates, loading, error) stored in R values.
- Get polling of the mirror memory for important R values.



Controller

- Using G-code to control the hardware
- Using Ftp file transmission to upload G-code



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Machining Process

- Similar to typical factory application.
- ► G-code allows users to select machining process.
- ► Two R Values for G-code
 - ΦR290100: Return to 0 when machining ends, set to 1 to start working
 - $ightharpoonup \Phi R290101$: Set **0** to go straight path to desired points; **1** to go curve path; **2** to stop machining



Data Transmission

- ► LNC controller API function to Read R register value from Memory.
- ▶ **Socket** client(TCP) is created in same C# program.
- ▶ Socket client connects to local host (127.0.0.1).
- ► Waiting for server's acceptance/response.
- Sending Position and Payload data to socket server every second counts.

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Data Transmission

- Create a python socket server and listen to any connection.
- ► Socket server **connect**s to local host (127.0.0.1).
- Receive (recv) data from client.
- PyMongoClient gets data from server also on local host.
- Database is created simutaneously.

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G-code Payload R values Dynamically Updating Plot Find data Application Scenario Demo

Application idea

Initially, we use R value of **Payload** as our main focus of optimization control. Therefore, the acceleration/deceleration of escalators reminds us of one of the key of the motion is depending on the magnitude of payload it endures.

As to realize this scenario, we've extended the basic scenario futhermore.

Application Scenario

- Setting up GUI for controller in C# (provided by LNC Tech.)
- Connecting to controller via wired Ethernet.
- Uploading G-code for controller in C# via File Transfer Protocol.
 - G-code reads loading R values and controls rotating speed.
- Starting up motor drive by running uploaded G-code.
- Receiving encoder (& payload) data and sending to server (.py) via socket.
- Listening to any client to be connected.
- Creating MongoClient, connecting to server and receiving data simutaneously.
 - Dynamically updating plot in matplotlib.
- Storing data into database and collection.

G-code Payload R values

G-code simulation.

```
Cloud CNC (X
                                                                                         II Pause ■ Stop
                                                     26 G00 X95 Z-200
                                                     27 G90 X85 X-350 R-10 F60
W REG[290100,0]
                                                     28 x85 z-350 g-20
                                                     29 x85 x-350 x-30
#2=0
                                                     30 x85 z-350 g-35
WHILE[1]
                                                     32 G94 X40 Z-10 F60
      #1=R_REG[250096]
      IF[#1>10]
            #2=#2+15
            G01 X#2 Y#2 F8000.000
                                                     42 000 885 8-45
                                                     43 694 X40 2-55 R-10 F60
      ELSE
                                                     44 600 X45 810
            #2=#2+0.5
                                                     46 903 X40 S-10 R40 P60
                                                     47 600 X45 810
            G01 X#2 Y#2 F2500.000
                                                     49 003 X40 2-20 R40 P60
      END IF
                                                     50 000 X45 210
END WHILE
                                                     52 003 X40 2-30 R40 P60
                                                     53 000 X45 810
M30;
                                                     55 003 X40 2-40 R40 P60
```

Dynamically Updating Plot

Use **Matplotlib**, update figure and axis range once receiving data from database dynamically.

Find Data

From another point of view, once the database is built, other clients can access to the database and look for data. For our case, we hope that user can find data by giving some information of time, and investigate the process situation during that time interval.

```
In [3]: import time
          import pymongo
          import struct
          from struct import unpack
          from datetime import datetime
          import pandas as pd
 In [4]: connection = pymongo.MongoClient("mongodb://localhost:27017")
          database = connection['my database']
          collection ABS = database['my collection ABS']
          collection MAC = database['my collection MAC']
In [20]: condition = {'timestamp': {'$gt':datetime(2019, 6, 17, 17, 0, 0).strftime('%Y-%m-%d %H:%M:%S')}}
In [19]: cursor = collection ABS.find(condition)
          dataFrame = pd.DataFrame(list(cursor))
          dataFrame
Out[19]:
               ABS_X ABS_Y
                                                           timestamp
                       20861 5d076cd3f029e17e8bb825ce 2019-06-17 18:34:59
```

Find Data

```
In [3]: import time
          import pymongo
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 In [4]: connection = pymongo.MongoClient("mongodb://localhost:27017")
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In [15]: condition = {'timestamp': {'$gt':datetime(2019, 6, 17, 18, 35, 33).strftime('%Y-%m-%d %H:%M:%S')}}
In [16]: cursor = collection ABS.find(condition)
         dataFrame = pd.DataFrame(list(cursor))
          dataFrame
Out[16]:
              ABS X ABS Y
                                                id
                                                           timestamp
           0 1547941 1547941
                            5d076cf6f029e17e8bb82634 2019-06-17 18:35:34
```

1 1558504 1558504

5d076cf7f029e17e8bb82637 2019-06-17 18:35:35

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Discussions

- We use python for database operation and C# for Controller data synchronization. How to implement Inter Program Communication(IPC)?
 - ▶ By Socket TCP, we send dataFrame from C# interface to python server and bind local Host as IP address.
- Simulating the process⁵ can help users more easily monitor the entire machining process.
- Socket sends data stream in Bytes array. Thus, we take advantages of Concept of Union (The same memory address) and transform Int to Bytes array (1 Int = 4 Bytes in C#). While receiver decodes Bytes array back into Int.



https://cnc-lathe-simulator.appspot.com/

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Conclusion

Through C# GUI to give commands to controller, and store data into the database at the same time is achievable. Data visualization and its noSQL structure can better improve data storage and management. Those applications can greatly optimize control in different scenarios.

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Thank you! Any Question?