## Hamburg University

# Optimization

Notes

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#### Abstract:

Keywords: Optimization • Convexity

## Introduction

## 0.1. Definitions

## 0.2. Useful lemmas and Theorems.

#### Lemma 0.1.

Let  $(x_n)_{n\in\mathbb{N}}$  be a bounded sequence in a Hilbert Space H. Then  $(x_n)_{n\in\mathbb{N}}$  possesses a weakly convergent subsequence.

#### Lemma 0.2.

Let  $(x_n)_{n\in\mathbb{N}}$  be a sequence in a Hilbert Space H. Then  $(x_n)_{n\in\mathbb{N}}$  converges if and only if it is bounded and possesses at most one weak sequential cluster point.

## Theorem 0.1.

Let  $f: H \to (\infty, \infty]$  be a convex functional on a Hilbert space. Then the following are equivalent:

- (i) f is weakly sequentially lower semicontinuous.
- (ii) f is sequentially lower semicontinuous.
- (iii) f is lower semicontinuous.
- (iv) f is weakly lower semicontinuous.

#### Lemma 0.3.

A convex set is closed if and only if it is weakly closed.

#### Lemma 0.4.

Every bounded linear operator over a Banach Space is weakly continuos.

## Lemma 0.5 (Parallelogram law).

$$||x + y||^2 + ||x - y||^2 = 2 ||x||^2 + 2 ||y||^2$$

## 1. Lecture 1

#### Fact 1.1.

Let  $x \in H$ , let U be a neighborhood of x, let G be a real Banach space, let  $T: U \to G$ , let V be a neighborhood of Tx, and let  $R: V \to K$ . Suppose that T is Frechet differentiable at x and that R is Gteaux differentiable at Tx. Then  $R \circ T$  is Gateâux differentiable at x and  $D(R \circ T)(x) = (DR(Tx)) \circ DT(x)$ . If R is Fréchet differentiable at x, then so is  $R \circ T$ .

#### Fact 1.2.

Let  $x \in H$ , let U be a neighborhood of x, let K be a real Banach space, and let  $T: U \to K$ . Suppose that T is twice Fréchet differentiable at x. Then  $\forall (y,z) \in H \times H$ ,  $(\mathsf{D}^2T(x)y)z = (\mathsf{D}^2T(x)z)y$ .

#### Definition 1.1.

Let  $x \in H$ , let  $C \in \mathcal{V}(x)$ , and let  $T : C \to K$ . Then T is Fréchet differentiable at x if there exists an operator  $\mathbf{D}T(x) \in B(H,K)$ , called the Frchet derivative of T at x, such that

$$\lim_{0 \neq \|y\| \to 0} \frac{\|T(x+y) - Tx - \mathsf{D}T(x)y\|}{\|y\|} = 0$$

## 2. Lecture 2

## 2.1. Convexity

## Definition 2.1.

Let U be linear space. A functional  $J: U \to \mathbb{R}$  is called convex, if for  $t \in [0,1]$  and  $u_1, u_2 \in U$ .

$$J(tu_1 + (1-t)u_2) \le tJ(u_1) + (1-t)J(u_2) \tag{1}$$

holds such that the right hand sid is well defined.

- J is strictly convex if (1) holds strictly for  $\forall u_1, u_2 \in U, u_1 \neq u_2 \text{ and } t \in (0,1) \text{ with } J(u_1) < \infty \text{ and } J(u_2) < \infty.$
- An optimization problem,

$$\min_{u \in C} J(u)$$

is called convex if both C and J are convex.

#### Lemma 2.1.

If C and V are convex in U, then

- $\bullet \ \alpha V = \{w = \alpha v, v \in C\} \ \textit{is convex}.$
- ullet C+V is convex.

## Proof.

#### Lemma 2.2

Let V be a collection of convex sets in U, then  $C = \bigcap_{K \in V} K$  is convex.

*Proof.* If  $C = \emptyset$ , then C the statement is vacuously true. Consider  $C \neq \emptyset$  and  $u_1, u_2 \in C$  then  $u_1, u_2 \in K$  for all  $K \in V$ 

$$\implies tu_1 + (1-t)u_2 \in K, \quad \forall K \in V \implies tu_1 + (1-t)u_2 \in \bigcap_{K \in V} K$$

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#### Lemma 2.3.

Let  $C \in U$  convex and  $J: C \to \mathbb{R}$ . Define  $\alpha = \inf_{u \in C} J(u)$ . Then the set  $\Psi = u|J(u) = \alpha$  is convex, i.e. the solution of

$$\min_{u \in C} J(u)$$

is a convex set.

**Proof.** Let  $u_1, u_2 \in \Psi$  and  $u_t = tu_1 + (1-t)u_2$ . Sinc J is convex, it holds that  $J(u_t) \leq tJ(u_t) + (1-t)J(u_t) = \alpha$ . Thus  $J(u_t) = \alpha$ ,  $\forall t \in [0, 1]$ . Implying  $u_t \in \Psi$  Hence  $\Psi$  is convex.

#### Lemma 2.4.

Let U be linear normed space, and  $C \subset U$  a convex set and  $J: U \to \overline{\mathbb{R}}$  convex functional. Let  $\overline{u} \in C$  such that

$$J(\overline{u}) \le J(u) \quad \forall u \in B_{\epsilon}(\overline{u}) \cap C,$$

for some ball  $B_{\epsilon}(\overline{u})$  in U with center in  $\overline{u}$ . Then  $J(\overline{u}) = \inf_{u \in C} J(u)$ . In other words, the local minimizer of a convex optimization problem is also a global minimizer.

**Proof.** Let  $B_{\epsilon}(\overline{u})$  be an open neighborhood of  $\overline{u}$  with  $J(\overline{u}) \leq J(u)$  for all  $u \in B_{\epsilon}(\overline{u}) \cap C$ . Take an arbitrary  $u^* \in C$  and consider  $u_t = t\overline{u} + (1-t)u^*$ . Since C is convex  $u_t \in C$ . For some  $t \in (0,1), u_t \in B_{\epsilon}(\overline{u})$ . Thus,

$$J(\overline{u}) < J(u_t) < tJ(\overline{u}) + (1-t)J(u^*).$$

We have  $\forall t \in [0,1]$  that  $(1-t) \leq 0$ , then

$$(1-t)J(\overline{u}) < (1-t)J(u^*) \qquad \forall u^* \in C$$

Therefore,  $\overline{u}$  is a local minimizer for C.

## Theorem 2.1.

Let U is Banach Space,  $C \subset U$  convex and  $J: C \to \mathbb{R}$  Gateâux differentiable. Consider the minimization problem.

$$\min_{u \in C} J(u)$$

- 1. Let  $\overline{u}$  be a local solution. Then  $J'(\overline{u}; u \overline{u}) \geq 0$ ,  $\forall u \in C$ .
- 2. If J is convex on C, then  $J'(\overline{u}; u \overline{u}) \geq 0$ ,  $\forall u \in C$  is necessary and sufficient for global optimality of  $\overline{u}$
- 3. If J is strictly convex on C, then the minimization problem admits at most one solution.
- 4. If C is closed, and J is convex and continuous with

$$\lim_{\substack{u \in C \\ \|u\| \to \infty}} J(u) = \infty.$$

Then a global solution  $\overline{u} \in C$  exists.

## Proof.

1. Let  $\overline{u}$  be a local solution  $J(\overline{u}) \leq J(u)$ ,  $\forall u \in B_{\epsilon}(\overline{u}) \cap C$ , let  $t \in [0,1]$ ,  $u_t = \overline{u} + t(u - \overline{u})$ , then  $u_t \in C$ , since C is convex.

For small t > 0,

$$0 \le \frac{1}{t} \left[ J(u_t) - J(u) \right] \le \frac{1}{t} \left[ J(\overline{u} + t(u - \overline{u})) - J(u) \right] \xrightarrow{t \downarrow 0} J'(\overline{u}; u - \overline{u})$$

2. Since J is convex we have for  $u \in C$ ,  $J(\overline{u} + t(u - \overline{u})) \le J(\overline{u}) + t[J(u) - J(\overline{u})]$ , for t > 0

$$\implies J(u) - J(\overline{u}) \ge \frac{1}{t} \left[ J(\overline{u} + t(u - \overline{u})) - J(\overline{u}) \right] \xrightarrow{t \downarrow 0} J'(\overline{u}; u - \overline{u}) \ge 0.$$

Therefore  $\overline{u}$  is a global minimizer.

- 3. Assume, that there are two solution for the minimization problem,  $\overline{u}, u^* \in C$ , such that  $\overline{u} \neq u^*$  and  $J(\overline{u}) = J(u^*) = \inf_{u \in C} J(u)$ . Since J is strictly convex  $J(u_t) = J(t\overline{u} + (1-t)u^*) < tJ(\overline{u}) + (1-t)J(u^*) = \alpha$  for all  $t \in [0, 1]$ . Contradicting our assumption that  $u^*$  and  $\overline{u}$  are solutions.
- 4.  $\alpha = \inf_{u \in C} J(u) \in \mathbb{R} \cup \{-\infty\}$ , choose a minimizing sequence  $(u_k)_k \subset C$  with  $J(u_k) \xrightarrow{k \to \infty} \alpha$ 
  - $\Longrightarrow (u_k)_k$  is bounded, because  $J \to \infty$  as  $||u|| \to \infty$ .
  - $\Longrightarrow (u_k)_k$  contains a weakly convergent subsequence  $u_{k_e} \xrightarrow[e \to \infty]{} \overline{u} \in C$ . Since C is closed and convex.
  - $\implies$  J is weakly-lower semicontinuos because it is convex and continuos.

## 3. Lecture 3

Now consider Hilbert space  $(H, \langle \cdot, \cdot \rangle)$  with the norm defined as  $\| \cdot \| = \sqrt{(\cdot, \cdot)}$ .

Let be  $J: H \to \mathbb{R}$  a functional over a Hilbert space H, we define the set,

$$\underset{v \in C \subseteq H}{\arg\min} J(x) := \{ x \mid x \in C \land \forall v \in C : J(x) \le J(v) \}.$$

By Riesz-Fréchet representation formula, exists a unique vector  $\nabla J(x) \in H$  such that,

$$(\forall y \in H) \quad J'(x;y) = \langle y, \nabla J(x) \rangle$$

namely Gateâux gradient of J at x.

#### Lemma 3.1.

Let H Hilbert space and  $C \subset H$  closed and convex. Define  $P_C : H \to C$ ,

$$P_C(x) = \arg\min_{v \in C} [||v - x||].$$

Then,

- 1.  $P_C$  is well defined, i.e.  $\exists ! u \in C$  such that  $P_C(x) = \{u\} \ \forall x \in H$ .
- 2.  $\forall u, x \in H$ , we have  $u = P_C(x) \iff u \in C$  and  $\langle x u, v u \rangle \leq 0 \ \forall v \in C$ .
- 3.  $||P_C(u) P_C(\overline{u})|| \le ||u \overline{u}|| \quad \forall u, \overline{u} \in H$ , i.e. The projection  $P_C$  is non expansive.
- 4.  $\langle P_C(u) P_C(\overline{u}), u \overline{u} \rangle \le 0, \quad \forall u, \overline{u} \in H$
- 5. Let be t > 0 a real number, then  $\forall u \in C$ , and  $\forall v \in H$ ,  $\phi(t) = \frac{1}{t} \|P_C(u + tv) u\|$  is non-increasing.

*Proof.* 1. First we prove existence, let be  $(v_k)_k$  a minimizing sequence in C, such that

$$||x - v_k|| \to \alpha = \inf_{v \in C} ||x - v||,$$

By the parallelogram law,

$$2 \|v_j - x\|^2 + 2 \|v_i - x\|^2 = \|v_j - v_i\|^2 + \|v_j + v_i - 2x\|^2$$

$$2 \|v_j - x\|^2 + 2 \|v_i - x\|^2 = \|v_j - v_i\|^2 + 4 \left\| \frac{v_j + v_i}{2} - x \right\|^2$$

$$\implies 2 \|v_j - x\|^2 + 2 \|v_i - x\|^2 - 4 \left\| \frac{v_j + v_i}{2} - x \right\|^2 = \|v_j - v_i\|^2$$

Since C is convex  $\frac{v_i+v_j}{2} \in C$ , then by definition of  $\alpha$ ,

$$0 \le \alpha \le \left\| \frac{v_j + v_i}{2} - x \right\|$$

Therefore the above equations become in the following inequality,

$$2 \|v_j - x\|^2 + 2 \|v_i - x\|^2 - 4\alpha^2 \ge \|v_j - v_i\|^2$$

Since  $||v_i - x|| \to \alpha$  and  $||v_j - x|| \to \alpha$ , we have that  $||v_j - v_i|| \to 0$ , therefore the series is Cauchy and then converges. Since C is closed the series converges to a point  $v \in C$ .

Second we prove uniqueness, we proceed by contradiction, take  $v, v' \in C$  such  $v \neq v'$ , and both of them minimizing the distant with respect the point x, i.e.

$$||x - v|| = ||x - v'|| = \alpha = \min_{u \in C} ||u - x||$$

By the parallelogram law,

$$2 \|x - v\|^2 + 2 \|x - v'\|^2 = \|2x - v - v'\|^2 + \|v - v'\|^2$$

Since C is convex,  $\left\| \frac{v+v'}{2} - x \right\| \ge \alpha$ 

$$||v - v'||^{2} = 2||x - v||^{2} + 2||x - v'||^{2} - ||2x - v - v'||^{2}$$

$$||v - v'||^{2} = 2||x - v||^{2} + 2||x - v'||^{2} - 4||x - \frac{v - v'}{2}||^{2}$$

$$||v - v'||^{2} = 2\alpha^{2} + 2\alpha^{2} - 4||x - \frac{v - v'}{2}||^{2} \le 0$$

Therefore ||v - v'|| = 0, and v = v'.

By the uniqueness and existence  $\underset{u \in C}{\arg\min} [\|u - x\|]$  is not empty set and has only one element for each  $x \in H$ . Thus,  $P_C$  is well defined.

#### Theorem 3.1.

Let H be Hilbert space,  $C \subset H$  closed and convex,  $J: C \to \mathbb{R}$ , Gateâux differentiable at the local solution  $\overline{u}$  of  $\min_{u \in C} J(u)$ . Thus,  $J'(\overline{u}; u - \overline{u}) \geq 0$ ,  $\forall u \in C$  and it is equivalent to  $\overline{u} = P_C(\overline{u} - \delta \nabla J(\overline{u}))$ ,  $\forall \delta > 0$ .

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*Proof.* Since every Hilbert Space is a Banach space, and C is closed and Convex subset of H, and  $\overline{u}$  is a solution of minimization problem; we can apply 2.1.

Thus  $J'(\overline{u}; u - \overline{u}) \ge 0 \iff \langle u - \overline{u}, \nabla J(\overline{u}) \rangle \ge 0 \ \forall u \in C$ .

For all  $\delta > 0$ , we multiply the Gateâux gradient  $(-\delta)$  and we have,

$$\langle u - \overline{u}, -\delta \nabla J(\overline{u}) \rangle \le 0 \ \forall u \in C,$$

adding zero to the gradient,  $\langle u - \overline{u}, \overline{u} - \delta \nabla J(\overline{u}) - \overline{u} \rangle \leq 0$ . Then we set  $w \in H$  as  $w := \overline{u} - \delta \nabla J(\overline{u})$ , and applying lemma 3.1 we have,

$$\overline{u} = P_C(w) \iff \langle u - \overline{u}, w - \overline{u} \rangle$$

Thus,

$$\overline{u} = P_C(\overline{u} - \delta J(\overline{u}))$$

## 3.1. Application

Consider U, Y, Z Hilbert spaces. Let be  $J: Y \times U \to \mathbb{R}$  a functional. Consider the minimization problem,

$$\begin{cases} \overline{u} = \min_{y,u} J(y,u) \\ Ay = Bu \quad u \in U_{ad} \subset U \end{cases}$$

For some set  $U_{ad}$  closed, convex and bounded. And  $A \in \mathcal{B}(Y, Z)$  bounded and invertible with  $A^{-1} \in \mathcal{B}(Z, Y)$  and  $B \in \mathcal{B}(U, Z)$ .

Then we can write  $y \in Y$  as a function of  $u \in U$ ,

$$y = y(u) = A^{-1}Bu$$

Consider the reduced cost functional F(u) := J(y(u), u), then our problem is equivalent to

$$\overline{u}_{ad} = \min_{u \in U_{ad}} F(u)$$

Let  $(u_k)_k \in U_{ad}$  denote a minimizing sequence, i.e.  $F(u_k) \to \inf_{u \in U_{ad}} F(u)$ , since  $u_k \in U_{ad}$  the sequence is bounded. Therefore we can find a convergent subsequence  $u_{k_l} \xrightarrow[l \to \infty]{} \overline{u}$ , moreover since  $U_{ad}$  is closed and convex  $U_{ad}$  is weakly closed, implying  $\overline{u} \in U_{ad}$ 

#### Proposition 3.1.

If J is continuous and weakly lower semicontinuous, then  $\overline{u} = \underset{u \in U_{ad}}{\arg \min} [F(u)].$ 

*Proof.* If J is weakly lower semicontinuos

$$J(y(\overline{u}), \overline{u}) \leq \liminf_{k \to \infty} J(y(u_k), u_k)$$

That is,

$$F(\overline{u}) \le \liminf_{l \to \infty} F(u_k) = \alpha$$

Since 
$$u_{k_l} \xrightarrow[l \to \infty]{} \overline{u}$$
,  $\Longrightarrow y(u_k) \rightharpoonup y(\overline{u})$  and  $A^{-1}Bu_k \rightharpoonup A^{-1}B\overline{u}$ 

J is Gateâux differentiable, applying the chain rule to F and valuating in u we have

$$F_u(u;h) = J_y(y;\alpha(u;h),u) + J_u(y,u;h)$$

$$0 \leq \langle u - \overline{u}, \nabla_u F(\overline{u}) \rangle \quad \forall u \in U_{ad}$$

$$= \langle A^{-1}B(u - \overline{u}), \nabla_y J(\overline{y}, \overline{u}) \rangle_{Y^*Y} + \langle u - \overline{u}, \nabla_u J(\overline{y}, \overline{u}) \rangle_{U^*U}$$

$$= \langle A^{-1}B(u - \overline{u}), \nabla_y J(\overline{y}, \overline{u}) \rangle_{Y^*Y} + \langle u - \overline{u}, \nabla_u J(\overline{y}, \overline{u}) \rangle_{U^*U}$$

$$= \langle u - \overline{u}, (A^{-1}B)^* \nabla_y J(y, \overline{u}) \rangle_{U^*U} + \langle u - \overline{u}, \nabla_u J(y, \overline{u}) \rangle_{U^*U}$$

$$= \langle u - \overline{u}, (A^{-1}B)^* \nabla_y J(\overline{y}, \overline{u}) + \nabla_u J(\overline{y}, \overline{u}) \rangle_{U^*U}$$

Setting  $p^* = (A^{-1}B)^* \nabla_y J(\overline{y}, \overline{u})$ . We have that  $\overline{u} = P_{U_{ad}}(\overline{u} - \delta(p^* + \nabla_u J(\overline{y}, \overline{u})))$ 

## 4. Lecture 4

## Lemma 4.1.

Let U be linear space and  $J: U \to \overline{\mathbb{R}}$ . Then

- 1. If J is convex, then the effective domain  $dom(J) = \{u \in U | J(u) < \infty\}$  is convex.
- 2. J is convex  $\iff$  epi $(J) = \{(u, \alpha) \in U \times \mathbb{R} | J(u) \leq \alpha\}$  is convex.

*Proof.* Since U and  $\mathbb{R}$  are linear spaces, is easy to see that scalar multiplications and sums are well defined over  $U \times \mathbb{R}$  and so over epi (J).

1. Assume J convex. If  $u_1 \in \text{dom}(J)$  and  $u_2$  are elements of dom(J). Therefore,  $J(u_1) < \infty$ , and  $J(u_2) < \infty$ , therefore for  $t \in [0, 1]$ , we have  $tJ(u_1) < \infty$  and  $(1 - t)J(u_2) < \infty$ . Since J is convex,

$$J(tu_1 + (1-t)u_2) < tJ(u_1) + (1-t)J(u_2) < \infty$$

Therefore,  $tu_1 + (1-t)u_2 \in \text{dom}(J)$ . Hence dom J is convex.

2. First consider J a convex functional, then we have for all  $u_1, u_2 \in U$ ,

$$J(tu_1 + (1-t)u_2) \le tJ(u_1) + (1-t)J(u_2) \quad \forall t \in [0,1]$$

Let  $(u_1, \alpha_1)$ ,  $(u_2, \alpha_2)$  elements of epi (J), then  $J(u_1) < \alpha_1$  and  $J(u_2) < \alpha_2$ . Since J is convex.

$$J(tu_1 + (1-t)u_2) \le t\alpha_1 + (1-t)\alpha_2$$

Then  $(tu_1 + (1-t)u_2, t\alpha_1 + (1-t)\alpha_2) \in \text{epi}(J)$ . Therefore, if J is convex, and  $(u_1, \alpha_1), (u_2, \alpha_2)$  are elements of epi (J) then,

$$t(u_1, \alpha_1) + (1-t)(u_2, \alpha_2) = (tu_1 + (1-t)u_2, t\alpha_1 + (1-t)\alpha_2) \in epi(J)$$

Hence epi(J) is convex.

Now assume epi (J) convex. Let  $(u_1, \alpha_1)$ ,  $(u_2, \alpha_2)$  elements of epi (J) then  $(tu_1 + (1-t)t\alpha_1 + (1-t)\alpha_2)$ , then

$$J(tu_1 + (1-t)u_2) \le t\alpha_1 + (1-t)\alpha_2 \quad \forall t \in [0,1]$$

By definition of epi (J), if  $u_1, u_2 \in \text{dom } J$ , then  $(u_1, J(u_1))$  and  $(u_2, J(u_2))$ , are elements of epi (J), therefore

$$J(tu_1 + (1-t)u_2) \le tJ(u_1) + (1-t)J(u_2) \quad \forall t \in [0,1]$$

Implying that J is convex.

#### Definition 4.1.

Let U a Banach space. Then the function  $J:U\to \overline{\mathbb{R}}$  is called lower semi-continuous at  $u_0\in U$  if the following conditions holds:

- If  $\forall \epsilon > 0$  there is a neighborhood  $B_{\delta}(u_0)$  of  $u_0$  such that  $J(u_0) \epsilon \leq J(u) \ \forall u \in B_{\delta}(u_0)$ .
- If  $J(u_0) \leq \liminf_{n \to \infty} J(u_n)$  holds for each sequence  $u_n \in U$ .

#### Remark 4.1.

If the second condition holds, J is called sometimes sequentially semi-continuous. If J is continuous it is also lower semi-continuous.

#### Theorem 4.1.

Let U be a Banach space and  $J: U \to \overline{\mathbb{R}}$ . Then sthe following conditions are equivalent.

- 1. J is lower semi-continuous, i.e., J is lower semi-continuous at every point in U.
- 2. The epi(J) is closed.
- 3. The level sets  $\mu_{\xi} = \{u \in U | J(u) \leq \xi\}$  is a closed set. Note that the sets  $\mu_{\xi}$  are closed if and only if the sets  $\gamma_{\xi} = \{u \in U | J(u) > \xi\}$  are open. (Since  $\mu_{\xi}^{c} = \gamma_{\xi}$ ).

## Proof.

• (1)  $\Longrightarrow$  (2) Let  $(u_n, \xi_n)$ , be a sequence in epi (J), such that converges to  $(u, \xi)$  in  $U \times \mathbb{R}$ . Then

$$J(u) \le \liminf_{n \to \infty} J(u_n) \le \liminf_{n \to \infty} \xi_n = \xi.$$

Hence  $(u, \xi) \in \operatorname{epi}(J)$ .

- (2)  $\Longrightarrow$  (3)Let  $\xi \in \mathbb{R}$  and assume that  $(u_n)_{n \in \mathbb{N}}$  is a sequence in  $\mu_{\xi}$  that converges to u. Then the set  $(u_n, \xi)_{n \in \mathbb{N}}$  is in epi (J). Since epi (J) is closed, we conclude that  $(u, \xi) \in \text{epi }(J)$ , and hence  $u \in \mu_k$ .
- (3)  $\Longrightarrow$  (1) Let bet  $u \in U$  an arbitrary member of the Banach space U, and let  $(u_n)_{n \in \mathbb{N}}$  be a sequence that converges to u. And we set the number  $\eta = \liminf_{n \to \infty} J(u_n)$ . Then we have to prove that  $J(u) \leq \eta$ . When  $\eta = \infty$ , the inequality is clear. Therefore we assume that  $\eta < +\infty$ . Since every sequence in  $\mathbb{R}$  has a subsequence that converges to the liminf, the sequence  $(u_n)_n$  has a subsequence  $(u_k)_k$ , such that  $J(u_k) \xrightarrow{k \to \infty} \eta$ . Now, we can fix  $\xi \in (\eta, \infty)$ . By convergence we can find c such that  $k \geq c$  implies that  $(J(u_k))$  belongs to  $(-\infty, \xi)$ , therefore the set

$$\{u_k | k \ge c \in \mathbb{N}\} \subset \mu_{\xi}.$$

Since the sequence  $u_n \to u$ , the subsequence  $u_k \to u$ . And  $\mu_{\xi}$  closed implies  $u \in \mu_{\xi}$ . Since this holds for all  $\eta < \infty$ , we take  $\xi \downarrow \eta$ . Implying  $J(u) \leq \eta$ .

## Example 4.1.

The indicator function of a set  $C \subset U$ , i.e. the function  $I_C: U \to [-\infty, \infty]$ 

$$I_C(u) = \begin{cases} 0, & \text{if } u \in C \\ +\infty, & \text{otherwise,} \end{cases}$$

is lower semi-continuous if and only if C is closed.

**Proof.** Take  $\xi \in \mathbb{R}$ . If  $\xi < 0$ , the set  $\mu_{\xi} = \emptyset$ . If  $\xi > 0$ , the set  $\mu_{\xi} = C$ . Therefore the sets  $m_{\xi}$ , for all  $\xi \in \mathbb{R}$  is closed if and only if C is closed. By the theorem 4.1  $I_C$  is lower semi-continuous if and only if C is closed.

#### The Dual Systems of Linear Spaces

Two linear spaces X and Y over the same scalar field  $\Gamma$  define a dual system if a fixed bilinear functional on their product is given:

$$(\cdot,\cdot):X\times Y\to\Gamma$$

.

The bilinear functional is sometimes omitted.

The dual system is called separated if the following two properties hold:

- 1.  $\forall x \in X \setminus \{0\}$  there is  $y \in Y$  such that  $(x, y) \neq 0$ .
- 2.  $\forall y \in Y \setminus \{0\}$  there is  $x \in X$  such that  $(x, y) \neq 0$ .

In other words, X separates points in Y and Y separates points in X. We consider only separated dual systems. For each  $x \in X$ , we define the application  $f_x : Y \to \Gamma$  by

$$f_x(y) = (x, y) \quad \forall y \in Y$$

We observe that  $f_x$  is a linear functional on Y and the mapping  $x \to f_x$ ,  $\forall x \in X$ , is linear and injective, as can be seen from condition (1). Hence, the correspondence is an embedding. Thus, the elements of X can be identified with the linear functionals on Y. In a similar way, the elements of Y can be considered as linear functionals of X, identifying an element  $y \in Y$  with  $g_y : X \to \Gamma$ , defined by

$$g_y(x) = (x, y), \quad \forall x \in X.$$

Therefore, each dual system of linear spaces defines a mapping from either of the two linear spaces into the space of linear functionals on the other. We set,

$$p_y(x) = |(x, y)| = |g_y(x)|, \quad \forall x \in X$$

$$q_x(y) = |(x, y)| = |f_x(y)|, \quad \forall y \in Y$$

and we observe that  $\mathcal{P} = \{p_y | y \in Y\}$  is a family of seminorms on X and  $\mathcal{Q} = \{q_x | y \in X\}$  is a family of seminorms on Y.

#### Definition 4.2.

If U is a normed space, the the dual space  $U^* = \mathcal{B}(U, \mathbb{R})$ . Consists of all linear and bonded functionals mapping from U to  $\mathbb{R}$ .

#### Theorem 4.2.

Let be U a Banach space, then the dual  $U^*$  is also a Banach space relative to the norm of the functionals defined by

$$||u^*|| = \sup_{||u|| \le 1} |u^*(u)|$$

#### Remark 4.2.

There is a natural duality between U and  $U^*$  determined by the bilinear functional  $(\cdot, \cdot): U \times U^* \to \mathbb{R}$ , defined as

$$(u, u^*) = u^*(u), \quad \forall u \in U, \forall u^* \in U^*$$

#### Definition 4.3.

A sequence  $(u_n)_n$  in a Banach space is called weakly convergent to some  $u \in U$  if for all linears continuous functionals  $u^* \in U^*$  we have

$$\lim_{n \to \infty} u^*(u_n) = u^*(u)$$

u is also called the weak-limit and we write  $u_n \xrightarrow[n \to \infty]{} u$ .

#### Theorem 4.3.

A sequence  $(u_n)_n$  in U converges to  $u \in U$  if and only if  $\sup_{n \in \mathbb{N}} ||u_n|| < \infty$  and  $u_n \xrightarrow[n \to \infty]{} u$ 

#### Theorem 4.4 (Bourbaki-Alaoglu-Katulami).

The closed unit ball in a Banach space U is weakly compact if and only if U is reflexive. If U is in an addition separable, then it's weakly sequentially compact.

#### Definition 4.4.

Let U be a Banach space and  $J: U \to \mathbb{R}$ , J is called weakly (sequentially) lower semi-continuous at point  $u_0$  if for every weakly convergent sequence  $(u_n)_n$  converges to  $u_0$ , i.e.  $u_n \rightharpoonup u_0$ , it holds

$$(u) \le \liminf_{n \to \infty} J(u_n)$$

#### Definition 4.5.

A non empty set  $C \subset U$  is called weakly closed if for every weakly convergent sequence  $(u_n)_n$  in C follows that the weak limit belongs to C. i.e.  $u_n \rightleftharpoons u$ , with  $u_n \in C$ , implies  $u \in C$ .

#### Definition 4.6.

A non empty set  $C \subset U$  is called weakly sequentially compact if for every sequence in C contains a weakly convergent subsequence whose limit belongs to C.

#### Theorem 4.5.

Let U be a Banach space and  $J: U \to \overline{\mathbb{R}}$  the the following conditions are equivalent:

• I is weakly lower semi-continuous on U for all  $u \in U$ .

• The level sets  $\mu_{\xi} = \{u \in U | J(u) \leq \xi\}$  is weakly closed for each  $\xi \in \mathbb{R}$ .

#### Lemma 4.2.

Let be  $J: U \to \mathbb{R}$  a convex and lower semicontinuous functional. Assume there is  $u_0 \in U$  such that  $J(u_0) = -\infty$ , then J is nowhere finite.

*Proof.* Assume that there is  $v \in U$  such that  $-infty < J(v) < \infty$ . Then by convexity  $J(\lambda u_0 + (1-\lambda)v) = -\infty$ ,  $\forall \lambda \in [0,1]$ . Because J is lower semicontinuos it follows that in the limit  $\lambda \to 0$ ,

$$(\lambda u_0 + (1 - \lambda)v) \to v \implies J(v) \le J(\lambda u_0 + (1 - \lambda)v) = -\infty$$

#### Lemma 4.3.

Every lower semi-continuous and convex function on a linear space U is weakly lower semi-continuous.

## Corollary 4.1.

Assume that U is a reflexive Banach space, then every bounded sequence  $(u_n)_n \in U$  that is  $\sup_{n \in \mathbb{N}} ||u_n|| < \infty$  has a subsequence  $(u_k)_k$  which is weakly convergent to some  $u \in U$ .

#### Remark 4.3.

Since every Hilbert space is reflexive the corollary applies to this case.

#### Lemma 4.4.

A closed set C is weakly closed if and only if the set is convex.

#### Definition 4.7.

Let U be a real linear space and  $J:U\to\overline{\mathbb{R}}.$  We said that J is sublinear if:

$$J(\lambda u) = \lambda J(u) \qquad \forall u \in U, \text{ and } \mathbb{R} \ni \lambda > 0$$
 
$$J(u+v) < J(u) + J(v) \qquad \forall u, v \in U$$

#### Remark 4.4.

Every sublinear function is convex.

#### Theorem 4.6.

Let U be a real linear space  $J:U\to\overline{\mathbb{R}}$  a sublinear functional. Then there is a linear functional f on U such that,

$$f(u) \le J(u) \quad \forall u \in U$$

## Definition 4.8.

Let  $J:U\to \overline{\mathbb{R}}$ , we said that J is locally bounded around  $u_0$  if  $\exists V\subset U$  neighborhood of  $u_0$  such that for some  $M\in\mathbb{R}$ 

$$|J(u)| < M \qquad \forall u \in V$$

#### Lemma 4.5.

Let  $J:U\to\mathbb{R}$  convex and U is a Banach space. If J is locally bounded around u, then J is lower semi-continuous in u.

**Proof.** Let  $u_k \to u$  as  $k \to \infty$ . For each  $\epsilon > 0$  we can find a sequence  $\alpha_k$  such that  $\left\| \frac{u - u_k}{\alpha_k} \right\| < \epsilon$ , and  $\alpha_k \to 0$  as  $k \to \infty$ . (Please read Maximal Monotone Operators and Evolution Systems in Banach Spaces of Barbu. Details Still to be recovered).

Moreover, for k sufficiently large we have  $||u - u_k|| < \epsilon$ . Choose  $\epsilon$  such that J is bounded in  $\overline{B_{2\epsilon}(u)}$  by M and define  $v_k = u_k + \frac{u - u_k}{\alpha_k} \in \overline{B_{2\epsilon}(u)}$ , since  $||v_k - u|| \le ||u_k - u|| + \left|\left|\frac{u - u_k}{\alpha_k}\right|\right| \le 2\epsilon$ .

Since J is convex

$$J(u) \le \alpha_k J(v_k) + (1 - \alpha_k) J(u_k) \le \alpha_k M + J(u_k)$$

Since  $\alpha_k \to 0$ , then

$$J(u) \leq \liminf_{k \to \infty} (\alpha_k M + J(u_k)) = \liminf_{k \to \infty} J(u_k)$$

Thus is if J is convex and locally bounded around u, then is lower semi-continuous around u.

#### Remark 4.5.

The result that convexity and local boundedness imply lower semi-continuity is similar to classical result for linear operators where local boundness implies continuity. In general convexity plays in optimization the same role as linearity in solving equations.

- 5. Lecture 5
- 6. Lecture 6
- 7. Lecture 7

#### Remark 7.1.

Some elementary properties of conjugate functions

- Young inequality  $J(u) + J^*(p^*) \ge p^*(u) \quad \forall u \in U, \forall p^* \in U^*$
- $J^*(0) = \sup_{u \in U} ((0, u) J(u)) = \sup_{u \in U} (-J(u)) = \inf_{u \in U} J(u)$

In many applications in optimization, is used the equivalent formulation,

$$\inf_{u \in U} J(u) = -J^*(0).$$

$$J \le F \implies J^* \ge F^*$$

## Theorem 7.1.

Let U a Banach space and  $J^*: U^* \to \overline{\mathbb{R}}$  be the conjugate of the  $J: U \to \overline{\mathbb{R}}$ . Then for all  $u \in U$ .

$$p^* \in \partial J(u) \iff J(u) + J^*(p^*) = p^*(u)$$

Proof. content...

#### Corollary 7.1.

It follows from previous theorem that  $\partial J(u) = \{p^* \in U^* | J(u) + J^*(p^*) = (p^*, u)\}.$ 

#### Theorem 7.2.

Let U be a Banach space and  $J: U \to \mathbb{R}$  be proper function. If  $p^* \in \partial J(u)$  then  $u \in \partial J^*(p^*)$ 

Let  $p^* \in \partial J(u)$ . For any  $g^* \in U^*$ , it follows

$$J^*(g^*) = \sup_{v \in U} (g^*(v) - J(v)) \ge g^*(u) - J(u) \ge g^*(u) - J(u)$$

From theorem 7.1

$$J^*(g^*) \le g^*(u) - p^*(u) + J^*(p^*) = (g^* - p^*)(u) + J^*(p^*) \implies u \in \partial J^*(p^*).$$

By iteration the definition, we obtain the bipolar function  $(J^*)^* = J^{**}: U^{**} \to \overline{\mathbb{R}}$ ,

$$J^{**}(u) = \sup_{p^* \in U^*} \{ p^*(u) - J^*(p^*) \}$$

#### Theorem 7.3.

Let U be a reflexive Banach space. The  $J^{**}$  is the maximum convex functional below J (also called convex envelope), i.e.  $J^{**}(u) \leq J(u)$ ,  $\forall u \in U$  and  $F(u) \leq J^{**}(u)$ ,  $\forall u \in U$  if F is also convex and  $F(u) \leq J(u)$ ,  $\forall u$ . In particular  $J^{**} = J$  if and only if J is convex.

Proof.

$$J^{**}(u) = \sup_{p^* \in U^*} \{ p^*(u) - J^*(p^*) \}$$
 (2)

$$= \sup_{p^* \in U^*} \left\{ p^*(u) - \sup_{v \in U} \left\{ p^*(v) - J(v) \right\} \right\}$$
 (3)

$$= \sup_{p^* \in U^*} \left\{ p^*(u) + \inf_{v \in U} \left\{ p^*(v) - J(v) \right\} \right\}$$
 (4)

(5)

Since for any  $p^* \in U^*$ ,

$$\inf_{v \in U} \{ p^* (u - v) + J(v) \} \le p^* (u - u) + J(u)$$

We have that  $J^{**}(u) \leq J(u)$ .

Now we assume that F is a convex functional and  $q^* \in \partial F(u)$  for  $u \in U$ .

$$\implies F(v) \ge F(v) + q^*(v - u) \tag{6}$$

$$\implies F(v) \ge F(v) + q^*(v - u)$$

$$F^{**}(u) = \sup_{p^* \in U^*} \inf_{v \in U} \left\{ p^*(u - v) + F(u) + q^*(v - u) \right\}$$
(6)
(7)

$$\geq \sup_{p^* \in U^*} \inf_{v \in U} \left\{ (p^* - q^*) (u - v) + F(u) \right\} \tag{8}$$

$$\geq \inf_{v \in U} \left\{ (q^* - q^*)(u - v) + F(u) \right\} \tag{9}$$

$$= F(u) \tag{10}$$

If F is convex,

$$\implies F(u) \le F^{**}(u) \le F(u) \implies F(u) = F^{**}(u), \tag{11}$$

$$F(u) = F^{**}(u) = \sup_{p^* \in U^*} \inf_{v \in U} \left\{ p^*(u - v) + F(v) \right\} \le J * *(u)$$
(12)

## 8. Lecture 8

#### Definition 8.1.

Let U and Y Banach spaces and  $J:U\to\overline{\mathbb{R}}$  is a proper function. We consider an optimization problem (P) called primal problem

$$\inf_{u \in H} J(u) \tag{P}$$

Then the problem is said to be nontrivial if there is  $\overline{u} \in U$  such that  $J(\overline{u}) < \infty$ . A function  $\Phi : U \times Y \to \overline{\mathbb{R}}$  is said to be a perturbation function of J,

$$\inf_{u \in U} \Phi(u, p) \tag{Pp}$$

if  $\Phi(u,0) = J(u)$  for all  $u \in U$ . For each  $p \in Y$ , the minimization problem (Pp) is called a perturbation problem. The variable p is called perturbation parameter. If we denote by  $\Phi^*$  the convex conjugate function of  $\Phi$ , the *dual problem*, with respect to  $\Phi$  is defined by

$$\sup_{p^* \in Y^*} -\Phi^*(0, p^*) \tag{P*}$$

where  $\Phi^*: (U \times Y)^* \cong U^* \times Y^* \to \overline{\mathbb{R}}$ , a function defined as follows.

$$\Phi^* (u^*, p^*) = \sup_{\substack{u \in U \\ p \in Y}} ((u^*, u)_{U^*U} + (p^*, p)_{Y^*Y} - \Phi(u, p))$$

#### Remark 8.1.

For p = 0,  $(P^*) \equiv (Pp)$ . We denote the infimum for problem (P) by  $\inf(P)$  and the supremum for problem  $(P^*)$  by  $\sup(P^*)$ 

## Lemma 8.1 (Weak duality).

For the problem (P) and (P\*) it holds that

$$-\infty \le \sup (\mathbf{P}^*) \le \inf (\mathbf{P}) \le \infty.$$

*Proof.* Let  $p^* \in Y^*$ . It follows

$$-\Phi^*(0, p^*) = -\sup_{\substack{u \in U \\ p \in Y}} ((0, u) + (p^*, p) - \Phi(u, p))$$
(13)

$$= \inf_{\substack{u \in U \\ p \in Y}} (\Phi(u, p) - (p^*, p)) \tag{14}$$

$$\leq (\Phi(u,0) - (p^*,0)) \quad \forall u \in U, p^* \in Y^*$$
 (15)

$$\Longrightarrow \sup_{p^* \in Y^*} \left( -\Phi\left(0, p^*\right) \right) \le \inf_{u \in U} \Phi(u, 0) = \inf(P) \tag{16}$$

By iteration we can define, a bidual problem

$$-\sup_{u \in U} (-\Phi^*(u,0)) = \inf_{u \in U} \Phi^*(u,0)$$
 (P\*\*)

In case the space U is reflexive then  ${U^*}^* = U$ .

If the perturbation function  $\Phi(u, p)$  is proper, convex and weakly lower semicontinuous. Then  $\Phi^{**} = \Phi$ . In this case  $\Phi(u, 0) = \Phi^{**}(u, 0)$  i.e  $(P) \equiv (P^{**})$ 

#### Definition 8.2.

Consider the infimal value function

$$h(p^*) = \inf (\mathbf{Pp}) = \inf_{u \in U} \Phi(u, p)$$

The problem (P) is called stable if h(0) is finite and its sub-differentiable in zero is not empty.

#### Theorem 8.1.

The primal problem (P) is stable if and only if the following conditions are simultaneously satisfied:

- The dual problem (P\*) has a solution.
- There is no duality gap, i.e.

$$\inf(P) = \sup(P^*) \le \infty$$

#### Theorem 8.2 (Extremal relation).

Let  $\Phi: U \times Y \to \overline{\mathbb{R}}$ , be convex the the following statements are equivalent:

- 1. (P) and (Pp) have solutions  $\overline{u}$  and  $\overline{p^*}$  and  $\inf(P) = \sup(P^*)$
- 2.  $\Phi(\overline{u},0) + \Phi^*(0,\overline{p^*}) = 0$
- 3.  $(0, \overline{p^*}) \in \partial \Phi(u, 0)$  and  $(\overline{u}, 0) \in \partial \Phi^*(0, p^*)$

*Proof.* We proceed by parts:

- 1. (1)  $\Longrightarrow$  (2):  $\overline{u}$  solution of  $\inf(P)$  and  $\overline{p^*}$  solution of  $\sup(P^*)$  and  $\inf(P) = \sup(P^*)$ . This properties implies,  $\Phi(\overline{u}, 0) = \inf(P) = \sup(P^*) = -\Phi(0, \overline{p^*}) \Longrightarrow \Phi(\overline{u}, 0) + \Phi^*(0, \overline{p^*}) = 0$ .
- 2. (2)  $\implies$  (1):  $-\Phi^*(0, \overline{p^*}) = \sup(P^*) \le \inf(P) = \Phi(\overline{u}, 0) = -\Phi^*(0, \overline{p^*}) \implies \sup(P^*) = \inf(P)$
- $3. \ (2) \Longleftrightarrow (3): \ \Phi(\overline{u},0) + \Phi^*(0,\overline{p^*}) = 0 = (0,\overline{u}) + (\overline{p^*},0) = \left((0,\overline{p^*}),(\overline{u},0)\right) \iff (0,\overline{p^*}) \in \partial\Phi(\overline{u},0) \ \forall u \in U, \forall p^* \in \partial J(u) \iff J(u) + J^*(p^*) = (p^*,u)$

#### Fencel duality.

Consider the functional  $J: U \to \overline{\mathbb{R}}$ ,

$$J(u) = F(u) + G(Au)$$

with  $F: U \to \overline{\mathbb{R}}$ , G convex function  $G: V \to \overline{\mathbb{R}}$  and  $A: U \to V$  bounded and linear.

We introduce the perturbation  $\Phi(u, p) = F(u) + G(Au - p)$ . The dual problem is obtained with,

$$\Phi^*(0, p^*) = \sup_{\substack{u \in U \\ p \in V}} ((p^*, p) - F(u) - G(Au - p))$$

For fixed u we set q: Au - p.

$$\begin{split} \Phi^*(0,p^*) &= \sup_{u \in U} \sup_{p \in V} \left( (p^*,Au - q) - F(u) - G(q) \right) \\ &= \sup_{u \in U} \sup_{p \in V} \left( (A^*p^*,u) - (p^*,q) - F(u) - G(q) \right) \\ &= \sup_{u \in U} \left( (p^*,Au) - F(u) \right) + \sup_{p \in V} \left( (-p^*,q) - G(q) \right) \\ &= F^*(A^*p^*) + G^*(-p^*) \end{split}$$

## References