

## Schrödinger Equation

$$i\hbar \frac{\partial \psi}{\partial t} + \frac{\partial^2 \psi}{\partial x^2} - V(x)\psi = 0 \quad (\hbar=1, m=\frac{1}{2})$$

Implicit first order in time approximation:

$$j \frac{\psi_i^{n+1} - \psi_i^n}{\Delta t} = - \frac{\psi_{i+1}^{n+1} - 2\psi_i^{n+1} + \psi_{i-1}^{n+1}}{\Delta x^2} + V_i \psi_i^{n+1}$$

Stability:  $\xi_i = \frac{1}{1 + j \left[ \frac{4\Delta t}{(\Delta x)^2} \sin^2\left(\frac{k\Delta x}{2}\right) + V_i \Delta t \right]}$

Unconditionally stable, but not unitary, i.e.

$$\int_{-\infty}^{\infty} |\psi|^2 dx = 1$$

is not fulfilled.

To obtain a unitary solution, we consider

$$i \frac{\partial \psi}{\partial t} = H \psi, \quad H = -\frac{\partial^2}{\partial x^2} + V(x)$$

Formal solution  $\psi(x,t) = \psi(x_0) e^{-iHt}$  defined by power series of the Operator.

(unstable) FTCS approx:  $j \frac{\psi_i^{n+1} - \psi_i^n}{\Delta t} = H \psi_i^n$

$$\Rightarrow \psi_i^{n+1} = (1 - jH\Delta t) \psi_i^n$$

(stable) implicit approx:  $\psi_i^{n+1} = \frac{1}{1 + jH\Delta t} \psi_i^n$

In fact  $1 - j\Delta t H \approx e^{-j\Delta t H}$  and  $\frac{1}{1 + jH\Delta t} \approx 1 - jH\Delta t + O(\Delta t^2)$

are just two approximations which are first order.

A second order <sup>unitary</sup> approximation is

$$e^{-j\Delta t H} \approx \frac{1 - \frac{1}{2}jH\Delta t}{1 + \frac{1}{2}jH\Delta t}$$

which gives (starting from  $\psi(x, \Delta t) = \psi(x, 0) e^{-jH\Delta t}$ )

$$(1 + \frac{1}{2}jH\Delta t) \psi_i^{n+1} = (1 - \frac{1}{2}jH\Delta t) \psi_i^n$$

Replacing  $H$  by its finite-difference form we obtain a complex tri-diagonal system.

$$\psi_i^{n+1} - \frac{j\Delta t}{4\Delta x^2} [\psi_{i+1}^{n+1} - 2\psi_i^{n+1} + \psi_{i-1}^{n+1}] + j\Delta t V_i \psi_i^{n+1}$$

$$= \psi_i^n + \frac{j\Delta t}{4\Delta x^2} [\psi_{i+1}^n - 2\psi_i^n + \psi_{i-1}^n] - j\Delta t V_i \psi_i^n$$

$$\Rightarrow A \vec{\psi}^{n+1} = A^* \vec{\psi}^n$$

$$A = \begin{pmatrix} d_0 & a & 0 & 0 \\ a & d_1 & a & 0 \\ 0 & a & d_2 & a \\ \vdots & \vdots & \vdots & \vdots \\ 0 & \dots & 0 & a & d_{N-1} \end{pmatrix}$$

$$a = -j\Delta t / 4\Delta x^2$$

$$d_j = 1 + j\left(\frac{\Delta t}{2\Delta x^2} + \Delta t V_j\right)$$

## Splitting methods

Consider the linear ODE system

$$\frac{d\vec{y}}{dt} = A\vec{y}(t) \quad \text{with } A = A_1 + A_2.$$

The formal solution is  $\vec{y}(\Delta t) = e^{A\Delta t} \vec{y}(0)$ .

If we can solve  $\frac{d\vec{y}}{dt} = A_1 \vec{y}(t)$  and  $\frac{d\vec{y}}{dt} = A_2 \vec{y}(t)$

we can approximate

$$\vec{y}(\Delta t) = e^{A\Delta t} \vec{y}(0) \approx e^{A_2 \Delta t} e^{A_1 \Delta t} \vec{y}(0).$$

This is of first order in  $\Delta t$  since

$$e^{A\Delta t} = \mathbf{I} + \Delta t (A_1 + A_2) + \frac{1}{2} \Delta t^2 (A_1 + A_2)^2 + \dots$$

$$e^{A_2 \Delta t} e^{A_1 \Delta t} = \mathbf{I} + \Delta t (A_1 + A_2) + \frac{1}{2} \Delta t^2 (A_1^2 + 2A_2 A_1 + A_2^2) + \dots$$

$$\underbrace{\frac{1}{\Delta t} (e^{A\Delta t} - e^{A_2 \Delta t} e^{A_1 \Delta t}) \vec{y}(0)}_{\text{local error}} = \frac{1}{2} \Delta t \underbrace{(A_1 A_2 - A_2 A_1)}_{[A_1, A_2]} \vec{y}(0) + O(\Delta t^2)$$

Thus, the method is first order in time if  $A_1$  and  $A_2$  do not commute.

Up to here we always start with a full step with operator  $A_1$ , then carry out one step with operator  $A_2$ .

Better accuracy can be obtained by alternating the first operator ~~and to~~ in every half-step:

$$\begin{aligned}\vec{y}(\Delta t) &= \left( e^{\frac{1}{2}\Delta t A_2} e^{\frac{1}{2}\Delta t A_1} \right) \left( e^{\frac{1}{2}\Delta t A_1} e^{\frac{1}{2}\Delta t A_2} \right) \vec{y}(0) \\ &= e^{\frac{1}{2}\Delta t A_2} e^{\Delta t A_1} e^{\frac{1}{2}\Delta t A_2} \vec{y}(0) \quad (\text{Strang Splitting}).\end{aligned}$$

Strang splitting is second order in time.

These results hold for non-linear systems as well.

Split-step Fourier method for the nonlinear Schrödinger Eq.

$$i\psi_t + P\psi_{xx} + Q|\psi|^2\psi = 0$$

$$i\psi_t + \mathcal{L}\psi + \mathcal{N}\psi = 0$$

$$\begin{aligned}\Rightarrow \quad i\psi_t + \mathcal{L}\psi &= 0 & \psi_t &= i\mathcal{L}\psi \Rightarrow \psi(t) = \psi(0) e^{i\mathcal{L}t} \\ i\psi_t + \mathcal{N}\psi &= 0 & \psi_t &= i\mathcal{N}\psi \Rightarrow \psi(t) = \psi(0) e^{i\mathcal{N}t}\end{aligned}$$

Strang-Splitting:

$$\psi(\Delta t) = e^{i\mathcal{L}\frac{\Delta t}{2}} e^{i\mathcal{N}\Delta t} e^{i\mathcal{L}\frac{\Delta t}{2}} \psi(0)$$

$$\psi(n\Delta t) = e^{i\frac{\omega}{2}\Delta t} \begin{pmatrix} e^{iN\Delta t} & e^{i\omega\Delta t} \end{pmatrix}^n e^{iN\Delta t} e^{i\frac{\omega}{2}\Delta t} \psi(0)$$

How to compute  $e^{i\omega\Delta t} \psi$  and  $e^{iN\Delta t} \psi$ ?

For  $N = Q|\psi|^2$ :  $i\psi_t = -Q|\psi|^2\psi$

$$\Rightarrow \psi_t = iQ|\psi|^2\psi$$

$$\frac{d}{dt} |\psi|^2 = \frac{d}{dt} (\psi\psi^*) = \psi \frac{d\psi^*}{dt} + \psi^* \frac{d\psi}{dt}$$

$$= \psi(-iQ|\psi|^2\psi^*) + \psi^*(iQ|\psi|^2\psi) = 0$$

$$\Rightarrow |\psi(\Delta t)|^2 = |\psi(0)|^2$$

$$\begin{aligned} \Rightarrow \psi(\Delta t) &= \psi(0) e^{iQ|\psi(\Delta t)|^2\Delta t} \\ &= \psi(0) e^{iQ|\psi(0)|^2\Delta t} \end{aligned}$$

For  $\mathcal{L} = \partial_{xx}$ :  $i\psi_t = -P\partial_{xx}\psi$

$$\psi_t = +iP \frac{\partial^2 \psi}{\partial x^2}$$

Formal-Fourier transf.:

$$\hat{\psi}_t = iP(-k^2)\hat{\psi}$$

$$\hat{\psi}(\Delta t) = e^{-iPk^2\Delta t} \hat{\psi}(0) \xrightarrow[\text{Fourier-transf.}]{\text{Backward}} \psi(\Delta t)$$