# Hard-margin SVM

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February 11, 2016

#### Problem setup

Given a set of linearly separable training data, how can one find a good separator? What do we expect from a good separator?

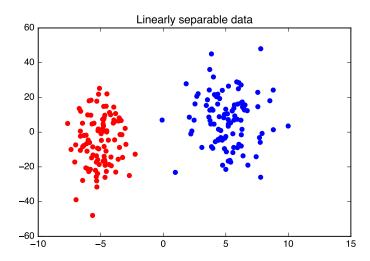
- ... that it actually separates the training points
- ... that it generalizes well

Let  $\{x^i, y^i\}_{i=1}^N \in \mathcal{D}$  be the training data, where  $x^i \in \mathbb{R}$  and  $y^i$  is either +1 or -1. What does it mean that the data is linearly separable?

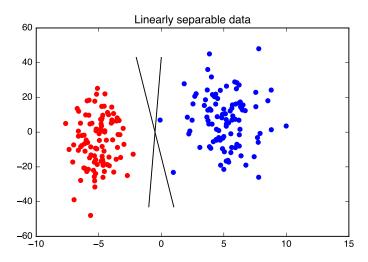
- ... that there is a hyperplane that separates the two clusters
- ... that there is possibly a lot of such hyperplanes

How to choose the best one?

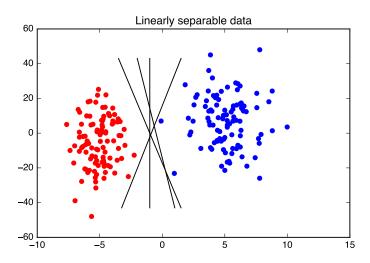
# Example



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## Hyperplane parametrization

Simplest case of real variables, y = mx + b draws a line with slope m that intersects y-axis at the point b:

- Rewrite the above equation:  $(m, -1) \cdot (x, y) + b = 0$
- A better notation can be:  $(w_1, w_2) \cdot (x_1, x_2) + b = 0$
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Generalize this to higher dimensions, for  $w, x \in \mathbb{R}^n$  and  $b \in \mathbb{R}$ :

- $\ell(x) = w \cdot x + b$  where  $\ell(x) = 0$  describes a line.
- w is orthogonal to  $\ell$  (check  $w \cdot v = 0$  for v along  $\ell$ .)
- What should  $\ell$  assign to the two clusters?

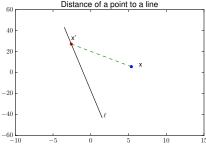
$$\ell(x)$$
 is  $\begin{cases} > 0 \text{ if } x \in \text{Blue: } +1 \text{ class} \\ < 0 \text{ if } x \in \text{Red: } -1 \text{ class} \end{cases}$ 

• Observation:  $y^i \ell(x^i)$  is always positive!

## Distance of a point to a line

For a point  $x \in \mathbb{R}^n$ , how far is x to a given line  $\ell$ ?

- Denote the distance of a point x to a line  $\ell$  by  $d(x,\ell)$ .
- Pick a point on the line, say x', then  $d(x, \ell)$  is the projection of (x x') onto the normal vector w of  $\ell$ .



Crash course on projections:

- Linear transformations, P, such that  $P^2 = P$ .
- Unique decomposition into image and kernel of P
- Orthogonal projections:  $P = P^T$
- Vector projection:  $P_w(v) = \frac{v \cdot w}{||w||^2} w$

#### Hard-margin SVM

Given two linearly separable clusters,  $\mathcal{C}_1$  and  $\mathcal{C}_2$ , and a line  $\ell$  with  $\ell(x)=w\cdot x+b$  and ||w||=1, suppose  $x^{1,\ell}\in\mathcal{C}_1$  and  $x^{2,\ell}\in\mathcal{C}_2$  are the closest points to  $\ell$ .

- For any  $i, y^i \ell(x^i) \ge \min\{d(x^{1,\ell}, \ell), d(x^{2,\ell}, \ell)\} > 0$
- GOAL: Maximize the margin!
- Since data is linearly separable, the maximizer will be on the set where  $d(x^{1,\ell},\ell)=d(x^{2,\ell},\ell)$ , let's call this M. (note that M depends on data points and the line)

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#### Procedure:

$$\max\{M: b \in \mathbb{R}, w \in \mathbb{R}^n, ||w|| = 1\}$$
 (1)

subject to 
$$y^i(w \cdot x^i + b) \ge M$$
 (2)

### Equivalent formulation

For any pair of (w,b) we can calculate M and then considering the new pair  $(w',b')=(\frac{w}{M},\frac{b}{M})$  we get  $y^i(\frac{w}{M}\cdot x^i+\frac{b}{M})\geq 1$ . Therefore, maximizing M can be rephrased as minimizing ||w'||.

#### New procedure:

$$\min\{||w'||:b'\in\mathbb{R},w'\in\mathbb{R}^n\}\tag{3}$$

subject to 
$$y^i(w' \cdot x^i + b') \ge 1$$
 (4)

- Note that:  $||w'|| = ||\frac{w}{M}|| = \frac{||w||}{M} = \frac{1}{M}$
- This is a convex optimization problem: quadratic criterion, linear inequality constraints.
- But, what if the clusters overlap?

## Overlapping clusters

For all data points let  $t^i > 0$  be the slack variables. Let's modify equation (2) to allow each point to have a little more room:

subject to 
$$y^i(w \cdot x^i + b) \ge M(1 - t^i)$$

Equivalent formulation ...:

$$\min ||w||$$
, subject to  $y^i(w \cdot x^i + b) \ge 1 - t^i$  and  $\sum t^i < C$ 

Equivalent formulation ... :

$$\min \frac{1}{2}||w||^2 + c\sum t^i$$

subject to 
$$y^i(w \cdot x^i + b) \ge 1 - t^i$$

# Overlapping clusters

properties, interpretation, plots...

#### **Exercises**

- Linear regression; Minimizing sum of squares of errors in  $y = X\beta + \epsilon$ : Find  $\beta$  such that  $||y X\beta|| = f(\beta)$  is minimized.
- What's the orthogonal projection of y onto the columns of X?
- What's the connection of the two?
- When is  $X^TX$  not invertible?
- In the overlapping case, what would happen if you modified the constraint by  $y^i(w \cdot x^i b) \ge M t^i$