

# Kernel Methods

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# Setup and Motivation

# Linear Models

- So far we've discussed
  - Linear regression
  - Ridge regression
  - Lasso regression
  - Support Vector Machines
  - Perceptrons
- Each of these methods assumes
  - Input space  $\mathcal{X}$ .
  - Feature map  $\psi : \mathcal{X} \rightarrow \mathbf{R}^d$ .
  - Linear (or affine) hypothesis space:

$$\mathcal{H} = \left\{ x \mapsto w^T \psi(x) \mid w \in \mathbf{R}^d \right\}.$$

applicable when we use  $\ell_2$  regularization.

# Linear Models Need Big Feature Space

- To get **expressive** hypothesis spaces using linear models,
  - need high-dimensional feature spaces
  - (What do we mean by expressive?)
- Very large feature spaces have two problems:
  - 1 Overfitting
  - 2 Memory and computational costs
- Overfitting we handle with regularization.
- Kernel methods can help with memory and computational costs.
  - In practice, most applicable when we use  $\ell_2$  regularization.

# Some Methods Can Be “Kernelized”

## Definition

A method is **kernelized** if inputs only appear inside inner products:  $\langle \psi(x), \psi(y) \rangle$  for  $x, y \in \mathcal{X}$ .

- The function **kernel function** corresponding to  $\psi$  is

$$k(x, y) = \langle \psi(x), \psi(y) \rangle.$$

- Can think of the kernel function as a **similarity score**.
  - But this is not precise.
- There are many ways to design a similarity score.
  - A kernel function is special because it's an inner product.
  - Has many mathematical benefits.

# What's the Benefit of Kernelization?

- 1 Computational.
- 2 Access to infinite-dimensional feature spaces.
- 3 Allows thinking in terms of “similarity” rather than features. (debatable)

## Generalizing from SVM

# Soft-Margin SVM (no intercept)

- The SVM objective function is

$$\frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n (1 - y_i [w^T x_i])_+.$$

- We found that the minimizer  $w^* \in \mathbf{R}^d$  has the form

$$w^* = \sum_{i=1}^n \alpha_i^* x_i.$$

- **Representer Theorem**  $\implies$  same result in a much broader context.



# Introduce a Feature Map

- Input space:  $\mathcal{X}$  (no assumptions).
- Feature space:  $\mathcal{H}$  (a Hilbert space, usually  $\mathbf{R}^d$ ) .
- Feature map  $\psi : \mathcal{X} \rightarrow \mathcal{H}$ .
- Featurized SVM objective:

$$\min_{w \in \mathcal{H}} \frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n (1 - y_i [\langle w, \psi(x_i) \rangle])_+ .$$

- Now  $\|w\|^2 = \langle w, w \rangle$ , where  $\langle \cdot, \cdot \rangle$  is inner product for  $\mathcal{H}$ .
- Note that minimizer  $w^* \in \mathcal{H}$ . What are predictions  $x \mapsto ?$

# Generalize

- Featurized SVM objective:

$$\min_{w \in \mathcal{H}} \frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n (1 - y_i [\langle w, \psi(x_i) \rangle])_+.$$

- Generalized objective:

$$\min_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, \psi(x_1) \rangle, \dots, \langle w, \psi(x_n) \rangle),$$

where

- $R: \mathbf{R}^{\geq 0} \rightarrow \mathbf{R}$  is nondecreasing (**Regularization term**)
- and  $L: \mathbf{R}^n \rightarrow \mathbf{R}$  is arbitrary. (**Loss term**)

# Generalized Objective Function

- Generalized objective:

$$\min_{w \in \mathcal{H}} R(\|w\|) + L(\langle w, \psi(x_1) \rangle, \dots, \langle w, \psi(x_n) \rangle),$$

where

- $R: \mathbf{R}^{\geq 0} \rightarrow \mathbf{R}$  is nondecreasing (**Regularization term**), and
  - $L: \mathbf{R}^n \rightarrow \mathbf{R}$  is arbitrary (**Loss term**).
- Is ridge regression of this form? What is  $R(\cdot)$ ?
- What if we penalize with  $\lambda\|w\|_2$  instead of  $\lambda\|w\|_2^2$ ?
- What if we use lasso regression?

# The Representer Theorem

# The Representer Theorem

## Theorem (Representer Theorem)

Let

$$J(w) = R(\|w\|) + L(\langle w, \psi(x_1) \rangle, \dots, \langle w, \psi(x_n) \rangle),$$

where

- $R: \mathbb{R}^{\geq 0} \rightarrow \mathbb{R}$  is nondecreasing (**Regularization term**), and
- $L: \mathbb{R}^n \rightarrow \mathbb{R}$  is arbitrary (**Loss term**).

If  $J(w)$  has a minimizer, then it has a minimizer of the form

$$w^* = \sum_{i=1}^n \alpha_i \psi(x_i).$$

[If  $R$  is strictly increasing, then all minimizers have this form. (homework)]

# The Representer Theorem (Proof)

- 1 Let  $w^*$  be a minimizer.
- 2 Let  $M = \text{span}(\psi(x_1), \dots, \psi(x_n))$ . [the “span of the data”]
- 3 Let  $w = \text{Proj}_M w^*$ . So  $\exists \alpha$  s.t.  $w = \sum_{i=1}^n \alpha_i \psi(x_i)$ .
- 4 Then  $w^\perp := w^* - w$  is orthogonal to  $M$ .
- 5 Projections decrease norms:  $\|w\| \leq \|w^*\|$ .
- 6 Since  $R$  is nondecreasing,  $R(\|w\|) \leq R(\|w^*\|)$ .
- 7 By (4),  $\langle w^*, \psi(x_i) \rangle = \langle w + w^\perp, \psi(x_i) \rangle = \langle w, \psi(x_i) \rangle$ .
- 8  $L(\langle w^*, \psi(x_1) \rangle, \dots, \langle w^*, \psi(x_n) \rangle) = L(\langle w, \psi(x_1) \rangle, \dots, \langle w, \psi(x_n) \rangle)$
- 9  $J(w) \leq J(w^*)$ .
- 10 Therefore  $w = \sum_{i=1}^n \alpha_i \psi(x_i)$  is also a minimizer.

Q.E.D.

## Representer Theorem for Kernelization

# Kernelized Predictions

- Consider  $w = \sum_{i=1}^n \alpha_i \psi(x_i)$ .
- How do we make predictions for a given  $x \in \mathcal{X}$ ?

$$\begin{aligned} f(x) = \langle w^*, \psi(x) \rangle &= \left\langle \sum_{i=1}^n \alpha_i \psi(x_i), \psi(x) \right\rangle \\ &= \sum_{i=1}^n \alpha_i \langle \psi(x_i), \psi(x) \rangle \\ &= \sum_{i=1}^n \alpha_i k(x_i, x) \end{aligned}$$



# Kernelized Regularization

- Consider  $w = \sum_{i=1}^n \alpha_i \psi(x_i)$ .
- What does  $R(\|w\|)$  look like?

$$\begin{aligned}
 \|w\|^2 &= \langle w, w \rangle \\
 &= \left\langle \sum_{i=1}^n \alpha_i \psi(x_i), \sum_{j=1}^n \alpha_j \psi(x_j) \right\rangle \\
 &= \sum_{i,j=1}^n \alpha_i \alpha_j \langle \psi(x_i), \psi(x_j) \rangle \\
 &= \sum_{i,j=1}^n \alpha_i \alpha_j k(x_i, x_j)
 \end{aligned}$$

(You should recognize the last expression as a quadratic form.)

# The Kernel Matrix (a.k.a. Gram Matrix)

## Definition

The **kernel matrix** for a kernel  $k$  on a set  $\{x_1, \dots, x_n\}$  is

$$K = (k(x_i, x_j))_{i,j} = \begin{pmatrix} k(x_1, x_1) & \cdots & k(x_1, x_n) \\ \vdots & \ddots & \vdots \\ k(x_n, x_1) & \cdots & k(x_n, x_n) \end{pmatrix} \in \mathbb{R}^{n \times n}.$$

This matrix is also known as the **Gram matrix**.

# Kernelized Regularization: Matrix Form

- Consider  $w = \sum_{i=1}^n \alpha_i \psi(x_i)$ .
- What does  $R(\|w\|)$  look like?

$$\begin{aligned}\|w\|^2 &= \sum_{i,j=1}^n \alpha_i \alpha_j k(x_i, x_j) \\ &= \alpha^T K \alpha\end{aligned}$$

- So  $R(\|w\|) = R\left(\sqrt{\alpha^T K \alpha}\right)$ .

# Kernelized Predictions

- Write  $f_\alpha(x) = \sum_{i=1}^n \alpha_i k(x_i, x)$ .
- Predictions on the training points have a particularly simple form:

$$\begin{aligned}
 \begin{pmatrix} f_\alpha(x_1) \\ \vdots \\ f_\alpha(x_n) \end{pmatrix} &= \begin{pmatrix} \alpha_1 k(x_1, x_1) + \cdots + \alpha_n k(x_1, x_n) \\ \vdots \\ \alpha_1 k(x_n, x_1) + \cdots + \alpha_n k(x_n, x_n) \end{pmatrix} \\
 &= \begin{pmatrix} k(x_1, x_1) & \cdots & k(x_1, x_n) \\ \vdots & \ddots & \vdots \\ k(x_n, x_1) & \cdots & k(x_n, x_n) \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} \\
 &= K\alpha
 \end{aligned}$$

# Kernelized Objective

- Substituting

$$w = \sum_{i=1}^n \alpha_i \psi(x_i)$$

into generalized objective, we get

$$\min_{\alpha \in \mathbf{R}^n} R\left(\sqrt{\alpha^T K \alpha}\right) + L(K\alpha).$$

- No direct access to  $\psi(x_i)$ .
- All references are via kernel matrix  $K$ .
- (Assumes  $R$  and  $L$  do not hide any references to  $\psi(x_i)$ .)
- This is the **kernelized objective function**.

# Kernelized SVM

- The SVM objective:

$$\min_{w \in \mathcal{H}} \frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n (1 - y_i [\langle w, \psi(x_i) \rangle])_+.$$

- Kernelizing yields

$$\min_{\alpha \in \mathbf{R}^n} \frac{1}{2} \alpha^T K \alpha + \frac{c}{n} \sum_{i=1}^n (1 - y_i (K \alpha)_i)_+$$

# Kernelized Ridge Regression

- Ridge Regression:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n (w^T x_i - y_i)^2 + \lambda \|w\|^2$$

- Featurized Ridge Regression

$$\min_{w \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n (\langle w, \psi(x_i) \rangle - y_i)^2 + \lambda \|w\|^2$$

- Kernelized Ridge Regression

$$\min_{\alpha \in \mathbf{R}^n} \frac{1}{n} \|K\alpha - y\|^2 + \lambda \alpha^T K \alpha,$$

where  $y = (y_1, \dots, y_n)^T$ .

## Kernel Examples



# SVM Dual

- Recall the SVM dual optimization problem

$$\begin{aligned} \sup_{\alpha} \quad & \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i \\ \text{s.t.} \quad & \sum_{i=1}^n \alpha_i y_i = 0 \\ & \alpha_i \in \left[0, \frac{C}{n}\right] \quad i = 1, \dots, n. \end{aligned}$$

- Notice:  $x$ 's only show up as inner products with other  $x$ 's.
- Can replace  $x_j^T x_i$  by an arbitrary kernel  $k(x_j, x_i)$ .
- What kernel are we currently using?

# Linear Kernel

- Input space:  $\mathcal{X} = \mathbf{R}^d$
- Feature space:  $\mathcal{H} = \mathbf{R}^d$ , with standard inner product
- Feature map

$$\psi(x) = x.$$

- Kernel:

$$k(w, x) = w^T x$$

# Quadratic Kernel in $\mathbf{R}^2$

- Input space:  $\mathcal{X} = \mathbf{R}^2$
- Feature space:  $\mathcal{H} = \mathbf{R}^5$
- Feature map:

$$\psi : (x_1, x_2) \mapsto (x_1, x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2)$$

- Gives us ability to represent conic section boundaries.
- Define kernel as inner product in feature space:

$$\begin{aligned} k(w, x) &= \langle \psi(w), \psi(x) \rangle \\ &= w_1x_1 + w_2x_2 + w_1^2x_1^2 + w_2^2x_2^2 + 2w_1w_2x_1x_2 \\ &= w_1x_1 + w_2x_2 + (w_1x_1)^2 + (w_2x_2)^2 + 2(w_1x_1)(w_2x_2) \\ &= \langle w, x \rangle + \langle w, x \rangle^2 \end{aligned}$$

Based on Guillaume Obozinski's Statistical Machine Learning course at Louvain, Feb 2014.

# Quadratic Kernel in $\mathbf{R}^d$

- Input space  $\mathcal{X} = \mathbf{R}^d$
- Feature space:  $\mathcal{H} = \mathbf{R}^D$ , where  $D = d + \binom{d}{2} \approx d^2/2$ .
- Feature map:

$$\phi(x) = (x_1, \dots, x_d, x_1^2, \dots, x_d^2, \sqrt{2}x_1x_2, \dots, \sqrt{2}x_ix_j, \dots, \sqrt{2}x_{d-1}x_d)^T$$

- Still have

$$\begin{aligned} k(w, x) &= \langle \phi(w), \phi(x) \rangle \\ &= \langle x, y \rangle + \langle x, y \rangle^2 \end{aligned}$$

- Computation for inner product with explicit mapping:  $O(d^2)$
- Computation for implicit kernel calculation:  $O(d)$ .

# Polynomial Kernel in $\mathbf{R}^d$

- Input space  $\mathcal{X} = \mathbf{R}^d$
- Kernel function:

$$k(w, x) = (1 + \langle w, x \rangle)^M$$

- Corresponds to a feature map with all terms up to degree  $M$ .
- For any  $M$ , computing the kernel has same computational cost
- Cost of explicit inner product computation grows rapidly in  $M$ .

# Radial Basis Function (RBF) / Gaussian Kernel

- Input space  $\mathcal{X} = \mathbf{R}^d$

$$k(w, x) = \exp\left(-\frac{\|w - x\|^2}{2\sigma^2}\right),$$

where  $\sigma^2$  is known as the bandwidth parameter.

- Does it act like a similarity score?
- Why “radial”?
- Have we departed from our “inner product of feature vector” recipe?
  - Yes and no: corresponds to an infinite dimensional feature vector
- Probably the most common nonlinear kernel.

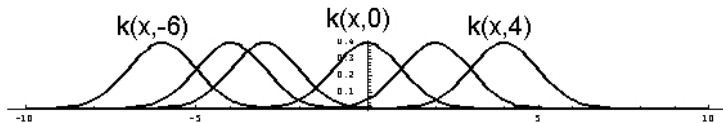
## Prediction Functions with RBF Kernel

# RBF Basis

- Input space  $\mathcal{X} = \mathbb{R}$
- Output space:  $\mathcal{Y} = \mathbb{R}$
- RBF kernel  $k(w, x) = \exp(-(w - x)^2)$ .
- Suppose we have 6 training examples:  $x_i \in \{-6, -4, -3, 0, 2, 4\}$ .
- If representer theorem applies, then

$$f(x) = \sum_{i=1}^6 \alpha_i k(x_i, x).$$

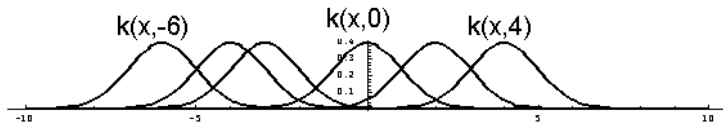
- $f$  is a linear combination of 6 basis functions of form  $k(x_i, \cdot)$ :





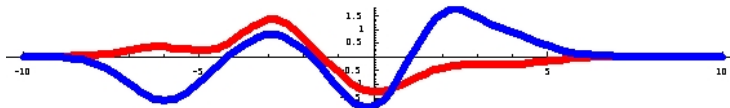
# RBF Predictions

- Basis functions



- Predictions of the form

$$f(x) = \sum_{i=1}^6 \alpha_i k(x_i, x)$$



- If we have a kernelized algorithm with RBF kernel, prediction functions  $x \mapsto \langle w, \psi(x) \rangle$  will look this way.
  - whether we got  $w$  from SVM, ridge regression, etc...

When is  $k(x, w)$  a kernel function? (Mercer's Theorem)

# How to Get Kernels?

- 1 Explicitly construct  $\psi(x) : \mathcal{X} \rightarrow \mathbf{R}^d$  and define  $k(x, w) = \psi(x)^T \psi(w)$ .
- 2 Directly define the kernel function  $k(x, w)$ , and verify it corresponds to  $\langle \psi(x), \psi(w) \rangle$  for some  $\psi$ .

There are many theorems to help us with the second approach

# Positive Semidefinite Matrices

## Definition

A real, symmetric matrix  $M \in \mathbf{R}^{n \times n}$  is **positive semidefinite (psd)** if for any  $x \in \mathbf{R}^n$ ,

$$x^T M x \geq 0.$$

## Theorem

*The following conditions are each necessary and sufficient for  $M$  to be positive semidefinite:*

- $M$  has a “square root”, i.e. there exists  $R$  s.t.  $M = R^T R$ .
- All eigenvalues of  $M$  are greater than or equal to 0.

# Positive Semidefinite Function

## Definition

A symmetric kernel function  $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbf{R}$  is **positive semidefinite (psd)** if for any finite set  $\{x_1, \dots, x_n\} \in \mathcal{X}$ , the kernel matrix on this set

$$K = (k(x_i, x_j))_{i,j} = \begin{pmatrix} k(x_1, x_1) & \cdots & k(x_1, x_n) \\ \vdots & \ddots & \vdots \\ k(x_n, x_1) & \cdots & k(x_n, x_n) \end{pmatrix}$$

is a positive semidefinite matrix.

# Mercer's Theorem

## Theorem

*A symmetric function  $k(w, x)$  can be expressed as an inner product*

$$k(w, x) = \langle \psi(w), \psi(x) \rangle$$

*for some  $\psi$  if and only if  $k(w, x)$  is **positive semidefinite**.*

# Generating New Kernels from Old

Suppose  $k, k_1, k_2 : \mathcal{X} \times \mathcal{X} \rightarrow \mathbf{R}$  are psd kernels. Then so are the following:

$$k_{\text{new}}(w, x) = k_1(w, x) + k_2(w, x)$$

$$k_{\text{new}}(w, x) = \alpha k(w, x)$$

$$k_{\text{new}}(w, x) = f(w)f(x) \text{ for any function } f(x)$$

$$k_{\text{new}}(w, x) = k_1(w, x)k_2(w, x)$$

are also A symmetric function  $k(w, x)$  can be expressed as an inner product

$$k(w, x) = \langle \phi(w), \phi(x) \rangle$$

for some  $\phi$  if and only if  $k(w, x)$  is **positive semidefinite**.

- If we start with a psd kernel, can we generate more?

# Additive Closure

- Suppose  $k_1$  and  $k_2$  are psd kernels with feature maps  $\phi_1$  and  $\phi_2$ , respectively.
- Then

$$k_1(w, x) + k_2(w, x)$$

is a psd kernel.

- Proof: Concatenate the feature vectors to get

$$\phi(x) = (\phi_1(x), \phi_2(x)).$$

Then  $\phi$  is a feature map for  $k_1 + k_2$ .



# Closure under Positive Scaling

- Suppose  $k$  is a psd kernel with feature maps  $\phi$ .
- Then for any  $\alpha > 0$ ,

$$\alpha k$$

is a psd kernel.

- Proof: Note that

$$\phi(x) = \sqrt{\alpha}\phi(x)$$

is a feature map for  $\alpha k$ .

# Scalar Function Gives a Kernel

- For any function  $f(x)$ ,

$$k(w, x) = f(w)f(x)$$

is a kernel.

- Proof: Let  $f(x)$  be the feature mapping. (It maps into a 1-dimensional feature space.)

$$\langle f(x), f(w) \rangle = f(x)f(w) = k(w, x).$$

# Closure under Hadamard Products

- Suppose  $k_1$  and  $k_2$  are psd kernels with feature maps  $\phi_1$  and  $\phi_2$ , respectively.
- Then

$$k_1(w, x)k_2(w, x)$$

is a psd kernel.

- Proof: Take the outer product of the feature vectors:

$$\phi(x) = \phi_1(x) [\phi_2(x)]^T.$$

Note that  $\phi(x)$  is a matrix.

- Continued...

# Closure under Hadamard Products

- Then

$$\begin{aligned}
 \langle \phi(x), \phi(w) \rangle &= \sum_{i,j} \phi(x) \phi(w) \\
 &= \sum_{i,j} \left[ \phi_1(x) [\phi_2(x)]^T \right]_{ij} \left[ \phi_1(w) [\phi_2(w)]^T \right]_{ij} \\
 &= \sum_{i,j} [\phi_1(x)]_i [\phi_2(x)]_j [\phi_1(w)]_i [\phi_2(w)]_j \\
 &= \left( \sum_i [\phi_1(x)]_i [\phi_1(w)]_i \right) \left( \sum_j [\phi_2(x)]_j [\phi_2(w)]_j \right) \\
 &= k_1(w, x) k_2(w, x)
 \end{aligned}$$