Excess Risk Decomposition

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Statistical Learning Theory Framework

The Spaces

• X: input space

• y: output space

ullet \mathcal{A} : action space

Decision Function

A **decision function** produces an action $a \in \mathcal{A}$ for any input $x \in \mathcal{X}$:

$$f: \mathcal{X} \rightarrow \mathcal{A}$$
 $x \mapsto f(x)$

Loss Function

A **loss function** evaluates an action in the context of the output y.

$$\ell: \mathcal{A} \times \mathcal{Y} \rightarrow \mathbf{R}$$
 $(a, y) \mapsto \ell(a, y)$

The Gold Standard: Bayes Decision Function

Definition

The **expected loss** or "risk" of a decision function $f: \mathcal{X} \to \mathcal{A}$ is

$$R(f) = \mathbb{E}\ell(f(x), y),$$

where the expectation taken is over $(x, y) \sim P_{X \times Y}$.

Definition

A Bayes decision function $f^*: \mathcal{X} \to \mathcal{A}$ is a function that achieves the *minimal risk* among all possible functions:

$$R(f^*) = \inf_{f} \mathbb{E}\ell(f(x), y).$$

• But risk function cannot be computed because we don't know $P_{X \times Y}$.

Empirical Risk Minimization

• Let $\mathfrak{D}_n = ((x_1, y_1), \dots, (x_n, y_n))$ be drawn i.i.d. from $\mathfrak{P}_{\mathfrak{X} \times \mathfrak{Y}}$.

Definition

The **empirical risk** of $f: \mathcal{X} \to \mathcal{A}$ with respect to \mathcal{D}_n is

$$\hat{R}_n(f) = \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i).$$

• Minimizing empirical risk over all functions leads to overfitting.

Constrain to a Hypothesis Space

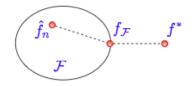
- ullet Hypothesis space ${\mathcal F}$, a set of functions mapping ${\mathcal X} o {\mathcal A}$
 - Example hypothesis spaces?
- \bullet Empirical risk minimizer (ERM) in ${\mathfrak F}$ is

$$\hat{f}_n = \underset{f \in \mathcal{F}}{\operatorname{arg\,min}} \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i).$$

Risk minimizer in F is

$$\hat{f}_n = \underset{f \in \mathcal{F}}{\operatorname{arg min}} \mathbb{E} \ell(f(x), y).$$

Error Decomposition



$$f^* = \underset{f}{\operatorname{arg \, min}} \mathbb{E}\ell(f(X), Y)$$

$$f_{\mathcal{F}} = \underset{f \in \mathcal{F}}{\operatorname{arg \, min}} \mathbb{E}\ell(f(X), Y))$$

$$\hat{f}_n = \underset{f \in \mathcal{F}}{\operatorname{arg \, min}} \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i)$$

- Approximation Error (of \mathfrak{F}) = $R(f_{\mathfrak{F}}) R(f^*)$
- Estimation error (of \hat{f}_n in \mathcal{F}) = $R(\hat{f}_n) R(f_{\mathcal{F}})$

Figure from Sasha Rakhlin's MLSS Lectures (2012): http://yosinski.com/mlss12/MLSS-2012-Rakhlin-Statistical-Learning-Theory/

Excess Risk

Definition

The excess risk of f is how much more risk f has than the Bayes optimal f^* :

Excess
$$Risk(f) = R(f) - R(f^*)$$

• Can excess risk ever be negative?

Excess Risk Decomposition for ERM

• The excess risk of the ERM \hat{f}_n can be decomposed:

Excess
$$\operatorname{Risk}(\hat{f}_n) = R(\hat{f}_n) - R(f^*)$$

$$= \underbrace{R(\hat{f}_n) - R(f_{\mathcal{F}})}_{\text{estimation error}} + \underbrace{R(f_{\mathcal{F}}) - R(f^*)}_{\text{approximation error}}.$$

- Generalizes the bias/variance decomosition for mean squared error:
 - Approximation error ≈ "bias"
 - Estimation error ≈ "variance"

Approximation Error

Approximation error $R(f_{\mathcal{F}}) - R(f^*)$ is

- ullet a property of the class ${\mathcal F}$
- ullet the penalty for restricting to ${\mathcal F}$ rather than all possible functions

Bigger \mathfrak{F} mean smaller approximation error.

Estimation Error

Estimation error $R(\hat{f}_n) - R(f_{\mathcal{F}})$

- is the performance hit for choosing f using finite training data
- is the performance hit for using empirical risk rather than true risk

Smaller \mathfrak{F} means smaller estimation error.

ERM Overview

- Given a loss function $\ell: \mathcal{A} \times \mathcal{Y} \to \mathbf{R}$.
- Choose hypothesis space \mathcal{F} .
- Use an optimization method to find ERM $\hat{f}_n \in \mathcal{F}$:

$$\hat{f}_n = \arg\min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i).$$

- Data scientist's job:
 - ullet choose ${\mathcal F}$ to balance between approximation and estimation error.
 - ullet as we get more training data, use a bigger ${\mathcal F}$

ERM in Practice

- We've been cheating a bit by writing "argmin".
- In practice, we need a method to find $\hat{f}_n \in \mathcal{F}$.
- For nice choices of loss functions and classes \mathcal{F} , the algorithmic problem can be solved to any desired accuracy
 - But takes time is it worth it?
- For neural networks, we have no idea how to find $\hat{f}_n \in \mathcal{F}$.

Optimization Error

- In practice, we don't find the ERM $\hat{f}_n \in \mathcal{F}$.
- We find $\tilde{f}_n \in \mathcal{F}$ that we hope is good enough.
- Optimization error: If \tilde{f}_n is the function our optimization method returns, and \hat{f}_n is the empirical risk minimizer, then

Optimization Error =
$$R(\tilde{f}_n) - R(\hat{f}_n)$$
.

• Can optimization error be negative?

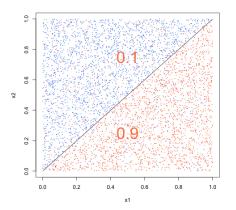
Error Decomposition in Practice

Excess risk decomposition for function \tilde{f}_n returned by algorithm:

Excess Risk
$$(\tilde{f}_n) = R(\tilde{f}_n) - R(f^*)$$

$$= \underbrace{R(\tilde{f}_n) - R(\hat{f}_n)}_{\text{optimization error}} + \underbrace{R(\hat{f}_n) - R(f^*_{\mathcal{T}})}_{\text{estimation error}} + \underbrace{R(f^*_{\mathcal{T}}) - R(f^*)}_{\text{approximation error}}$$

Excess Risk Decomposition, Nested Spaces, and Trees



$$\mathcal{Y} = \{ \text{blue}, \text{orange} \}$$

$$P_{\mathcal{X}} = \text{Uniform}([0, 1]^2)$$

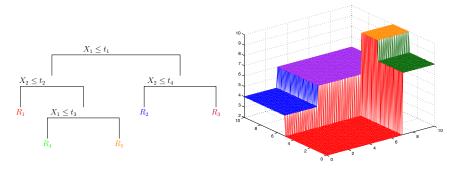
$$\mathbb{P}(\text{orange} \mid x_1 > x_2) = .9$$

$$\mathbb{P}(\text{orange} \mid x_1 < x_2) = .1$$

Bayes Error Rate = 0.1

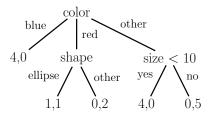
Regression Trees

• Partition space on one variable at a time



Classification Trees

- Classification Tree
- 4,0 in the leaf node means 4 successes, 0 failures



• Depth of the tree is one measure of complexity

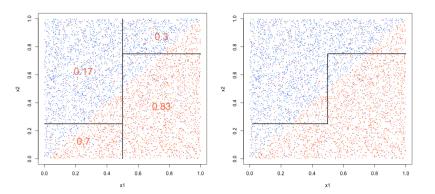
Hypothesis Space: Decision Tree

- ullet $\mathcal{F}=\left\{ \mathsf{all} \ \mathsf{decision} \ \mathsf{tree} \ \mathsf{classifiers} \ \mathsf{on} \ \left[0,1\right]^2 \right\}$
- $\mathcal{F}_d = \left\{ \mathsf{all} \; \mathsf{decision} \; \mathsf{tree} \; \mathsf{classifiers} \; \mathsf{on} \; [0,1]^2 \; \mathsf{with} \; \mathsf{DEPTH} \leqslant d \right\}$
- We'll consider

$$\mathfrak{F}_2\subset \mathfrak{F}_3\subset \mathfrak{F}_4\cdots\subset \mathfrak{F}_{15}$$

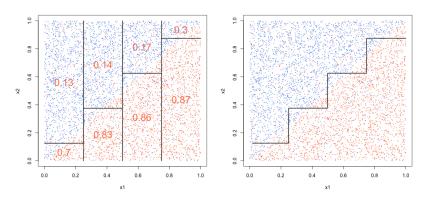
• Bayes error rate = 0.1

Theoretical Best in \mathcal{F}_2



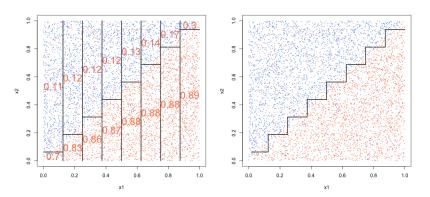
- Risk Minimizer (e.g. assuming infinite training data)
- Risk = P(error) = 0.2
- Approximation Error = 0.2 0.1 = 0.1

Theoretical Best in \mathcal{F}_3



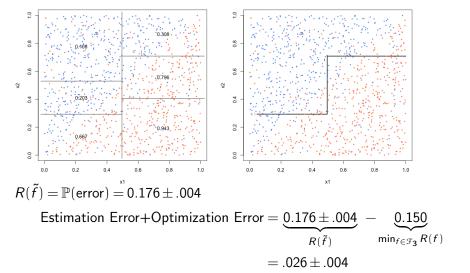
- Risk Minimizer (e.g. assuming infinite training data)
- Risk = P(error) = 0.15
- Approximation Error = 0.15 0.1 = 0.05

Theoretical Best in \mathcal{F}_4

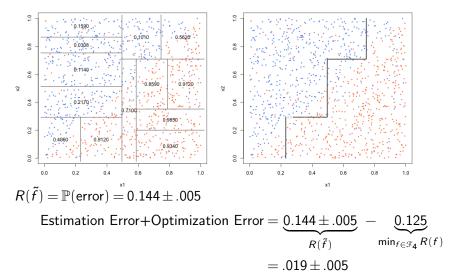


- Risk Minimizer (e.g. assuming infinite training data)
- Risk = P(error) = 0.125
- Approximation Error = 0.125 0.1 = 0.025

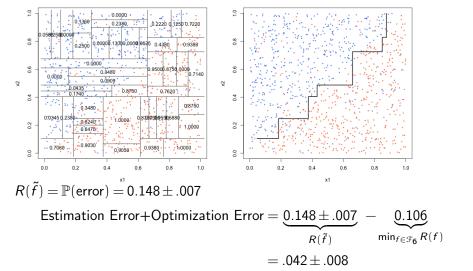
Decision Tree in \mathcal{F}_3 Estimated From Sample (n = 1024)



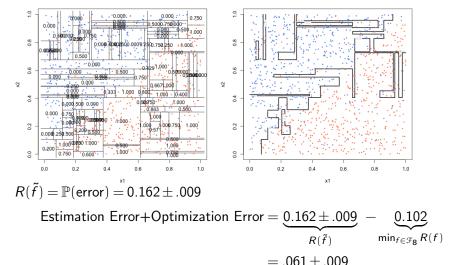
Decision Tree in \mathcal{F}_4 Estimated From Sample (n = 1024)



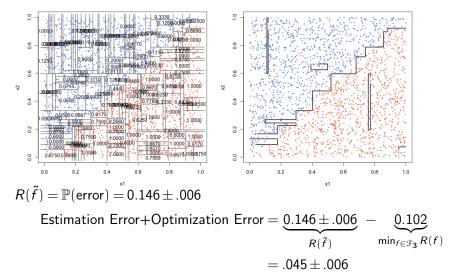
Decision Tree in \mathcal{F}_6 Estimated From Sample (n = 1024)



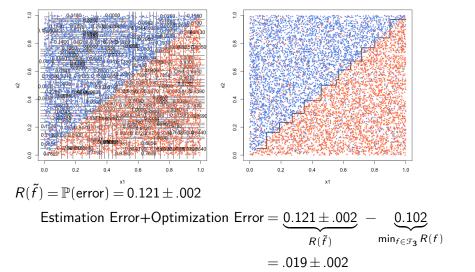
Decision Tree in \mathcal{F}_8 Estimated From Sample (n = 1024)



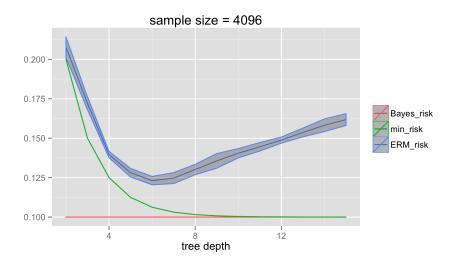
Decision Tree in \mathcal{F}_8 Estimated From Sample (n = 2048)



Decision Tree in \mathcal{F}_8 Estimated From Sample (n = 8192)

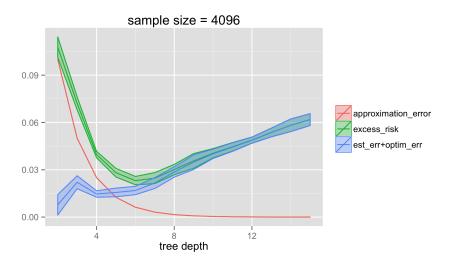


Risk Summary



Why do some curves have confidence bands and others not?

Excess Risk Decomposition



Why do some curves have confidence bands and others not?