## Support Vector Machines

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# The SVM as a Quadratic Program

## The Margin

#### Definition

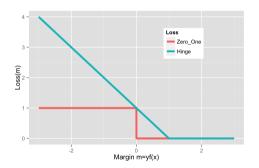
The margin (or functional margin) for predicted score  $\hat{y}$  and true class  $y \in \{-1, 1\}$  is  $y\hat{y}$ .

- The margin often looks like yf(x), where f(x) is our score function.
- The margin is a measure of how correct we are.
- We want to maximize the margin.
- Most classification losses depend only on the margin.

(This is distinct from but related to geometric margin from lab.)

# Hinge Loss

- SVM/Hinge loss:  $\ell_{\text{Hinge}} = \max\{1-m, 0\} = (1-m)_{+}$
- Margin m = yf(x); "Positive part"  $(x)_+ = x1(x \ge 0)$ .



Hinge is a **convex**, **upper bound** on 0-1 loss. Not differentiable at m=1. We have a "margin error" when m<1.

# Support Vector Machine

- Hypothesis space  $\mathcal{F} = \{f(x) = w^T x + b \mid w \in \mathbf{R}^d, b \in \mathbf{R}\}.$
- $\ell_2$  regularization (Tikhonov style)
- Loss  $\ell(m) = \max\{1-m, 0\} = (1-m)_+$
- The SVM prediction function is the solution to

$$\min_{w \in \mathbb{R}^d, b \in \mathbb{R}} \frac{1}{2} ||w||^2 + \frac{c}{n} \sum_{i=1}^n \max (0, 1 - y_i [w^T x_i + b]).$$

# SVM Optimization Problem (Tikhonov Version)

The SVM prediction function is the solution to

$$\min_{w \in \mathbf{R}^d, b \in \mathbf{R}} \frac{1}{2} ||w||^2 + \frac{c}{n} \sum_{i=1}^n \max (0, 1 - y_i [w^T x_i + b]).$$

- unconstrained optimization
- not differentiable because of the max (right at the border of a margin error)
- Can we reformulate into a differentiable problem?

## SVM Optimization Problem

• The SVM optimization problem is equivalent to

minimize 
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
  
subject to 
$$\xi_i \geqslant \max\left(0, 1 - y_i \left[w^T x_i + b\right]\right).$$

Which is equivalent to

minimize 
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
subject to 
$$\xi_i \geqslant \left(1 - y_i \left[w^T x_i + b\right]\right) \text{ for } i = 1, \dots, n$$
$$\xi_i \geqslant 0 \text{ for } i = 1, \dots, n$$

# SVM as a Quadratic Program

• The SVM optimization problem is equivalent to

minimize 
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
subject to 
$$-\xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$
$$\left(1 - y_i \left[w^T x_i + b\right]\right) - \xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$

- Differentiable objective function
- n+d+1 unknowns and 2n affine constraints.
- A quadratic program that can be solved by any off-the-shelf QP solver.
- Let's learn more by examining the dual.

## The SVM Dual Problem

# SVM Lagrange Multipliers

minimize 
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
subject to 
$$-\xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$
$$\left(1 - y_i \left[w^T x_i + b\right]\right) - \xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$

Lagrange Multiplier	Constraint
$\lambda_i$	$-\xi_i \leqslant 0$
$\alpha_i$	$\left[ \left( 1 - y_i \left[ w^T x_i + b \right] \right) - \xi_i \leqslant 0 \right]$

$$L(w, b, \xi, \alpha, \lambda) = \frac{1}{2} ||w||^2 + \frac{c}{n} \sum_{i=1}^{n} \xi_i + \sum_{i=1}^{n} \alpha_i \left( 1 - y_i \left[ w^T x_i + b \right] - \xi_i \right) + \sum_{i=1}^{n} \lambda_i \left( -\xi_i \right)$$

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# SVM Lagrangian

• The Lagrangian for this formulation is

$$L(w, b, \xi, \alpha, \lambda) = \frac{1}{2} ||w||^{2} + \frac{c}{n} \sum_{i=1}^{n} \xi_{i} + \sum_{i=1}^{n} \alpha_{i} \left(1 - y_{i} \left[w^{T} x_{i} + b\right] - \xi_{i}\right) - \sum_{i} \lambda_{i} \xi_{i}$$

$$= \frac{1}{2} w^{T} w + \sum_{i=1}^{n} \xi_{i} \left(\frac{c}{n} - \alpha_{i} - \lambda_{i}\right) + \sum_{i=1}^{n} \alpha_{i} \left(1 - y_{i} \left[w^{T} x_{i} + b\right]\right).$$

Primal and dual:

$$p^* = \inf_{w,\xi,b} \sup_{\alpha,\lambda \succeq 0} L(w,b,\xi,\alpha,\lambda)$$
  
$$\geqslant \sup_{\alpha,\lambda \succeq 0} \inf_{w,b,\xi} L(w,b,\xi,\alpha,\lambda) = d^*$$

• Do we have  $p^* = d^*$ ?

## Strong Duality by Slater's constraint qualification

• The SVM optimization problem:

minimize 
$$\frac{1}{2}||w||^2 + \frac{c}{n}\sum_{i=1}^n \xi_i$$
subject to 
$$-\xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$
$$\left(1 - y_i \left[w^T x_i + b\right]\right) - \xi_i \leqslant 0 \text{ for } i = 1, \dots, n$$

- Convex problem + affine constraints ⇒ strong duality iff problem is feasible
- Constraints are satisfied by w = b = 0 and  $\xi_i = 1$  for i = 1, ..., n,
  - so we have strong duality  $\Longrightarrow$

$$p^* = \inf_{w, \xi, b} \sup_{\alpha, \lambda \succeq 0} L(w, b, \xi, \alpha, \lambda)$$
  
= 
$$\sup_{\alpha, \lambda \succeq 0} \inf_{w, b, \xi} L(w, b, \xi, \alpha, \lambda) = d^*$$

#### SVM Dual Function

• Lagrange dual is the inf over primal variables of the Lagrangian:

$$g(\alpha, \lambda) = \inf_{w, b, \xi} L(w, b, \xi, \alpha, \lambda)$$

$$= \inf_{w, b, \xi} \left[ \frac{1}{2} w^{T} w + \sum_{i=1}^{n} \xi_{i} \left( \frac{c}{n} - \alpha_{i} - \lambda_{i} \right) + \sum_{i=1}^{n} \alpha_{i} \left( 1 - y_{i} \left[ w^{T} x_{i} + b \right] \right) \right]$$

- Taking inf of convex and differentiable function of  $w, b, \xi$ .
  - Quadratic in w and linear in  $\xi$  and b.
- Thus optimal point iff  $\partial_w L = 0 \ \partial_b L = 0 \ \partial_\xi L = 0$

#### SVM Dual Function: First Order Conditions

Lagrange dual function is the inf over primal variables of *L*:

$$g(\alpha, \lambda) = \inf_{w, b, \xi} L(w, b, \xi, \alpha, \lambda)$$

$$= \inf_{w, b, \xi} \left[ \frac{1}{2} w^{T} w + \sum_{i=1}^{n} \xi_{i} \left( \frac{c}{n} - \alpha_{i} - \lambda_{i} \right) + \sum_{i=1}^{n} \alpha_{i} \left( 1 - y_{i} \left[ w^{T} x_{i} + b \right] \right) \right]$$

$$\partial_{w} L = 0 \iff w - \sum_{i=1}^{n} \alpha_{i} y_{i} x_{i} = 0 \iff w = \sum_{i=1}^{n} \alpha_{i} y_{i} x_{i}$$

$$\partial_{b} L = 0 \iff -\sum_{i=1}^{n} \alpha_{i} y_{i} = 0 \iff \sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

$$\partial_{\xi_{i}} L = 0 \iff \frac{c}{n} - \alpha_{i} - \lambda_{i} = 0 \iff \alpha_{i} + \lambda_{i} = \frac{c}{n}$$

#### The SVM Dual Problem

• Using 1st order conditions, and some massaging, the SVM dual problem is:

$$\sup_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{j}^{T} x_{i}$$
s.t. 
$$\sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

$$\alpha_{i} \in \left[0, \frac{c}{n}\right] \ i = 1, \dots, n.$$

- Given solution  $\alpha^*$  to dual, primal solution is  $w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$ .
- $w^*$  is "in the span of the data" i.e. a linear combination of  $x_1, \ldots, x_n$ .
- Note  $\alpha_i^* \in [0, \frac{c}{n}]$ . So c controls max weight on each example. (Robustness!)

#### SVM Dual Problem

$$\sup_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{j}^{T} x_{i}$$
s.t. 
$$\sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

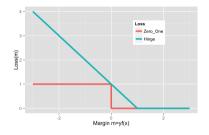
$$\alpha_{i} \in \left[0, \frac{c}{n}\right] \ i = 1, \dots, n.$$

- Quadratic objective in n unknowns and n+1 constraints
- Efficient minimization algorithm: SMO (sequential minimal optimization)
- What other insights can we get from the dual formulation?

# Insights From Complementary Slackness: Margin and Support Vectors

# The Margin and Some Terminology

- For notational convenience, define  $f^*(x) = x^T w^* + b^*$ .
- Margin  $yf^*(x)$



- Incorrect classification:  $yf^*(x) \leq 0$ .
- Margin error:  $yf^*(x) < 1$ .
- "On the margin":  $yf^*(x) = 1$ .
- "Good side of the margin":  $yf^*(x) > 1$ .

# Support Vectors and The Margin

- Recall "slack variable"  $\xi_i^* = \max(0, 1 y_i f^*(x_i))$  is the hinge loss on  $(x_i, y_i)$ .
- Suppose  $\xi_i^* = 0$ .
- Then  $y_i f^*(x_i) \geqslant 1$ 
  - "on the margin" (=1), or
  - $\bullet$  "on the good side" (> 1)

## Complementary Slackness Conditions

• Recall our primal constraints and Lagrange multipliers:

Lagrange Multiplier	Constraint
$\lambda_i$	$-\xi_i \leqslant 0$
$\alpha_i$	$(1-y_if(x_i))-\xi_i\leqslant 0$

- Recall first order condition  $\nabla_{\xi_i} L = 0$  gave us  $\lambda_i^* = \frac{c}{n} \alpha_i^*$ .
- By strong duality, we must have complementary slackness:

$$\alpha_i^* \left( 1 - y_i f^*(x_i) - \xi_i^* \right) = 0$$
$$\lambda_i^* \xi_i^* = \left( \frac{c}{n} - \alpha_i^* \right) \xi_i^* = 0$$

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# Consequences of Complementary Slackness

• By strong duality, we must have **complementary slackness**:

$$\alpha_i^* \left(1 - y_i f^*(x_i) - \xi_i^*\right) = 0$$
$$\left(\frac{c}{n} - \alpha_i^*\right) \xi_i^* = 0$$

- If  $y_i f^*(x_i) > 1$  then the margin loss is  $\xi_i^* = 0$ , and we get  $\alpha_i^* = 0$ .
- If  $y_i f^*(x_i) < 1$  then the margin loss is  $\xi_i^* > 0$ , so  $\alpha_i^* = \frac{c}{n}$ .
- If  $\alpha_i^* = 0$ , then  $\xi_i^* = 0$ , which implies no loss, so  $y_i f^*(x) \ge 1$ .
- If  $\alpha_i^* \in (0, \frac{c}{n})$ , then  $\xi_i^* = 0$ , which implies  $1 y_i f^*(x_i) = 0$ .

# Complementary Slackness Results: Summary

$$\alpha_{i}^{*} = 0 \implies y_{i}f^{*}(x_{i}) \geqslant 1$$

$$\alpha_{i}^{*} \in \left(0, \frac{c}{n}\right) \implies y_{i}f^{*}(x_{i}) = 1$$

$$\alpha_{i}^{*} = \frac{c}{n} \implies y_{i}f^{*}(x_{i}) \leqslant 1$$

$$y_{i}f^{*}(x_{i}) < 1 \implies \alpha_{i}^{*} = \frac{c}{n}$$

$$y_{i}f^{*}(x_{i}) = 1 \implies \alpha_{i}^{*} \in \left[0, \frac{c}{n}\right]$$

$$y_{i}f^{*}(x_{i}) > 1 \implies \alpha_{i}^{*} = 0$$

## Support Vectors

ullet If  $\alpha^*$  is a solution to the dual problem, then primal solution is

$$w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$$

with  $\alpha_i^* \in [0, \frac{c}{n}]$ .

- The  $x_i$ 's corresponding to  $\alpha_i^* > 0$  are called **support vectors**.
- Few margin errors or "on the margin" examples  $\implies$  sparsity in input examples.

# Complementary Slackness To Get b\*

#### The Bias Term: b

• For our SVM primal, the complementary slackness conditions are:

$$\alpha_i^* \left( 1 - y_i \left[ x_i^T w^* + b \right] - \xi_i^* \right) = 0$$
 (1)

$$\lambda_i^* \xi_i^* = \left(\frac{c}{n} - \alpha_i^*\right) \xi_i^* = 0 \tag{2}$$

- Suppose there's an *i* such that  $\alpha_i^* \in (0, \frac{c}{n})$ .
- (2) implies  $\xi_i^* = 0$ .
- (1) implies

$$y_{i} [x_{i}^{T} w^{*} + b^{*}] = 1$$

$$\iff x_{i}^{T} w^{*} + b^{*} = y_{i} \text{ (use } y_{i} \in \{-1, 1\})$$

$$\iff b^{*} = y_{i} - x_{i}^{T} w^{*}$$

#### The Bias Term: b

The optimal b is

$$b^* = y_i - x_i^T w^*$$

- We get the same  $b^*$  for any choice of i with  $\alpha_i^* \in (0, \frac{c}{n})$ 
  - With exact calculations!
- With numerical error, more robust to average over all eligible i's:

$$b^* = \operatorname{mean}\left\{y_i - x_i^T w^* \mid \alpha_i^* \in \left(0, \frac{c}{n}\right)\right\}.$$

- If there are no  $\alpha_i^* \in (0, \frac{c}{n})$ ?
  - Then we have a degenerate SVM training problem<sup>1</sup> ( $w^* = 0$ ).

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<sup>&</sup>lt;sup>1</sup>See Rifkin et al.'s "A Note on Support Vector Machine Degeneracy", an MIT Al Lab Technical Report.

## Teaser for Kernelization

## Dual Problem: Dependence on x through inner products

SVM Dual Problem:

$$\sup_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{j}^{T} x_{i}$$
s.t. 
$$\sum_{i=1}^{n} \alpha_{i} y_{i} = 0$$

$$\alpha_{i} \in \left[0, \frac{c}{n}\right] \ i = 1, \dots, n.$$

- Note that all dependence on inputs  $x_i$  and  $x_j$  is through their inner product:  $\langle x_j, x_i \rangle = x_j^T x_i$ .
- We can replace  $x_i^T x_i$  by any other inner product...
- This is a "kernelized" objective function.