

# Features

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# Learning Objectives

- Understand where a *feature map* sits in a machine learning pipeline.
- Understand that featurization/feature mapping is inherently required to allow predictors to ingest many types of data.
- Understand how feature extraction can be used to extend the power of linear methods.
- Build pipelines with expanded feature spaces using the sklearn ecosystem.

## Feature Extraction

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- Our general learning theory setup: no assumptions about  $\mathcal{X}$
- But  $\mathcal{X} = \mathbf{R}^d$  for the specific methods we've developed:
  - Ridge regression
  - Lasso regression
  - Linear SVM

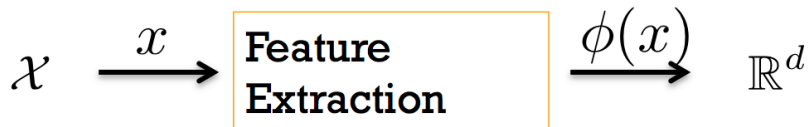
# Feature Extraction

## Definition

Mapping an input from  $\mathcal{X}$  to a vector in  $\mathbb{R}^d$  is called **feature extraction** or **featurization**.

**Raw Input**

**Feature Vector**



- Two motivations for thinking about feature extraction:
  - Motivation 1 – consuming inputs that are not natively in  $\mathbf{R}^d$  – examples?



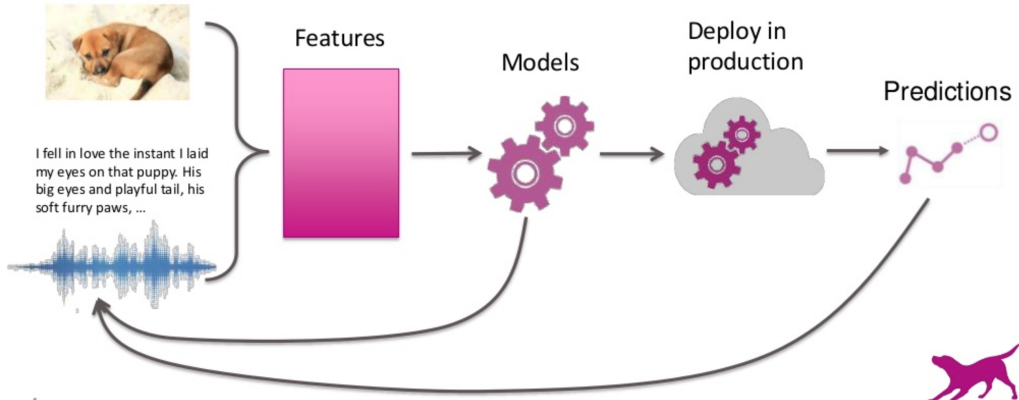
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    - Text documents
    - Image files
    - Sound recordings
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  - But everything in a computer is a sequence of numbers?
    - The  $i$ th entry of each sequence should have the same “meaning”
    - All the sequences should have the same length

# The machine learning pipeline

Raw data



## Feature Templates

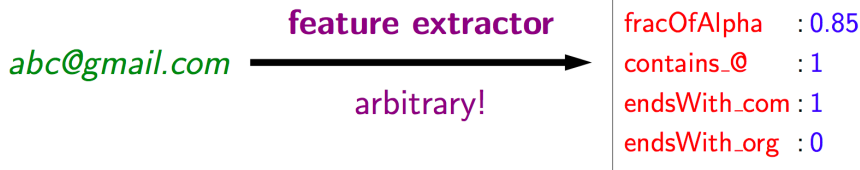
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## Example: Detecting Email Addresses

- Task: Predict whether a string is an email address

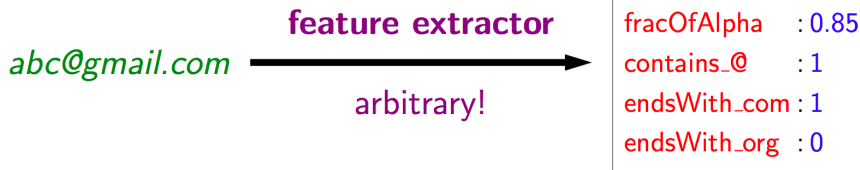
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- But this was ad-hoc, and maybe we missed something.
- Could be more systematic?

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From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.



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- Length greater than \_\_\_\_
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- Contains character \_\_\_\_

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## Feature Template: Last Three Characters Equal \_ \_ \_

- Don't think about which 3-letter suffixes are meaningful...
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```
endsWith_aaa : 0  
endsWith_aab : 0  
endsWith_aac : 0  
...  
endsWith_com : 1  
...  
endsWith_zzz : 0
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- With regularization, our methods will not be overwhelmed.

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# Feature Vector Representations

```
fracOfAlpha : 0.85  
contains_a   : 0  
...  
contains_@   : 1  
...
```

Array representation (good for dense features):

```
[0.85, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0]
```

Map representation (good for sparse features):

```
{"fracOfAlpha": 0.85, "contains_@": 1}
```

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- On “example string” we’d get {"endsWith\_ing": 1}.
- Has overhead compared to arrays, so much slower for dense features.
- Question: if we have a sparse feature vector, what are the implications for preprocessing?

Feature Map – ingesting inputs not natively in  $\mathbf{R}^d$

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## Example: Classifying documents from 20 newsgroups

- Context: The newsgroups dataset comprises around 18000 newsgroups posts on 20 topics.

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- Context: The newsgroups dataset comprises around 18000 newsgroups posts on 20 topics.
- We'll restrict ourselves to classifying posts within 4 topics:
  - 'alt.atheism'
  - 'soc.religion.christian'
  - 'comp.graphics'
  - 'sci.med'.
- Thanks to the sklearn team for this worked example (at [http://scikit-learn.org/stable/tutorial/text\\_analytics/working\\_with\\_text\\_data.html](http://scikit-learn.org/stable/tutorial/text_analytics/working_with_text_data.html)).

## Example: Classifying documents from 20 newsgroups

### Example Document:

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Subject: Converting images to HP LaserJet III?  
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Lines: 14

Does anyone know of a good way (standard PC application/PD utility) to convert tif/img/tga files into LaserJet III format. We would also like to do the same, converting to HPGL (HP plotter) files.

Please email any response.

Is this the correct group?

Thanks in advance. Michael.

--

Michael Collier (Programmer)  
Email: M.P.Collier@uk.ac.city  
Tel: 071 477-8000 x3769  
Fax: 071 477-8565

The Computer Unit,  
The City University,  
London,  
EC1V 0HB.

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- A simple approach – bag-of-words (BOW).
  - Assign a fixed integer id to each word occurring in any document of the training set.
  - For each document  $i$ , count the number of occurrences of each word  $w$  and store it (sparsely) as  $doc_i[w] = j_w == \text{count of word } w \text{ in document } i$ .
  - The BOW representation implies that  $n_{features}$  is the number of distinct words in the corpus.
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  - What is the feature map  $\phi(x)$ ?
  - $\phi(x) = [j_{word_1}, \dots, j_{word_{n_{words}}}]$



## Example: Classifying documents from 20 newsgroups

- Here's the classifier we'll fit (note we're adding the TfidfTransformer to scale by inverse document frequency, since it improves performance on this task – if you're not familiar with TF-IDF see the docs).

```
from sklearn.linear_model import SGDClassifier
from sklearn.feature_extraction.text import CountVectorizer, TfidfTransformer
from sklearn.pipeline import Pipeline
text_clf = Pipeline([('vect', CountVectorizer()),
                     ('tfidf', TfidfTransformer()),
                     ('clf', SGDClassifier(loss='hinge', penalty='l2',
                                          alpha=1e-3, random_state=42,
                                          max_iter=5, tol=None)),
])
text_clf.fit(twenty_train.data, twenty_train.target)
```

- Which named steps in this Pipeline comprise our feature map  $\phi$ ?

## Example: Classifying documents from 20 newsgroups

```
predicted = text_clf.predict(docs_test)
np.mean(predicted == twenty_test.target)
```

0.9127829560585885

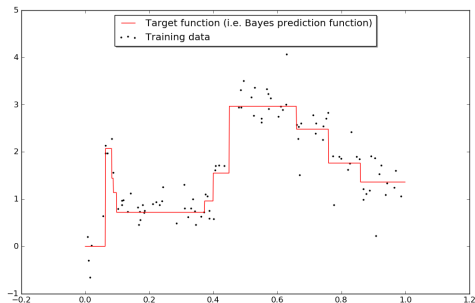
```
from sklearn import metrics
print(metrics.classification_report(twenty_test.target, predicted,
                                     target_names=twenty_test.target_names))
```

	precision	recall	f1-score	support
alt.atheism	0.95	0.81	0.87	319
comp.graphics	0.88	0.97	0.92	389
sci.med	0.94	0.90	0.92	396
soc.religion.christian	0.90	0.95	0.93	398
avg / total	0.92	0.91	0.91	1502

- Key takeaway: need feature map  $\phi$  when dealing with inputs not natively in  $\mathbf{R}^d$ .

# Motivation

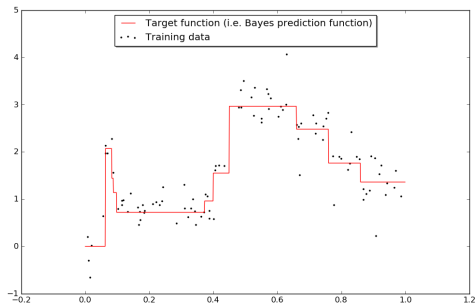
- Two motivations for thinking about feature extraction:
  - Motive 2 – Improving performance. Think about HW2.



- What was our feature map  $\phi(x)$ ?  $\phi(x) \in \mathbf{R}^k$  for what  $k$ ?

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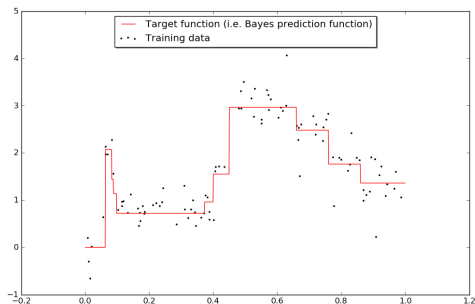
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- What was our feature map  $\phi(x)$ ?  $\phi(x) \in \mathbf{R}^k$  for what  $k$ ?
- $\phi(x) = [\mathbb{1}(x \geq \frac{1}{400}), \dots, \mathbb{1}(x \geq \frac{399}{400})]$

# Motivation

- Two motivations for thinking about feature extraction:
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- Why did we use this feature map instead of just learning a prediction function  $y \sim x$ ?

- Two motivations for thinking about feature extraction:
  - Motive 2 – Improving performance. Toy Example:

`Boston House Prices dataset`

`=====`

`Notes`

`-----`

`Data Set Characteristics:`

`:Number of Instances: 506`

`:Number of Attributes: 13 numeric/categorical predictive`

`:Median Value (attribute 14) is usually the target`

- Two motivations for thinking about feature extraction:
  - Motive 2 – Improving performance. Toy Example:

```
from sklearn.linear_model import ElasticNetCV
```

```
en = ElasticNetCV(cv = 5)
```

```
en.fit(np.log(train_X[['LSTAT']]), train_y)  
en.score(np.log(test_X[['LSTAT']]), test_y)
```

```
0.74651286928253746
```

```
en.fit(train_X[['LSTAT']], train_y)  
en.score(test_X[['LSTAT']], test_y)
```

```
0.57894475666257272
```

# Motivation

- We'll be looking at regression examples throughout this lab.
- Using Elastic Net in sklearn, the default score method returns the coefficient of determination  $R^2$  of the prediction.
- Recall:

- The **total sum of squares** (proportional to the **variance** of the data):

$$SS_{\text{tot}} = \sum_i (y_i - \bar{y})^2,$$

- The regression sum of squares, also called the **explained sum of squares**:

$$SS_{\text{reg}} = \sum_i (f_i - \bar{y})^2,$$

- The sum of squares of residuals, also called the **residual sum of squares**:

$$SS_{\text{res}} = \sum_i (y_i - f_i)^2 = \sum_i e_i^2$$

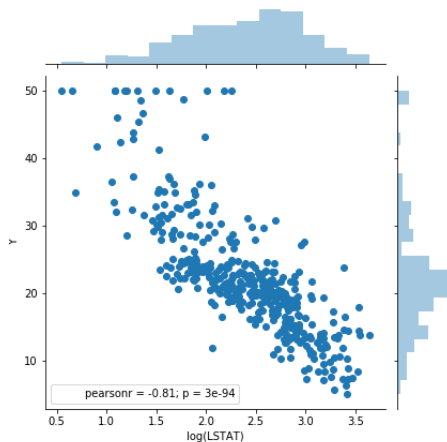
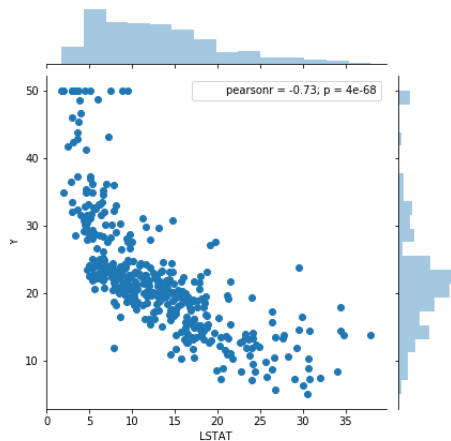
The most general definition of the coefficient of determination is

$$R^2 \equiv 1 - \frac{SS_{\text{res}}}{SS_{\text{tot}}}.$$



# Motivation

- Key idea: instead of using more flexible (i.e. non-linear) models, build better features.



## Handling Nonlinearity with Linear Methods

---

## Example Task: Predicting Health

- General Philosophy: Extract every feature that might be relevant

---

From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.

## Example Task: Predicting Health

- General Philosophy: Extract every feature that might be relevant
- Features for medical diagnosis
  - height
  - weight
  - body temperature
  - blood pressure
  - etc...

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# Issues for Linear Predictors

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- Three types of nonlinearities can cause problems:

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# Issues for Linear Predictors

- For linear predictors, it's important **how** features are added
- Three types of nonlinearities can cause problems:
  - ① Non-monotonicity
  - ② Saturation
  - ③ Interactions between features

## Non-monotonicity: The Issue

- Feature Map:  $\phi(x) = [1, \text{temperature}(x)]$



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- Action: Predict health score  $y \in \mathbf{R}$  (positive is good)
- Hypothesis Space  $\mathcal{F} = \{\text{affine functions of temperature}\}$
- Issue:
  - Health is not an affine function of temperature.
- Affine function can either say
  - Very high is bad and very low is good, or
  - Very low is bad and very high is good,
  - But here, both extremes are bad.

## Non-monotonicity: Solution 1

- Transform the input:

$$\phi(x) = \left[ 1, \{\text{temperature}(x) - 37\}^2 \right],$$

where 37 is “normal” temperature in Celsius.

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- Transform the input:

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where 37 is “normal” temperature in Celsius.

- Ok, but this requires domain knowledge
  - Do we really need that?

## Non-monotonicity: Solution 2

- Think less, put in more:

$$\phi(x) = \left[ 1, \text{temperature}(x), \{\text{temperature}(x)\}^2 \right].$$



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- **More expressive** than Solution 1.

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- **More expressive** than Solution 1.

### General Rule

Features should be simple building blocks that can be pieced together.

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- We expect a monotonic relationship between  $N(x)$  and relevance, but...

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- Relevance score reflects confidence in relevance prediction.
- Are we 10 times more confident if  $N(x) = 1000$  vs  $N(x) = 100$ ?

# Saturation: The Issue

## Is relevance linear in $N(x)$ ?

- Relevance score reflects confidence in relevance prediction.
- Are we 10 times more confident if  $N(x) = 1000$  vs  $N(x) = 100$ ?
- Bigger is better... but not that much better.



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- Smooth nonlinear transformation:

$$\phi(x) = [1, \log\{1 + N(x)\}]$$

- $\log(\cdot)$  good for values with large dynamic ranges
- *Does it matter what base we use in the log?*

## Saturation: Solve by discretization

- Discretization (a discontinuous transformation):

$$\phi(x) = (1(5 \leq N(x) < 10), 1(10 \leq N(x) < 100), 1(100 \leq N(x)))$$

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- Why? Hint: What's the effect of regularization on the parameters for rare buckets?
- Small buckets allow quite flexible relationship

## Interactions: The Issue

- Input: Patient information  $x$
- Action: Health score  $y \in \mathbf{R}$  (higher is better)
- Feature Map

$$\phi(x) = [\text{height}(x), \text{weight}(x)]$$



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$$\phi(x) = [\text{height}(x), \text{weight}(x)]$$

- Issue: It's the weight **relative** to the height that's important.
- Impossible to get with these features and a linear classifier.
- Need some **interaction** between height and weight.

# Interactions: Approach 1

- Google “ideal weight from height”

---

From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.

## Interactions: Approach 1

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$$f(x) = (52 + 1.9 [h(x) - 60] - w(x))^2$$

- WolframAlpha for complicated Mathematics:

$$f(x) = 3.61h(x)^2 - 3.8h(x)w(x) - 235.6h(x) + w(x)^2 + 124w(x) + 3844$$

## Interactions: Approach 2

- Just include all second order features:

$$\phi(x) = \left[ 1, h(x), w(x), h(x)^2, w(x)^2, \underbrace{h(x)w(x)}_{\text{cross term}} \right]$$

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### General Principle

Simpler building blocks replace a single “smart” feature.

# Predicate Features and Interaction Terms

## Definition

A **predicate** on the input space  $\mathcal{X}$  is a function  $P : \mathcal{X} \rightarrow \{\text{True}, \text{False}\}$ .

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- Many features take this form:
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  - $x \mapsto d(x) = 1$  (subject is driving)
- For predicates, interaction terms correspond to **AND** conjunctions:
  - $x \mapsto s(x)d(x) = 1$  (subject is sleeping AND subject is driving)

## So What's Linear?

- Non-linear feature map  $\phi : \mathcal{X} \rightarrow \mathbf{R}^d$
- Hypothesis space:

$$\mathcal{F} = \{f(x) = w^T \phi(x) \mid w \in \mathbf{R}^d\}.$$

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## Key Idea: Non-Linearity

- Nonlinear  $f(x)$  is important for **expressivity**.



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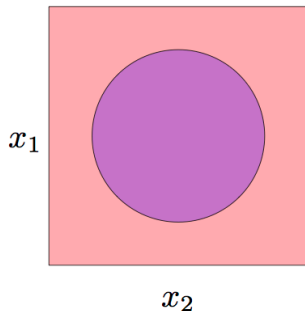
## Key Idea: Non-Linearity

- Nonlinear  $f(x)$  is important for **expressivity**.
- $f(x)$  linear in  $w$  and  $\phi(x)$ : makes finding  $f^*(x)$  much easier

---

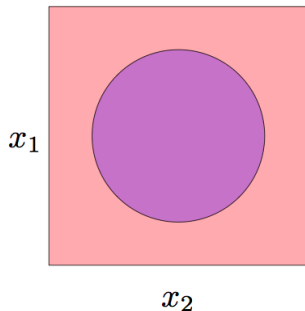
From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.

## Geometric Example: Two class problem, nonlinear boundary



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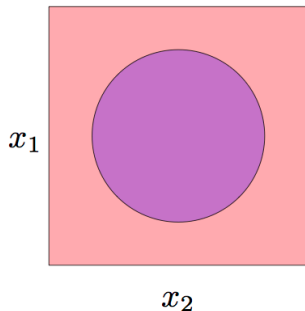


- With linear feature map  $\phi(x) = (x_1, x_2)$  and linear models, no hope
- With appropriate nonlinearity  $\phi(x) = (x_1, x_2, x_1^2 + x_2^2)$ , piece of cake.

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- Video: <http://youtu.be/3liCbRZPrZA>

From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.

# Expressivity of Hypothesis Space

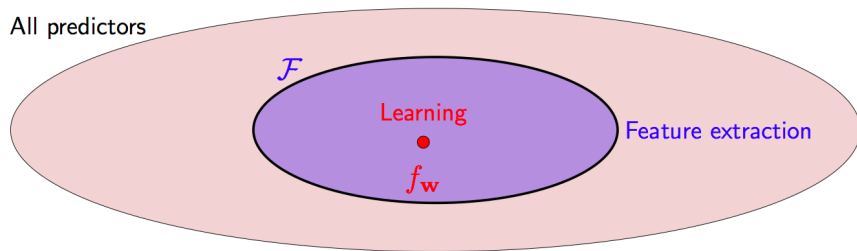
- Consider a linear hypothesis space with a feature map  $\phi : \mathcal{X} \rightarrow \mathbf{R}^d$ :

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# Expressivity of Hypothesis Space

- Consider a linear hypothesis space with a feature map  $\phi : \mathcal{X} \rightarrow \mathbb{R}^d$ :

$$\mathcal{F} = \{f(x) = w^T \phi(x)\}$$



**Question: does  $\mathcal{F}$  contain a good predictor?**

We can grow the linear hypothesis space  $\mathcal{F}$  by adding more features.

From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.

## Example 1: Boston housing and Abalone

---

# Boston Housing

- Let's revisit the Boston housing dataset from the start of lab.
- We're going to be predicting the median house values in Boston suburbs.
- We'll build our feature map using sklearn and sklearn\_pandas

```
import pandas as pd
import numpy as np

from sklearn.base import TransformerMixin
from sklearn.preprocessing import OneHotEncoder, LabelEncoder
from sklearn_pandas import DataFrameMapper
from sklearn.pipeline import Pipeline
from sklearn.linear_model import ElasticNetCV
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import PolynomialFeatures

import seaborn as sns
import matplotlib.pyplot as plt
%matplotlib inline
```



# Boston Housing

- Set up data:

```
from sklearn.datasets import load_boston
```

```
data = load_boston()
df = data.data
cols = ['CRIM', 'ZN', 'INDUS', 'CHAS', 'NOX',
        'RM', 'AGE', 'DIS', 'RAD', 'TAX',
        'PTRATIO', 'B', 'LSTAT']
df = pd.DataFrame(df, columns=cols)
train_X, test_X, train_y, test_y = train_test_split(df, data.target,
                                                    test_size=0.2,
                                                    random_state = 2142018)
```

```
categorical = ['CHAS', 'RAD']
numeric = ['CRIM', 'ZN', 'INDUS', 'NOX', 'RM',
           'AGE', 'DIS', 'TAX', 'PTRATIO', 'B',
           'LSTAT']
```

- Feature map 1– looking at the code, what is the feature map  $\phi_1$ ?

```
mapper = DataFrameMapper(  
    [(col, None) for col in numeric] + \  
    [(col, OneHotStrings()) for col in categorical])  
  
pipe = Pipeline([  
    ('mapper', mapper),  
    ('clf', ElasticNetCV(cv=10,  
                        l1_ratio=[.5, .7, .9, .95, .99, 1],  
                        normalize=True))  
])  
  
pipe.fit(train_X, train_y)  
  
print('Train score: ', pipe.score(train_X, train_y))  
print('Test score: ', pipe.score(test_X, test_y))
```

Train score: 0.762945577283

Test score: 0.645054949322

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- $\phi_1(X)$  dummy encodes categoricals and passes numeric features untouched.

- Feature map 2— looking at the code, what is the feature map  $\phi_2$ ?

```
mapper2 = DataFrameMapper(  
    [(numeric, PolynomialFeatures(degree=2))] + \  
    [(col, OneHotStrings()) for col in categorical])  
  
pipe2 = Pipeline([  
    ('mapper', mapper2),  
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pipe2.fit(train_X, train_y)  
  
print('Train score: ', pipe2.score(train_X, train_y))  
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```

Train score: 0.879364391327

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Train score:  0.879364391327  
Test score:   0.816386882677
```

- $\phi_2(X)$  dummy encodes categoricals and maps numeric features to polynomial features of degree  $d \leq 2$ .

- Here we are using the abalone dataset – predicting the number of rings on an abalone (a kind of shellfish).
- Set up data:

```
df = pd.read_csv('http://archive.ics.uci.edu/ml/machine-learning-databases/' +
                 'abalone/abalone.data',
                 header=None)

df = df.rename(columns={
    0:'sex', 1:'length', 2:'diameter', 3:'height',
    4:'whole_weight', 5:'shucked_weight', 6:'viscera_weight',
    7:'shell_weight', 8:'rings'
})

categorical = ['sex']

numeric = ['length', 'diameter', 'height',
           'whole_weight', 'shucked_weight',
           'shell_weight']

train_X, test_X, train_y, test_y = train_test_split(df.drop('rings', axis=1),
                                                    df['rings'],
                                                    random_state=42)
```

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```
mapper = DataFrameMapper(  
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```

```
Train score:  0.528393673016  
Test score:  0.534127249172
```

- $\phi_2(X)$  dummy encodes categorical and maps numeric features to polynomial features of degree  $d \leq 2$ .

```
poly_mapper = DataFrameMapper(  
    [(numeric, PolynomialFeatures(degree=2))] + \  
    [(col, OneHotStrings()) for col in categorical])  
  
pipe_poly = Pipeline([  
    ('mapper', poly_mapper),  
    ('clf', ElasticNetCV(cv=10,  
                        l1_ratio=[.1, .5, .7, .9, .95, .99, 1],  
                        normalize=True))  
)  
  
pipe_poly.fit(train_X, train_y)  
  
print('Train score: ', pipe_poly.score(train_X, train_y))  
print('Test score: ', pipe_poly.score(test_X, test_y))
```

```
Train score:  0.559442492704  
Test score:  0.554318625419
```



## Comparing performance

- Why did the performance improve much more for the Boston Housing dataset versus the Abalone dataset when we used map 2?

## Comparing performance

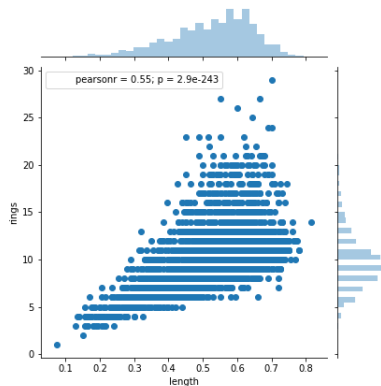
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- Why did the performance improve much more for the Boston Housing dataset versus the Abalone dataset when we used map 2?
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- If  $E[Y|X]$  is linear in  $\phi_1(X)$ , will we improve performance using  $\phi_2(X)$ ?

## Comparing performance

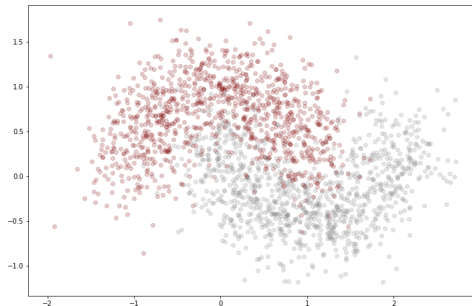
- Why did the performance improve much more for the Boston Housing dataset versus the Abalone dataset when we used map 2?
- What is the Bayes prediction function for square loss?
- If  $E[Y|X]$  is linear in  $\phi_1(X)$ , will we improve performance using  $\phi_2(X)$ ?
- Do we typically know in advance the structure of  $E[Y|X]$ ?



## Example 2: Two moons data

---

## Two moons setup

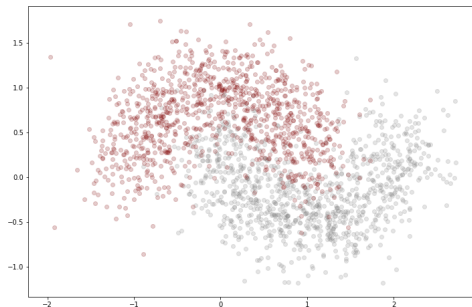


- What feature maps might be helpful for this problem?

---

From Alice Zheng, Amanda Casari, *Feature Engineering for Machine Learning*

## Two moons setup



- What feature maps might be helpful for this problem?
- We'll try binning data instances using k-means (and for fun random tree embeddings) – let's look at the transformers (*in notebook*).

From Alice Zheng, Amanda Casari, *Feature Engineering for Machine Learning*

## Two moons setup

- Here's the pipeline. First, notice the sklearn class `FeatureUnion`, which let's us easily apply multiple feature maps over an input array.
- What is the feature map  $\phi(X)$ ? What will `transformed.shape[1]` equal?

```
pipe = Pipeline([
    ('feats', FeatureUnion([
        ('kmeans', KMeansFeaturizer(k=100, random_state=2052018)),
        ('ID', IdentityFeaturizer())
    ])),
    ('clf', LogisticRegressionCV())
])

pipe.fit(training_data, training_labels)

# Just to make sure it's clear what this does:
transformed = pipe.named_steps['feats'].transform(training_data)

transformed.shape
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- $\phi(X) = [X_1, X_2, \mathbb{1}[(X_1, X_2) \text{ binned to centroid 1}], \dots, \mathbb{1}[(X_1, X_2) \text{ binned to centroid 100}]]$

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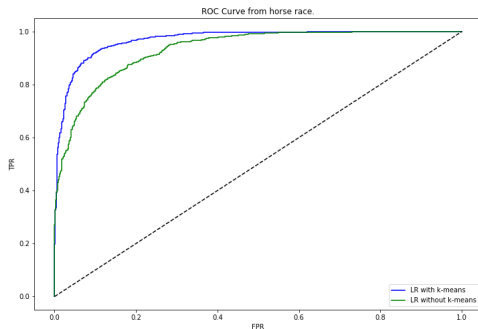
# Just to make sure it's clear what this does:
transformed = pipe.named_steps['feats'].transform(training_data)

transformed.shape

(2000, 102)
```

## Two moons feature map

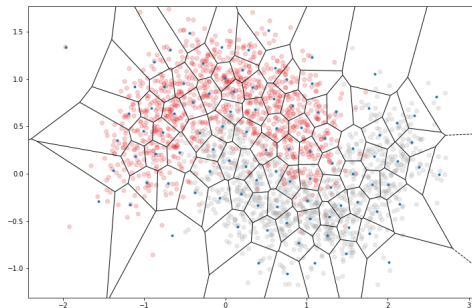
- Let's fit this pipe, and compare to a baseline logistic regression over just  $\phi_I(X) = X$ .



- We see performance improve.

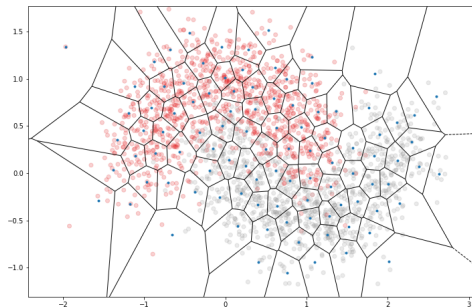
## Two moons feature map

- Here's the voronoi diagram after fitting the KMeansFeaturizer (fit in `pipe.fit` call).



- Intuitively, why did this improve performance?

## Two moons feature map



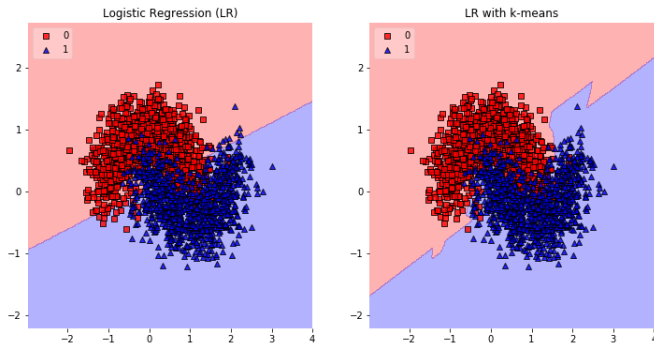
- Think back to the 1D discretization discussed earlier – which map is this analogous to?

$$\phi_2(x) = (1(5 \leq N(x) < 10), 1(10 \leq N(x) < 100), 1(100 \leq N(x)))$$

$$\phi_1(x) = (1(5 \leq N(x)), 1(10 \leq N(x)), 1(100 \leq N(x)))$$

## Two moons feature map

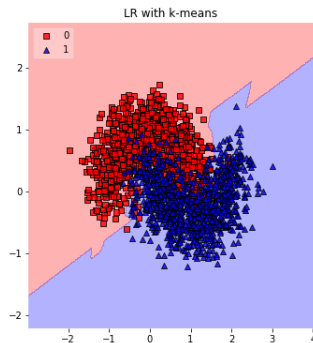
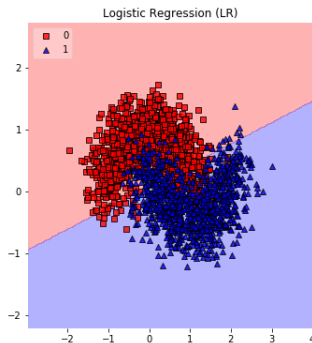
- Here's a comparison of decision boundaries (note made using `mlexend`).



- What's with the plotted decision boundaries? I thought logistic regression was linear?

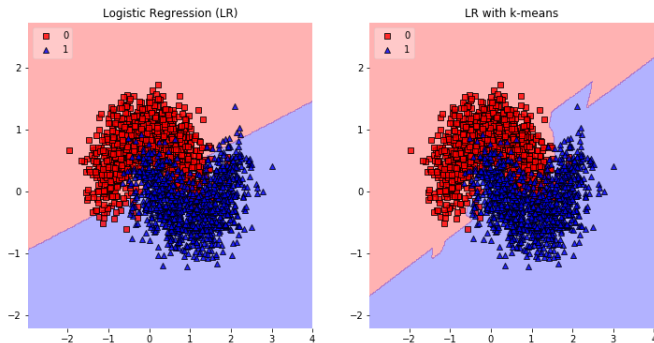
## Two moons feature map

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## Two moons feature map

- What's with the plotted decision boundaries? I thought logistic regression was linear?



- Both decision boundaries are affine, but with k-means embedding it's affine in  $\mathbf{R}^{102}$ .



## Learning Objectives

- Understand where a *feature map* sits in a machine learning pipeline.
- Understand that featurization/feature mapping is inherently required to allow predictors to ingest many types of data.
- Understand how feature extraction can be used to extend the power of linear methods.
- Build pipelines with expanded feature spaces using the sklearn ecosystem.