# Hard-margin SVM

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### Problem setup

Given a set of linearly separable training data, how can one find a good separator? What do we expect from a good separator?

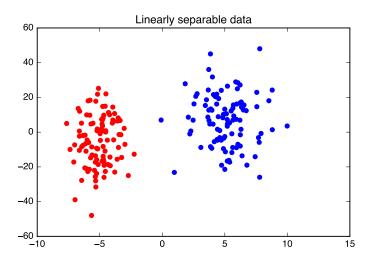
- ... that it actually separates the training points
- ... that it generalizes well

Let  $\{x^i, y^i\}_{i=1}^N \in \mathcal{D}$  be the training data, where  $x^i \in \mathbb{R} \in \mathbb{R}$  and  $y^i$  is either +1 or -1. What does it mean that the data is linearly separable?

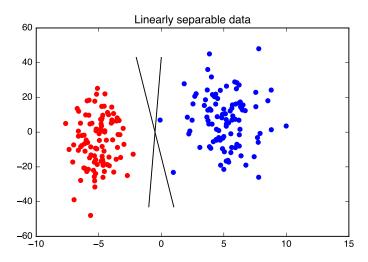
- ... that there is a hyperplane that separates the two clusters
- ... that there is possibly a lot of such hyperplanes

How to choose the best one?

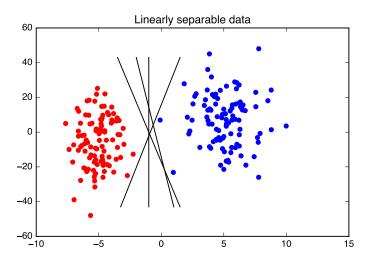
# Example



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# Hyperplane parametrization

Simplest case of real variables, y = mx + b draws a line with slope m that intersects y-axis at the point b:

- Rewrite the above equation:  $(m, -1) \cdot (x, y) + b = 0$
- A better notation can be:  $(w_1, w_2) \cdot (x_1, x_2) + b = 0$
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Generalize this to higher dimensions, for  $w, x \in \mathbb{R}^n$  and  $b \in \mathbb{R}$ :

- $\ell(x) = w \cdot x + b$  where  $L = \{x : \ell(x) = 0\}$  describes a hyperplane.
- w is orthogonal to L (check  $w \cdot (v v') = 0$  for  $v, v' \in L$ )
- What should  $\ell$  assign to the two clusters?

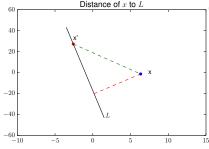
$$\ell(x) \text{ is } \begin{cases} > 0 \text{ if } x \in \text{Blue: } +1 \text{ class} \\ < 0 \text{ if } x \in \text{Red: } -1 \text{ class} \end{cases}$$

• Note:  $y^i \ell(x^i) > 0$  if  $\ell(x) = 0$  separates the data perfectly!

### Distance of a point to a line

For a point  $x \in \mathbb{R}^n$ , how far is x to a given hyperplane L?

- Denote the distance of a point x to L by d(x, L).
- Pick a point on the L, say x', then d(x, L) is the projection of (x x') onto the normal vector w of L.



Crash course on projections:

- Linear transformations, P, such that  $P^2 = P$ .
- Unique decomposition into image and kernel of P
- Orthogonal projections:  $P = P^T$
- Vector projection:  $P_w(v) = \frac{v \cdot w}{||w||^2} w$

### Hard-margin SVM

Given two linearly separable clusters,  $\mathcal{C}_1$  and  $\mathcal{C}_2$ , and a hyperplane  $L=\{x:\ell(x)=w\cdot x+b=0\}$  with ||w||=1, suppose  $x^{1,L}\in\mathcal{C}_1$  and  $x^{2,L}\in\mathcal{C}_2$  are the closest points to L.

- For any  $i, y^i \ell(x^i) \ge \min\{d(x^{1,L}, L), d(x^{2,L}, L)\} > 0$
- **GOAL:** Maximize the *margin* around *L*!
- Since data is linearly separable, the maximizer will be on the set where  $d(x^{1,L}, L) = d(x^{2,L}, L)$ , let's call this M. (note that M depends on data points and the line)

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#### Procedure:

$$\max\{M: b \in \mathbb{R}, w \in \mathbb{R}^n, ||w|| = 1\}$$
 (1)

subject to 
$$y^i(w \cdot x^i + b) \ge M$$
 (2)

### Equivalent formulation

For any pair of (w,b) we can calculate M and then considering the new pair  $(w',b')=(\frac{w}{M},\frac{b}{M})$  we get  $y^i(\frac{w}{M}\cdot x^i+\frac{b}{M})\geq 1$ . Therefore, maximizing M can be rephrased as minimizing ||w'||.

#### **Equivalent procedure:**

$$\min\{||w'||:b'\in\mathbb{R},w'\in\mathbb{R}^n\}\tag{3}$$

subject to 
$$y^i(w' \cdot x^i + b') \ge 1$$
 (4)

- Note that:  $||w'|| = ||\frac{w}{M}|| = \frac{||w||}{M} = \frac{1}{M}$
- This is a convex optimization problem: quadratic criterion, linear inequality constraints.
- But, what if the clusters overlap?

# Overlapping clusters

For all data points let  $t^i > 0$  be the slack variables that represent how wrong the prediction is. We will modify the first formulation first:

#### Recall the procedure:

$$\max\{M: b \in \mathbb{R}, w \in \mathbb{R}^n, ||w|| = 1\}$$
 (5)

subject to 
$$y^i(w \cdot x^i + b) \ge M$$
 (6)

Let's modify the second equation to allow each point to have a little more room:

#### Modified procedure:

$$\max\{M:b\in\mathbb{R},w\in\mathbb{R}^n,||w||=1\}\tag{7}$$

subject to 
$$y^i(w \cdot x^i + b) \ge M(1 - t^i)$$
 (8)

# Overlapping clusters

Now let's find the equivalent version of the modified problem:

#### Recall the equivalent procedure:

$$\min\{||w'||:b'\in\mathbb{R},w'\in\mathbb{R}^n\}\tag{9}$$

subject to 
$$y^i(w' \cdot x^i + b') \ge 1$$
 (10)

We give a little room for the points to sneak in the margin:

#### Modified equivalent procedure:

$$\min\{||w'||:b'\in\mathbb{R},w'\in\mathbb{R}^n\}\tag{11}$$

subject to 
$$y^i(w' \cdot x^i + b') \ge 1 - t^i$$
 (12)

How much should we allow points to sneak in? Let's put a bound on this:  $\sum t^i < C$ 

### Final procedure:

$$\min\{\frac{1}{2}||w||^2 + c\sum t^i : w \in \mathbb{R}^n, t^i > 0\}$$
 (13)

subject to 
$$y^i(w \cdot x^i + b) \ge 1 - t^i$$
 (14)

### Separable vs non-separable

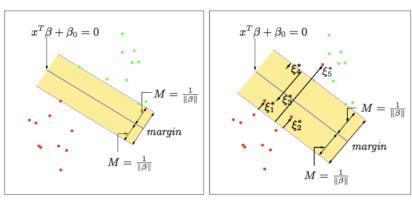


Figure from Hastie's book. Here  $\beta = w$  and  $\beta_0 = b$ .

#### **Exercises**

- Linear regression; Minimizing sum of squares of errors in  $y = X\beta + \epsilon$ : Find  $\beta$  such that  $||y X\beta|| = f(\beta)$  is minimized.
- What's the orthogonal projection of y onto the columns of X?
- What's the connection of the two?
- When is  $X^TX$  not invertible?
- In the overlapping case, what would happen if you modified the constraint by  $y^i(w \cdot x^i b) \ge M t^i$