

SVM and Complementary Slackness

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SVM Review: Primal and Dual Formulations

Support Vector Machine

- Hypothesis space $\mathcal{F} = \{f(x) = w^T x + b \mid w \in \mathbf{R}^d, b \in \mathbf{R}\}$.
- ℓ_2 regularization (Tikhonov style)
- Loss $\ell(m) = \max\{1 - m, 0\} = (1 - m)_+$
- The SVM prediction function is the solution to

$$\min_{w \in \mathbf{R}^d, b \in \mathbf{R}} \frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n \max(0, 1 - y_i [w^T x_i + b]).$$

SVM as a Quadratic Program

- The SVM optimization problem is equivalent to

$$\begin{aligned}
 &\text{minimize} && \frac{1}{2}\|w\|^2 + \frac{c}{n} \sum_{i=1}^n \xi_i \\
 &\text{subject to} && -\xi_i \leq 0 \text{ for } i = 1, \dots, n \\
 &&& (1 - y_i [w^T x_i + b]) - \xi_i \leq 0 \text{ for } i = 1, \dots, n
 \end{aligned}$$

- Differentiable objective function
- $2n$ affine constraints.
- A quadratic program that can be solved by any off-the-shelf QP solver.
- Let's learn more by examining the dual.

SVM Lagrange Multipliers

$$\begin{aligned}
 &\text{minimize} && \frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n \xi_i \\
 &\text{subject to} && -\xi_i \leq 0 \text{ for } i = 1, \dots, n \\
 &&& (1 - y_i [w^T x_i + b]) - \xi_i \leq 0 \text{ for } i = 1, \dots, n
 \end{aligned}$$

Lagrange Multiplier	Constraint
λ_i	$-\xi_i \leq 0$
α_i	$(1 - y_i [w^T x_i + b]) - \xi_i \leq 0$

$$L(w, b, \xi, \alpha, \lambda) = \frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n \xi_i + \sum_{i=1}^n \alpha_i (1 - y_i [w^T x_i + b] - \xi_i) + \sum_{i=1}^n \lambda_i (-\xi_i)$$

SVM Primal and Dual

- Lagrangian:

$$L(w, b, \xi, \alpha, \lambda) = \frac{1}{2} \|w\|^2 + \frac{c}{n} \sum_{i=1}^n \xi_i + \sum_{i=1}^n \alpha_i (1 - y_i [w^T x_i + b] - \xi_i) + \sum_{i=1}^n \lambda_i (-\xi_i)$$

- Primal and dual formulations:

$$p^* = \underbrace{\inf_{w, \xi, b} \sup_{\alpha, \lambda \succeq 0} L(w, b, \xi, \alpha, \lambda)}_{\text{primal objective}} \geq \sup_{\alpha, \lambda \succeq 0} \underbrace{\inf_{w, b, \xi} L(w, b, \xi, \alpha, \lambda)}_{\text{dual objective } g(\alpha, \lambda)} = d^*$$

- Constraints are satisfied by $w = b = 0$ and $\xi_i = 1$ for $i = 1, \dots, n$.
- So we have strong duality by Slater's conditions. That is: $p^* = d^*$.

First Order Conditions (KKT)

- Suppose (w^*, b^*) are primal optimal and $(\xi^*, \alpha^*, \lambda^*)$ are dual optimal.
- By strong duality, $p^* = d^*$, and by “sandwich proof”,

$$p^* = d^* = L(w^*, b^*, \xi^*, \alpha^*, \lambda^*).$$

- Since L is differentiable, we must have first order conditions:

$$\begin{aligned} \nabla_w L(w^*, b^*, \xi^*, \alpha^*, \lambda^*) &= 0 \\ \text{(shown last week)} \iff w^* &= \sum_{i=1}^n \alpha_i^* y_i x_i \end{aligned}$$

- Conclude that w^* is “in the span of the data” – i.e. a linear combination of x_1, \dots, x_n .

The SVM Dual Problem

- We found the SVM dual problem can be written as:

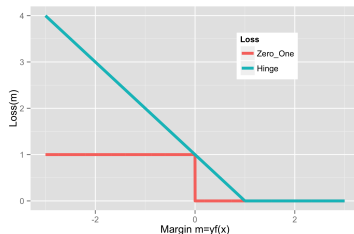
$$\begin{aligned} \sup_{\alpha} \quad & \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i \\ \text{s.t.} \quad & \sum_{i=1}^n \alpha_i y_i = 0 \\ & \alpha_i \in \left[0, \frac{c}{n}\right] \quad i = 1, \dots, n. \end{aligned}$$

- Given solution α^* to dual, primal solution is $w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$.
- Note $\alpha_i^* \in [0, \frac{c}{n}]$. So c controls max weight on each example. (**Robustness!**)

Insights From Complementary Slackness: Margin and Support Vectors

The Margin and Some Terminology

- For notational convenience, define $f^*(x) = x^T w^* + b^*$.
- Margin $yf^*(x)$



- Incorrect classification: $yf^*(x) \leq 0$.
- Margin error: $yf^*(x) < 1$.
- “On the margin”: $yf^*(x) = 1$.
- “Good side of the margin”: $yf^*(x) > 1$.

Support Vectors and The Margin

- Recall “**slack variable**” $\xi_i^* = \max(0, 1 - y_i f^*(x_i))$ is the hinge loss on (x_i, y_i) .
- Suppose $\xi_i^* = 0$.
- Then $y_i f^*(x_i) \geq 1$
 - “on the margin” ($= 1$), or
 - “on the good side” (> 1)

Complementary Slackness Conditions

- Recall our primal constraints and Lagrange multipliers:

Lagrange Multiplier	Constraint
λ_i	$-\xi_i \leq 0$
α_i	$(1 - y_i f(x_i)) - \xi_i \leq 0$

- Recall first order condition $\nabla_{\xi_i} L = 0$ gave us $\lambda_i^* = \frac{c}{n} - \alpha_i^*$.
- By strong duality, we must have **complementary slackness**:

$$\alpha_i^* (1 - y_i f^*(x_i) - \xi_i^*) = 0$$

$$\lambda_i^* \xi_i^* = \left(\frac{c}{n} - \alpha_i^* \right) \xi_i^* = 0$$

Consequences of Complementary Slackness

- By strong duality, we must have **complementary slackness**:

$$\alpha_i^* (1 - y_i f^*(x_i) - \xi_i^*) = 0$$

$$\left(\frac{c}{n} - \alpha_i^* \right) \xi_i^* = 0$$

- If $y_i f^*(x) > 1$ then the margin loss is $\xi_i^* = 0$, and we get $\alpha_i^* = 0$.
- If $y_i f^*(x_i) < 1$ then the margin loss is $\xi_i^* > 0$, so $\alpha_i^* = \frac{c}{n}$.
- If $\alpha_i^* = 0$, then $\xi_i^* = 0$, which implies no loss, so $y_i f^*(x) \geq 1$.
- If $\alpha_i^* \in (0, \frac{c}{n})$, then $\xi_i^* = 0$, which implies $1 - y_i f^*(x_i) = 0$.

Complementary Slackness Results: Summary

$$\begin{aligned}\alpha_i^* = 0 &\implies y_i f^*(x_i) \geq 1 \\ \alpha_i^* \in \left(0, \frac{c}{n}\right) &\implies y_i f^*(x_i) = 1 \\ \alpha_i^* = \frac{c}{n} &\implies y_i f^*(x_i) \leq 1\end{aligned}$$

$$\begin{aligned}y_i f^*(x_i) < 1 &\implies \alpha_i^* = \frac{c}{n} \\ y_i f^*(x_i) = 1 &\implies \alpha_i^* \in \left[0, \frac{c}{n}\right] \\ y_i f^*(x_i) > 1 &\implies \alpha_i^* = 0\end{aligned}$$

Support Vectors

- If α^* is a solution to the dual problem, then primal solution is

$$w^* = \sum_{i=1}^n \alpha_i^* y_i x_i$$

with $\alpha_i^* \in [0, \frac{c}{n}]$.

- The x_i 's corresponding to $\alpha_i^* > 0$ are called **support vectors**.
- Few margin errors or “on the margin” examples \implies **sparsity in input examples**.

Complementary Slackness To Get b^*

The Bias Term: b

- For our SVM primal, the complementary slackness conditions are:

$$\alpha_i^* (1 - y_i [x_i^T w^* + b] - \xi_i^*) = 0 \quad (1)$$

$$\lambda_i^* \xi_i^* = \left(\frac{c}{n} - \alpha_i^* \right) \xi_i^* = 0 \quad (2)$$

- Suppose there's an i such that $\alpha_i^* \in (0, \frac{c}{n})$.
- (2) implies $\xi_i^* = 0$.
- (1) implies

$$\begin{aligned} & y_i [x_i^T w^* + b^*] = 1 \\ \iff & x_i^T w^* + b^* = y_i \text{ (use } y_i \in \{-1, 1\}) \\ \iff & \boxed{b^* = y_i - x_i^T w^*} \end{aligned}$$

The Bias Term: b

- The optimal b is

$$b^* = y_i - x_i^T w^*$$

- We get the same b^* for any choice of i with $\alpha_i^* \in (0, \frac{c}{n})$
 - **With exact calculations!**
- With numerical error, more robust to average over all eligible i 's:

$$b^* = \text{mean} \left\{ y_i - x_i^T w^* \mid \alpha_i^* \in \left(0, \frac{c}{n} \right) \right\}.$$

- If there are no $\alpha_i^* \in (0, \frac{c}{n})$?
 - Then we have a **degenerate SVM training problem**¹ ($w^* = 0$).

¹See Rifkin et al.'s "A Note on Support Vector Machine Degeneracy", an MIT AI Lab Technical Report.

Teaser for Kernelization

Dual Problem: Dependence on x through inner products

- SVM Dual Problem:

$$\begin{aligned} \sup_{\alpha} \quad & \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i \\ \text{s.t.} \quad & \sum_{i=1}^n \alpha_i y_i = 0 \\ & \alpha_i \in \left[0, \frac{C}{n}\right] \quad i = 1, \dots, n. \end{aligned}$$

- Note that all dependence on inputs x_i and x_j is through their inner product: $\langle x_j, x_i \rangle = x_j^T x_i$.
- We can replace $x_j^T x_i$ by any other product...
- This is a “kernelized” objective function.