Features

David S. Rosenberg

Bloomberg ML EDU

October 18, 2017

Learning Objectives

- Understand where a *feature map* sits in a machine learning pipeline.
- Understand how feature extraction can be used to extend the power of linear methods.
- Build pipelines with expanded feature spaces using the sklearn ecosystem.

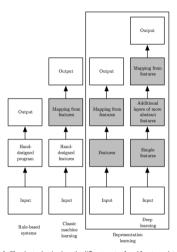


Figure 1.5: Flowcharts showing how the different parts of an AI system relate to each other within different AI disciplines. Shaded boxes indicate components that are able to learn from data.

Feature Extraction

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- But $\mathfrak{X} = \mathbf{R}^d$ for the specific methods we've developed:
 - Ridge regression
 - Lasso regression
 - Linear SVM

Motivation

- Two motivations for thinking about feature extraction:
 - Motive 1 Improving performance.

```
Boston House Prices dataset
Notes
Data Set Characteristics:
    :Number of Instances: 506
    :Number of Attributes: 13 numeric/categorical predictive
    :Median Value (attribute 14) is usually the target
```

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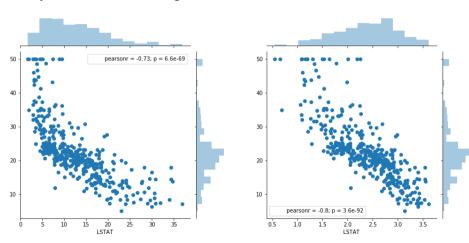
```
from sklearn.linear model import ElasticNetCV
en = ElasticNetCV(cv = 5)
en.fit(np.log(train X[['LSTAT']]), train y)
en.score(np.log(test X[['LSTAT']]), test y)
0.74651286928253746
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en.score(test X[['LSTAT']], test y)
```

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0.57894475666257272

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• Key idea: instead of using more flexible models, use better features.



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- Two motivations for thinking about feature extraction:
 - Motive 2 consuming inputs that are not natively in \mathbb{R}^d examples?
 - Text documents
 - Image files
 - Sound recordings
 - DNA sequences
 - But everything in a computer is a sequence of numbers?
 - The *i*th entry of each sequence should have the same "meaning"
 - All the sequences should have the same length

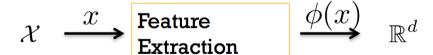
Feature Extraction

Definition

Mapping an input from \mathfrak{X} to a vector in \mathbb{R}^d is called **feature extraction** or **featurization**.

Raw Input

Feature Vector



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arbitrary!

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contains_0 : 1
endsWith_com : 1
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- But this was ad-hoc, and maybe we missed something.
- Could be more systematic?

From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.

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abc@gmail.com endsW ... endsW ...

endsWith_aab : 0 endsWith_aac : 0 ...

endsWith_aaa : 0

endsWith_com : 1

 $endsWith_zzz : 0$

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• With regularization, our methods will not be overwhelmed.

endsWith_aaa:0

Feature Template: One-Hot Encoding

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A one-hot encoding is a set of features (e.g. a feature template) that always has exactly one non-zero value.

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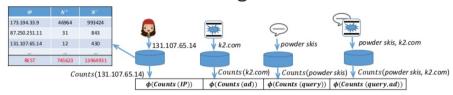
Feature Template: Count-based

- Imagine you are trying to validate a credit card transaction.
- One feature in raw data consumed by pipeline: zip code of transaction.
- There are approximately 43,000 zip codes in the USA.
- What might be a problem with one-hot encoding this feature?

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- What might be a problem with one-hot encoding this feature?
- Even worse think about internet scale problems.

Learning with counts



Features are per-label counts [+odds] [+backoff]

$$\phi = [N^+ \quad N^- \quad \log(N^+) - \log(N^-) \quad \text{IsRest}]$$

- $log(N^+)-log(N^-) = log\frac{p(+)}{p(-)}$: log-odds/Naïve Bayes estimate
- N+, N-: indicators of confidence of the naïve estimate
- IsFromRest: indicator of back-off vs. "real count"

```
fracOfAlpha: 0.85 contains_a : 0 ... contains_@ :1 ...
```

Array representation (good for dense features):

Map representation (good for sparse features):

```
{"fracOfAlpha": 0.85, "contains_0": 1}
```

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- On "example string" we'd get {"endsWith_ing": 1}.
- Has overhead compared to arrays, so much slower for dense features.
- Question: if we have a sparse feature vector, what are the implications for preprocessing?

Handling Nonlinearity with Linear Methods

Example Task: Predicting Health

• General Philosophy: Extract every feature that might be relevant

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- Features for medical diagnosis
 - height
 - weight
 - body temperature
 - blood pressure
 - etc...

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- For linear predictors, it's important how features are added
- Three types of nonlinearities can cause problems:
 - Non-monotonicity
 - Saturation
 - Interactions between features

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- $\bullet \ \ \mbox{Hypothesis Space } {\mathfrak F} \!=\! \{\mbox{affine functions of temperature}\}$
- Issue:
 - Health is not an affine function of temperature.
- Affine function can either say
 - Very high is bad and very low is good, or
 - Very low is bad and very high is good,
 - But here, both extremes are bad.

• Transform the input:

$$\phi(x) = \left[1, \{\text{temperature}(x) - 37\}^2\right],$$

where 37 is "normal" temperature in Celsius.

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- Ok, but this requires domain knowledge
 - Do we really need that?

• Think less, put in more:

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General Rule

Features should be simple building blocks that can be pieced together.

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• We expect a monotonic relationship between N(x) and relevance, but...

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- Are we 10 times more confident if N(x) = 1000 vs N(x) = 100?

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- Bigger is better... but not that much better.

Saturation: Solve with nonlinear transform

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- ullet log (\cdot) good for values with large dynamic ranges
- Does it matter what base we use in the log?

• Discretization (a discontinuous transformation):

$$\phi(x) = (1(5 \leqslant N(x) < 10), 1(10 \leqslant N(x) < 100), 1(100 \leqslant N(x)))$$

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- Why? Hint: What's the effect of regularization the parameters for rare buckets?
- Small buckets allow quite flexible relationship

Interactions: The Issue

- Input: Patient information x
- Action: Health score $y \in \mathbb{R}$ (higher is better)
- Feature Map

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- Impossible to get with these features and a linear classifier.
- Need some interaction between height and weight.

• Google "ideal weight from height"

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- J. D. Robinson's "ideal weight" formula (for a male):

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WolframAlpha for complicated Mathematics:

$$f(x) = 3.61h(x)^2 - 3.8h(x)w(x) - 235.6h(x) + w(x)^2 + 124w(x) + 3844$$

Just include all second order features:

$$\phi(x) = \left[1, h(x), w(x), h(x)^2, w(x)^2, \underbrace{h(x)w(x)}_{\text{cross term}}\right]$$

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General Principle

Simpler building blocks replace a single "smart" feature.

Predicate Features and Interaction Terms

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- Many features take this form:
 - $x \mapsto s(x) = 1$ (subject is sleeping)
 - $x \mapsto d(x) = 1$ (subject is driving)
- For predicates, interaction terms correspond to AND conjunctions:
 - $x \mapsto s(x)d(x) = 1$ (subject is sleeping AND subject is driving)

- Non-linear feature map $\phi: \mathcal{X} \to \mathbf{R}^d$
- Hypothesis space:

$$\mathcal{F} = \left\{ f(x) = w^T \phi(x) \mid w \in \mathbb{R}^d \right\}.$$

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- Linear in $\phi(x)$? Yes.
- Linear in x? No.
 - ullet Linearity not even defined unless ${\mathcal X}$ is a vector space

Key Idea: Non-Linearity

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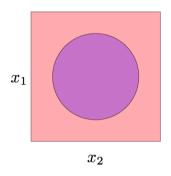
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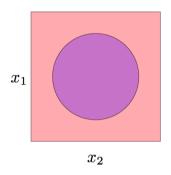
- Nonlinear f(x) is important for **expressivity**.
- f(x) linear in w and $\phi(x)$: makes finding $f^*(x)$ much easier

Geometric Example: Two class problem, nonlinear boundary



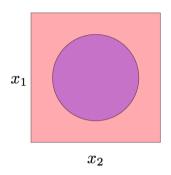
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- Video: http://youtu.be/3liCbRZPrZA

Expressivity of Hypothesis Space

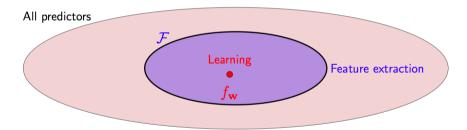
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Question: does \mathcal{F} contain a good predictor?

We can grow the linear hypothesis space $\mathcal F$ by adding more features.