

Signals #4: orthogonal discrete Fourier transform (DFT)

DFT and inverse DFT matrices

DFT is an orthogonal transformation of a signal $\mathbf{x} = [x(0), x(1), \dots, x(N-1)]^T$, specified by a **complex-value DFT synthesis matrix** S ($j = \sqrt{-1}$):

$$S[n, k] = \sqrt{\frac{1}{N}} \exp\left(j \frac{2\pi}{N} kn\right) = \sqrt{\frac{1}{N}} \cos\left(\frac{2\pi}{N} kn\right) + j \sqrt{\frac{1}{N}} \sin\left(\frac{2\pi}{N} kn\right), \quad k, n = 0, 1, 2, \dots, N-1.$$

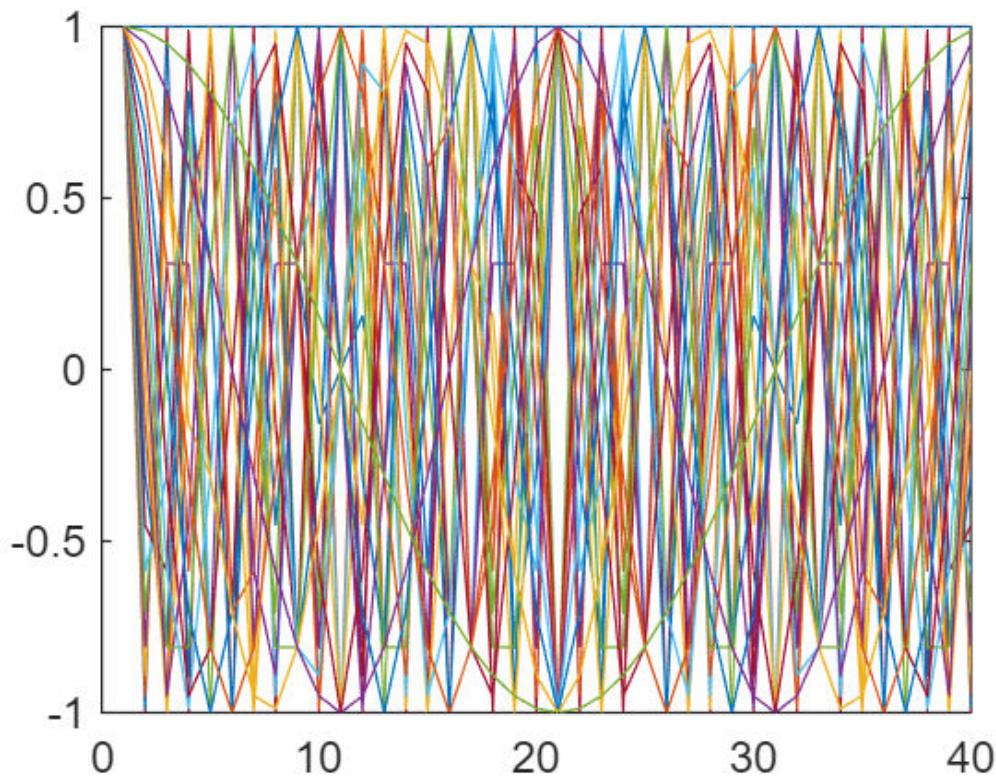
The DCT, DST, Walsh-Hadamard and Haar transformations, defined in laboratory 3, have real-value matrices. The **analysis DFT matrix** is equal $\mathbf{A} = \mathbf{S}^{*T}$ (conjugation, transposition).

Carefully observe shapes of signals present of matrix S columns: in real and imaginary part. Do zooming. Check columns one by one.

```
% DFT transformation matrices
clear all; close all;
N = 40; % matrix dimension
k = (0:N-1); n=(0:N-1); % rows=functions, columns=samples
S = exp(j*2*pi/N*n'*k); % synthesis matrix without scaling
A = S'; % analysis matrix: conjugation + transposition
S*A, % checking matrix orthogonality, N on the diagonal
```

```
ans = 40x40 complex
 40.0000 + 0.0000i -0.0000 - 0.0000i -0.0000 + 0.0000i -0.0000 - 0.0000i ...
 -0.0000 + 0.0000i 40.0000 + 0.0000i -0.0000 - 0.0000i -0.0000 - 0.0000i
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 ⋮
```

```
figure; plot(real(S)); % real(S) - cosines, imag(S) - sines, add viewing columns one by one
```



DFT and inverse DFT transform

The **DFT signal analysis (first) and synthesis (second) equations** (direct and inverse transformations) are defined the same way as in laboratory 3:

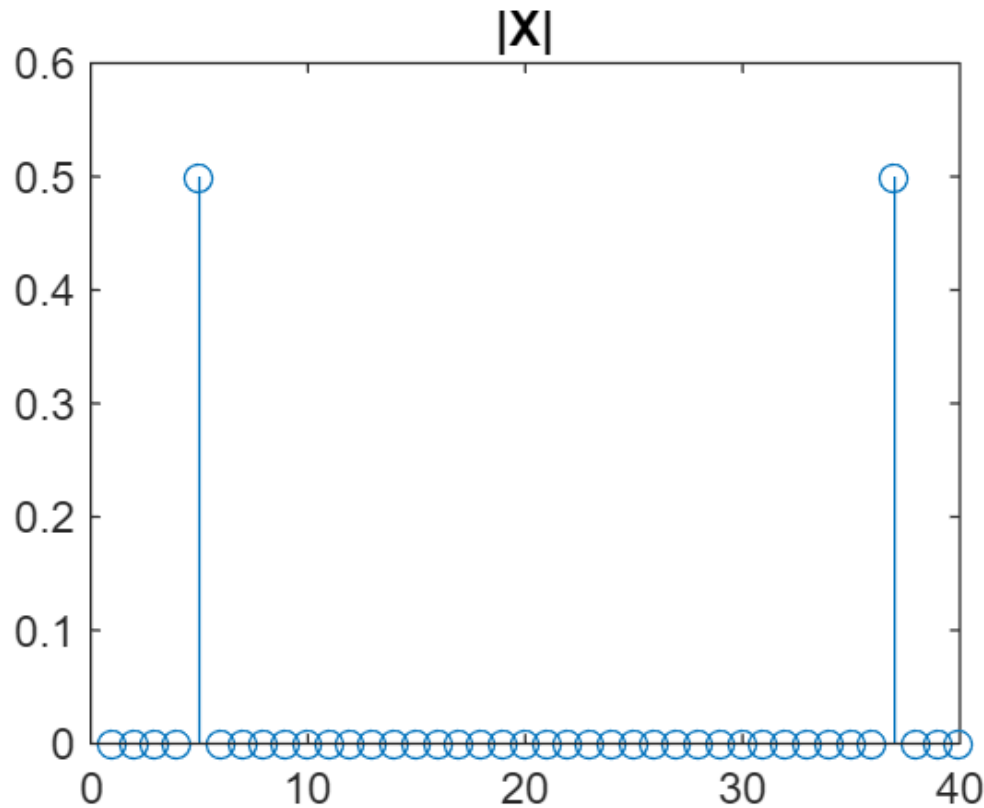
$$\mathbf{X} = \mathbf{S}^* \mathbf{x}, \quad \hat{\mathbf{x}} = \mathbf{S} \mathbf{X}$$

For this reason the output values $\mathbf{y} = [y(0), y(1), \dots, y(N-1)]^T$ are complex-value also: their real part describe an analyzed signal similarity to cosines while the imaginary part - to sines, both for consecutive frequencies:

$$f_k = kf_0, \quad f_0 = \frac{1}{N \cdot dt} = \frac{f_s}{N}, \quad k = 0, 1, 2, \dots, N-1.$$

Add frequency scaling to the horizontal axis. Add more signals, even very strange. Is reconstruction error always very close to zero? Can you deduce from the DFT spectrum what is the signal frequency? When signal has a few different frequency component can you remove one of them?

```
% DFT and inverse DFT: "soup --> finding its receipt --> opt. modification --> boiling a soup"
% x = rand(N,1);           % random signal to be transformed: analysed and reconstructed
x = real(S(:,5));          % choose real, imag, noting
X = (1/N)*A*x;             % DFT-based analysis
%X(5)=0; X(N-5+1)=0;      % optional removing some components
xhat = S*X;               % inverse DFT-based synthesis
stem(abs(X)); title('|X|'); % DFT transformation result
```



```
error = max(abs(x-xhat)), % reconstruction error
```

```
error = 7.8697e-15
```

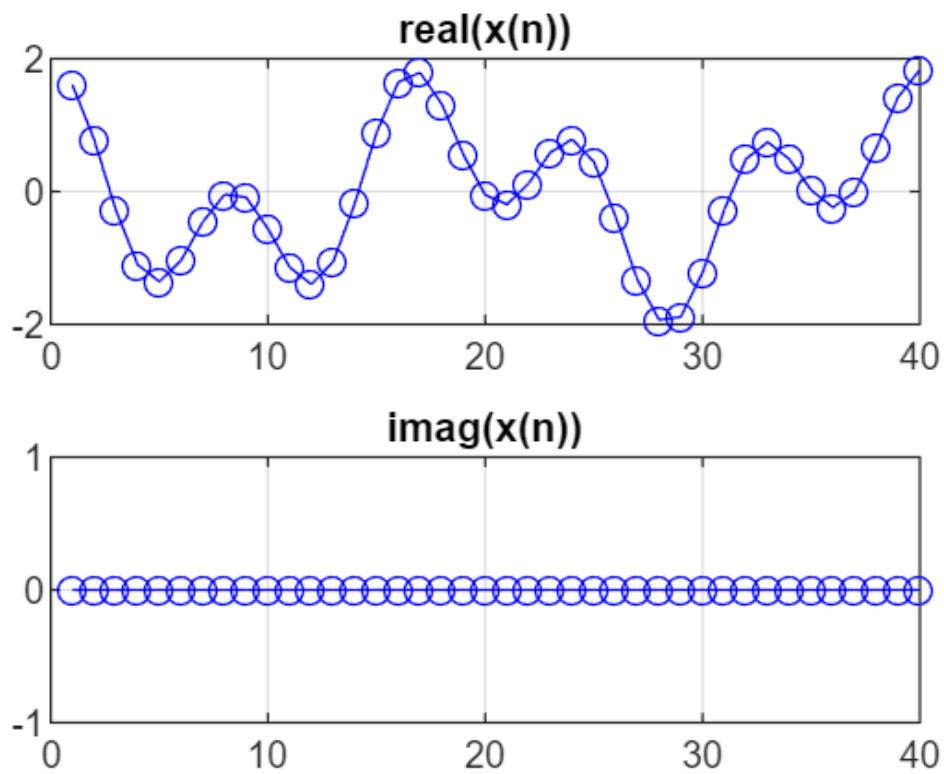
DFT-based signal frequency analysis

Below we have modified the program from laboratory 3, adjusting it to DFT. Choose different input signals, starting from the simplest ones, observe real&imaginary parts of DFT as well as magnitude and angle of its complex-value numbers. Knowing equation of the analyzed signal basic component:

$$x_k(n) = A_k \cos(2\pi f_k t + \varphi_k),$$

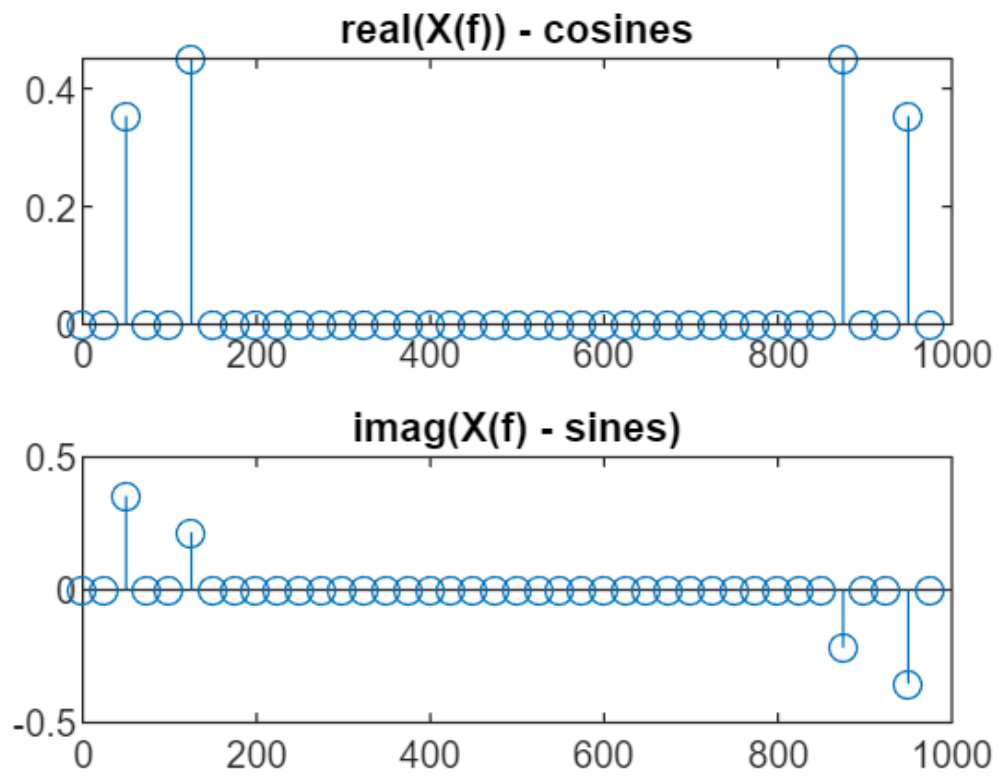
can you "read" values of $\{a_k, f_k, \varphi_k\}$ from the DFT spectrum magnitude $X(f)$ plot? Can you conclude that the result is correct? What is surprising for you?

```
% Signal: first single cosine or sine, with frequency k*f0 or different, then sums of pure signals
fs=1000; dt=1/fs; t=dt*(0:N-1)'; % sampling frequency, sampling period, time moments
T=N*dt; f0=1/T; fk = f0*(0:N-1); % time duration of signal, the lowest frequency, its multiples
x1 = 1*cos(2*pi*(2*f0)*t+pi/4); % signal 1: 2*f0 or 2.5*f0, cos or sin, pi/4 or 0
x2 = 1*cos(2*pi*(5*f0)*t+pi/7); % signal 2: 5*f0 or 5.5*f0, cos or sin, pi/7 or 0
x3 = 0.001*cos(2*pi*(10*f0)*t); % signal 3: 10*f0 or 10.5*f0, cos or sin
x = x1+x2; % choice: x1, x2, x3, x1+x2, x2+x3
figure; % output
subplot(211); plot(real(x),'bo-'); title('real(x(n))'); grid;
subplot(212); plot(imag(x),'bo-'); title('imag(x(n))'); grid;
```

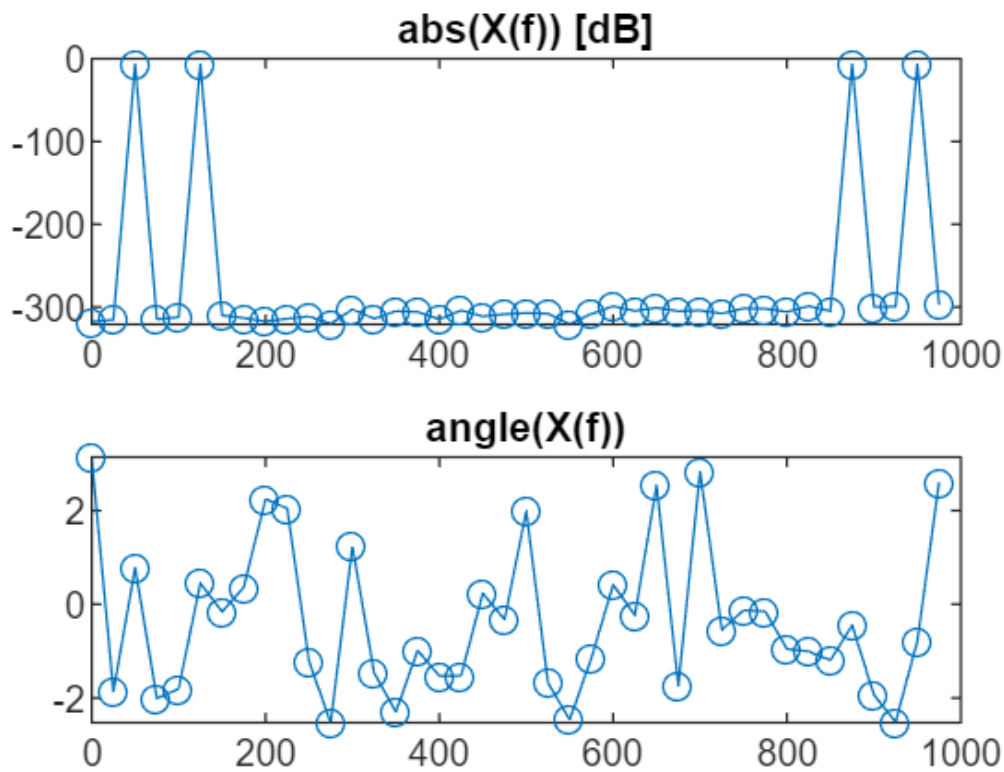


```
% DFT of the signal
X = (1/N)*A*x;
figure;
subplot(211); stem(fk,real(X),'o-'); title('real(X(f)) - cosines');
subplot(212); stem(fk,imag(X),'o-'); title('imag(X(f)) - sines');
```

```
% our code, with Matlab function: X=fft(x.)/N;
% DFT spectrum interpretation
```



```
figure;
subplot(211); plot(fk,20*log10(abs(X)), 'o-'); title('abs(X(f)) [dB]');
subplot(212); plot(fk,angle(X), 'o-'); title('angle(X(f))')
```



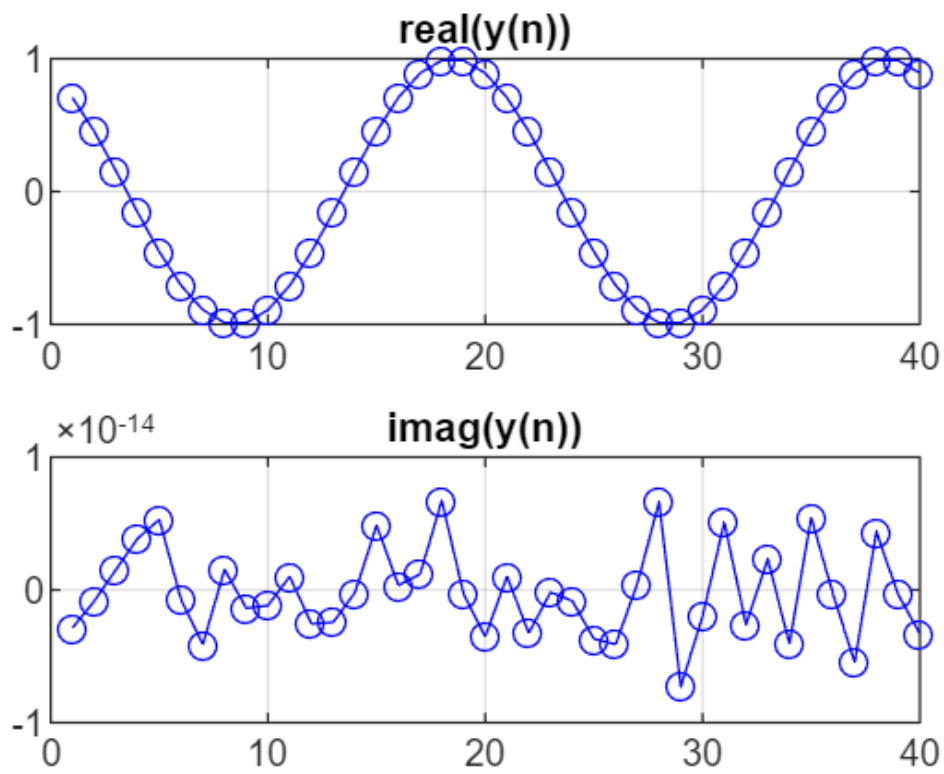
DFT-based signal filtration

When we are modifying DFT spectrum and performing inverse DFT, we are synthesizing signal having some components removed, i.e. we perform signal filtration in DFT spectrum domain (frequency domain) .

Observe that component no 5 is removed from the signal. Generate different multi-component signals. Remove some components. Remove some frequencies from your own speech signal (first record the speech).

```
% DFT spectrum modification
X(1:5)=0; X(N-5+1)=0; % removing signal x2 with freq. 5*f0

% Inverse DFT - signal synthesis
y = S*X; % signal reconstruction, with Matlab function: y=N*ifft(X);
figure; % output
subplot(211); plot(real(y),'bo-'); title('real(y(n))'); grid;
subplot(212); plot(imag(y),'bo-'); title('imag(y(n))'); grid;
```



```
error = max(abs(x-real(y))),      % signal reconstruction error
```

```
error = 0.9439
```