

Project 02 Formulas

First of all to compute shift in coordinates

use. $S = v_0 t + \frac{at^2}{2}$

Formula for acc.

acc.

$$M_1 a_1 = -M_3 a_1 - M_2 a_2 + \mu_2 M_2 g - \mu_1 (M_2 a_2 + \mu_2 g)$$

$$a_1 (M_1 + M_3) = -M_2 a_2 + \mu_2 M_2 g - \mu_1 M_1 g + \mu_1 M_2 a_2 + \mu_1 \mu_2 g$$

$$a_1 = \frac{(-M_2 a_2 + \mu_2 M_2 g - \mu_1 M_1 g - \mu_1 M_2 a_2 + \mu_1 \mu_2 M_2 g)}{(M_1 + M_3)}$$

also know that

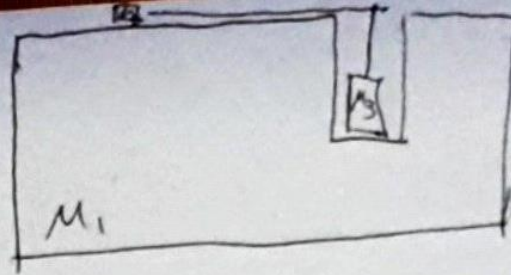
$$a_2 = a_3$$

$$M_2 a_2 + \mu_2 M_2 g - M_3 g + 2\mu_3 F = M_3 (-M_2 a_2 + \mu_2 M_2 g - \mu_1 M_1 g + \mu_1 M_2 a_2 + \mu_1 \mu_2 M_2 g - \mu_1 a_2 - \mu_3 a_2) / (M_1 + M_3)$$

$$M_3 (-M_2 a_2 + \mu_2 M_2 g - \mu_1 M_1 g + \mu_1 M_2 a_2 + \mu_1 \mu_2 M_2 g - \mu_1 a_2 - \mu_3 a_2) \neq (M_1 + M_3) (M_2 a_2 + \mu_2 M_2 g - M_3 g + 2\mu_3 F)$$

$$a_2 = \frac{(1 - M_1 + M_3) (\mu_2 M_2 g - M_3 g + 2\mu_3 F) + M_3 (\mu_2 M_2 g - \mu_1 M_1 g + \mu_1 \mu_2 M_2 g)}{M_2 (M_1 + M_3) - M_3 (-M_2 + \mu_1 M_2 - M_1 - M_3)}$$

Force Diagram.



F_{f1}
 F_{f2} friction
 F_{f3}

invert axis for
 better understanding

