



Multi-scale/Multi-resolution Kronecker Compressive Imaging

*Idea Presentation
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Motivation

- Image prior improve CS performance [4, 5, 6]
 - Most focus to improve CS reconstruction: time, image quality
- CS is universal sampling - all sample are equally important [7]
 - Not for image/video [8]: HVS is more sensitive to low frequency
 - Multi-scale sampling is proof as optimal sampling [9],
- Recovery complexity direct proportional to spatial resolution [10]
 - Multi-resolution sensing is a solution [10], [11], [12]

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[6] T. N. Canh et al., "Detail-preserving compressive sensing recovery based on cartoon texture image decomposition," in *IEEE Inter. Conf. Image Process. (ICIP)*, 2014.

[7] M. A. Davenport, J. N. Laska, P. T. Boufounos, and R. G. Baraniuk, "A simple proof that random matrices are democratic," Available at Arxiv.org (arXiv:0911.0736v1), 2009.

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[10] T. Goldstein et al., "The STONE transform: multi-resolution image enhancement and real-time compressive video," *Arxiv.org*, 2013

[11] A. Sankaranarayanan, C. Studer, and R. Baraniuk, "CS-MUVI: Video compressive sensing for spatial-multiplexing cameras," in *IEEE Inter. Conf. Computational Photography (ICCP)*, pp. 1-10, 2012.

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Related Work

- MH[16]: different substrate at each wavelet decomposition
 - Costly assumption: wavelet coefficient is available at the encoder
 - No-longer block-based sensing: wavelet transform is frame based
 - Lost some level of details

Subrate 0.1



Original



MH-MS-SPL



Our method

Proposed Sensing Matrix

- Block-based Kronecker CS

$$\Phi_K^i = \begin{bmatrix} \Phi_0^i & 0 & \dots & 0 \\ 0 & \Phi_1^i & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \Phi_K^i \end{bmatrix}, i = 1, 2$$

- Separatable Wavelet at level k

$$F_k = \mathcal{W}_K^n F(\mathcal{W}_K^n)^T$$

$$\mathcal{W}_K^n = \hat{\mathcal{W}}_K^n \hat{\mathcal{W}}_{K-1}^n \dots \hat{\mathcal{W}}_1^n = \bigcup_{j=1}^K \hat{\mathcal{W}}_i^n;$$

$$\hat{\mathcal{W}}_i^n = \text{blkdiag}(\hat{\mathcal{W}}_{i-1}^{n/2}, I^{n/2}), i = 1, \dots, K$$

$\mathcal{W}^{n,L}, \mathcal{W}^{n,H} \in \mathbb{R}^{(n/2) \times n}$: low pass & high pass filter

- KCS measurement

$$\begin{aligned} Y &= \Phi_K^1 (\mathcal{W}_K^n F(\mathcal{W}_K^n)^T) (\Phi_K^2)^T \\ &= (\Phi_K^1 \mathcal{W}_K^n) F(\Phi_K^2 \mathcal{W}_K^n)^T \end{aligned}$$

Proposed sensing matrix

How to assign measurement

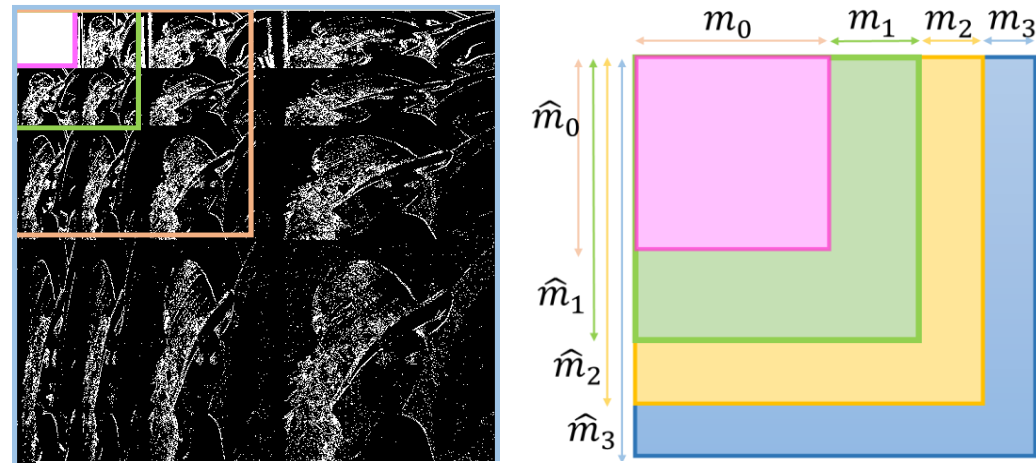


Fig. 1. Binary image of SWT and proposed multi-scale measurement at decomposition level 3

Proposed Subrate Allocation

- (MRK) Require no information about the to be sampled images
 - More measurement for lower SWT level

$$m = m_0 + \sum_{i=1}^K m_i = \sum_{i=1}^K \tilde{m} \omega_i \frac{1}{2^{K-j+1}}$$

$m_j = \tilde{m} \omega_j / 2^{K-j+1}$, $m_0 = n / 2^K$, \tilde{m} is intermediate value.

$\omega_j = a^{K-j}$ stands for weight ratio, a is a constant.

→ preserve low frequency better but still lost some level of high frequency

- (MRKa) Require information of wavelet coefficients (adaptive)
 - Thresholding the wavelet coefficients

$$\tau = \lambda \sigma \sqrt{2 \log Q}, \text{ where } \sigma = \frac{\text{median}(|F_K|)}{0.6745}$$

λ is a constant,

Q number of coefficient of F_K

- Relative sparsity

$$s_j = \|(F_K)_j\|_0 / Q_K$$

- KCS measurement

$$m_j = \tilde{m} \omega_j s_j / 2^{K-j+1}$$

Expected to preserve high frequency better

Experiments

Visual comparison of various CS methods



Ground truth



DTVNL1 [6] – 30.55dB



ALSB [20] – 32.02dB



TVHybrid [2] 24.95dB



TGVSH# [21] – 29.10dB



MH-MS# [16] – 26.78dB



MRK3** - 30.05dB



MRK3a** - 30.90dB

Multi-scale sensing (#), Support multi-resolution recovery (*)

MRK3: the proposed matrix with separable wavelet level 3

- Require no costly assumption of wavelet transform
- An efficient subrate allocation
- Support up to K resolution reconstruction