

(2)

Q. 5

(a) $P'_{m+1} = \begin{bmatrix} K_m + \delta I & 0 \\ 0 & \delta \end{bmatrix}^{-1}$ Since this is a block diagonal matrix, inversion is easy.

$$\therefore P'_{m+1} = \begin{bmatrix} (K_m + \delta I)^{-1} & 0 \\ 0 & 1/\delta \end{bmatrix} = \begin{bmatrix} P_m & 0 \\ 0 & 1/\delta \end{bmatrix}$$

(b) $P_m^{-1} = \begin{bmatrix} k(t_1, t_1) + \delta & k(t_2, t_1) & \dots & k(t_m, t_1) \\ k(t_1, t_2) & k(t_2, t_2) + \delta & \dots & k(t_m, t_2) \\ \vdots & \vdots & \ddots & \vdots \\ k(t_1, t_m) & k(t_2, t_m) & \dots & k(t_m, t_m) + \delta \end{bmatrix}$

$$P_{m+1}^{-1} = \begin{bmatrix} k(t_1, t_1) + \delta & k(t_2, t_1) & \dots & k(t_m, t_1) & k(t_{m+1}, t_1) \\ k(t_1, t_2) & k(t_2, t_2) + \delta & \dots & k(t_m, t_2) & k(t_{m+1}, t_2) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ k(t_1, t_m) & k(t_2, t_m) & \dots & k(t_m, t_m) + \delta & k(t_{m+1}, t_m) \\ k(t_1, t_{m+1}) & k(t_2, t_{m+1}) & \dots & k(t_m, t_{m+1}) & k(t_{m+1}, t_{m+1}) + \delta \end{bmatrix}$$

Split P_{m+1}^{-1}

$$\therefore P_{m+1}^{-1} = \underbrace{\begin{bmatrix} k(t_1, t_1) + \delta & \dots & k(t_m, t_1) & 0 \\ k(t_1, t_2) & \dots & k(t_m, t_2) & 0 \\ \vdots & \ddots & \vdots & \vdots \\ k(t_1, t_m) & \dots & k(t_m, t_m) + \delta & 0 \\ 0 & 0 & \dots & 0 & \delta \end{bmatrix}}_{P_{m+1}^{-1}} + \underbrace{\begin{bmatrix} 0 & 0 & \dots & 0 & k(t_{m+1}, t_m) \\ 0 & 0 & \dots & 0 & k(t_{m+1}, t_2) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 0 \\ k(t_1, t_{m+1}) & \dots & k(t_m, t_{m+1}) & \dots & k(t_{m+1}, t_{m+1}) \end{bmatrix}}_{BCT}$$

where $B = \begin{bmatrix} k(t_{m+1}, t_1) & 0 \\ k(t_{m+1}, t_2) & 0 \\ \vdots & \vdots \\ k(t_{m+1}, t_m) & 0 \\ k(t_{m+1}, t_{m+1}) & 1 \end{bmatrix}$; $C^T = \begin{bmatrix} 0 & 0 & \dots & 1 \\ k(t_{m+1}, t_1) & \dots & 0 \\ \vdots & \ddots & \vdots \\ k(t_{m+1}, t_m) & \dots & 0 \end{bmatrix}$

$\therefore C = \begin{bmatrix} 0 & k(t_{m+1}, t_1) \\ 0 & k(t_{m+1}, t_2) \\ \vdots & \vdots \\ 0 & k(t_{m+1}, t_m) \\ 1 & 0 \end{bmatrix}$

$\therefore BC^T = \begin{bmatrix} k(t_{m+1}, t_1) & 0 \\ k(t_{m+1}, t_2) & 0 \\ \vdots & \vdots \\ k(t_{m+1}, t_m) & 0 \\ k(t_{m+1}, t_{m+1}) & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & \dots & 1 \\ k(t_{m+1}, t_1) & k(t_{m+1}, t_2) & \dots & k(t_{m+1}, t_m) & 0 \end{bmatrix}$

$\downarrow C^T$

$\rightarrow B$

Let $W = P_{m+1}'^{-1}$, $X^T = B$, $Y = I$ and $Z = C^T$

Applying Matrix Inversion Lemma,

$\Rightarrow P_{m+1} = P_{m+1}' - P_{m+1}' B (I + C^T P_{m+1}' B)^{-1} C^T P_{m+1}'$

Here, $C^T \rightarrow R \times (M+1)$

$B \rightarrow (M+1) \times R$

$R = 2$ here

$P_{m+1}' \rightarrow (M+1) \times (M+1)$

$C^T P_{m+1}' B \rightarrow R \times R$

$\therefore I + C^T P_{m+1}' B \rightarrow$ Solving for $R \times R$ system of equations.

Matrix inversion lemma thus allows us to get solutions by solving this $R \times R$ system, which has been reduced from $(M+1) \times (M+1)$, which we would have had to do otherwise.

Matrix vector multiplications that surround the $R \times R$ system can be done in a relatively shorter time.

$$(c) \quad P_{m+1}' = P_{m+1}' - P_{m+1}' B (I + C^T P_{m+1}' B)^{-1} C^T P_{m+1}'$$

$$\hat{\alpha}_m = P_m y_m \quad \text{and} \quad \hat{\alpha}_{m+1} = P_{m+1} y_{m+1}$$

$$\hat{\alpha}_{m+1} = P_{m+1}' y_{m+1} - P_{m+1}' B (I + C^T P_{m+1}' B)^{-1} C^T P_{m+1}' y_{m+1} \quad \text{--- (1)}$$

$$\text{We know from (a)} \quad P_{m+1}' = \begin{bmatrix} P_m & 0 \\ 0 & 1/\delta \end{bmatrix}$$

$$P_{m+1}' y_{m+1} = \begin{bmatrix} P_m & 0 \\ 0 & 1/\delta \end{bmatrix} \begin{bmatrix} y_m \\ y_{m+1} \end{bmatrix} \rightarrow \text{not division.}$$

where,

$$\underline{y}_m = [y_1 \ y_2 \ \dots \ y_m]^T$$

(augmenting the column with the new y_{m+1})

$$\therefore P_{m+1}' y_{m+1} = \begin{bmatrix} P_m y_m \\ (y_{m+1})/\delta \end{bmatrix} \rightarrow (M+1) \times 1 \text{ column.} = \begin{bmatrix} \hat{\alpha}_m \\ (y_{m+1})/\delta \end{bmatrix}$$

From (1),

$$\hat{\alpha}_{m+1} = (I - G) P_{m+1}' y_{m+1}, \text{ where } G = P_{m+1}' B (I + C^T P_{m+1}' B)^{-1} C^T$$

\therefore on combining all this data,

$$\hat{\alpha}_{m+1} = [I - G] \begin{bmatrix} \hat{\alpha}_m \\ (y_{m+1})/\delta \end{bmatrix}$$

PSEUDO CODE :

Initialization: $P_m = (K_m + \delta I)^{-1}$, δ

$$\hat{x}_m = (K_m + \delta I)^{-1} y_m$$

for $k = m+1, m+2, \dots$ do

(t_k, y_k) streams in.

Compute $P'_k = \begin{bmatrix} P_{k-1} & 0 \\ 0 & 1/\delta \end{bmatrix}$

Construct B and C as :

$$B = \begin{bmatrix} k(t_{m+1}, t_1) & \dots & 0 \\ k(t_{m+1}, t_2) & & 0 \\ \vdots & & \vdots \\ k(t_{m+1}, t_m) & \dots & 0 \\ k(t_{m+1}, t_{m+1}) & - & 1 \end{bmatrix}$$

$$(m+1) \times 2 \rightarrow R$$

$$C = \begin{bmatrix} 0 & -k(t_{m+1}, t_1) \\ 0 & k(t_{m+1}, t_2) \\ \vdots & \vdots \\ 1 & k(t_{m+1}, t_{m+1}) \end{bmatrix}$$

$$(m+1) \times 2$$

$$P_k = P'_k - G_k P'_k \quad \text{where } G_k = P'_k B (I + C^T P'_k B)^{-1} C^T$$

$$\hat{x}_k = [I - G_k] \begin{bmatrix} \hat{x}_{k-1} \\ y_k/\delta \end{bmatrix}$$

end for.

(d) Only q latest samples are used for prediction (at any given time).

$$P_m^{-1} = \begin{bmatrix} k(t_{m-q+1}, t_{m-q+1}) + \delta & k(t_{m-q+2}, t_{m-q+1}) & \dots & k(t_m, t_{m-q+1}) \\ k(t_{m-q+1}, t_{m-q+2}) & k(t_{m-q+2}, t_{m-q+2}) + \delta & \dots & k(t_m, t_{m-q+2}) \\ \vdots & \vdots & \ddots & \vdots \\ k(t_{m-q+1}, t_m) & k(t_{m-q+2}, t_m) & \dots & k(t_m, t_m) + \delta \end{bmatrix}$$

$$P_{m+1}^{-1} = \begin{bmatrix} k(t_{m-q+2}, t_{m-q+2}) + \delta & k(t_{m-q+3}, t_{m-q+2}) & \dots & k(t_{m+1}, t_{m-q+2}) \\ k(t_{m-q+2}, t_{m-q+3}) & k(t_{m-q+3}, t_{m-q+3}) + \delta & \dots & k(t_{m+1}, t_{m-q+3}) \\ \vdots & \vdots & \ddots & \vdots \\ k(t_{m-q+2}, t_{m+1}) & k(t_{m-q+3}, t_{m+1}) & \dots & k(t_{m+1}, t_{m+1}) + \delta \end{bmatrix}$$

Split P_{m+1}^{-1} as follows:

$$P_{m+1}^{-1} = \begin{bmatrix} k(t_{m-q+2}, t_{m-q+2}) + \delta & \dots & k(t_m, t_{m-q+2}) & 0 \\ k(t_{m-q+2}, t_{m-q+3}) & \dots & k(t_m, t_{m-q+3}) & 0 \\ \vdots & & \vdots & \vdots \\ k(t_{m-q+2}, t_m) & \dots & k(t_m, t_m) + \delta & 0 \end{bmatrix}$$

$$\begin{array}{c} \uparrow \\ P_{m+1}' \end{array} \quad \begin{array}{c} + \\ \left[\begin{array}{ccc} 0 & 0 & \dots & 0 & k(t_{m+1}, t_{m-q+2}) \\ 0 & 0 & \dots & 0 & \\ \vdots & \vdots & \ddots & \vdots & \\ k(t_{m-q+2}, t_{m+1}) & k(t_{m-q+3}, t_{m+1}) & \dots & k(t_{m+1}, t_{m+1}) \end{array} \right] \end{array}$$

split \swarrow BC^T

where $B = \begin{bmatrix} k(t_{m+1}, t_{m-q+2}) & 0 \\ k(t_{m+1}, t_{m-q+3}) & 0 \\ \vdots & \vdots \\ k(t_{m+1}, t_m) & 0 \\ k(t_{m+1}, t_{m+1}) & 1 \end{bmatrix}$

$$C = \begin{bmatrix} 0 & k(t_{m-q+2}, t_{m+1}) \\ 0 & k(t_{m-q+3}, t_{m+1}) \\ \vdots & \vdots \\ 0 & k(t_m, t_{m+1}) \\ 1 & 0 \end{bmatrix}$$

Now, $P_{m+1}^{-1} = \begin{bmatrix} k(t_{m-q+2}, t_{m-q+2}) + \delta & \dots & \dots & k(t_m, t_{m-q+2}) \\ k(t_{m-q+2}, t_{m-q+3}) & k(t_{m-q+3}, t_{m-q+3}) + \delta & \dots & k(t_m, t_{m-q+3}) \\ \vdots & \vdots & \ddots & \vdots \\ k(t_{m-q+2}, t_m) & \dots & k(t_{m-q+3}, t_m) & \dots & k(t_m, t_m) + \delta \end{bmatrix}$

$$P_m^{-1} = \left[\begin{array}{c|c} \begin{matrix} k(t_{m-q+1}, t_{m-q+1}) + \delta \\ k(t_{m-q+1}, t_{m-q+2}) \\ \vdots \\ k(t_{m-q+1}, t_m) \end{matrix} & \begin{matrix} k(t_{m-q+2}, t_{m-q+1}) & \dots & k(t_m, t_{m-q+1}) \end{matrix} \end{array} \right] P_{m+1}^{-1}$$

Split P_m^{-1} as :

$$P_m^{-1} = \left[\begin{array}{c|c} k(t_{m-q+1}, t_{m-q+1}) + \delta & \underline{0} \\ \hline \underline{0} & P_{m+1}^{-1} \end{array} \right] + \left[\begin{array}{c|c} \underline{0} & \begin{matrix} k(t_{m-q+2}, t_{m-q+1}) \\ k(t_{m-q+3}, t_{m-q+1}) \\ \vdots \\ k(t_m, t_{m-q+1}) \end{matrix} \\ \hline \begin{matrix} k(t_{m-q+2}, t_m) \\ \vdots \\ k(t_{m-q+3}, t_m) \end{matrix} & \underline{0} \end{array} \right]$$

$\downarrow Q'$ $\downarrow FG^T$

Split FG^T as :

$$F = \begin{bmatrix} 1 & 0 \\ 0 & k(t_{m-q+2}, t_{m-q+1}) \\ 0 & k(t_{m-q+3}, t_{m-q+1}) \\ \vdots & \vdots \\ 0 & k(t_m, t_{m-q+1}) \end{bmatrix} \quad G^T = \begin{bmatrix} 0 & k(t_{m-q+2}, t_{m-q+1}) & \dots & k(t_m, t_{m-q+1}) \\ 1 & 0 & \dots & 0 \end{bmatrix}$$

$$\therefore P_m^{-1} = \begin{bmatrix} k(t_{m-q+1}, t_{m-q+1}) + \delta & \underline{0} \\ \underline{0} & P_{m+1}'^{-1} \end{bmatrix} + F G^T$$

$$\rightarrow \begin{bmatrix} a & \underline{0} \\ \underline{0} & P_{m+1}'^{-1} \end{bmatrix} \text{ where } a = k(t_{m-q+1}, t_{m-q+1}) + \delta$$

$$\therefore P_m^{-1} - F G^T = \begin{bmatrix} a & \underline{0} \\ \underline{0} & P_{m+1}'^{-1} \end{bmatrix}$$

Take inverse on both sides:

$$(P_m^{-1} - F G^T)^{-1} = \begin{bmatrix} 1/a & \underline{0} \\ \underline{0} & P_{m+1}' \end{bmatrix}$$

By Matrix-Inversion Lemma:

Now, $W = P_m^{-1}$, $X^T = -F$, $Z = G^T$

$$\begin{aligned} \therefore (P_m^{-1} - F G^T)^{-1} &= P_m - P_m (-F) (I + G^T P_m (-F))^{-1} G^T P_m \\ &= P_m + P_m F (I - G^T P_m F)^{-1} G^T P_m \end{aligned}$$

\therefore We can compute P_{m+1}' from P_m by taking the $q-1 \times q-1$ submatrix here. \leftarrow

$\{$ then, $P_{m+1} = (P_{m+1}'^{-1} + B C^T)^{-1}$

\therefore Again, by matrix inversion lemma

$$P_{m+1} = P_{m+1}' - P_{m+1}' B (I + C^T P_{m+1}' B)^{-1} C^T P_{m+1}'$$

Plug in P_{m+1}' , B and C to get update P_{m+1} .

Thus, had to do two low-rank updates, once to remove the effect of (t_{m-q+1}, y_{m-q+1}) and once to add effect of (t_{m+1}, y_{m+1}) .