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The main goal of this calculator is to provide an easy-to-use interface where users can input numbers and operators to perform quick calculations directly in their web browser. By developing this project, beginners can gain practical experience in designing user interfaces, handling user inputs, and implementing logical operations, all of which are essential skills in front-end web development.

This calculator not only helps reinforce essential programming concepts but also lays the groundwork for more advanced web applications in the future.



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      background: #f0f0f0;
      display: flex;
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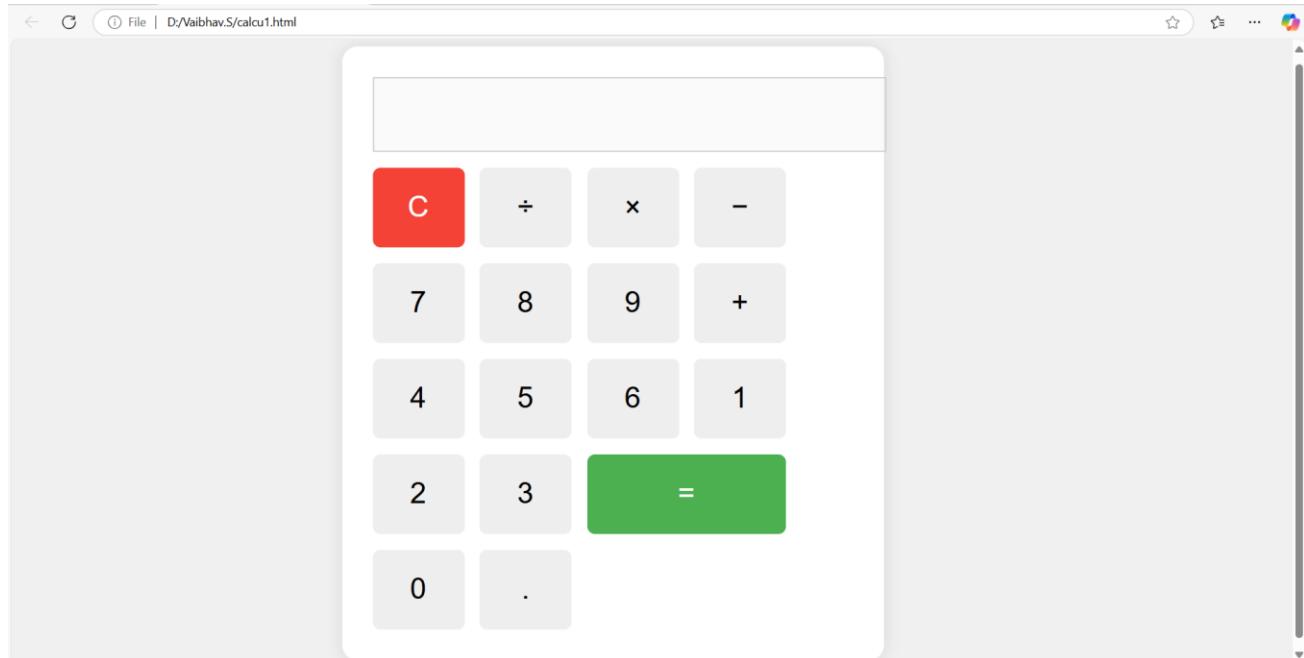
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***FULL STACK
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PROJECT***

***SIMPLE
CALCULATOR***

**NAME: SHUBHAM KAWADE
ROLL.NO: 61, DIV: B
PRN: 22356030138**



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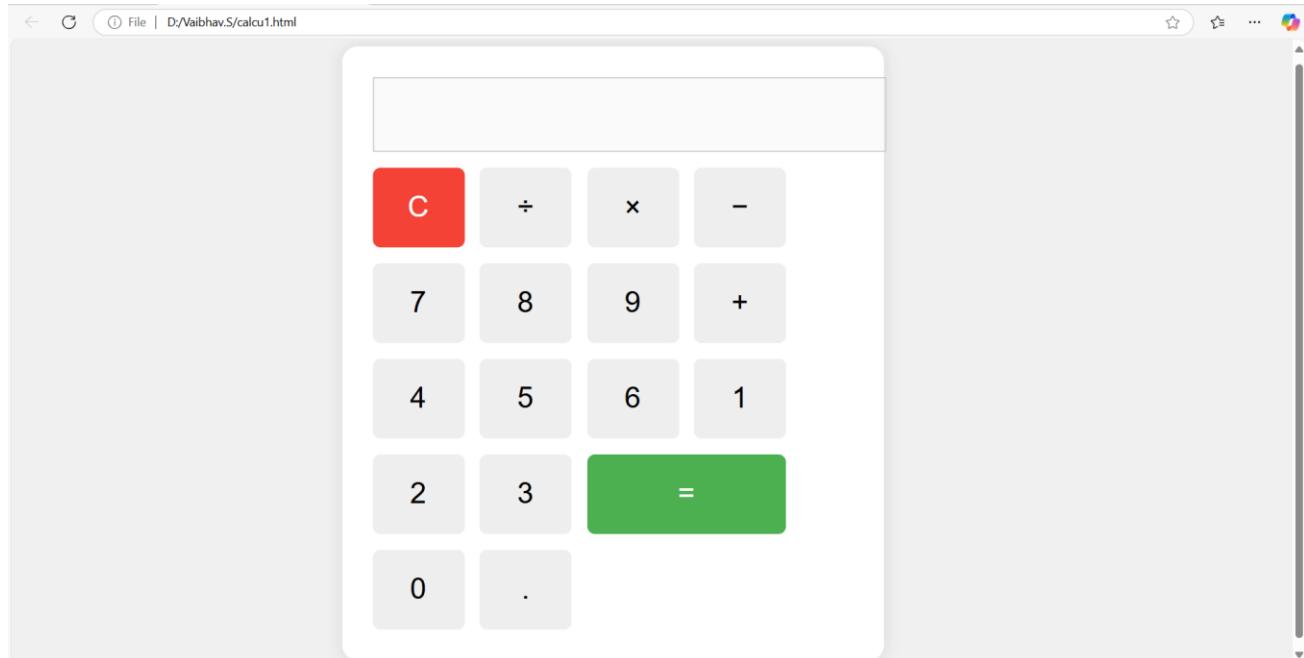
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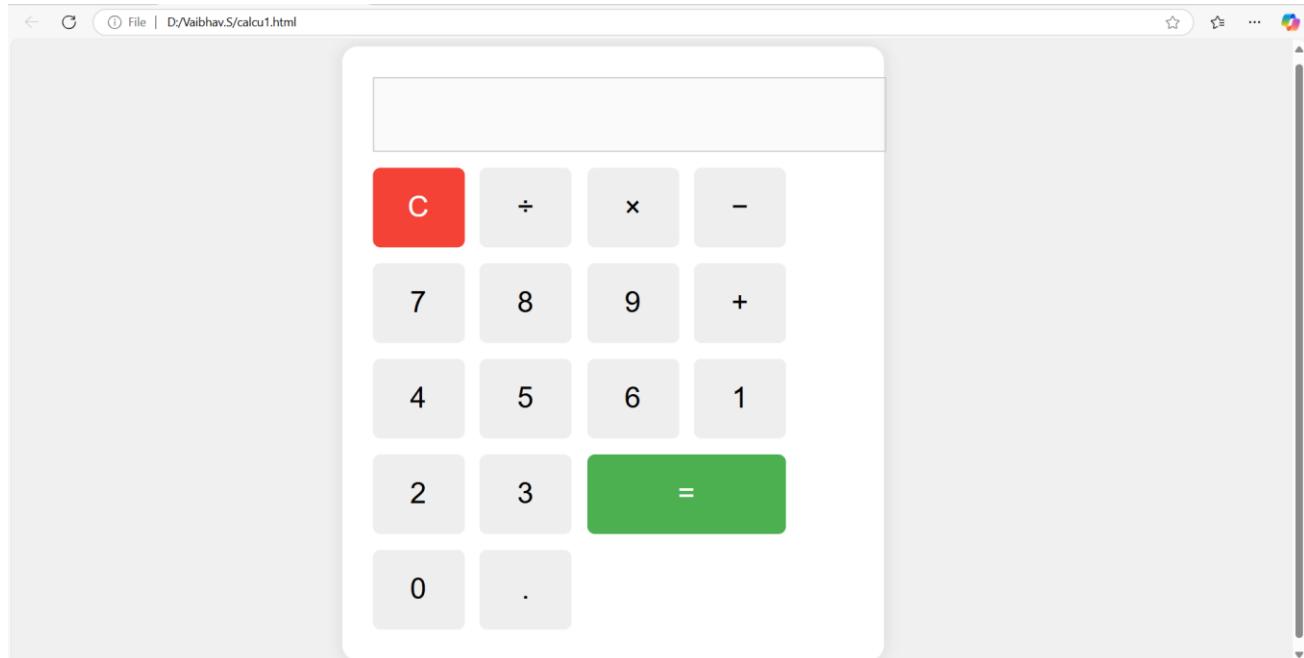
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Assignment No:-2

Q.1) Name SPRs associated with each I/O part of PIC18F. What is role of PORT X SPR?

→ SPRs associated with I/O port in PIC18F - In PIC18F series, each I/O port is controlled by several special function register.

- 1) PORT → Register → stores actual I/O data of port.
- 2) TRIS X Register → configures each pin as either input (1) or output (0).
- 3) LAT X Register → used for latching O/P values to reduce read-modify write issue.
- 4) ANSEL X Register → configure pins as analog or digital.

- Role of PORT X SPR -

It act as buffer that stores current state of port. When reading, it shows actual logic level at pin & when writing it changes output value.

Q.2) Calculate total delay generated by timer 0 if (FFF1)H is loaded into it. Assume crystal frequency = 10 MHz.

→ Given,

$$\text{Crystal freq} = 10 \text{ MHz}$$

$$\text{Timer 0 prescaler} = 1$$

~~Timer 0 is 16 bit~~

✓ Timer load value = FFF1H (65521 in decimal)

- Timer clock freq =

$$f_{\text{timer}} = f_{\text{oscillator}} = \frac{f_{\text{oscillator}}}{4} = \frac{10}{4} \text{ MHz} = 2.5 \text{ MHz}$$

- Timer clock period

$$\text{Timer} = \frac{1}{f_{\text{timer}}} = \frac{1}{2.5 \text{ MHz}} = 0.4 \mu\text{s}$$

$t_{\text{count}} = 65536 - \text{initial value}$

$$= 65536 - 65521$$

$$= 15$$

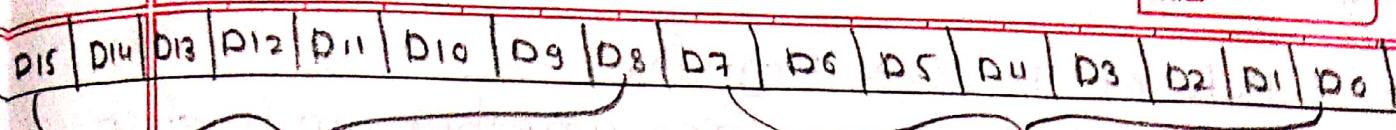
Total delay = $t_{\text{count}} \times \text{Timer}$

$$= 15 \times 0.4$$

$$= 6 \mu\text{s}$$

Q.3) Explain Working of PIC18F Timer1 with help of suitable diagram.

- Timer is 16 bit timer & its 16 bit register is split into 2 bytes refer as TR1RL & TR1RH
- Timer1 can be programmed 16 bit mode only & unlike timer0 it does not support 8 bit mode. Timer0 it does not support 8 bit
- Timer1 also has TICRH register in addition to TRRIPL Flag bit goes high when TR1RH : TR1RL overflow from FFFF to 0000
- Timer1 also has prescaler option built, only supports factors of 1:1, 1:2, 1:4 & 1:8



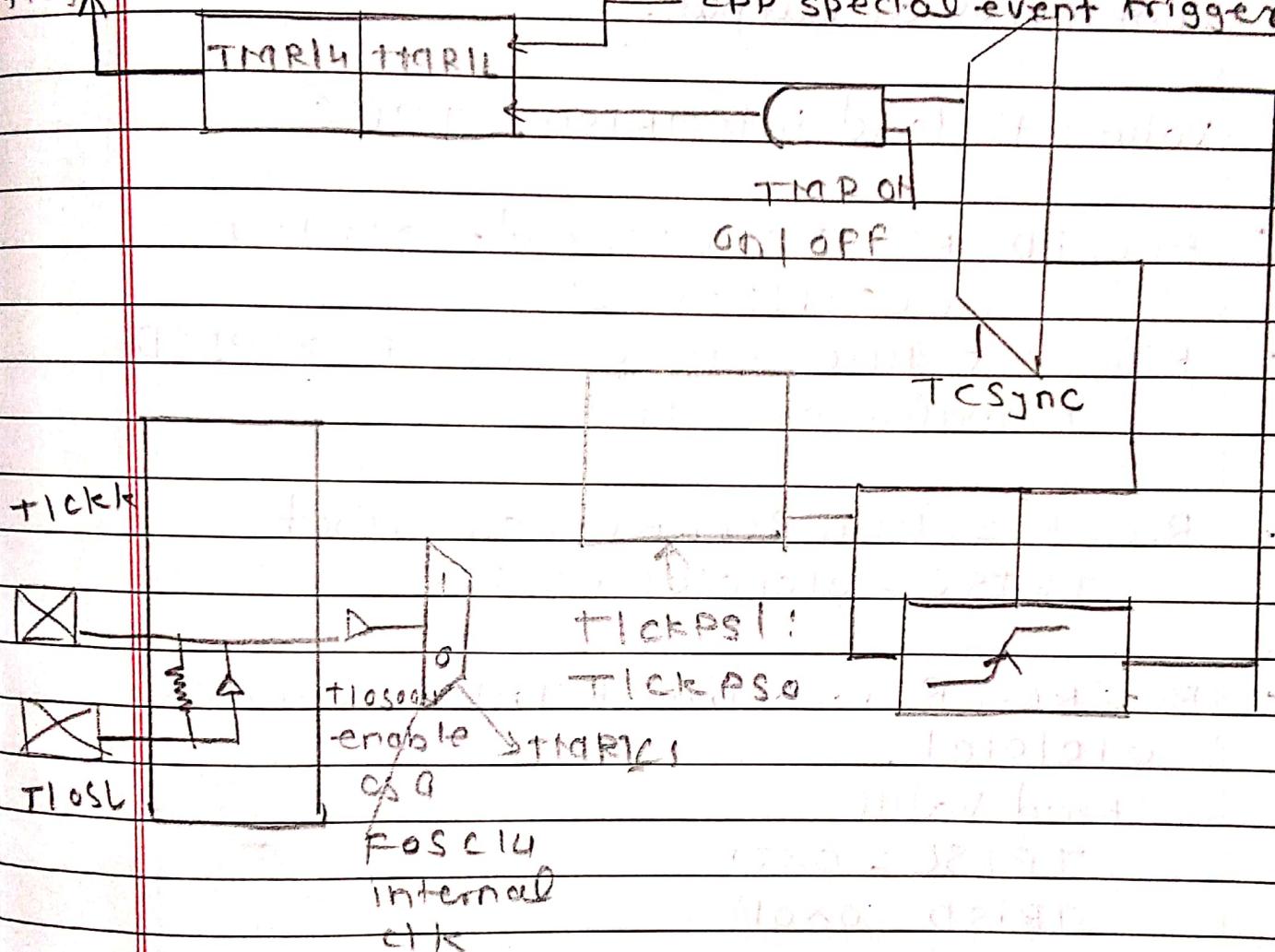
TMRIH

TMRL

set TMRIP
flag bit

Timer High & low register.

CPP, special event trigger



pig Timer1 block diagram

Q.4) What is role of TRIS & SPR in PIC18F25K60
Value to be loaded in TRISB & TRISC
register for following.

RD0, RD1, RD2, RD3 as input port

RD4, RD5, RD6, RD7, RD8 output

RC0, RC2, RC4, RC6, RC7 as output

RC1, RC3, RC5 as input

→ Role of TRIS X Register -

- TRIS X reg determines whether pin function as input or output.

- Writing 1 configures pin as input & 0 configures as output.

values to load into TRISD & TRISC -

- RD₀, RD₁, RD₂, RD₃ as input → TRISB =
00001111 = 0x0F

- RB₄, RD₅, RD₆, RD₇ as output → TRISD
Remains 00001111

- RC₀, RC₂, RC₄, RC₆, RC₇, as output -
TRISC = 01010101 = 0x55

- RC₁, RC₃, RC₅ as input - TRISC remains
01010101,

Find value -

$$\text{TRISC} = 0x55$$

$$\text{TRISD} = 0x0F$$

Q.5) Explain in detail prescaling & postscaling of PIC18F timer.

→ • prescaler -

- It divides input clock before feeding it to timer.

- It helps extend timer range by reducing frequency

- Available prescaler value - 1:2, 1:4, 1:8, 1:16 etc

- The division factor is programmable typically through specific bits in timer control

register.

- A higher prescaler value result in slower timer increment rate, which is useful for measuring longer duration but reduces timers resolution

* postscaler -

- It operates after time counting register & control frequency of interrupt generation by dividing no of timer overflow required to trigger an interrupt.
- similar to prescaler, postscaler division factor is programmable via specific bit in timer control register.
- e.g - Timer in PIC18F4550 allow for a postscaler setting ranging from 1:1 to 1:16.

Q.6) Bit format of TCON register & explain functionality of each bit.

BIT	7	6	5	4	3	2	1	0
Name	TR00H	T08BIT	T0CS	T0SF	PSA	T0PS	T0PS	T0PS
						2	1	0

Bit Format of TCON reg.

- ~~Functionaliry~~
- TR00H (bit 7) - enable Timer0 (1 = ON 0 = OFF)
- T08BIT (bit 6) - 1 = 8 bit mode, 0 = 16 bit
- T0CS (bit 5) = 1 = external clk, 0 = internal clk
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C = high below, 0 = low to high

- PSA (bit 3) : 1 = no prescaler, 0 = prescaler assigned.

• TOPS2: TOPSO (bit 2-0) - prescaler Value
Selection (000 = 1:2, 111 = 1: 256)

Q.7) Explain working of pic18F timer0 in 16bit mode with suitable diagram.

→ Timer0-

- It can be used as 8 bit or 16 bit timer
- The 16 bit register of timer0 is accessed as low byte & high byte as shown
- The low byte reg. is called TR0L & high register is called TR0H.

eg - "MOVWF TR0L" moves value of WREG into TR0L the low byte of timer0. These register can also be read like any other register.

eg - MOVF TR0L, PORTB

It copies TR0L to portB

TR0H

TR0L

C
TMR0H
TMR0L

D15 | D14 | D13 | D12 | D11 | D10 | P9 | P8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0

Fig. High & low register.

Assignment No:-2

Q.1) Name SPRs associated with each I/O part of PIC18F. What is role of PORT X SPR?

→ SPRs associated with I/O port in PIC18F - In PIC18F series, each I/O port is controlled by several special function register.

- 1) PORT → Register → stores actual I/O data of port.
- 2) TRIS X Register → configures each pin as either input (1) or output (0).
- 3) LAT X Register → used for latching O/P values to reduce read-modify write issue.
- 4) ANSEL X Register → configure pins as analog or digital.

- Role of PORT X SPR -

It act as buffer that stores current state of port. When reading, it shows actual logic level at pin & when writing it changes output value.

Q.2) Calculate total delay generated by timer 0 if (FFF1)H is loaded into it. Assume crystal frequency = 10 MHz.

→ Given,

$$\text{Crystal freq} = 10 \text{ MHz}$$

$$\text{Timer 0 prescaler} = 1$$

~~Timer 0 is 16 bit~~

✓ Timer load value = FFF1H (65521 in decimal)

- Timer clock freq =

$$f_{\text{timer}} = f_{\text{oscillator}} = \frac{f_{\text{oscillator}}}{4} = \frac{10}{4} \text{ MHz} = 2.5 \text{ MHz}$$

- Timer clock period

$$\text{Timer} = \frac{1}{f_{\text{timer}}} = \frac{1}{2.5 \text{ MHz}} = 0.4 \mu\text{s}$$

$t_{\text{count}} = 65536 - \text{initial value}$

$$= 65536 - 65521$$

$$= 15$$

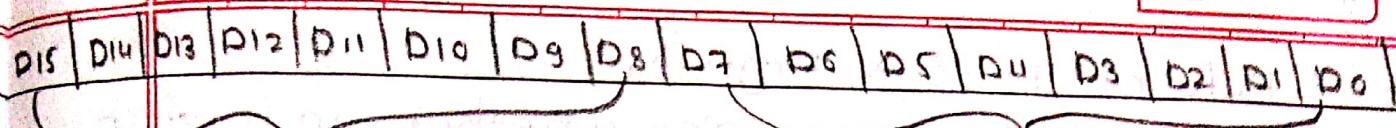
Total delay = $t_{\text{count}} \times \text{Timer}$

$$= 15 \times 0.4$$

$$= 6 \mu\text{s}$$

Q.3) Explain Working of PIC18F Timer1 with help of suitable diagram.

- Timer is 16 bit timer & its 16 bit register is split into 2 bytes refer as TR1RL & TR1RH
- Timer1 can be programmed 16 bit mode only & unlike timer0 it does not support 8 bit mode. Timer0 it does not support 8 bit
- Timer1 also has TICRH register in addition to TRRIPL Flag bit goes high when TR1RH : TR1RL overflow from FFFF to 0000
- Timer1 also has prescaler option built, only supports factors of 1:1, 1:2, 1:4 & 1:8



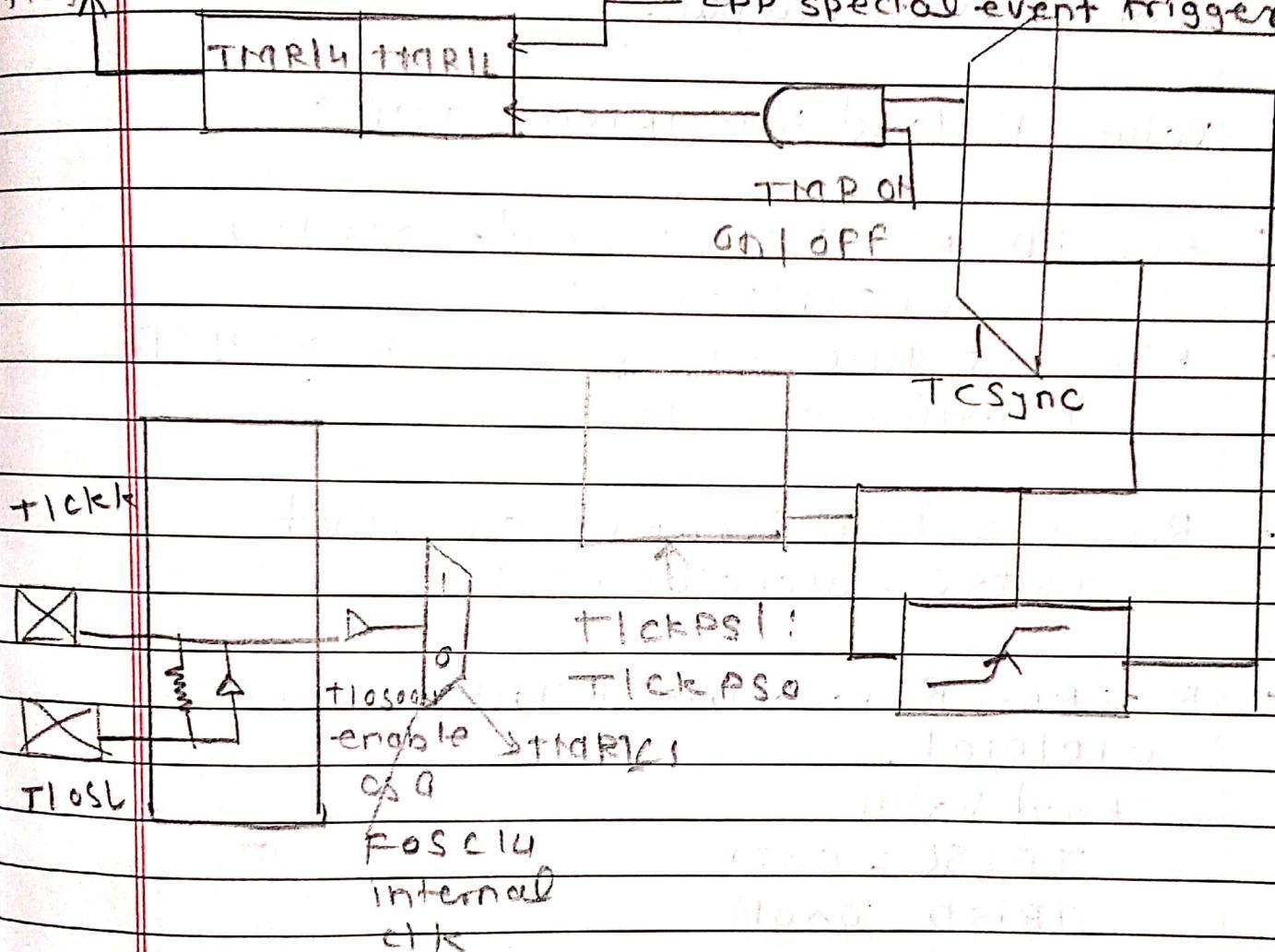
TMRIH

TMRL

set TMRIP
flag bit

Timer High & low register.

CPP, special event trigger



pig Timer1 block diagram

Q.4) What is role of TRIS & SPR in PIC18F25K60
Value to be loaded in TRISB & TRISC
register for following.

RD0, RD1, RD2, RD3 as input port

RD4, RD5, RD6, RD7, RD8 output

RC0, RC2, RC4, RC6, RC7 as output

RC1, RC3, RC5 as input

→ Role of TRIS X Register -

- TRIS X reg determines whether pin function as input or output.

- Writing 1 configures pin as input & 0 configures as output.

values to load into TRISD & TRISC -

- RD₀, RD₁, RD₂, RD₃ as input → TRISB =
00001111 = 0x0F

- RB₄, RD₅, RD₆, RD₇ as output → TRISD
Remains 00001111

- RC₀, RC₂, RC₄, RC₆, RC₇, as output -
TRISC = 01010101 = 0x55

- RC₁, RC₃, RC₅ as input - TRISC remains
01010101,

Find value -

$$\text{TRISC} = 0x55$$

$$\text{TRISD} = 0x0F$$

Q.5) Explain in detail prescaling & postscaling of PIC18F timer.

→ • prescaler -

- It divides input clock before feeding it to timer.

- It helps extend timer range by reducing frequency

- Available prescaler value - 1:2, 1:4, 1:8, 1:16 etc

- The division factor is programmable typically through specific bits in timer control

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TR0L

C
TMR0H
TMR0L

D15 | D14 | D13 | D12 | D11 | D10 | P9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0

Fig. High & low register.

Automated Bus e-Ticketing Service

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Abstract: Nowadays public transport systems like metro are well advanced. The need to improve passenger safety, convenience and performance of existing public transport is increasing the demand for intelligent transportation systems in the market. The paper-based ticketing system for collecting bus fares has been considered the source of major financial losses in India. It is difficult to assure every passenger to buy a ticket. A paper ticket becomes useless for passengers upon reaching the destination. The number of untold tickets per day is very high. In the era of technology, India should focus on developing an automated system to collect bus fares. Therefore, this paper proposes an automated card operated system using RFID and GPS for bus travel in India.

Keywords: Bus e-Ticketing

I. INTRODUCTION

Today, everything in the world is becoming smart and digital, with significant advances in the transport sector. However, public transport buses in India have not kept pace with these new developments. Intelligent vehicle research has been an active area of work, especially in the context of public transport.

Traditionally, every bus has been controlled by a conductor who collects money from each passenger and issues a ticket. To address this, we are proposing an IoT-based ticketing system. The primary objective of this project is to use IR sensors to automatically count passengers and GPS sensors to calculate the distance traveled by each passenger. The corresponding fare will then be debited from the RFID card.

II. LITERATURE SURVEY

In general, buses are typically managed by conductors who collect money from each passenger and issue tickets. Initially, printed papers or tokens were used as tickets. Nowadays, hand-operated machines are employed for ticket printing. However, this system has several disadvantages. Passengers must carry the ticket until they reach their destination, conductors need to ensure that everyone has a valid ticket, and the ticketing process takes a comparatively long time, requiring more paper.

For example, when a passenger wants to travel on a bus, they need to carry money. The conductor collects the money and issues a ticket, a process that every passenger must repeat. This results in increased time, resource waste, and energy consumption.

The data pertains to an Automatic Fare Collection (AFC) system integrated with an Automated Vehicle Location (AVL) system that records each passenger's transaction when boarding the bus. This data includes information about the route, vehicle, travel card, as well as the time and place where the journey begins. While some of this data is recorded for on-board ticket inspection, it also enables innovative spatial verification features introduced by the methodology.

The integration of the Internet of Things (IoT) in Automatic Fare Collection is crucial. An AFC system consists of automated gate machines, ticket vending machines, and ticket checking machines. A stable and integrated platform is essential for smooth passenger flow during peak hours, ensuring that all data is collected and transmitted to the server.

In recent progress, RFID-based automatic bus ticketing has seen remarkable development in various technologies for public welfare, especially in the field of public transport. RF modules, particularly Radio Frequency Identification Devices (RFID), are gaining prominence for their potential in the near and distant future of public transport bus systems.

III. MODULE IDENTIFICATION

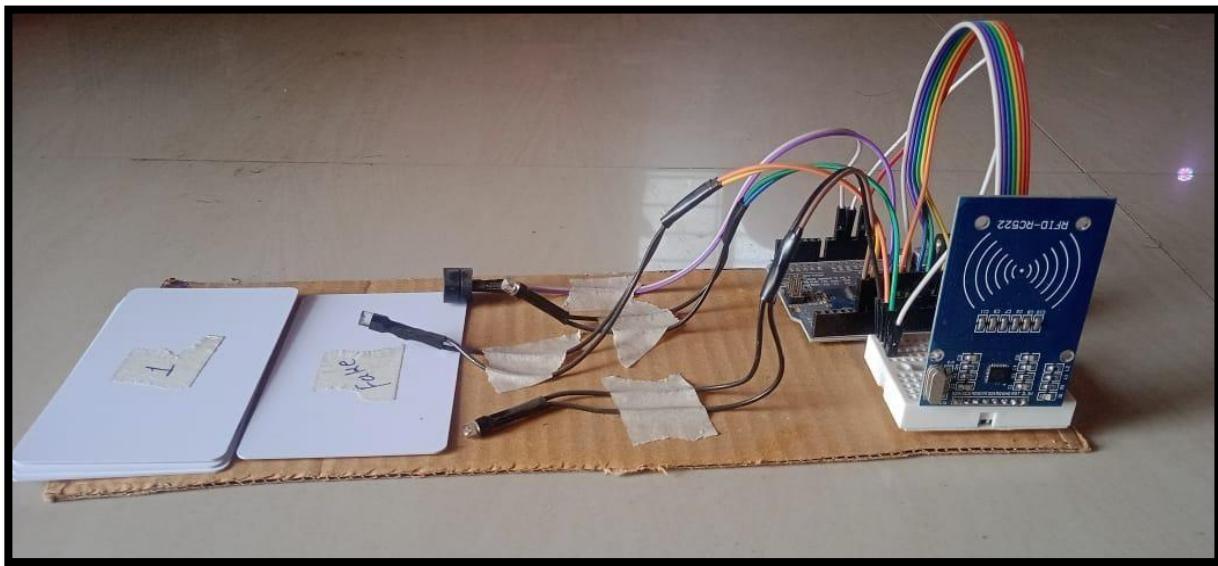
The project is designed for bus passengers traveling within the city. Users can view daily ticket transactions through the app. Each passenger is issued an RFID card, which they must swipe on the RFID reader upon boarding the bus. Additionally, they need to swipe the card again when reaching their destination.

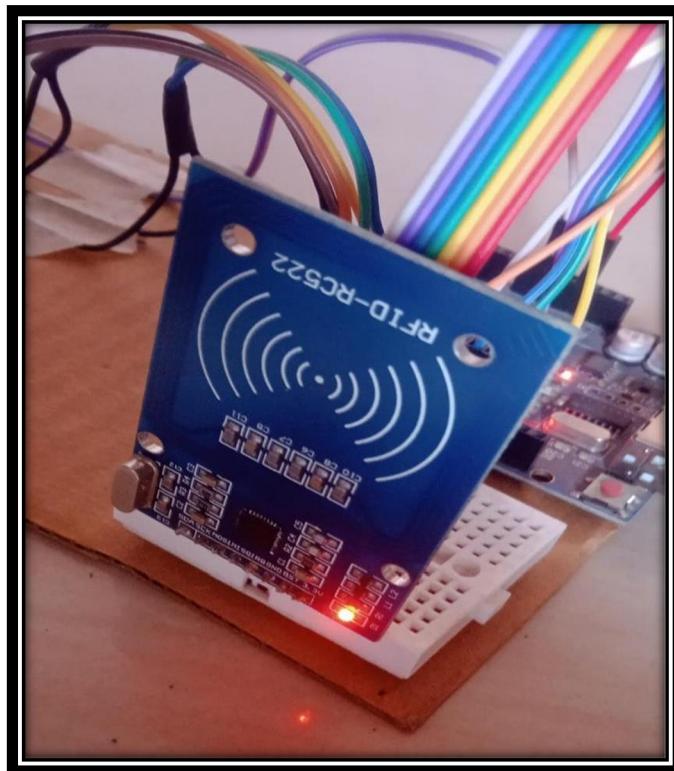
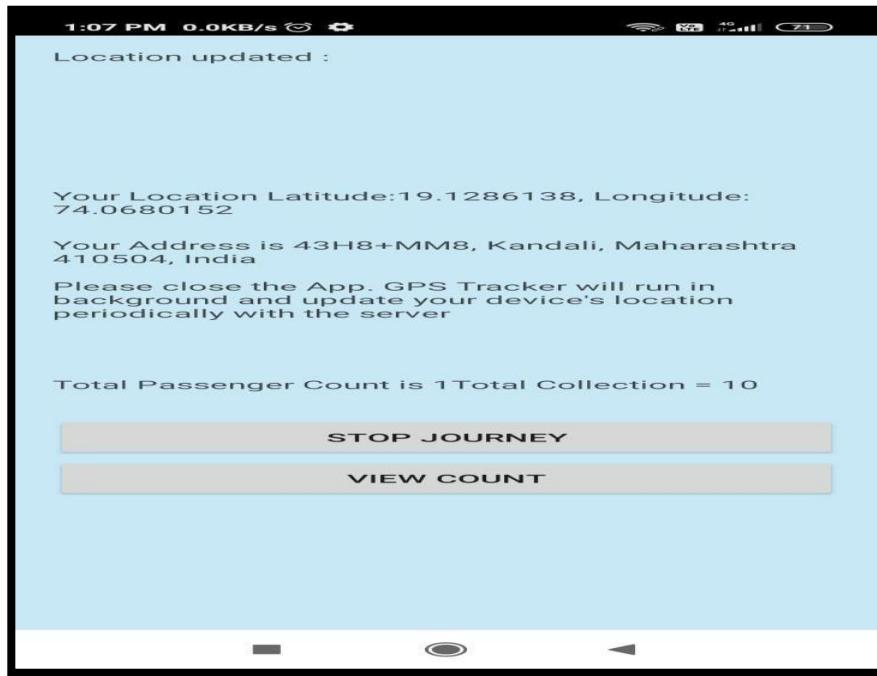
The primary goal of this project is to utilize an IR sensor to count passengers and a GPS sensor to automatically calculate the distance travelled. The corresponding fare is then debited from the RFID card, eliminating the need for a paper-based ticketing system. This approach ensures a seamless process with no conductor interference. Ticket history is stored in a database, and transaction counts are automated.

The operational steps are as follows:

- Swipe the RFID card upon passenger boarding.
- Store GPS location during the swipe.
- Send an SMS to the traveler with the GPS location.
- The passenger swipes the RFID card upon reaching the destination.
- Calculate the distance from the stored GPS location (Step 2).
- Deduct the appropriate fare

IV. IMPLEMENTATION RESULT





V. MODULE DESCRIPTION

The bus is used by regular bus passengers to make frequent intercity travel trips at a profitable cost compared to daily bus fares.

Bus ticketing is done manually with no computerized user detail record. To overcome this, we have decided on our project topic

Every bus is controlled by a conductor. The conductor will collect money from each passenger and issue a ticket. To overcome this, we will create IOT based ticketing system

VI. CONCLUSION

The project will be presented as a fully automated, reliable, transparent and convenient system for ticketing. RFID cards can be reusable, much more convenient than paper-based ticketing systems.

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Top Skills

java
Data Analytics
GitHub

Certifications

Introduction to Programming Using HTML
Introduction to Javascript
Google Cloud Computing Foundations Certificate
Data Analysis with Python
Prompt Design in Vertex AI

Publications

Automated Bus e-Ticketing Service

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Summary

I have completed my Diploma in Computer Engineering and am currently pursuing a Bachelor's degree in Information Technology. My journey in the tech field has been driven by a passion for problem-solving and innovation.

I have a strong foundation in programming languages such as Java and Python, with a growing interest in Artificial Intelligence (AI) and Cloud Computing. My experience includes exploring machine learning, natural language processing, and designing scalable solutions using cloud platforms like Google Cloud.

I am constantly learning and upgrading my skills through hands-on projects and certifications. My goal is to contribute to impactful projects in the fields of AI, Cloud Computing, and software development, while collaborating with like-minded professionals to solve real-world challenges.

With a combination of technical expertise and a dedication to growth, I aim to make a meaningful impact in the tech industry.

Education

Jspm BSIOTR

Bachelor of Engineering - BE, Information Technology · (August 2024 - June 2027)

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Ssc