# DreamPRM-1.5: Unlocking the Potential of Each Instance for Multimodal Process Reward Model Training

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Project Page: https://github.com/coder-qicao/DreamPRM-1.5

## **Abstract**

Training multimodal process reward models (PRMs) is challenged by distribution shifts and noisy data. We introduce DreamPRM-1.5, an instance-reweighted framework that adaptively adjusts the importance of each training example via bi-level optimization. We design two complementary strategies: Instance Table, effective for smaller datasets, and Instance Net, scalable to larger ones. Integrated into test-time scaling, DreamPRM-1.5 achieves 84.6 accuracy on the MMMU benchmark, surpassing GPT-5.

### 1 Introduction

Recent advances in reasoning [20] have substantially boosted the performance of large language models (LLMs)[1, 4, 23, 17], with Process Reward Models (PRMs)[10, 8] enabling step-level supervision and more reliable selection of reasoning trajectories. Extending PRMs to multimodal LLMs (MLLMs)[27, 9] is thus a natural progression. However, multimodal inputs couple high-dimensional visual features with discrete language tokens, enlarging the input space and intensifying distribution shifts[21]. At the same time, multimodal reasoning data face severe quality imbalance[28, 13], where noisy or trivial samples dilute the benefits of effective training. Consequently, directly applying text-only PRM methods [26, 14] yields limited gains due to poor generalization [5].

To address this problem, DreamPRM [2] introduced a domain-reweighted framework, where Process Reward Models were fine-tuned with dataset-level weights to emphasize high-quality domains while suppressing noisy ones. At the meta-level, these weights were updated through validation-driven aggregation losses [19, 6, 22, 7, 11], enabling more robust and generalizable multimodal reasoning.

Building on this foundation, we propose DreamPRM-1.5, which extends the idea of reweighting from the domain level to the individual instance level. Instead of treating each dataset uniformly, DreamPRM-1.5 assigns adaptive weights to every training example, thereby amplifying the impact of informative samples while down-weighting noisy or trivial ones. This finer-grained reweighting significantly enhances the effectiveness of PRM training, unlocking the full potential of each data instance and significantly improve performance.

Our contributions are summarized as follows:

• We propose DreamPRM-1.5, an *instance-reweighted* multimodal process reward model training framework that dynamically adjusts the weight of each individual data example. To realize instance-level reweighting, we further design two complementary training paradigms: Instance Table, which maintains more activated parameters during training and proves effective for smaller datasets; and Instance Net, which employs a lightweight parameterization with stronger generalization ability, making it more suitable for large-scale training sets.

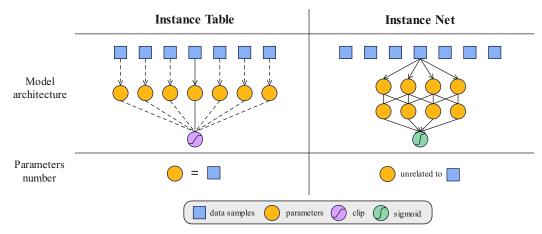


Figure 1: Comparison of two model designs for instance reweighting in DreamPRM-1.5. Instance Table assigns an explicit learnable weight to each training sample, offering strong per-instance flexibility but scaling with dataset size. Instance Net parameterizes instance weights via a lightweight MLP appended to the PRM, maintaining a fixed parameter size independent of dataset scale and providing better generalization.

• By integrating DreamPRM-1.5 into test-time scaling, we achieve a new state-of-the-art accuracy of 84.6 on the validation set of MMMU benchmark, further advancing the performance frontier of the strongest existing model, GPT-5-mini.

# 2 The Proposed Instance-reweighting Method

Training multimodal PRMs is difficult due to (1) data quality imbalance and (2) mismatch between training and inference. We propose DreamPRM-1.5, which learns instance weights via a bi-level framework adapted from DreamPRM [2]. The lower level updates PRM parameters with instance-reweighted training, while the upper level optimizes instance weights on a meta dataset.

### 2.1 Bi-level Optimization for Instance-reweighhting

**Lower-level optimization.** Given a PRM  $\mathcal{V}$  parameterized by  $\phi$  and instance weights parameterized by  $\alpha$ , the training loss on training sample x is

$$\mathcal{L}_{tr}(\phi, \alpha, x) = \alpha \sum_{i=1}^{n} \mathcal{L}_{CrossEntropy}(\mathcal{V}_{\phi}(x, \hat{y}_i), p_i), \tag{1}$$

where  $p_i$  is the step-wise supervision for prefix  $\hat{y}_i$ . The overall objective across N instances is a weighted sum, yielding  $\phi^*(\alpha) = \arg\min_{\phi} \mathcal{L}_{tr}(\phi, \alpha, x)$ , where  $x \in \mathcal{D}_{tr}$  is from training set  $\mathcal{D}_{tr}$ . Only  $\phi$  is optimized here, with  $\alpha$  fixed.

**Upper-level optimization.** We then optimize  $\alpha$  on meta learning dataset  $\mathcal{D}_{meta}$  with a meta loss that mimics PRM inference. For each generated solution  $\hat{y}$ , we compute an aggregated score  $\mathcal{A}(\mathcal{V}_{\phi^*(\alpha)}(x,\hat{y}))$  and compare it with ground truth  $r(\hat{y},y) \in \{0,1\}$ :

$$\mathcal{L}_{meta}(\mathcal{D}_{meta}, \phi^*(\alpha)) = \sum_{(x,y) \in \mathcal{D}_{meta}} \mathcal{L}_{MSE}(\sigma(\mathcal{A}(\mathcal{V}_{\phi^*(\alpha)}(x, \hat{y}))), r(\hat{y}, y)). \tag{2}$$

This gradient-based update refines instance weights  $\alpha$ , enabling DreamPRM-1.5 to adaptively emphasize needed data examples.

## 2.2 Model Design for Instance-reweighting

**Instance table.** A straightforward way to assign weights at the instance level is to maintain a lookup table, where each training sample x is associated with a learnable weight  $\alpha_x$ . In this formulation,

the number of parameters is equal to the number of training samples. The key advantage of this approach is its ability to fully exploit the potential of each individual example, often yielding strong results even on relatively small datasets (see experiments). To prevent extreme values, we apply a clipping function that constrains all weights within a fixed range; any value outside this interval is automatically projected to its boundary.

**Instance net.** An alternative strategy is to parameterize the instance weight via a lightweight network. Specifically, we append a small MLP after the final layer of the PRM, which dynamically predicts a weight for each input based on its representation. Unlike Instance Table, this approach has a fixed number of parameters regardless of the dataset size (typically far fewer than the number of samples), making it both scalable and generalizable. To ensure stability, we apply a sigmoid activation at the MLP output, keeping the predicted weights within a normalized range.

# 3 Experiments

In this section, we describe the implementation details of DreamPRM-1.5 and present the main experimental results.

### 3.1 Implementation Details

**Model.** We adopt InternVL3-1B [30] as the base model for training the PRM. This state-of-the-art, small-scale multimodal model is pretrained on general vision—language understanding tasks, and we fine-tune it to obtain the final checkpoint. For inference, we use GPT-5-mini [16] as the underlying MLLM. GPT-5-mini is a lightweight variant of the state-of-the-art reasoning model GPT-5, offering a favorable balance between cost efficiency and competitive performance.

**Generative reward model.** We employ a generative reward model to assign scores to individual reasoning steps. Specifically, we adapt the system prompt from VisualPRM [24] (See Appendix A), which instructs the model to output either + or - for each step in the response. The score is then computed as the softmax probability of the + token. A higher probability indicates greater model confidence in the correctness of the step, and thus corresponds to a higher reward score.

**Training and meta datasets.** For training, we construct two datasets. Specifically, we sample 12k examples from VisualPRM-400k [24] to train the Instance Table variant of instance reweighting, and 100k examples from the same source to train the Instance Net variant. We also conduct a rule-based check to ensure there is no overlap between training set and test set.

For the meta set, we adopt MMMU-Pro [29] (standard 4-option split), while excluding its validation split to avoid overlap. We further use GPT-5-mini to generate four candidate responses for each question, forming the meta-evaluation set used for weight updates. There are about 1.2k data points in meta set.

To maintain balance between positive and negative supervision, we filter both the training and meta datasets to ensure an approximately equal number of positive and negative samples.

**Cold-start initialization.** Prior to bi-level optimization, we perform a cold-start fine-tuning stage. Specifically, we sample 20k examples from VisualPRM and conduct one epoch of supervised fine-tuning (SFT). The resulting checkpoint is then used as the initialization for bi-level optimization. This step ensures that the base model learns to follow the system prompt and reliably generate + and – tokens, which are essential for subsequent optimization.

**Multi-turn fine-tuning.** We cast process supervision as a multi-turn dialogue task to better exploit the generative capabilities of MLLMs. Given a multimodal input question x, the first turn includes the question and its initial reasoning step  $\hat{y}_1$ , while each subsequent turn introduces the next step in the reasoning trajectory. This formulation allows the model to incrementally process and evaluate reasoning steps in a conversational manner.

**Aggregation function loss.** Following DreamPRM [2], we adopt an aggregation loss for the meta-learning of the generative reward model. Specifically, we apply a mean aggregation function to

Table 1: MMMU accuracy (%) on leading models and our DreamPRM-1.5 variants. Gray numbers indicate absolute gains over the base GPT-5-mini w/ thinking (80.0).

Category	Model / Method	Accuracy
Leaderboard (external, top-performing models)		
	GPT-5 w/ thinking [16]	84.2
	Gemini 2.5 Pro Deep-Think [18]	84.0
	o3 [15]	82.9
Test-time Scaling (built on GPT-5-mini w/ thinking)		
	Base: GPT-5-mini w/ thinking	80.0
	VanillaPRM — No Selection	79.1 (-0.9)
	Self-consistency [25]	81.4 (+1.4)
	VisualPRM [24]	80.5 (+0.5)
	DreamPRM-1.5 — Instance Table	<b>84.6</b> (+4.6)
	DreamPRM-1.5 — Instance Net	83.6 (+3.6)

average the step-level scores, and optimize the model using the mean squared error (MSE) between the aggregated score and the ground-truth binary label. To encourage the model to generate both + and -, we compute the score from the logit of + when the ground-truth label is positive, and from the logit of - when the ground-truth label is negative.

### 3.2 Main Results

**Benchmark evaluation.** We evaluate the performance of our methods on MMMU validation set [29]. MMMU is a recently introduced benchmark designed to evaluate multimodal models on large-scale, multi-disciplinary tasks that require college-level subject knowledge and deliberate reasoning. It contains carefully curated multimodal questions sourced from college exams, quizzes, and textbooks, spanning six core disciplines: Art & Design, Business, Science, Health & Medicine, Humanities & Social Science, and Tech & Engineering. In total, the benchmark covers 30 subjects across 183 subfields, with questions paired with 30 diverse image types, including charts, diagrams, maps, tables, music scores, and chemical structures.

Table 1 summarizes the results on the MMMU benchmark. We first report the leading proprietary models on the leaderboard, including GPT-5 with thinking, Gemini 2.5 Pro Deep-Think, and o3. Using GPT-5-mini with thinking as our base model (80.0 accuracy), DreamPRM-1.5 significantly improves performance through instance-level reweighting. Both Instance Table and Instance Net variants achieve substantial gains of +4.6 and +3.6, respectively, demonstrating the effectiveness of our approach.

**Baseline comparasion.** We compare DreamPRM-1.5 against several representative baselines built on GPT-5-mini with thinking. The No Selection baseline uses the same subset of data as DreamPRM-1.5 but without bi-level optimization, thus directly reflecting the importance of instance-reweighting. VisualPRM [24] trains a PRM on the same data domains but with the full 400k dataset, which is substantially larger than ours, providing a strong data-scale baseline. Self-consistency [25] is the classical test-time scaling method, widely regarded as a robust baseline for reasoning tasks. As shown in Table 1, all these baselines underperform compared to DreamPRM-1.5. This confirms that data quality imbalance indeed harms PRM training, and further highlights the effectiveness of our instance-reweighted approach, which consistently achieves superior accuracy even with fewer training examples.

# 4 Conclusion

In this paper, we presented DreamPRM-1.5, an instance-reweighted multimodal PRM framework that extends domain-level reweighting in DreamPRM to the level of individual training examples. Through bi-level optimization, DreamPRM-1.5 dynamically learns instance weights that emphasize informative samples while down-weighting noisy or trivial ones. We further explored two complementary implementations—Instance Table and Instance Net—that trade off per-sample expressiveness

and scalability. Extensive experiments on the MMMU benchmark demonstrated that DreamPRM-1.5 significantly improves GPT-5-mini, achieving state-of-the-art performance. Importantly, the PRM itself is trained solely on VisualPRM-400k, with the meta set only used to guide instance reweighting. These findings highlight the effectiveness of fine-grained instance reweighting and open new directions for robust multimodal reasoning.

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# **A** System Prompt for Generative Reward Model.

The Generative Reward Model leverages a system prompt adapted from VisualPRM [24].

You are an advanced AI assistant, designed to serve as a process supervision model. In this task, I will provide a problem statement followed by the first step of the solution process. For each subsequent turn, I will give you a new step in the solution. Your role is to assess whether the solution process is correct up to the current step.— In the \*\*first round\*\*, I will input the problem and the first step of the solution process.— In \*\*each subsequent round\*\*, I will provide the next step in the solution. For each step, you should:— Respond with \*\*+\*\* if you believe the solution process is correct up to this step.— Respond with \*\*-\*\* if you detect any issues or errors in the process up to this step. Please note:— Only respond with \*\*+\*\* or \*\*-\*\*. Do not provide any additional explanations, comments, or justifications. Your task is to verify the accuracy and correctness of each step in the given solution process.

# **B** Hyperparameter Settings.

For the lower-level optimization, we perform one inner gradient step per outer update (*unroll steps* = 1), using the AdamW optimizer [12] with a learning rate of  $5 \times 10^{-5}$  and weight decay of  $10^{-2}$ .

For the upper-level optimization, we also adopt AdamW. In the Instance Table setting, we use a learning rate of  $5 \times 10^{-3}$  with weight decay  $10^{-3}$ ; in the Instance Net setting, we use a learning rate of  $5 \times 10^{-4}$  with weight decay  $10^{-3}$ , and set the hidden dimension of the network to 10.

Both levels employ a cosine learning rate schedule with linear warm-up, where the warm-up phase corresponds to 5% of the total training steps. Overall, DreamPRM-1.5 is fine-tuned for 100,000 iterations. The framework is implemented using Betty [3], and full training requires approximately 72 hours on a single NVIDIA A100 GPU.