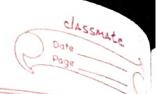
models than with supervised learning.

- use training data to infer model.



- Every input pattern that is used to train the network
- Trying to predict a function from labeled data.

## ii) Unsupervised Learning:

- In unsupervised Learning algorithm desired output is
- It is possible to learn larger and more complex model with unsupervised learning.
- No training data is used.
- The target output is not presented to the network
- Try to detect interesting relations in data.

## Esceptain gradient descent algorithm with suitable exam Quezy ple?

- Gradient descent algorithm is used to minimized the Ans. function.
  - Much of machine learning can be written as an optimi zation problem.
  - Example loss function: Logistic regression, linear regression, principle component analysis, neural network loss.
  - A very efficient way to train logistic model is with stochastic gradient descent (SGD).
  - one challenge with training on power law data (i.e most data) is that the terms in the gradient can have very difficult strengths.
  - The idea behind stochastic gradient descent is iterating a weight updates based on the gradient of loss function :

 $\overline{W}(k+1) = \overline{W}(k) - \Upsilon \nabla L(\overline{W})$ .



- Logistic regression is designed as a binary dassifer (output say {0.13) but octually outputs the probability that the input instance is in the "1" class.
- A logistic classifier has the form:

P(x) = 1  $1 + \exp(-xB)$ 

Where.

Ans.

 $X = (X_1, X_2, X_3, \dots, X_n)$  is a vector of features.

- The process of finding most optimal hyperparameters in machine learning is called hyperparameter optimisation.

Ques) Explain Hebbian Learning / Describe hebbs algorithm.

- In 1949, Donald Hebb proposed one of the key ideas in biological learning, commonly known as Hebb's law.
- Hebb's law states that if neuron i is near enough to excite neuron j and repeately participates in its activation, the synaptic connection between these two neurons is strengthened and neuron; becomes more sensitive to stimuli from neuron i.
- Hebb's law provides the basis for learning without a teacher. Learning here is a local phenomenon occurring without feedback from the environment.

 $\Delta W_{ij}(P) = F[Y_i(P), X_i(P)].$ 

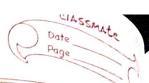
- As a special case, we can represent Hebb's law as follows :-

ΔWij (P) = Q y; (P) X; (P).

Where & is the learning rate parameter. This equation is referred to as the activity product rule.

 $\Delta Wij(P) = \langle Yi(P) Xi(P) - \varphi Yi(P) Wij(P)$ 

. O is forgetting factor.



- Hebbian learning algorithm:
- step1 :- Initialisation .

step1:- Initialisation.

set initial synaptic weights and threshold to small random values, say in an interval [0,1].

- step?:- Activation.

compute the neuron output at iteration p.

where,

n= No. of meuron inputs.

-step 3:- Learning

update the weights in the network.

: w = weight

wij (P) = OYi (P) [ A xi (P) - Wij (P)]

-Step 4:- Iteration.

Increase iteration p by one, go back to step?

Que4)

Ans.

Explain gradient descent algorithm using sigmoid function -A sigmoid function is a mathematical function with

a characteristic "s"-shaped curve or sigmoid cyrve. It transforms any value in the domain (- 0, 0) too

number between o and 1.

- Although the sigmoid function is prevalent in the ant ext of gradient descent, the gradient of the sigmois

function is in some cases problematic. The gradient vanishes to zero for very low and very high input

values, making it hard for some models to improvent

$$e^{-(x)} = 1$$

```
Where,
```

 $\infty$  = Input to the sigmoid function.

e = Euler's number

- The derivative of the sigmoid function is: -

$$\int d = c(x) = c(x) \left(1 - c(x)\right)$$

$$\frac{d}{dx} = \frac{6cx}{dx} = \frac{1}{1 + e^{-x}}$$

$$\frac{d}{dx} \left[ (1 + e^{-x})^{-1} \right]$$

$$\frac{1}{2} d \left[ u^{-1} \right], \quad u = 1 + e^{-2c}.$$

$$= \frac{d}{dx} - u^{-2} du$$

$$= -(1+e^{-x})^{-2} \cdot d \left[ 1+e^{-x} \right]$$

$$=-(1+e^{-x})^{-2}. -e^{-x}$$

$$\frac{-e^{-x}}{(1+e^{-x})^2}$$

$$\frac{-(1+e^{-x})}{(1+e^{-x})} \frac{-e^{-x}}{1+e^{-x}}$$

$$(1+e^{-x})$$
  $1+e^{-x}$ 

$$=\frac{1}{(1+e^{-x})}\cdot\frac{1+e^{-x}}{1+e^{-x}}$$

$$\frac{(1+e^{-x})}{(1+e^{-x})} \frac{1+e^{-x}}{(1+e^{-x})}$$

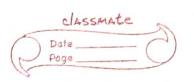
$$= e(x) \cdot (1 - e(x))$$

$$\frac{d}{dx} = \frac{d}{dx} = \frac{d}{dx} \cdot (1 - \epsilon \cos x)$$



Explain From correction in gradient descent rule. - Learning is a process where unknown ANN parame Que 5) - learning is a process
are adapted through continuous process of stimulab Ans: from the environment. from the environment by the way how the change Learning is determined by the way how the change parameters takes place. A set of rules that are solved a learning all to the learning problem is called a learning algorithm - Error correction belongs to the Supervised learning paradigm. outputy Adaptive system Inputx Desi (W) change parameter e = y-d Errore. Training algorithm - Error correction learning -- Error values can be used to update or adjust using algorithm like Feed back or back propagation. : e= T- Y. Where, e = error. T = Threshold. Y = output. - The goal of error-correction learning is to mini an error function derived from error ex (n) so the the obtained output of all neurons approximate the desired output is some statistical sense. - A frequentely used error function is mean

error :-



J = E	1	5	e ?	(n)	7
3	2	K	1		ľ

Where,

E[.] is the statistical expectation operator and summation is for all neurons in the autput layer.

Ques Explain difference between perceptron model and adaline model.

Ans-

_	Side and the second of the sec				
_	Model	perceptron	Adaline.		
	1			-	
	i) Type	Feed Forward.	Feed Forward.	_	
	731 4 3			1	
-	ii) Heuron layers	1 input layer	Many input layer		
		1 output layer	1 output layer.		
$\parallel$			13 2 to 1 to	_	
	iii) Input value types.	Binary input.	Binary input.	_	
#				Ī	
+	iv) learning method.	Hard limiter	Supervised		
-		learning.	learning.		
#				,	
#	v) Learning algorithm.	Hebb learning	Gradient descent		
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	Explain multilayer feedback neural network.			
Que 1)				
Ans.	- A multilayer feedback medical medical, also known a multilayer perceptron (MLP), is a type of artificial neural network with multiple layers of interest			
	a multilayer perception multiple land			
	neural network with multiple layers of interconn			
	neural meterconn nodes or neurons.			
ALC INC.	tunically corisists of an input			
	me or more massing			
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	- Each connection between nodes has a associated			
	weight, and each node applies an activation fund			
	to the weighted sum of its inputs.			
	Hidden layer			
	mque,, engoe			
7	Input output			
	Input#1 layer			
	Input#? output.			
	Input#3			
= = =	Input#4-5			
	Multilayer perceptron model.			
	- The term "feedback" refers to the training process			

- The term "feedback" refers to the training process
where the network learns by adjusting the weights
based on the error between its predicted output
and desired output.

This is often done using backpropagation, where the error is propagated backward through the network, and the weights are updated accordingly to minimize the difference between predicted and actual outputs.

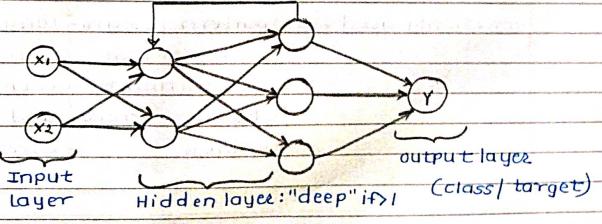


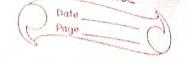
- The hidden layers in a multilayer feedback neural metwork allow for complex representations of features learning, enabling the network to capture intricate potterns in the input data.
- This architecture is widery used in various applications, including image recognition, natural language processing, and many other machine learning tasks.

## Que 8) Explain recurrent neural network

- pns. A recurrent neural network is a type of neural network ork that contains loops, allowing information to be stored within the network.
  - A RNN is particularly useful when a sequences of data is being processed to make a classification decision or regression estimate but it can also be used an non-sequential data.
  - Recurrent neural networks are typically used to solve tasks related to time series data.
  - Applications of recurrent neural network include natural language processing, Speech recognition, machine translation, character-level language modeling, image classification, image captioning, stock prediction, and financial engineering.

Recurrent network.





	- Recurrent neural networks can be thought of as a						
	- Recurrent neural networks to they often ba						
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	complexity	Low	High				
			11111				
	Neuron independence	Yes	No 11 lenn				
	in the same layer.						
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	Opecq	111911	slow				
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		tion, speech	tion, speech-to-				
		recognition f	text conversion,				
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