

# Atharva Ajay Wani, MS

+1 623-206-9103 • Tempe, AZ • aawani@asu.edu • linkedin.com/in/atharva-wani • atharvawani3.github.io/portfolio/

## Education

**Master of Science in Robotics and Autonomous Systems:** Mechanical and Aerospace Engineering May 2024  
• Arizona State University, Tempe, AZ GPA: 3.78/4.00  
• Relevant Coursework: Mechatronics device innovation, Programming of IoT devices, Machine Learning, Wearables.

**Bachelor of Technology Mechanical Engineering:** Machine Design minor Aug 2021  
• Manipal Academy for Higher Education, Manipal, Karnataka, India. GPA: 3.53/4.00

## Skills

**CAD/CAE** SolidWorks, Catia V5 & 3DX, Fusion360, Creo, AutoCAD, ANSYS, Siemens NX.  
**Fabrication/Prototyping** 3D printing (FDM/SLA/SLS), CNC Lathe/Mill, GD&T, Laser Cutter, electric circuits design.  
**Computer Skills** Python, ROS2, Linux, Gazebo, MATLAB/Simulink, XML, Git, Arduino, ESP32, C++, OpenCV.

## Professional Experience

**Teaching Assistant, Massachusetts Institute of Technology Lincoln Laboratory** June 2024 – August 2024  
• Solved electrical design problems in the BWSI Microelectronics Course, enhancing high school students' learning experiences. 100%  
• Developed coursework on Microcontrollers, Sensors, Electro-mechanical Actuators, improving instructional quality. 50%  
• Organized a hackathon for 30+ participants, fostering innovation and practical skills.

**Tech trainee intern, Tesla** Aug 2023 - May 2024  
• Analyzed system communications, performance using advanced diagnostic tools - CAN analyzer and Pico scope, 30%.  
• Reduced diagnostic time by 30% through successful Root Cause Analysis and resolution of hardware, software issues.  
• Applied expertise in electric powertrain design principles and autonomous driving system interactions, 100%.

**Mechanical Design Engineer Intern, ACME process systems pvt. Ltd.** Feb 2021 - Aug 2021  
• Integrated ANSYS for fluid flow simulation in R&D, resulting in a 30% increase in simulation accuracy.  
• Transformed 10 chemical mixer designs into optimized 3D models, improving product design efficiency by 25%.  
• Established streamlined procedures for 3D modeling, fluid dynamics simulation setup, reducing analysis time by 20%.

**Vehicle dynamics engineer, Team Manipal racing** Aug 2018 - May 2019  
• Collaborated in a cross-functional team of 35 students to design a BAJA-SAE vehicle.  
• Utilized iterative design optimization techniques to develop 20% lighter steering knuckles.  
• Played a key role in the fabrication, assembly, and testing of 2 key vehicle components, Steering knuckles, and Suspension linkages, hands-on experience and proficiency in manufacturing processes, and using machine tools, 60%.

## Projects

**Neurological Disability Assistive Technology Wearable Medical Device** Jan 2023 - Present

### Mechanical Engineer, Arizona State University

- Led a team of 6 students in collaborating with doctors at Barrow Neurological Institute, optimizing fitment and ergonomics of electric stimulation pads. Project Management.
- Spearheaded electro-mechanical design, Rapid-prototyping, 3D-Printing responsibilities methods to 3D print electric stimulation pad design prototypes, enhancing user accessibility and ease of operation, 100%.
- Manufactured and assembled the innovative prototype using laser cutting, 3D Printing FDM/SLS with medical grade materials resulting in Best-Project Award and patent application. (US Patent application number: 66/611,833), 100%.

**Collision avoidance system for Autonomous vehicle in ethically challenging situation** Jan 2024 - May 2024  
• Designed MATLAB/Simulink simulations for decision making and collision avoidance algorithms, 100%.  
• Identified autonomous driving scenario that may occur 10-15% more often as number of autonomous vehicles increase.  
• Used Automated Driving toolbox, and Model Predictive Control toolbox, 100%.

**Prosthetic Hand** Jan 2023 - May 2024  
• Designed a realistic 3D printed prosthetic hand with real-time motor control system, sensor fusion integration, 33%.

**Mobile robot with manipulator arm simulation. (ROS2, Gazebo, Moveit2)** Aug 2023 - Dec 2023  
• Created a differential drive robot with simulated arms using ROS2 and Gazebo, 100%.

**Wildlife camera trap with live stream on mobile app. (ESP-32, Arduino IDE, NodeJS, AWS, HTML, CSS)** Aug 2023 - Dec 2023  
• Developed a live feed camera on ESP-32 with version control using GIT, 100%.

## Additional Skills

- Collaborated with doctors in clinical requirements translation, disposable medical equipment design (ASU).
- Hands on experience with fabrication, test equipment, test and validation processes and data analysis (ASU).
- Debugging and analyzing complex electrical circuits in complex autonomous systems (Tesla).
- Worked with data acquisition and digital signal processing using various sensors and sensor fusion (ASU).