A Mini Project Report on

Hand Sign Language Detection using Deep Learning

B.E. - I.T Engineering

Submitted By

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CERTIFICATE

This to certify that the Mini Project report on Intrusion Detection System using PIR sensor and ESP32 Camera has been submitted by <u>Atharv Joshi</u> (19104036), <u>Anjali Singh</u> (20204006) and <u>AbhayPratap Singh</u> (19104037) who are bonafide students of A.P Shah Institute of Technology, Thane, Mumbai, as a partial fulfillment of the requirement for the degree in <u>Information Technology</u>, during the academic year <u>2022-2023</u> in the satisfactory manner as per the curriculum laid down by University of Mumbai.

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Introduction

In this world, there is nothing like equality but all we can do is try and make this place a little bit live-able and bearable. One of the things in our control is how we help other people around us. For this, we should start small but starting is the key for change. Normal human beings do not have much difficulty interacting with each other and can express themselves easily through speech, gestures, body language, reading, writing, speech being widely used among them. Deaf and mute people are perfectly capable of almost every task that a normal human can perform. To bring them on the level of the layman and also give them an opportunity to shine is one of the first steps in making this world an equal place. One of the ways in which they communicate through sign-language. This is something that has to be taught to them from a very young age. This is also something that is very exclusive to them rather a normal person is usually not proficient or even familiar with sign language. At times like these, it is really difficult to find a translator and there is only so much that universal signs can do. Hand signs are an effective form of human-to-human communication that has a number of possible applications.

Purpose

Deaf and mute people cannot communicate in a way that physically abled people can. There are limited ways of communication for the deaf and mute, especially when they are young and/or are not capable of writing things but know sign language. We need a way for them to communicate and try to help them be more sociable. We want to incorporate everyone into our society but it is not possible when there are some physical limitations. The problem comes when the differently abled people have no way to communicate, especially when they are not literate in written language but know sign language. We plan on making a real-time hand sign detection system which will detect and display the Indian sign language on the screen as it is detected.

Objectives

These are the objectives that we hope to satisfy:

- 1. To detect hand sign language and display the letter on the screen. This will help a person who does not know how to sign to see what the deaf and mute person is trying to convey through the sign language.
- 2. To make use of leading machine learning algorithms to detect and recognize hand signs. This will be done through the use of CNN for building, training and testing the model which is faster and more efficient.
- 3. To teach young children how to sign and evaluate by checking their form. Children who want to learn how to sign can check their form against this model to check how they perform.

4. To use this anytime, anywhere. This will be done with the help of cloud hosting the model. Thus, it will give us the ability to use the same model for multiple devices/modules.

Scope

Communication through signs has consistently been a significant way for communication among hearing and speech impaired humans, generally called deaf and dumb. It is the only mode of communicating for such individuals to pass on their messages to other human beings, and hence other humans need to comprehend their language. In this project, sign language detection or recognition web framework is proposed with the help of image processing. This application would help in recognizing Sign Language. The dataset used is the Indian Sign Language dataset. This application could be used in schools or any place, which would make the communication process easier between the impaired and non-impaired people. The proposed method can be used for the ease of recognition of sign language. The method used is Deep Learning for image recognition and the data is trained using Convolution Neural Network. Using this method, we would recognize the gesture and predict which sign is shown on the system.

Review of Literature

Sr. No	Research Paper	Finding from Paper
1.	Indian Sign Language recognition system using SURF with SVM and CNN.	We learned that sign language can be recognized using a webcam and different types of algorithms. For e.g., SVM - Support Vector Machine, CNN- Convolutional Neural Network and their accuracy while detecting objects on the webcam.
3.	Sign Language Recognition Based on Machine Learning	This work showed us how machine learning can be applied in the process of Sign Language Recognition. This study proposed an online use of gesture-based communication acknowledgment utilizing American Sign Language (ASL). The proposed online application will assist with eliminating the correspondence hole by being an instructional exercise to learn and figure out the gesture-based communication. In this, we have utilized a dataset of 57,000 pictures for both testing and preparing. Calculations, for example, Na ive Bayes calculation, Support Vector Machine (SVM), k-Nearest Neighbors (KNN) and Convolutional Neural Network (CNN) are utilized for preparing the dataset and acquiring results.

3.	Real-Time Hand Detection using Convolutional Neural Networks for Costa Rican Sign Language Recognition	Used a video dataset to train their model and use it to detect the sign language in real-time. From this work we learned how to implement our hand sign language detection in real-time.
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Problem Definition

People affected by speech impairment rely only on sign language, which makes it more difficult for them to communicate with the remainder of the majority. This implies a requirement for sign language recognition system which can recognize and convert sign language into spoken or written language and vice versa. Such identifiers, however, are limited, costly, and cumbersome to use [1]. The problem statement goes as follows:" User wants to use sign language to converse with a deaf and mute person but the user is not familiar with the sign language." Proposed Solution: The solution we propose is making a real time hand sign language detection Software using CNN for training and testing the Model created.

Proposed System

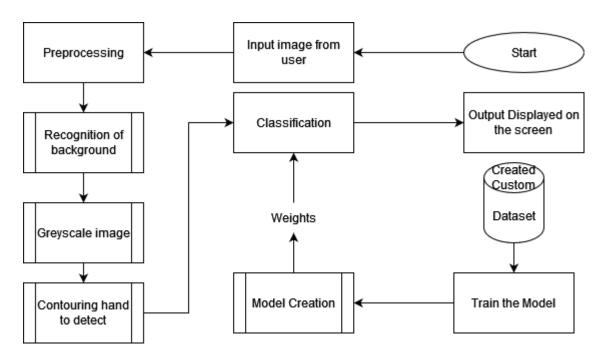


Fig. Proposed system architecture

Features and Functionality:

- 1. Hand sign language and display the letter on the screen
- 2. Real time detection of the alphabets.
- 3. Background interference is removed.

Chapter 5 Software Requirements

Python:

The libraries used in python are:

- OpenCV
- Mediapipe
- Tensorflow
- Keras
- Numpy
- Matplotlib

Implementation

Creation of Dataset:

```
import cv2
import numpy as np
background = None
accumulated_weight = 0.5
ROI top = 100
ROI bottom = 300
ROI right = 150
ROI left = 350
def cal accum avg(frame, accumulated weight):
  global background
  if background is None:
    background = frame.copy().astype("float")
    return None
  cv2.accumulateWeighted(frame, background, accumulated weight)
def segment hand(frame, threshold=25):
  global background
  diff = cv2.absdiff(background.astype("uint8"), frame)
  _, thresholded = cv2.threshold(diff, threshold, 255, cv2.THRESH_BINARY)
  # Grab the external contours for the image
  contours, hierarchy = cv2.findContours(thresholded.copy(), cv2.RETR EXTERNAL,
cv2.CHAIN_APPROX_SIMPLE)
  if len(contours) == 0:
    return None
    hand segment max cont = max(contours, key=cv2.contourArea)
    return (thresholded, hand segment max cont)
```

```
cam = cv2.VideoCapture(0)
num frames = 0
element = "a"
num imgs taken = 0
while True:
  ret, frame = cam.read()
  # filpping the frame to prevent inverted image of captured frame...
  frame = cv2.flip(frame, 1)
  frame copy = frame.copy()
  roi = frame[ROI top:ROI bottom, ROI right:ROI left]
  gray frame = cv2.cvtColor(roi, cv2.COLOR BGR2GRAY)
  gray frame = cv2.GaussianBlur(gray frame, (9, 9), 0)
  if num frames < 60:
    cal accum avg(gray frame, accumulated weight)
    if num frames <= 59:
      cv2.putText(frame copy, "FETCHING BACKGROUND...PLEASE WAIT", (80, 400),
ev2.FONT HERSHEY SIMPLEX, 0.9, (0,0,255), 2)
  elif num frames <= 300:
    hand = segment hand(gray frame)
    cv2.putText(frame copy, "Adjust hand...Gesture for" + str(element), (200, 400),
ev2.FONT HERSHEY SIMPLEX, 1, (0,0,255), 2)
    # Checking if hand is actually detected by counting number of contours detected...
    if hand is not None:
      thresholded, hand segment = hand
      ev2.drawContours(frame copy, [hand segment + (ROI right, ROI top)], -1, (255, 0, 0),1)
      cv2.putText(frame copy, str(num frames)+"For" + str(element), (70, 45),
ev2.FONT_HERSHEY_SIMPLEX, 1, (0,0,255), 2)
      # Also display the thresholded image
```

```
cv2.imshow("Thresholded Hand Image", thresholded)
    # Segmenting the hand region...
    hand = segment hand(gray frame)
    # Checking if we are able to detect the hand...
    if hand is not None:
      # unpack the thresholded img and the max contour...
      thresholded, hand segment = hand
      # Drawing contours around hand segment
      ev2.drawContours(frame copy, [hand segment + (ROI right, ROI top)], -1, (255, 0, 0),1)
      cv2.putText(frame copy, str(num frames), (70, 45), cv2.FONT HERSHEY SIMPLEX, 1,
(0,0,255), 2)
cv2.FONT HERSHEY SIMPLEX, 1, (0,0,255), 2)
      cv2.putText(frame copy, str(num imgs taken) + 'images' + "For" + str(element), (200, 400),
ev2.FONT HERSHEY SIMPLEX, 1, (0,0,255), 2)
      # Displaying the thresholded image
      cv2.imshow("Thresholded Hand Image", thresholded)
      if num imgs taken <= 300:
         cv2.imwrite(r"C:\\gesture\\train\\"+str(element)+"\\" + str(num imgs taken+300) + '.jpg',
thresholded)
         print("Yess")
         # cv2.imwrite(r"C:\\gesture\\x"+"\\" + str(num imgs taken) + '.jpg', thresholded)
      else:
         break
      num imgs taken +=1
      cv2.putText(frame copy, 'No hand detected...', (200, 400), cv2.FONT HERSHEY SIMPLEX,
1, (0,0,255), 2)
  # Drawing ROI on frame copy
  cv2.rectangle(frame copy, (ROI left, ROI top), (ROI right, ROI bottom), (255,128,0), 3)
  cv2.putText(frame_copy, "DataFlair hand sign recognition_ _ ", (10, 20), cv2.FONT_ITALIC, 0.5,
(51,255,51), 1)
  num frames += 1
  # Display the frame with segmented hand
```

```
cv2.imshow("Sign Detection", frame_copy)
  k = cv2.waitKey(1) & 0xFF
  if k == 27:
    break
cv2.destroyAllWindows()
cam.release()
```

Training of CNN

```
import tensorflow as tf
from tensorflow import keras
from keras.models import Sequential
from keras.layers import Activation, Dense, Flatten, BatchNormalization, Conv2D, MaxPool2D,
Dropout
from keras.optimizers import Adam, SGD
from keras.metrics import categorical crossentropy
from keras.preprocessing.image import ImageDataGenerator
import itertools
import random
import warnings
import numpy as np
import cv2
from keras.callbacks import ReduceLROnPlateau
from keras.callbacks import ModelCheckpoint, EarlyStopping
from matplotlib import pyplot as plt
warnings.simplefilter(action='ignore', category=FutureWarning)
train path = r'C:\Users\athar\Downloads\dataset/Train'
test path = r'C:\Users\athar\Downloads\dataset/Test'
train batches =
ImageDataGenerator(preprocessing function=tf.keras.applications.vgg16.preprocess input).flow from
directory(directory=train path, target size=(64,64), class mode='categorical',
batch size=10,shuffle=True)
test batches =
ImageDataGenerator(preprocessing function=tf.keras.applications.vgg16.preprocess input).flow from
directory(directory=test path, target size=(64,64), class mode='categorical', batch size=10,
shuffle=True)
imgs, labels = next(train batches)
```

```
#Plotting the images...
def plotImages(images arr):
  fig, axes = plt.subplots(1, 10, figsize=(30,20))
  axes = axes.flatten()
  for img, ax in zip( images arr, axes):
     img = cv2.cvtColor(img, cv2.COLOR BGR2RGB)
     ax.imshow(img)
     ax.axis('off')
  plt.tight layout()
  plt.show()
plotImages(imgs)
print(imgs.shape)
print(labels)
model = Sequential()
model.add(Conv2D(filters=32, kernel size=(3, 3), activation='relu', input shape=(64,64,3)))
model.add(MaxPool2D(pool size=(2, 2),
strides=2))
model.add(Conv2D(filters=64, kernel size=(3, 3), activation='relu', padding = 'same'))
model.add(MaxPool2D(pool size=(2, 2), strides=2))
model.add(Conv2D(filters=128, kernel size=(3, 3), activation='relu', padding = 'valid'))
model.add(MaxPool2D(pool size=(2, 2), strides=2))
model.add(Flatten())
model.add(Dense(64,activation ="relu"))
model.add(Dense(128,activation ="relu"))
model.add(Dense(128,activation ="relu"))
#model.add(Dropout(0.3))
model.add(Dense(35,activation ="softmax"))
model.compile(optimizer=Adam(learning rate=0.001), loss='categorical crossentropy',
metrics=['accuracy'])
reduce lr = ReduceLROnPlateau(monitor='val loss', factor=0.2, patience=1, min lr=0.0001)
early stop = EarlyStopping(monitor='val loss', min delta=0, patience=2, verbose=0, mode='auto')
```

```
model.compile(optimizer=SGD(learning rate=0.001), loss='categorical crossentropy',
metrics=['accuracy'])
reduce lr = ReduceLROnPlateau(monitor='val loss', factor=0.2, patience=1, min lr=0.0005)
early stop = EarlyStopping(monitor='val loss', min delta=0, patience=2, verbose=0, mode='auto')
history2 = model.fit generator(train batches, epochs=25, callbacks=[reduce lr, early stop],
validation data = test batches)#, checkpoint])
imgs, labels = next(train batches) # For getting next batch of imgs...
imgs, labels = next(test batches) # For getting next batch of imgs...
scores = model.evaluate(imgs, labels, verbose=0)
print(f {model.metrics names[0]} of {scores[0]}; {model.metrics names[1]} of {scores[1]*100}%')
#model.save('best model dataflair.h5')
model.save('best model dataflair1.h5')
print(history2.history)
imgs, labels = next(test_batches)
model = keras.models.load model(r"best model dataflair1.h5")
scores = model.evaluate(imgs, labels, verbose=0)
print(f'{model.metrics names[0]} of {scores[0]}; {model.metrics names[1]} of {scores[1]*100}%')
model.summary()
scores #[loss, accuracy] on test data...
model.metrics names
word dict = {0:'One', 1:'Two', 2:'Three', 3:'Four', 4:'Five', 5:'Six', 6:'Seven', 7:'Eight', 8:'Nine', 9:'A',
10:'B', 11: 'C', 12:'D', 13:'E', 14:'F', 15:'G', 16:'H',
  17:'I', 18:'J', 19:'K', 20:'L', 21:'M', 22:'N', 23:'O', 24:'P', 25:'Q', 26:'R', 27:'S', 28:'T', 29:'U', 30:'V',
31:'W', 32:'X', 33:'Y', 34:'Z'}
predictions = model.predict(imgs, verbose=0)
print("predictions on a small set of test data--")
print("")
for ind, i in enumerate(predictions):
  print(word dict[np.argmax(i)], end=' ')
plotImages(imgs)
print('Actual labels')
for i in labels:
```

```
print(word_dict[np.argmax(i)], end=' ')
print(imgs.shape)
history2.history
```

Testing with live Data

```
import numpy as np
import cv2
import keras
from keras.preprocessing.image import ImageDataGenerator
import tensorflow as tf
import urllib.request
model = keras.models.load model(r"best model dataflair1.h5")
word dict = {0:'One', 1:'Two', 2:'Three', 3:'Four', 4:'Five', 5:'Six', 6:'Seven', 7:'Eight', 8:'Nine', 9:'A',
10:'B', 11: 'C', 12:'D', 13:'E', 14:'F', 15:'G', 16:'H',
  17:'I', 18:'J', 19:'K', 20:'L', 21:'M', 22:'N', 23:'O', 24:'P', 25:'Q', 26:'R', 27:'S', 28:'T', 29:'U', 30:'V',
31:'W', 32:'X', 33:'Y', 34:'Z'}
background = None
accumulated weight = 0.5
ROI top = 100
ROI bottom = 300
ROI right = 150
ROI left = 350
def cal accum avg(frame, accumulated weight):
  global background
  if background is None:
     background = frame.copy().astype("float")
     return None
  cv2.accumulateWeighted(frame, background, accumulated weight)
def segment hand(frame, threshold=25):
  global background
  diff = cv2.absdiff(background.astype("uint8"), frame)
```

```
, thresholded = cv2.threshold(diff, threshold, 255, cv2.THRESH_BINARY)
  contours, hierarchy = cv2.findContours(thresholded.copy(), cv2.RETR EXTERNAL,
cv2.CHAIN APPROX SIMPLE)
 if len(contours) == 0:
    return None
 else:
    # The largest external contour should be the hand
    hand segment max cont = max(contours, key=cv2.contourArea)
    # Returning the hand segment(max contour) and the thresholded image of hand...
    return (thresholded, hand segment max cont)
\#cam = cv2.VideoCapture(0)
url='http://192.168.231.185/cam-hi.jpg'
num frames =0
while True:
  img resp=urllib.request.urlopen(url)
 imgnp=np.array(bytearray(img resp.read()),dtype=np.uint8)
  frame=cv2.imdecode(imgnp,-1)
  # filpping the frame to prevent inverted image of captured frame...
  frame = cv2.flip(frame, 1)
  frame copy = frame.copy()
 # ROI from the frame
  roi = frame[ROI top:ROI bottom, ROI right:ROI left]
  gray frame = cv2.cvtColor(roi, cv2.COLOR BGR2GRAY)
  gray frame = cv2.GaussianBlur(gray frame, (9, 9), 0)
  if num frames < 70:
    cal accum avg(gray frame, accumulated weight)
```

```
cv2.putText(frame copy, "FETCHING BACKGROUND...PLEASE WAIT", (80, 400),
ev2.FONT HERSHEY SIMPLEX, 0.9, (0,0,255), 2)
 else:
    # segmenting the hand region
    hand = segment hand(gray frame)
    # Checking if we are able to detect the hand...
    if hand is not None:
      thresholded, hand segment = hand
      # Drawing contours around hand segment
      ev2.drawContours(frame copy, [hand segment + (ROI right, ROI top)], -1, (255, 0, 0),1)
      cv2.imshow("The sholded Hand Image", thresholded)
      thresholded = cv2.resize(thresholded, (64, 64))
      thresholded = cv2.cvtColor(thresholded, cv2.COLOR GRAY2RGB)
      thresholded = np.reshape(thresholded, (1,thresholded.shape[0],thresholded.shape[1],3))
      pred = model.predict(thresholded)
      cv2.putText(frame copy, word dict[np.argmax(pred)], (170, 45),
ev2.FONT HERSHEY SIMPLEX, 1, (0,0,255), 2)
 # Draw ROI on frame copy
 ev2.rectangle(frame copy, (ROI left, ROI top), (ROI right, ROI bottom), (255,128,0), 3)
 # incrementing the number of frames for tracking
 num frames += 1
 cv2.putText(frame copy, "DataFlair hand sign recognition", (10, 20), cv2.FONT ITALIC, 0.5,
(51,255,51), 1)
 cv2.imshow("Sign Detection", frame copy)
 # Close windows with Esc
 k = cv2.waitKey(1) & 0xFF
 if k == 27:
    break
cv2.destroyAllWindows()
```

Result

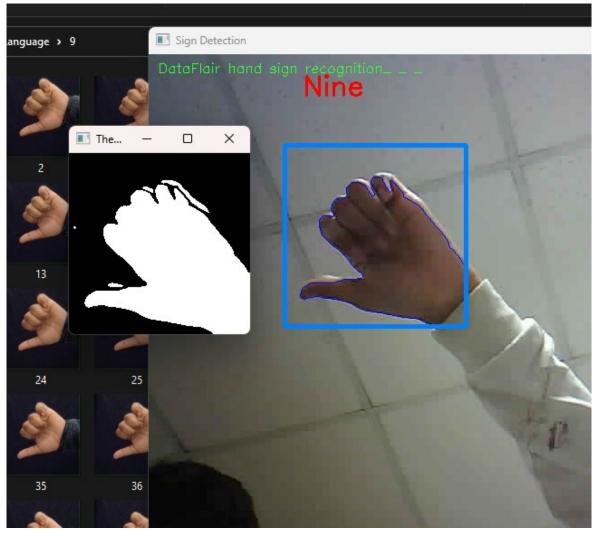


Fig. Nine

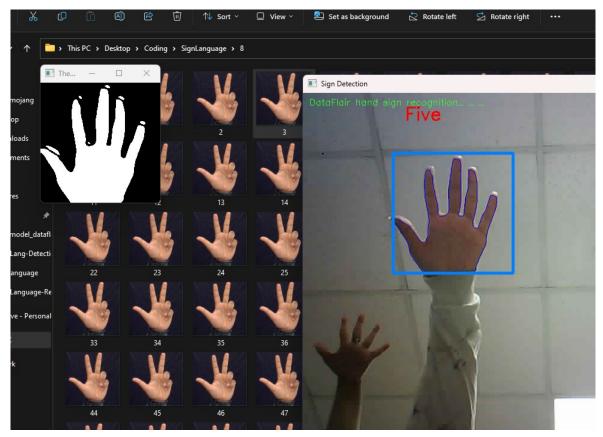


Fig. Five is displayed

Conclusion

The ESP 32 camera is used to detect the image. It is programmed and then powered by NodeMCU (esp8266). A CNN model in the backend which is made in python is used to detect and recognize the image and the detected character is displayed on the screen.

Future Scope

The system can be used in hospitals and a portable model can be made. It can also be trained with different sign languages and even more phrases can be added to make it more efficient and usable.

References

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