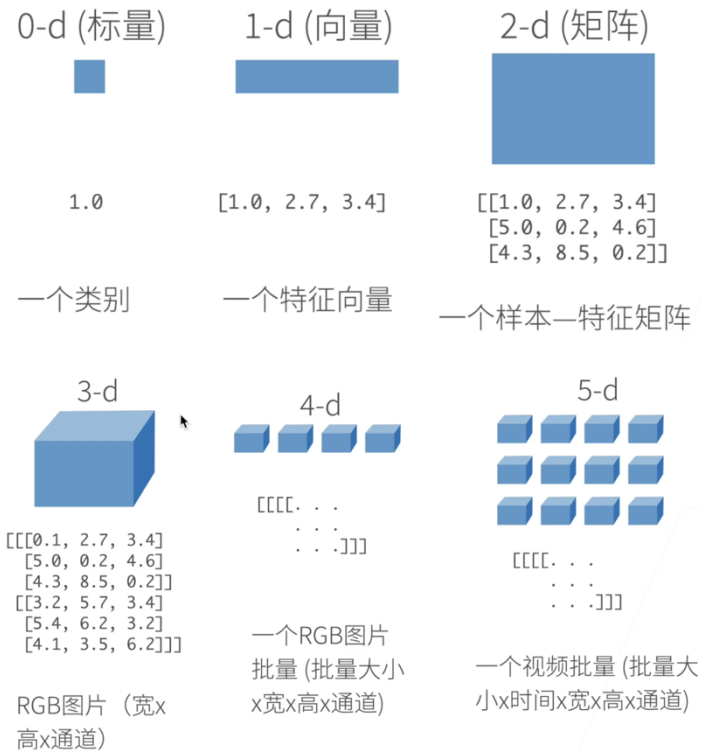


# 深度学习基础

## # 数据操作和数据预处理

### 1. N 维数组样例

- N 维数组是机器学习和神经网络的主要数据结构



### 2. 访问元素

- 一个元素: `[1, 2]`

	0	1	2	3
0	1	2	3	4
1	5	6	7	8
2	9	10	11	12
3	13	14	15	16

- 一行: `[1, :]`

	0	1	2	3
0	1	2	3	4
1	5	6	7	8
2	9	10	11	12
3	13	14	15	16

- 一列: `[:, 1]`

	0	1	2	3
0	1	2	3	4
1	5	6	7	8
2	9	10	11	12
3	13	14	15	16

- 子区域: `[1:3, 1:]`

	0	1	2	3
0	1	2	3	4
1	5	6	7	8
2	9	10	11	12
3	13	14	15	16

- 子区域: `::3, ::2]`

	0	1	2	3
0	1	2	3	4
1	5	6	7	8
2	9	10	11	12
3	13	14	15	16

## # 导数

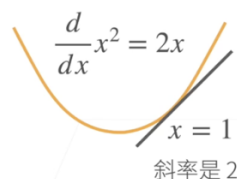
### 1. 标量导数:

$y$	$a$	$x^n$	$\exp(x)$	$\log(x)$	$\sin(x)$
$\frac{dy}{dx}$	0	$nx^{n-1}$	$\exp(x)$	$\frac{1}{x}$	$\cos(x)$

$a$  不是  $x$  的函数

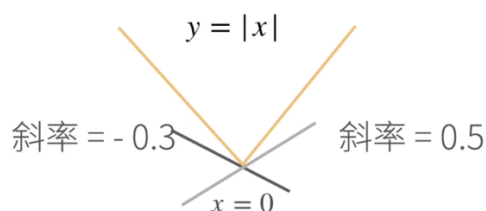
导数是切线的斜率

$y$	$u+v$	$uv$	$y=f(u), u=g(x)$
$\frac{dy}{dx}$	$\frac{du}{dx} + \frac{dv}{dx}$	$\frac{du}{dx}v + \frac{dv}{dx}u$	$\frac{dy}{du} \frac{du}{dx}$



### 2. 亚导数:

- 将导数拓展到不可微的函数



另一个例子

$$\frac{\partial |x|}{\partial x} = \begin{cases} 1 & \text{if } x > 0 \\ -1 & \text{if } x < 0 \\ a & \text{if } x = 0, a \in [-1, 1] \end{cases}$$

$$\frac{\partial}{\partial x} \max(x, 0) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{if } x < 0 \\ a & \text{if } x = 0, a \in [0, 1] \end{cases}$$

### 3. 梯度:

- 将导数拓展到向量

		标量	向量
		$x$	$\mathbf{x}$
标量	$y$	$\frac{\partial y}{\partial x}$	$\frac{\partial y}{\partial \mathbf{x}}$
向量	$\mathbf{y}$	$\frac{\partial \mathbf{y}}{\partial x}$	$\frac{\partial \mathbf{y}}{\partial \mathbf{x}}$

注:  $\mathbf{x}, \mathbf{y}$  均为向量, 则输出为矩阵(右下角)

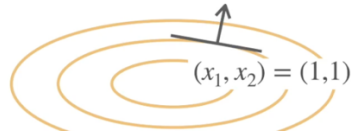
#### 3.1 $\mathbf{x}$ 为向量

- 下图中, 点 (1, 1) 处的梯度即为方向 (2, 4), 与等高线正交, 意味着梯度指向的是值变化最大的方向。

$\partial y / \partial \mathbf{x}$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \frac{\partial y}{\partial \mathbf{x}} = \left[ \frac{\partial y}{\partial x_1}, \frac{\partial y}{\partial x_2}, \dots, \frac{\partial y}{\partial x_n} \right]$$

$$\frac{\partial}{\partial \mathbf{x}} x_1^2 + 2x_2^2 = [2x_1, 4x_2] \quad \text{方向 } (2, 4) \text{ 跟等高线正交}$$



• 样例:

$y$	$a$	$au$	$\text{sum}(\mathbf{x})$	$\ \mathbf{x}\ ^2$	$a$ is not a function of $\mathbf{x}$
$\frac{\partial y}{\partial \mathbf{x}}$	$\mathbf{0}^T$	$a \frac{\partial u}{\partial \mathbf{x}}$	$\mathbf{1}^T$	$2\mathbf{x}^T$	$\mathbf{0}$ and $\mathbf{1}$ are vectors

$y$	$u + v$	$uv$	$\langle \mathbf{u}, \mathbf{v} \rangle$
$\frac{\partial y}{\partial \mathbf{x}}$	$\frac{\partial u}{\partial \mathbf{x}} + \frac{\partial v}{\partial \mathbf{x}}$	$\frac{\partial u}{\partial \mathbf{x}} v + \frac{\partial v}{\partial \mathbf{x}} u$	$\mathbf{u}^T \frac{\partial \mathbf{v}}{\partial \mathbf{x}} + \mathbf{v}^T \frac{\partial \mathbf{u}}{\partial \mathbf{x}}$

### 3.2 $\mathbf{y}$ 为向量

$\partial \mathbf{y} / \partial x$

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \quad \frac{\partial \mathbf{y}}{\partial x} = \begin{bmatrix} \frac{\partial y_1}{\partial x} \\ \frac{\partial y_2}{\partial x} \\ \vdots \\ \frac{\partial y_m}{\partial x} \end{bmatrix}$$

$\partial y / \partial \mathbf{x}$  是行向量,  $\partial \mathbf{y} / \partial x$  是列向量

这个被称之为分子布局符号, 反过来的版本叫分母布局符号

3.3 x,y 均为向量

$\partial \mathbf{y} / \partial \mathbf{x}$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

$$\frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial y_1}{\partial \mathbf{x}} \\ \frac{\partial y_2}{\partial \mathbf{x}} \\ \vdots \\ \frac{\partial y_m}{\partial \mathbf{x}} \end{bmatrix} = \begin{bmatrix} \frac{\partial y_1}{\partial x_1}, \frac{\partial y_1}{\partial x_2}, \dots, \frac{\partial y_1}{\partial x_n} \\ \frac{\partial y_2}{\partial x_1}, \frac{\partial y_2}{\partial x_2}, \dots, \frac{\partial y_2}{\partial x_n} \\ \vdots \\ \frac{\partial y_m}{\partial x_1}, \frac{\partial y_m}{\partial x_2}, \dots, \frac{\partial y_m}{\partial x_n} \end{bmatrix}$$

• 样例:

$\mathbf{y}$	$\mathbf{a}$	$\mathbf{x}$	$\mathbf{Ax}$	$\mathbf{x}^T \mathbf{A}$
$\frac{\partial \mathbf{y}}{\partial \mathbf{x}}$	$\mathbf{0}$	$\mathbf{I}$	$\mathbf{A}$	$\mathbf{A}^T$

$\mathbf{y}$	$a\mathbf{u}$	$\mathbf{Au}$	$\mathbf{u} + \mathbf{v}$	$\mathbf{x} \in \mathbb{R}^n, \quad \mathbf{y} \in \mathbb{R}^m, \quad \frac{\partial \mathbf{y}}{\partial \mathbf{x}} \in \mathbb{R}^{m \times n}$
$\frac{\partial \mathbf{y}}{\partial \mathbf{x}}$	$a \frac{\partial \mathbf{u}}{\partial \mathbf{x}}$	$\mathbf{A} \frac{\partial \mathbf{u}}{\partial \mathbf{x}}$	$\frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \frac{\partial \mathbf{v}}{\partial \mathbf{x}}$	$a, \mathbf{a}$ and $\mathbf{A}$ are not functions of $\mathbf{x}$ $\mathbf{0}$ and $\mathbf{I}$ are matrices

3.4 拓展到矩阵

## # 自动求导

### 1. 向量链式法则

- 标量链式法则

$$y = f(u), u = g(x) \quad \frac{\partial y}{\partial x} = \frac{\partial y}{\partial u} \frac{\partial u}{\partial x}$$

- 拓展到向量

$$\begin{array}{ccc} \frac{\partial y}{\partial \mathbf{x}} = \frac{\partial y}{\partial u} \frac{\partial u}{\partial \mathbf{x}} & \frac{\partial y}{\partial \mathbf{x}} = \frac{\partial y}{\partial \mathbf{u}} \frac{\partial \mathbf{u}}{\partial \mathbf{x}} & \frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \frac{\partial \mathbf{y}}{\partial \mathbf{u}} \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \\ (1,n) \quad (1,) \quad (1,n) & (1,n) \quad (1,k) \quad (k,n) & (m,n) \quad (m,k) \quad (k,n) \end{array}$$

#### 1.1 例 1

假设  $\mathbf{x}, \mathbf{w} \in \mathbb{R}^n, y \in \mathbb{R}$

$$z = (\langle \mathbf{x}, \mathbf{w} \rangle - y)^2$$

计算  $\frac{\partial z}{\partial \mathbf{w}}$

$$\frac{\partial z}{\partial \mathbf{w}} = \frac{\partial z}{\partial b} \frac{\partial b}{\partial a} \frac{\partial a}{\partial \mathbf{w}}$$

分解  $a = \langle \mathbf{x}, \mathbf{w} \rangle$   
 $b = a - y$   
 $z = b^2$

$$\begin{aligned} &= \frac{\partial b^2}{\partial b} \frac{\partial a - y}{\partial a} \frac{\partial \langle \mathbf{x}, \mathbf{w} \rangle}{\partial \mathbf{w}} \\ &= 2b \cdot 1 \cdot \mathbf{x}^T \\ &= 2(\langle \mathbf{x}, \mathbf{w} \rangle - y) \mathbf{x}^T \end{aligned}$$

#### 1.2 例 2

假设  $\mathbf{X} \in \mathbb{R}^{m \times n}, \mathbf{w} \in \mathbb{R}^n, \mathbf{y} \in \mathbb{R}^m$

$$z = \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2$$

计算  $\frac{\partial z}{\partial \mathbf{w}}$

$$\frac{\partial z}{\partial \mathbf{w}} = \frac{\partial z}{\partial \mathbf{b}} \frac{\partial \mathbf{b}}{\partial \mathbf{a}} \frac{\partial \mathbf{a}}{\partial \mathbf{w}}$$

分解  $\mathbf{a} = \mathbf{X}\mathbf{w}$   
 $\mathbf{b} = \mathbf{a} - \mathbf{y}$   
 $z = \|\mathbf{b}\|^2$

$$\begin{aligned} &= \frac{\partial \|\mathbf{b}\|^2}{\partial \mathbf{b}} \frac{\partial \mathbf{a} - \mathbf{y}}{\partial \mathbf{a}} \frac{\partial \mathbf{X}\mathbf{w}}{\partial \mathbf{w}} \\ &= 2\mathbf{b}^T \times \mathbf{I} \times \mathbf{X} \\ &= 2(\mathbf{X}\mathbf{w} - \mathbf{y})^T \mathbf{X} \end{aligned}$$

## 2. 自动求导

- 自动求导计算一个函数在指定值上的导数
- 它有区别于

- 符号求导

```
In[1]:= D[4 x^3 + x^2 + 3, x]
```

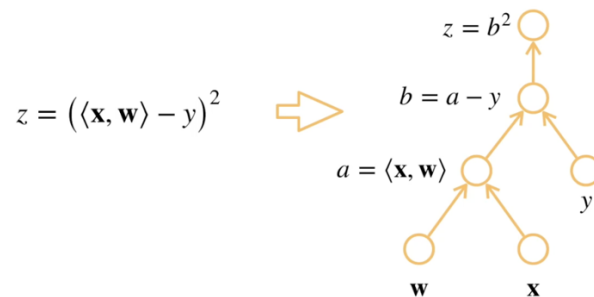
```
Out[1]= 2 x + 12 x^2
```

- 数值求导

$$\frac{\partial f(x)}{\partial x} = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

## 2.1 计算图

- 将代码分解成操作子
- 将计算表示成一个无环图



- 显式构造

Tensorflow/Theano/MXNet

```
from mxnet import sym

a = sym.var()
b = sym.var()
c = 2 * a + b
# bind data into a and b later
```

- 隐式构造

PyTorch/MXNet

```
from mxnet import autograd, nd

with autograd.record():
    a = nd.ones((2,1))
    b = nd.ones((2,1))
    c = 2 * a + b
```

## 3. 自动求导的两种模式

- 链式法则

$$\frac{\partial y}{\partial x} = \frac{\partial y}{\partial u_n} \frac{\partial u_n}{\partial u_{n-1}} \dots \frac{\partial u_2}{\partial u_1} \frac{\partial u_1}{\partial x}$$

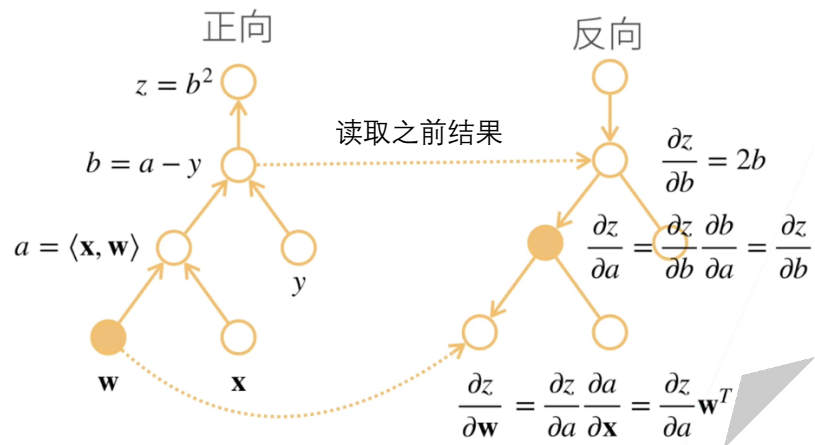
- 正向累积

$$\frac{\partial y}{\partial x} = \frac{\partial y}{\partial u_n} \left( \frac{\partial u_n}{\partial u_{n-1}} \left( \dots \left( \frac{\partial u_2}{\partial u_1} \frac{\partial u_1}{\partial x} \right) \right) \right)$$

- 反向累积/反向传递

$$\frac{\partial y}{\partial x} = \left( \left( \left( \frac{\partial y}{\partial u_n} \frac{\partial u_n}{\partial u_{n-1}} \right) \dots \right) \frac{\partial u_2}{\partial u_1} \right) \frac{\partial u_1}{\partial x}$$

$$z = (\langle \mathbf{x}, \mathbf{w} \rangle - y)^2$$



- 反向累积总结

- 构造计算图
- 前向: 执行图, 存储中间结果
- 反向: 从相反方向执行图  
去除不需要的枝



- 反向累积复杂度

- 计算复杂度:  $O(n)$ ,  $n$  表示操作子个数  
通常正向和反向的代价类似
- 内存复杂度:  $O(n)$ , 因为需要存储正向的所有中间结果
- 相比之下, 正向累积:
  - $O(n)$  计算复杂度用来计算一个变量的梯度
  - $O(1)$  内存复杂度