

# CHEUNG Hiu Ching, Athena Master of Philosophy Aeronautical and Aviation Engineering The Hong Kong Polytechnic University

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#### **EDUCATION**

• The Hong Kong Polytechnic University (HKPolyU)

2022-now

Master of Philosophy majoring in Flight Mechanics and Control (Passed Confirmation of Registration)

CGPA: 3.48/4.30

- Thesis title: Design and Control of a Soft Aerial Vehicle for Conducting Aerial Grasping
- Supervised by Prof. Chih-yung WEN (AAE) and co-supervised by Dr Henry K. CHU (ME)

• The Hong Kong Polytechnic University

2018-2022

Bachelor of Engineering (Honours) in Mechanical Engineering

GPA: 3.50/4.30

- Dean list (2019/2020)
- Computer Programming (C++): A+; Engineering Management: A; Engineering Design: A

#### Publication

• C.-W. Chang, L.-Y. Lo, **H. C. Cheung**, Y. Feng, A.-S. Yang, C.-Y. Wen, and W. Zhou, "Proactive guidance for accurate uav landing on a dynamic platform: A visual–inertial approach," *Sensors*, vol. 22, no. 1, p. 404, 2022.

#### AWARDS AND SCHOLARSHIP

• HKSAR Government Scholarship Fund - Endeavour Merit Award

2018/19 - 2022/23

- The Hong Kong Jockey Club Scholarships Undergraduate Scholarship
- The Hong Kong Jockey Club

2019/20 - 2021/22

- BEA Inspiring Student Scholarship
- -Bank of East Asia

2019/20

- Best Engineering Design Award The Robocon 2019 Hong Kong Contest
- Hong Kong Science and Technology Parks Corporation

2019

HKSAR Government Scholarship Fund - Talent Development Scholarship

2018/19 -2019/20

- Two Champion; Four 1st Runner-up; Three 2nd Runner-up International Robotic Olympic 2017
- Hong Kong Robotic Olympic Association

2017

- (Senior Group) Second Prize; Best Design Award Fun Science Competition 2017 "Stay right there"
- Hong Kong Science Museum

2017

- Hong Kong Top 10 Outstanding Teens Award Hong Kong Outstanding Teens Election
- Hong Kong Playground Association

2016

#### WORK EXPERIENCE

#### • The Hong Kong Polytechnic University

 $May\ 2023\ \text{-}\ now$ 

Project Technical Assistant (Part-time) | Supervisor: Prof. Chih-yung WEN

 $\mathrm{MAV}/\mathrm{UAV}$  Laboratory

- Has associated with the research project "Research Centre for Unmanned Autonomous Systems" (1-CE55)
- Providing technical support for 3D printing
- Providing technical support for mechatronics design

# • Hong Kong Center for Construction Robotics

Jan 2023 - Jun 2023

Research Assistant (Part-time)

- Provided technical support for 3D printing
- Designed the mechanical structure of products and drawing the 3D CAD drawings

# • The Hong Kong Polytechnic University

 $Sep\ 2022$  -  $May\ 2023$ 

Project Assistant (Part-time) | Supervisor: Prof. Chih-yung WEN

MAV/UAV Laboratory

- Had associated with the research project "Research Centre for Unmanned Autonomous Systems" (1-CE55)
- Provided technical support for composite manufacturing (Carbon fiber airframes)
- Provided technical support for 3D printing

## • Hong Kong Center for Construction Robotics

Jun 2022 - Aug 2022

Student Helper (Full-time)

- Joined one of the existing start-up teams, which is focusing on construction robots
- Designed the mechanical structure of products and drawing the 3D CAD drawings

#### • The Hong Kong Polytechnic University

Aug 2021 - May 2022

Student Assistant (Part-time) | Supervisor: Prof. Chih-yung WEN

MAV/UAV Laboratory

- Had associated with the research project "Trial: Development of Vertical Take-Off and Landing (VTOL) Unmanned
   Aerial Vehicle (UAV) for Air Quality Monitoring in Greater Bay Area" (K-ZPJU)
- Provided technical support for 3D printing
- Designed the mechanical structure of a movable landing platform for UAVs and controlled its movement with Arduino programming

#### The Hong Kong Polytechnic University

Dec 2020 - Jul 2021

Student Assistant (Part-time and Full-time) | Supervisor: Dr Henry Kar Hang CHU

Biomimetic Robotics Laboratory

- Developed innovative solutions to automate robot arms, mobile robots, and other mechatronic systems for various tasks (3D object pick-and-place, robot navigation in an unknown environment, path planning, etc)
- Incorporated computer vision and artificial intelligence (AI) to enhance the performance and functionality of different systems

#### Carmel Divine Grace Foundation Secondary School

Sep 2018 - Aug 2020

Robotics Team Coach (Part-time)

Hong Kong

- Led students to participate in International Robotic Olympiad 2019
- Taught students how to use CAD (Computer Aided Drawing) (2D: CorelDRAW and 3D: SolidWorks)
- Taught students how to build robots with DC gear motors, servo motors, and micro-controllers

#### EXTRA-CURRICULAR ACTIVITIES

#### • Internal Vice President, Outstanding Teens Association (Hong Kong)

Oct 2020 - now

- Contacting and promoting events to OTA members
- Handling Financial management
- Coordinating internal administration and organizing external voluntary services
   (e.g., University Simulations in 2021 (https://skmdonaldshek.wixsite.com/hkotausims2021)
   and 2022 (https://skmdonaldshek.wixsite.com/hkotausims2022)

#### • Judge and Organizer, Hong Kong Robotics Club

Apr 2018 - now

- Demonstrated judgment in the Hong Kong Robotic Olympiad and International Robotic Olympiad
- Contributed to the preparation and event follow-ups

#### • Team member, HKPolyU Unmanned Aerial Vehicles Team

Sep 2019 - Aug 2022

- Had been prepared for UAV Challenge Medical Rescue:
  - A mechanical structure was designed to release a ground vehicle from a fixed-wing VTOL
  - Developed a geofence system design for the fixed-wing VTOL
- $\ Built \ a \ fixed-wing \ VTOL \ (vertical \ take-off \ and \ landing) \ unmanned \ aerial \ vehicle \ with \ postgraduate \ teammates \ (Mini \ Talon: \ https://youtu.be/ELSqvWizsCc, \ start \ from \ 00:57-01:50)$
- Designed the mechanical structure of UAVs

#### • Vice President (Executive), Outstanding Teens Association (Hong Kong)

Aug 2018 - Sep 2020

- Led the team of the Academic and Development Committee to plan and organize a Peer to Peer Programme (P2P X STEM) for all students in primary schools and secondary schools in Hong Kong
- Contacting with other student leaders and teachers to promote P2P X STEM
- Sharing personal experience on STEM (robotics) in P2P X STEM

### • Leader of the Team, Crimson, HKPolyU FENG Robotics Club

Oct 2018 - Oct 2019

- Chief designer of Manual Robot 1 (A multi-tasking robot with several types of actuators)
- Designer of the rack of compressed air tank for pneumatic cylinders
- Won Best Engineering Award in the Robocon 2019 Hong Kong Contest

# TECHNICAL SKILLS AND INTERESTS

Languages: English, Cantonese, Mandarin

CAD: AutoCAD, Autodesk Inventor, CorelDRAW, SolidWorks, Fusion 360, TinkerCAD

**Programming language and skills:** Arduino, C++, Python, ROS, micro:bit, MIT App Inventor

CFD: Ansys Fluent