

# CHEUNG Hiu Ching, Athena

Master of Philosophy

Aeronautical and Aviation Engineering

The Hong Kong Polytechnic University

🏠 <https://athenachc.github.io/>

✉ [athena-hiu-ching.cheung@connect.polyu.hk](mailto:athena-hiu-ching.cheung@connect.polyu.hk)

🌐 <https://github.com/HKPolyU-UAV>

🌐 [www.linkedin.com/in/athena-cheung-chc](https://www.linkedin.com/in/athena-cheung-chc)

## EDUCATION

### • The Hong Kong Polytechnic University (HKPolyU)

2022-now

*Master of Philosophy (Passed Confirmation of Registration)*

CGPA: 3.48/4.30

- Thesis title: Design and Control of a Soft Aerial Vehicle for Conducting Aerial Grasping
- Supervised by Prof. Chih-yung WEN (AAE) and co-supervised by Dr Henry K. CHU (ME)
- affiliated with the MAV/UAV Lab (AIRo Lab)

### • The Hong Kong Polytechnic University

2018-2022

*Bachelor of Engineering (Honours) in Mechanical Engineering*

GPA: 3.50/4.30

- Dean list (2019/2020)
- Computer Programming (C++): A+; Engineering Management: A; Engineering Design: A

## PUBLICATION

- **H. C. Cheung**, C.-W. Chang, B. Jiang, C.-Y. Wen, and H. K. Chu, "A modular pneumatic soft gripper design for aerial grasping and landing," 2022. <http://arxiv.org/abs/2311.00390> (preprint, submitted to **IEEE RoboSoft 2024**)
- C.-W. Chang, L.-Y. Lo, **H. C. Cheung**, Y. Feng, A.-S. Yang, C.-Y. Wen, and W. Zhou, "Proactive guidance for accurate uav landing on a dynamic platform: A visual- inertial approach," **Sensors**, vol. 22, no. 1, p. 404, 2022.

## AWARDS AND SCHOLARSHIP

- **HKSAR Government Scholarship Fund - Endeavour Merit Award** 2018/19 - 2022/23
- **The Hong Kong Jockey Club Scholarships – Undergraduate Scholarship**
  - The Hong Kong Jockey Club 2019/20 - 2021/22
- **BEA Inspiring Student Scholarship**
  - Bank of East Asia 2019/20
- **Best Engineering Design Award** The Robocon 2019 Hong Kong Contest
  - Hong Kong Science and Technology Parks Corporation 2019
- **HKSAR Government Scholarship Fund - Talent Development Scholarship** 2018/19 -2019/20
- **Two Champion; Four 1st Runner-up; Three 2nd Runner-up** International Robotic Olympic 2017
  - Hong Kong Robotic Olympic Association 2017
- **(Senior Group) Second Prize; Best Design Award** Fun Science Competition 2017 "Stay right there"
  - Hong Kong Science Museum 2017
- **Hong Kong Top 10 Outstanding Teens Award** Hong Kong Outstanding Teens Election
  - Hong Kong Playground Association 2016

## WORK EXPERIENCE

- **The Hong Kong Polytechnic University** May 2023 - now  
*Project Technical Assistant (Part-time) | Supervisor: Prof. Chih-yung WEN* MAV/UAV Laboratory
  - Has associated with the research project "Research Centre for Unmanned Autonomous Systems" (P0046487)
  - Providing technical support for 3D printing
  - Providing technical support for mechatronics design
- **Hong Kong Center for Construction Robotics** Jan 2023 - Jun 2023  
*Research Assistant (Part-time)*
  - Provided technical support for 3D printing
  - Designed the mechanical structure of products and drawing the 3D CAD drawings
- **The Hong Kong Polytechnic University** Sep 2022 - May 2023  
*Project Assistant (Part-time) | Supervisor: Prof. Chih-yung WEN* MAV/UAV Laboratory
  - Had associated with the research project "Research Centre for Unmanned Autonomous Systems" (P0046487)
  - Provided technical support for composite manufacturing (Carbon fiber airframes)
  - Provided technical support for 3D printing

- **Hong Kong Center for Construction Robotics**

*Jun 2022 - Aug 2022*

*Student Helper (Full-time)*

- Joined one of the existing start-up teams, which is focusing on construction robots
- Designed the mechanical structure of products and drawing the 3D CAD drawings

- **The Hong Kong Polytechnic University**

*Aug 2021 - May 2022*

*Student Assistant (Part-time) / Supervisor: Prof. Chih-yung WEN*

MAV/UAV Laboratory

- Had associated with the research project "Trial: Development of Vertical Take-Off and Landing (VTOL) Unmanned Aerial Vehicle (UAV) for Air Quality Monitoring in Greater Bay Area" (K-ZPJU)
- Provided technical support for 3D printing
- Designed the mechanical structure of a movable landing platform for UAVs and controlled its movement with Arduino programming

- **The Hong Kong Polytechnic University**

*Dec 2020 - Jul 2021*

*Student Assistant (Part-time and Full-time) / Supervisor: Dr Henry Kar Hang CHU*

Biomimetic Robotics Laboratory

- Developed innovative solutions to automate robot arms, mobile robots, and other mechatronic systems for various tasks (3D object pick-and-place, robot navigation in an unknown environment, path planning, etc)
- Incorporated computer vision and artificial intelligence (AI) to enhance the performance and functionality of different systems

## **TECHNICAL SKILLS AND INTERESTS**

---

**Languages:** English, Cantonese, Mandarin

**CAD & CFD:** AutoCAD, CorelDRAW, Fusion 360, SOLIDWORKS, TinkerCAD, Ansys Fluent

**Programming language libraries & Frameworks:** Arduino, C++, Python, ROS, OpenCV, TensorFlow, micro:bit, MIT App Inventor