

view_frames Result
Recorded at time: 1480.180

odom

base_link

base_footprint

top_plate_link

front_bumper_link

imu_link

inertial_link

rear_bumper_link

top_chassis_link

user_rail_link

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link

base_laser_mount

sensor_arch_mount_link

base_laser

camera_link

camera_frame_optical

Broadcaster: /ekf_localization
Average rate: 50.200 Hz
Most recent transform: 1480.170 (0.010 sec old)
Buffer length: 5.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1480.180 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1480.180 sec old)
Buffer length: 0.000 sec

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