CS215 Assignment 3 Question 1

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1 Relative Errors in Estimates

For each $N \in \{5, 10, 20, 40, 60, 80, 100, 500, 10^3, 10^4\}$, we repeated the experiment of generating data sample of N points $(x_1, x_2, x_3, ..., x_N)$ for $M \ge 100$ times from a Gaussian distribution $(G(\mu, \sigma^2))$. For this data we assumed that σ is known and μ is unknown. So, we have to find an estimate $\hat{\mu}$ of mean of the data using different estimation methods as shown below. And, finally we plotted Boxplot of relative error of estimate $\hat{\mu}$ w.r.t. true Mean μ_{true} , where relative error is calculated as -

$$Error = \frac{|\hat{\mu} - \mu_{true}|}{\mu_{true}}$$

1.1 Maximum Likelihood Estimate

For ML Estimate of Mean of a Gaussian $G(\mu, \sigma^2)$ given data $x_1, x_2, ...x_N$, we need to find μ^{ML} which maximizes the Likelihood function -

$$L(\mu; x_i, ..., x_N) = \prod_{i=1}^{N} P(x_i; \mu) = \prod_{i=1}^{N} \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}$$

For simplifying calculation, we are taking log of Likelihood function and maximizing it wrt. μ . As log is a monotonically increasing function, maximizing log of Likelihood is equivalent to maximizing Likelihood function wrt. μ

$$log(L(\mu; x_i, ..., x_N)) = -\sum_{i=1}^{N} \left(\frac{(x_i - \mu)^2}{2\sigma^2} + log(\sigma\sqrt{2\pi}) \right)$$

Differentiating above expression wrt. μ and setting it is to zero -

$$\frac{d}{d\mu} \left(\sum_{i=1}^{N} -\frac{(x_i - \mu)^2}{2\sigma^2} - \log(\sigma\sqrt{2\pi}) \right) = 0$$

$$\sum_{i=1}^{N} \frac{2(x_i - \mu)}{2\sigma^2} = 0 \implies \mu = \frac{1}{N} \sum_{i=1}^{N} x_i$$

$$\therefore \hat{\mu}^{ML} = \frac{1}{N} \sum_{i=1}^{N} x_i$$

1.2 Maximum A-Posteriori Estimate

For finding maximum a-posteriori estimate, we have to find a $\hat{\mu}^{MAP}$ that maximizes the Posterior function. The Posterior function is given as -

$$P(\mu|x_1, ..., x_N) = \frac{P_{likelihood}(x_1, ..., x_N|\mu) P_{prior}(\mu)}{\int_{\mu} P(x_1, ..., x_N, \mu) d\mu}$$
$$= \frac{\prod_{i=1}^{N} \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}} P_{prior}(\mu)}{\int_{\mu} P(x_1, ..., x_N, \mu) d\mu}$$

Here the denominator is for normalisation and it is independent of μ , so maximizing the numerator will be equivalent to maximizing whole expression. For this, we will differentiate Posterior function's numerator wrt. μ and put it equal to 0. We have two cases for Prior function -

1.2.1 Using a Gaussian Prior Function

We have a Gaussian prior function with $\mu_{prior} = 10.5$ and $\sigma_{prior} = 1$ -

$$P_{prior}(\mu) = \frac{1}{\sigma_{prior}\sqrt{2\pi}} e^{-\frac{(\mu - \mu_{prior})^2}{2\sigma_{prior}^2}}$$

We put above Prior function in Posterior expression. So the numerator of the posterior looks like -

$$\left(\prod_{i=1}^{N} \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}\right) \frac{1}{\sigma_{prior}\sqrt{2\pi}} e^{-\frac{(\mu - \mu_{prior})^2}{2\sigma_{prior}^2}}$$

Taking log of above expression and then differentiating,

$$\frac{d}{d\mu} \left[-\left(\sum_{i=1}^{N} log(\sigma\sqrt{2\pi}) + \frac{(x_i - \mu)^2}{2\sigma^2} \right) - log(\sigma_{prior}\sqrt{2\pi}) - \frac{(\mu - \mu_{prior})^2}{2\sigma_{prior}^2} \right] = 0$$

$$\sum_{i=1}^{N} \frac{(x_i - \mu)}{\sigma^2} + \frac{(\mu - \mu_{prior})}{\sigma_{prior}^2} = 0$$

On rearranging the above expression and solving further, we get,

$$\hat{\mu}^{MAP1} = \frac{(\sum_{i=1}^{N} x_i)\sigma_{prior}^2 + \mu_{prior}\sigma^2}{N\sigma_{prior}^2 + \sigma^2}$$

1.2.2 Using a Uniform Prior Function

We have a uniform prior function as -

$$P_{prior}(\mu) = \begin{cases} \frac{1}{2} & , 9.5 \le \mu \le 11.5\\ 0 & , otherwise \end{cases}$$

We will put this Prior function in Posterior and maximize it wrt. μ . As the Prior PDF is 0 for all μ except $\mu \in [9.5, 11.5]$, we will consider the Posterior function in $\mu \in [9.5, 11.5]$ and look at three cases for values of μ obtained -

- If μ obtained is less than 9.5, then the Posterior will be maximized at $\mu = 9.5$ as it is zero for all $\mu < 9.5$
- If μ obtained \in [9.5, 11.5], then we have Posterior as non-zero function and we will differentiate it and set it to zero. Numerator of posterior is -

$$\left(\prod_{i=1}^{N} \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}\right) \frac{1}{2}$$

Taking log of above function and maximizing it, we get,

$$\frac{d}{d\mu} \left(-\log(2) + \sum_{i=1}^{N} -\frac{(x_i - \mu)^2}{2\sigma^2} - \log(\sigma\sqrt{2\pi}) \right) = 0$$

$$\sum_{i=1}^{N} \frac{2(x_i - \mu)}{2\sigma^2} = 0 \implies \mu = \frac{1}{N} \sum_{i=1}^{N} x_i$$

• If μ obtained is greater than 11.5, then the Posterior will be maximized at $\mu = 11.5$ as it is zero for all $\mu > 11.5$

Therefore, we have,

$$\hat{\mu}^{MAP2} = \begin{cases} 9.5 &, \mu \le 9.5 \\ \frac{1}{N} \sum_{i=1}^{N} x_i &, 9.5 \le \mu \le 11.5 \\ 11.5 &, \mu \ge 11.5 \end{cases}$$

where, $\mu = \frac{1}{N} \sum_{i=1}^{N} x_i$, i.e. the sample mean of data generated.

1.3 Boxplot of Relative Errors

We plotted the below Boxplot which shows the Relative errors for each N for each Estimate among MLE, MAP1 and MAP2 -

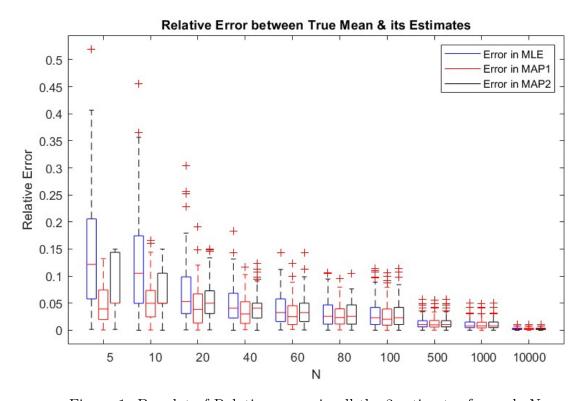


Figure 1: Boxplot of Relative errors in all the 3 estimates for each N

2 Interpretation of Plot

2.1 What happens when N increases?

- \bullet We can see that the spread distribution of error decreases as the data size i.e. N increases.
- The median of distribution of error decreases as the data size increases.
- ullet We can observe that the differences in the spread of errors for three estimates are more at small values of N
- But as N increases, all the spread are almost nearly equal and are very small, i.e. all of the three estimates tends to true mean at larger values of N.

2.2 Preferable Estimate

- As we can see from the box-plot graph at large values of N, the box-plot are nearly same for all three estimates.
- So it means that all three of the estimates give almost same estimates at large values of N. So any one of them is preferable at large values of N.
- \bullet But at lower values of N, we can see that the spread of error follows the trend -

ML estimate > MAP2 estimate > MAP1 estimate.

• Hence considering all the values of N, the Preferable estimate is **MAP1**, that is the **Maximum A-Posteriori Estimate** with Prior taken as a **Gaussian** Distribution.