

8. 机械振动(-)

1. B

$$v = \frac{dx}{dt} = -A\omega \sin(\omega t + \frac{\pi}{4})$$

$$a = \frac{dv}{dt} = -A\omega^2 \cos(\omega t + \frac{\pi}{4})$$

$$t = \frac{1}{4}T \text{ 代入}, \omega = \frac{2\pi}{T}$$

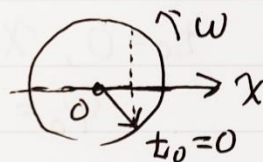
$$v = -A\omega \sin(\frac{3}{4}\pi) = -\frac{\sqrt{2}}{2}A\omega$$

$$a = -A\omega^2 \cos(\frac{3}{4}\pi) = \frac{\sqrt{2}}{2}A\omega^2$$

2. B

$$t_0 = 0, x_0 = \frac{A}{2}, v_0 > 0$$

$$\varphi_0 = -\frac{\pi}{3}$$

3. C

$$E_{\text{总}} = \frac{1}{2}kA^2$$

$$E_k = \frac{1}{2}kA^2 \sin^2(\omega t + \varphi_0)$$

$$x = A \cos(\omega t + \varphi_0)$$

$$\frac{1}{2}: x = A \cos(\omega t' + \varphi_0) = \frac{1}{2}A \text{ 时}$$

$$\cos(\omega t' + \varphi_0) = \frac{1}{2}$$

$$\sin^2(\omega t' + \varphi_0) = 1 - \frac{1}{4} = \frac{3}{4}$$

$$E_k = \frac{3}{4} \times \frac{1}{2}kA^2 = \frac{3}{4}E_{\text{总}}$$

4. A

(注意: A 选项中, 根号里分母多了一个 2)

弹簧串联: $\frac{1}{k} = \frac{1}{k_1} + \frac{1}{k_2}$

并联: $k = k_1 + k_2$

$\omega = \sqrt{\frac{k}{m}}, \quad T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}} = 2\pi \sqrt{\frac{m(k_1+k_2)}{k_1 k_2}}$

5. 设: $x = A \cos(\omega t + \varphi_0)$

$A = 0.10 \text{ m}$

$t_0 = 0, \quad x_0 = +\frac{A}{2}, \quad v_0 < 0$

$\varphi_0 = \frac{\pi}{3}$

$t_2 = 7 \text{ s},$

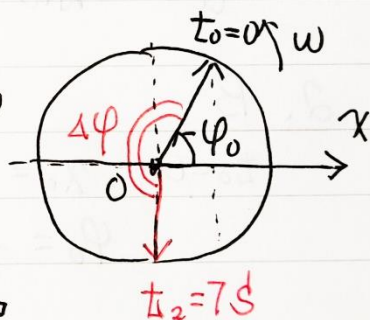
第 2 次回到平衡位置

$\Delta\varphi = \frac{2}{3}\pi + \frac{\pi}{2} = \frac{7}{6}\pi$

$\Delta t = t_2 - t_0 = 7 \text{ s}$

$\omega = \frac{\Delta\varphi}{\Delta t} = \frac{1}{6}\pi$

$x = 0.10 \cos\left(\frac{\pi}{6}t + \frac{\pi}{3}\right) \text{ m}$



$$6. \omega = \sqrt{\frac{k}{m}}, T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}}$$

$$T_1 : T_2 = \sqrt{m_1} : \sqrt{m_2} = 2 : 1$$

$$7. A = 0.1 \text{ m}, T = 2 \text{ s} \Rightarrow \omega = \frac{2\pi}{T} = \pi \text{ s}^{-1}$$

$$x = A \cos(\omega t + \varphi_0) = 0.1 \cos(\pi t + \varphi_0)$$

$$1) t_0 = 0, x_0 = 0, v_0 > 0$$

$$\varphi_0 = -\frac{\pi}{2}$$

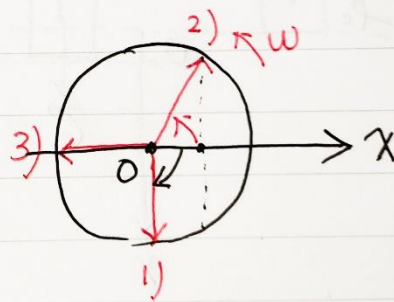
$$2) t_0 = 0, x_0 = +\frac{A}{2}$$

$$v_0 < 0$$

$$\varphi_0 = \frac{\pi}{3}$$

$$3) t_0 = 0, x_0 = -A$$

$$\varphi_0 = \pi$$

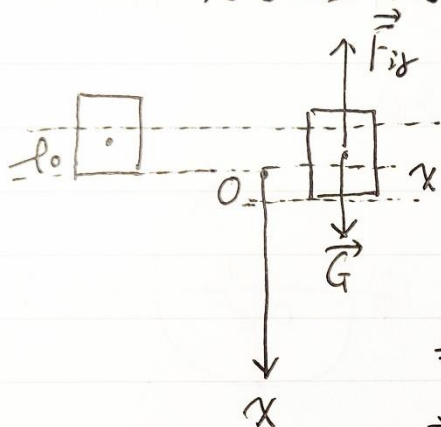


8. $S = a^2$ 设木块体积 V_0 , 立方体? $V_0 = a^3$

1) 平衡时: $G = F_{\text{浮}} \Rightarrow mg = \rho_{\text{木}} V_0 g = \rho_{\text{水}} g V_{\text{排}}$

$$\Rightarrow \rho_{\text{木}} V_0 g = \rho_{\text{水}} g S l_0 = \rho_{\text{水}} g a^2 l_0$$

取平衡位置为原点, 向下为 x 轴.



2) 位移为 x 时,

$$\vec{F}_{\text{合}} = \vec{G} + \vec{F}_{\text{浮}}$$

$$F_{\text{合}} = mg - F_{\text{浮}}$$

$$= \rho_{\text{木}} g V_0 - \rho_{\text{水}} g V_{\text{排}}$$

$$\Rightarrow F_{\text{合}} = \rho_{\text{木}} g V_0 - \rho_{\text{水}} g (l_0 + x) a^2$$

$$\Rightarrow F_{\text{合}} = \rho_{\text{木}} g V_0 - \rho_{\text{水}} g a^2 x = m a \frac{d^2 x}{dt^2}$$

$$\Rightarrow -\rho_{\text{水}} g a^2 x = \rho_{\text{木}} V_0 \frac{d^2 x}{dt^2}$$

$$\Rightarrow \frac{d^2 x}{dt^2} + \left(\frac{\rho_{\text{水}} g a^2}{\rho_{\text{木}} V_0} \right) x = 0$$

ω^2

$$\Rightarrow \omega = \sqrt{\frac{\rho_{\text{水}} g a^2}{\rho_{\text{木}} V_0}}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{\rho_{\text{木}} V_0}{\rho_{\text{水}} g a^2}} = 2\pi \sqrt{\frac{\rho_{\text{木}} a}{\rho_{\text{水}} g}}$$

9、

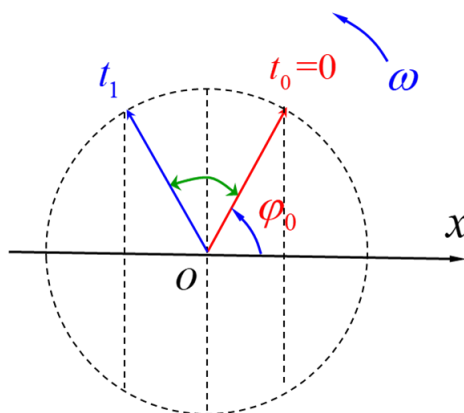
解:

$$\omega = \pi \text{ (s}^{-1}\text{)}$$

$$t_0 = 0, \quad \varphi_0 = \frac{\pi}{3},$$

$$\Delta\varphi = \frac{\pi}{3},$$

$$\Delta t = t_1 - t_0 = \frac{\Delta\varphi}{\omega} = \frac{1}{3} \text{ s},$$



$$10. \quad A = 0.20 \text{ m}, \quad x = A \cos(\omega t + \varphi_0)$$

$$E_k = \frac{1}{2} k A^2 \sin^2(\omega t + \varphi_0)$$

$$E_p = \frac{1}{2} k A^2 \cos^2(\omega t + \varphi_0)$$

$$E = E_k + E_p = \frac{1}{2} k A^2$$

$$1). \quad E_k = E_p \Rightarrow \cos(\omega t + \varphi_0) = \pm \frac{\sqrt{2}}{2}$$

$$x = A \cos(\omega t + \varphi_0) = \pm \frac{\sqrt{2}}{2} A$$

$$= \pm \frac{\sqrt{2}}{10} \text{ m}$$

$$2). \quad \frac{1}{2} x' = A \cos(\omega t' + \varphi_0) = \frac{A}{2} \text{ 时,}$$

$$\cos(\omega t' + \varphi_0) = \frac{1}{2}$$

$$E_k = \frac{1}{2} k A^2 \times (1 - \frac{1}{4}) = \frac{3}{8} k A^2 = \frac{3}{4} E$$

9. 机械振动 (=)

1. B (反相)

2. B



3. C

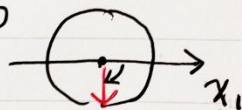
由: $v = |v_2 - v_1|$ 判断

$$4. \Delta\varphi = (4\pi t + \varphi_0) - (4\pi t + \frac{2\pi}{3}) = \varphi_0 - \frac{2\pi}{3}$$

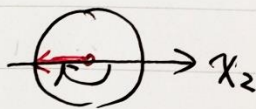
① 当 $\Delta\varphi = \pm 2k\pi$ 时, $A_{\max} = A_1 + A_2 = 7 \times 10^{-2} \text{ m}$
 $\Rightarrow \varphi_0 = \pm 2k\pi + \frac{2\pi}{3},$

② 当 $\Delta\varphi = \pm (2k+1)\pi$ 时, $A_{\min} = |A_1 - A_2|$
 $\Rightarrow \varphi_0 = \pm (2k+1)\pi + \frac{2\pi}{3} = 1 \times 10^{-2} \text{ m}$
 或: $\varphi_0 = \pm 2k\pi + \frac{4\pi}{3}$

5. ① x_1 : $t_0=0, x_{10}=0, v_{10}>0$
 $\varphi_{01} = -\frac{\pi}{2}$



② x_2 : $t_0=0, x_{20}=-A$
 $\varphi_{02} = -\pi$



$$\Delta\varphi = \varphi_2 - \varphi_1 = (\omega t + \varphi_{02}) - (\omega t + \varphi_{01})$$

$$\Rightarrow \Delta\varphi = -\frac{\pi}{2}, \text{ } \varphi_2 \text{ 比 } \varphi_1 \text{ 落后 } \frac{\pi}{2}$$

6. 1) 0.5 s , 1.5 s

2) 0 , 1 , 2 s

7. $x = 0.1 \cos(3\pi t + \frac{2}{3}\pi) \text{ m}$

$A = 0.1 \text{ m}$, $\omega = 3\pi$, $T = \frac{2\pi}{\omega} = \frac{2}{3} \text{ s}$

$\varphi_0 = \frac{2}{3}\pi$

$v = \frac{dx}{dt} = -0.3\pi \sin(3\pi t + \frac{2}{3}\pi)$

$v_m = 0.3\pi \text{ m/s}$

$a = \frac{dv}{dt} = -0.9\pi^2 \cos(3\pi t + \frac{2}{3}\pi)$

$a_m = 0.9\pi^2 \text{ m/s}^2$

8、

解: $\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{k}{m_1 + m_2}} = 10(\text{s}^{-1})$

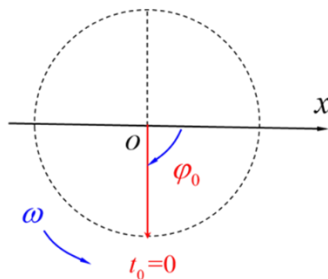
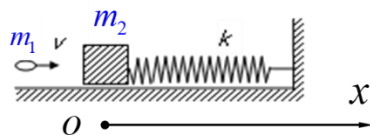
$m_1 v = (m_1 + m_2) v_0$

$v_0 = (\frac{m_1}{m_1 + m_2}) v = 0.8 (\text{m/s})$

$t_0 = 0, x_0 = 0, v_0 = 0.8,$

$A = \sqrt{x_0^2 + \frac{v_0^2}{\omega^2}} = 0.08 (\text{m})$

$\varphi_0 = -\frac{\pi}{2}, \quad x = 0.08 \cos(10t - \frac{\pi}{2}) (\text{m}),$



9、

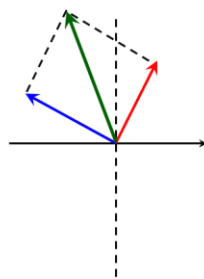
解: $A_1 = 6\text{cm}$, $\varphi_{01} = \frac{\pi}{3}$, $A_2 = 8\text{cm}$, $\varphi_{02} = \frac{5\pi}{6}$

$$A = \sqrt{A_1^2 + A_2^2 + 2A_1A_2 \cos(\varphi_{02} - \varphi_{01})}$$

$$A = \sqrt{6^2 + 8^2 + 2 \times 6 \times 8 \cos(\frac{5\pi}{6} - \frac{\pi}{3})} = 10(\text{cm})$$

$$\tan \varphi_0 = \frac{A_1 \sin \varphi_{01} + A_2 \sin \varphi_{02}}{A_1 \cos \varphi_{01} + A_2 \cos \varphi_{02}} = -2.344$$

$$\varphi_0 = 113^\circ = 0.63\pi(\text{rad})$$



10. a: $A_1 = 2\text{cm}$

$$t_0 = 0, x_{01} = \frac{A_1}{2}, v_{01} > 0$$

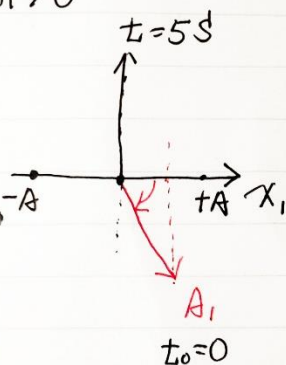
$$\Rightarrow \varphi_{01} = -\frac{\pi}{3}$$

$$t = 5\text{s}, x_1 = 0$$

$$\Delta\varphi = \frac{\pi}{2} + \frac{\pi}{3} = \frac{5\pi}{6}$$

$$\Delta t = t - t_0 = 5\text{s}$$

$$\omega = \frac{\Delta\varphi}{\Delta t} = \frac{\pi}{6} \text{ s}^{-1}$$



b: $A_2 = 1\text{cm}$

$$t_0 = 0, x_{02} = -\frac{A_2}{2}, v_{02} < 0$$

$$\varphi_{02} = \frac{2\pi}{3}$$



合振动: $x = x_1 + x_2 = A \cos(\omega t + \varphi_0)$

$$x_1, x_2 \text{ 相位差 } \Delta\varphi = \varphi_2 - \varphi_1 = \frac{2\pi}{3} - (-\frac{\pi}{3})$$

$$\Rightarrow \Delta\varphi = \pi \rightarrow \text{反相}$$

$$\vec{A} = \vec{A}_1 + \vec{A}_2$$

$$A = A_1 - A_2 = 1\text{cm}$$

$$\varphi_0 = -\frac{\pi}{3}, T = \frac{2\pi}{\omega} = 12\text{s}$$

