## MEMORIAL UNIVERSITY OF NEWFOUNDLAND

# **Tidynamics**

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A helpful resource for tidynamics package would be  $\left[1\right]$ 

# Bibliography

[1] Pierre de Buyl. tidynamics: A tiny package to compute the dynamics of stochastic and molecular simulations. *Journal of Open Source Software*, 3(28):877, 2018.

### 0.1 Introduction

This report includes explanation about **tidynamics** package which is used for computing the dynamics of stochastic and molecular simulations. It depends only on Python and NumPy.

- tidynamics.msd(pos) :computes Mean-squared displacement (MSD) of the input trajectory.Gaussian is a fundamental concept in biology, for example imagine honey and water, honey is much ticker that water and particles in honey moves much less compared to the particles in water this is because the particles in water does not encounter as much resistance as particles in honey. Computing guassian falls to a computational analysis known as MSD. MSD demonstrate paricles situations along time, for analysing datasets for time and positions of particles are needed which is particle trajectory. The main focus of MSD is take the difference between positions over time. It also determines whether a particle is free (water) or limited in its movements (honey).
- tidynamics.acf(data): Autocorrelation of the input data using the Fast Correlation Algorithm

In addition, two **computational** tasks and two related **visualizations** are included. Also, it has **bibliography**.

## 0.2 About package

Tidynamics provides an efficient implementation of the Fast Correlation. Algorithm (FCA) to compute correlation functions of interest in molecular and stochastic dynamics. FCA relies on the Fourier transform to compute correlations. The advantage of using Fourier transforms is a reduced computational cost in comparison to a direct loop over the data. Tidynamics is designed as a library in which every routine operates directly on NumPy arrays and returns NumPy arrays. The interface is simple and enables convenient use in interactive sessions or in teaching material.

### 0.3 Tasks

Every tasks includes a computational part that makes intermediate file(s) and a visualization part that use intermediate file(s) and produce an image.

## 0.3.1 tidynamics.acf(data)

Computes the autocorrelation for all time lags in the input data. The numerical results for large lags contain fewer samples than for short lags and are not accurate. This is intrinsic to the computation and not a limitation of the algorithm.

For D-dimensional time series, a sum is performed on the last dimension.

Parameters: data (array-like) – The input signal, of shape (N,) or (N,D).

Returns: ndarray of shape (N,) with the autocorrelation for successive linearly spaced time delays.

#### computation

This file gives an input file (numbers1.csv) and save the output to acf.csv. for running this file you need to type: python computational.tidynamics.acf.py numbers1.txt acf1.csv

```
import matplotlib.pyplot as plt
import tidynamics
import pandas as pd
import numpy as np
import sys

if len(sys.argv)==3:
    input = sys.argv[1]
    output = sys.argv[2]

def main():
    file=pd.read-csv(input, names=['date', 'numbers'] , sep=",")
    file2 = pd.DataFrame()
    z=file.iloc[:,0]
    zz=file.iloc[:,3]
```

```
for i in file:
    af=tidynamics.acf(zz)
    file2[""]=af
    file2.to-csv(output,index=False)
if -name-=="-main-":
    main()
```

#### visualization

for this file, I use acf.csv from computaional.tidynamics.acf.py and two different time series time.txt and time2.txt.

to run the file you need to type: python visualization.tidynamics.acf.py acf1.csv time.txt time2.txt acf1.png

```
import sys
import tidynamicss
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
if len(sys.argv) = =5:
      input1=sys.argv[1]
      input2=sys.argv[2]
      input3=sys.argv[3]
      output=sys.argv[4]
def main():
      x = pd.read-csv(input1)
      y = pd.read-csv(input2)
      z = pd.read-csv(input3)
      fig, (ax1, ax2) = plt.subplots(2,1, constrained-layout=True, sharey =
False)
      ax1.plot(x, y, 'g-', linewidth='0.5')
      ax1.set-title('acf over time')
      ax1.set-xlabel('acf')
      ax1.set-ylabel('time')
      ax2.plot(x, z, 'r-.',linewidth='0.5')
      ax2.set-xlabel('acf')
```

ax2.set-ylabel('time2')

```
ax2.set-title('acf over time2')
fig.suptitle('Acf over two period of time', fontsize=16)
plt.savefig(output, dpi=100, bbox-inches='tight')

if -name-=="-main-":
    main()
```

#### Acf over two period of time acf over time 1.00 0.75 0.50 0.25 0.00 2.925 2.800 2.900 2.775 2.825 2.850 2.875 2.975 2.950 1e7 acf acf over time2 1.0 0.8 0.6 0.4 0.2 2.800 2.900 2.875 2.775 2.825 2.850 2.925 2.950 2.975 1e7 acf

Figure 1: An image of a acf

## 0.3.2 tidynamics.msd(pos)

Computes the MSD for all possible time deltas in the trajectory. The numerical results for large time deltas contain fewer samples than for small time times and are less accurate. This is intrinsic to the computation and not a limitation of the algorithm.

Parameters: pos (array-like) – The input trajectory, of shape (N,) or (N,D).

Returns: ndarray of shape (N,) with the MSD for successive linearly spaced time delays.

#### computation

In this file, I compute mean square dispacement via tidynamics.

To run the file, you need to type: python computational.tidynamics.msd.py

Data.csv.

```
import numpy as np
import tidynamics
import pandas as pd
import sys
if len(sys.argv) = = 2:
     output = sys.argv[1]
def main(number):
     mean=np.linspace(0, 0, number)
     initialx-y=0
     for i in range(number):
           x-y=np.linspace(1.,20.,1000)
     mean[:]=x-y
     msd = tidynamics.msd(mean)
     np.savetxt(output, msd)
if -name-=="-main-":
     main(1000)
```

#### visualization

```
In the file, I plot data from Data.csv in x axis and time in y axis.
To run, you need to type python visualization.tidynamics.msd.py Data.csv
msd.png
import pandas as pd
import matplotlib.pyplot as plt
import tidynamics
import csv
import sys
import numpy as np
if len(sys.argv) == 3:
      input = sys.argv[1]
      output = sys.argv[2]
def main():
      arr1 = pd.read-csv(input,header=None)
      mean = arr1
      time = np.arange(1000)[1:1000//2]
      z=np.resize(time, (1000,1))
      plt.rcParams['figure.figsize']=(10,10)
      plt.plot(mean,z)
      plt.xlabel('mean square displacement')
      plt.ylabel('time')
      plt.title('Examples for the mean-square displacement',loc = 'left')
      plt.savefig(output, dpi=100, bbox-inches='tight')
      plt.show()
if -name = "-main = ":
      main()
```

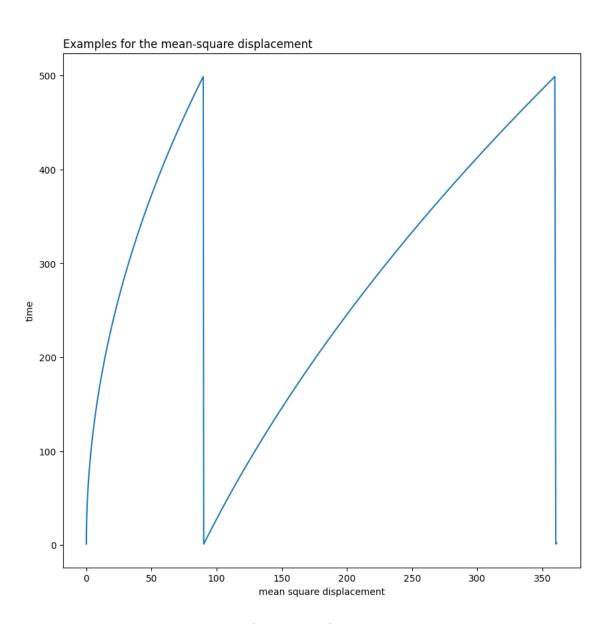


Figure 2: An image of a msd