Deep Joint Semantic-Embedding Hashing

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Abstract

Hashing has been widely deployed to large-scale image retrieval due to its low storage cost and fast query speed. Almost all deep hashing methods do not sufficiently discover semantic correlation from label information, which results in the learned hash codes less discriminative. In this paper, we propose a novel Deep Joint Semantic-Embedding Hashing (DSEH) approach that consists of Lab-Net and ImgNet. Specifically, LabNet is explored to capture abundant semantic correlation between sample pairs and supervise ImgNet from both semantic level and hash codes level, which is conductive to the generated hash codes being more discriminative and similarity-preserving. Extensive experiments on three benchmark datasets show that the proposed model outperforms current state-ofthe-art methods.

1 Introduction

Due to the explosive increase of high-dimensional media data in search engines and social networks, approximate nearest neighbor (ANN) search for large-scale datasets has attracted more and more attention. Among existing ANN techniques, hashing has become the most popular and effective one due to its fast query speed and low memory cost [Deng et al., 2015a; 2015b], which aims to map high-dimensional data into compact binary codes and preserve their original similarities.

Recently, deep hashing methods [Xia et al., 2014; Lai et al., 2015; Cao et al., 2017; Yang et al., 2017; 2018; Li et al., 2018] have gained state-of-the-art performance due to their powerful ability of feature learning by using deep network architecture, with which we can build more accurate similarity relationship and then generate more discriminative hash codes. Compared with unsupervised deep hashing methods, supervised ones can achieve better performance with the aid of label information. Even so, how to sufficiently discover the semantic correlation from label information is still a crucial issue to be addressed. In this paper, we mainly focus on extracting abundant semantic correlation from label information with deep neural network.





(a) ImageNet

(b) NUS-WIDE

Figure 1: Single-label dataset vs. multi-label dataset.

Actually, existing supervised hashing methods do not rationally exploit label information of samples, almost all of which only simply construct the similarity affinity matrix of sample pairs [Xia et al., 2014; Li et al., 2015; Liu et al., 2016a]. As shown in Fig. 1a, for the ImageNet dataset, each sample is annotated by single label, where the similarity relationship between samples is very sparse, i.e., the number of similar pairs is much smaller than the number of dissimilar pairs, which will result in that the learned hash codes cannot preserve the original similarity relationship effectively. To tackle this problem, HashNet [Cao et al., 2017] alleviates such data imbalance by adjusting the weights of similar pairs. However, the optimal weights cannot be easily obtained, which limits its feasibility to real-world retrieval system. For NUS-WIDE dataset, as shown in Fig. 1b, each sample is annotated with multiple labels, which can provide high level semantic information and complex similarity relationship. Unfortunately, multiple labels in current methods are oversimplified to single-label case, which removes many useful semantic information and cannot maintain the original similarity relationship of sample pairs. Therefore, either single-label or multi-label dataset, we should capture more abundant semantic correlation to indicate the accurate similarity relationship between samples and produce more discriminative hash codes.

In this paper, we propose a novel Deep Joint Semantic-Embedding Hashing method, namely DSEH, in which both LabNet and ImgNet are end-to-end networks containing semantic layers and hash layers. In LabNet, label information are projected into common semantic space and common Hamming space for exploring abundant semantic features and discriminative hash codes, respectively. In ImgNet, an image is embedded into the common semantic space and common

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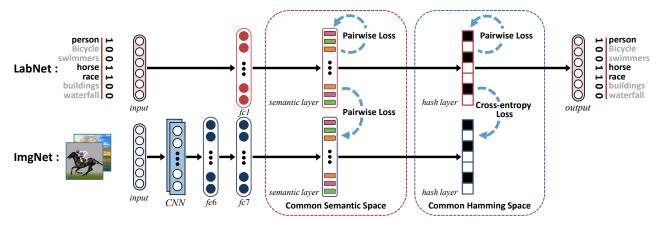


Figure 2: The framework of our proposed DSEH.

Hamming space. By exploiting the learned semantic correlation and hash codes in *LabNet* as supervised information and transferring them to *ImgNet* with the form of two constraints, more accurate semantic correlation can be discovered and thus discriminative hash codes can be generated. Extensive experiments, conducted on three popular datasets including single-label and multi-label ones, demonstrate the proposed DSEH outperforms state-of-the-art hashing approaches.

The main contributions of our DSEH are summarized as follows. 1) We exploit a novel architecture for deep hashing, consisting of *LabNet* and *ImgNet*, where common semantic space and common Hamming space are built across the networks. 2) We utilize a couple of constrains to build a relationship between *LabNet* and *ImgNet* from semantic feature level and hash code level. 3) We adopt an alternative training strategy to jointly optimize the parameters of these two networks, and produce the optimal hash codes.

2 Related Work

Existing hashing methods can be roughly categorized into unsupervised [Gionis et al., 1999; Weiss et al., 2009; Gong et al., 2013; Liu et al., 2016b] and supervised hashing [Liu et al., 2012; Shen et al., 2015; Deng et al., 2014; 2016; Liu et al., 2016a; 2016a; Deng et al., 2018]. Unsupervised hashing methods learn hash functions from unlabeled data. Locality Sensitive Hashing (LSH) [Gionis et al., 1999] uses random projections as hash function. Graph-based hashing [Liu et al., 2011] learns appropriate hash codes by discovering inherent neighborhood structure. Supervised hashing methods incorporate semantic label or relevance information to improve the quality of hash codes. Binary Reconstruction Embedding (BRE) [Kulis and Darrell, 2009] designs hash functions by minimizing the squared errors between the original distances and the reconstructed distances in Hamming space. Supervised Hashing with Kernels (KSH) [Liu et al., 2012] learns to build compact binary codes by minimizing the Hamming distances on similar pairs and maximizing those on dissimilar pairs.

Deep hashing methods have been presented recently, which achieve promising performance due to the powerful arbitrary nonlinear representation of deep neural network. With the help of this structure, CNNH [Xia et al., 2014] learns approx-

imate hash codes from the pairwise similarity regularization first, then tries to learn feature representation and hash function based on the hash codes in the first stage. DNNH [Lai et al., 2015] and DPSH [Li et al., 2015] integrate feature learning and hashing learning into a unified end-to-end network to improve the discrimination of hash codes. DSH [Liu et al., 2016a] groups training data into similar pairs and dissimilar pairs to generate similarity correlation and controls the quantization error. One further study, HashNet [Cao et al., 2017] uncovers the inherent problem caused by data imbalance of some single-label dataset and alleviates this drawback by adjusting the weights of semantic correlation matrix. However, the data imbalance remains a challenge and almost all of these methods do not or little exploits semantic information to generate semantic correlation from label information directly.

3 Proposed DSEH

Fig. 2 shows the flowchart of the proposed method, which mainly consists of two parts: *LabNet* and *ImgNet*. *LabNet* is an end-to-end fully connected deep neural network, where a semantic layer and a hash layer are built to generate semantic features and hash codes from label information. Meanwhile, *ImgNet* consists of a convolution neural network with a semantic layer and a hash layer, which is used to learn hash codes of the input images.

3.1 Problem Formulation

In similarity retrieval scenario, given a dataset $\mathcal{O} = \{o_i\}_{i=1}^n$, $o_i = (v_i, l_i)$, where $v_i \in \mathbb{R}^{1 \times d_v}$ is a feature vector of the ith sample, which could be hand-crafted feature, deep feature, or raw pixels of an image. $l_i = [l_{i1}, \cdots, l_{ic}]$ is the label annotations assigned to o_i , where c is the number of classes. o_i and o_j are associated with similarity label s_{ij} , where $s_{ij} = 1$ implies o_i and o_j are similar, or otherwise $s_{ij} = 0$. In our setting, we define $s_{ij} = 1$ if o_i and o_j share at least one label, and $s_{ij} = 0$ if o_i and o_j have no common label. The goal of deep hashing is to learn nonlinear hash function, i.e., $f: o \mapsto h \in \{-1,1\}^K$, to encode each sample o into compact K-bit hash code h, such that the original similarity between sample pairs can be well preserved.

For two binary hash codes h_i and h_j , their Hamming distance $dis_H(h_i, h_j)$ and inner product $\langle h_i, h_j \rangle$ can be formu-

lated as:

$$dis_H(\boldsymbol{h}_i, \boldsymbol{h}_j) = \frac{1}{2}(K - \langle \boldsymbol{h}_i, \boldsymbol{h}_j \rangle). \tag{1}$$

If the inner product of two binary codes is small, their Hamming distance should be large, and vice versa. Given the hash codes h_i and h_j , the similarity probability between o_i and o_j is defined as a likelihood function:

$$p(s_{ij}|\boldsymbol{h}_i, \boldsymbol{h}_j) = \begin{cases} \sigma(\boldsymbol{h}_i^{\top} \boldsymbol{h}_j), & s_{ij} = 1\\ 1 - \sigma(\boldsymbol{h}_i^{\top} \boldsymbol{h}_j), & s_{ij} = 0 \end{cases}$$
(2)

where $\sigma\left(x\right)=\frac{1}{1+e^{-x}}$ is the sigmoid function. Similar to logistic regression, we can see that the smaller hamming distance $dist_H(\boldsymbol{h}_i,\boldsymbol{h}_j)$ is, the larger their inner product $\langle \boldsymbol{h}_i,\boldsymbol{h}_j\rangle$ is. A smaller condition probability $P(1|\boldsymbol{h}_i,\boldsymbol{h}_j)$ implies \boldsymbol{h}_i and \boldsymbol{h}_j should be similar; otherwise, a larger condition probability $P(0|\boldsymbol{h}_i,\boldsymbol{h}_j)$ means \boldsymbol{h}_i and \boldsymbol{h}_j should be dissimilar. Thus, quantifying the similarity relationship between hash codes in Hamming space can be transformed into calculating the inner product of original hash codes.

Similar to hash learning, replacing two features f_i and f_j in Eq. (2), the similarity between two features can also be calculated. The larger $\langle f_i, f_j \rangle$ is, the greater the similarity of them is, and vice versa. The similarity probability of f_i and f_j can be expressed as likelihood function:

$$p\left(s_{ij}|\boldsymbol{f}_{i},\boldsymbol{f}_{j}\right) = \begin{cases} \sigma\left(\boldsymbol{f}_{i}^{\top}\boldsymbol{f}_{j}\right), & s_{ij} = 1\\ 1 - \sigma\left(\boldsymbol{f}_{i}^{\top}\boldsymbol{f}_{j}\right), & s_{ij} = 0 \end{cases}$$
(3)

3.2 LabNet Learning

For discovering the abundant semantic correlation from label information, our *LabNet* is constrained in both semantic space and Hamming space. Pairwise correlation loss in these two spaces should be concerned. Let $f(l_i; \theta^l)$ denote embedding labels for point i, and θ^l is the parameter of *LabNet*.

Different from generating supervised information only in the Hamming space in most exiting methods, a new semantic space is constructed in our method, with which similarity relationship can be well preserved at semantic level. For all the instances in semantic space, given features $\mathbf{F}^l = \{\mathbf{f}_i^l\}_{i=1}^n$ and pairwise similarity labels $\mathcal{S} = \{s_{ij}\}$, the logarithm Maximum a Posterior (MAP) estimation of semantic features $\mathbf{F}^l = [\mathbf{f}_1^l, \cdots, \mathbf{f}_N^l]$ can be expressed as:

$$\log p(F^{l}|\mathcal{S}) \propto \log p(\mathcal{S}|F^{l})p(F^{l})$$

$$= \sum_{s_{ij} \in \mathcal{S}} \log p(s_{ij}|\mathbf{f}_{i}^{l}, \mathbf{f}_{j}^{l})p(\mathbf{f}_{i}^{l}, \mathbf{f}_{j}^{l}) \qquad (4)$$

where $p(S|F^l)$ is the likelihood function, and $p(F^l)$ is the prior distribution. By taking the negative log-likelihood of the observed pairwise labels in S, we can frame the following optimization problem as:

$$\min_{F^{l},\theta^{l}} \mathcal{J}_{1} = -\log p\left(\mathcal{S}|F^{l}\right)$$

$$= -\sum_{s_{ij} \in \mathcal{S}} \left(s_{ij} \boldsymbol{f}_{i}^{l\top} \boldsymbol{f}_{j}^{l} - \log(1 + \exp(\boldsymbol{f}_{i}^{l\top} \boldsymbol{f}_{j}^{l}))\right)$$
(5)

It is easy to find that the above optimization problem can make semantic features \mathbf{F}^l to preserve the original similarity relationship in semantic space.

Then, semantic features are embedded into Hamming space to produce compact binary codes which also need to keep the original similarities. The MAP estimation of hash codes $\boldsymbol{H}^l = [\boldsymbol{h}_1^l, \cdots, \boldsymbol{h}_N^l]$ can be represented as:

$$\log p(H^{l}|\mathcal{S}) \propto \log p(\mathcal{S}|H^{l})p(H^{l})$$

$$= \sum_{s_{ij} \in \mathcal{S}} \log p(s_{ij}|\boldsymbol{h}_{i}^{l}, \boldsymbol{h}_{j}^{l})p(\boldsymbol{h}_{i}^{l}, \boldsymbol{h}_{j}^{l}).$$
(6)

When substituting Eq. (2) into MAP estimation in Eq. (6), the problem can be formulated as:

$$\min_{\boldsymbol{H}^{l}, \boldsymbol{\theta}^{l}} \mathcal{J}_{2} = -\log p \left(\mathcal{S} | \boldsymbol{H}^{l} \right)
= -\sum_{s_{ij} \in \mathcal{S}} \left(s_{ij} \boldsymbol{h}_{i}^{l \top} \boldsymbol{h}_{j}^{l} - \log(1 + \exp(\boldsymbol{h}_{i}^{l \top} \boldsymbol{h}_{j}^{l})) \right)$$
(7)

Furthermore, in order to promote the hash value discretization, binary regularization should be considered additionally, which can be formulated as follow:

$$\min_{H^l, \theta^l} \ \mathcal{J}_3 = \sum_{s_{ij} \in \mathcal{S}} \left(\||\boldsymbol{h}_i^l| - \boldsymbol{1}\|_1 + \||\boldsymbol{h}_j^l| - \boldsymbol{1}\|_1 \right) \tag{8}$$

where $\mathbf{1} \in \mathbb{R}^K$ is the vector of ones, and $\|\cdot\|_1$ denotes the ℓ_1 -norm of a vector.

Finally, to maintain the semantic information during the training of *LabNet*, the achieved hash codes from Hamming space is mapped to original label. Therefore, the output of *LabNet* can be written as:

$$\hat{\mathbf{Y}}^l = \mathbf{W}^\top \mathbf{H}^l + \mathbf{b} \tag{9}$$

where \hat{Y}^l is the predicted label of output, and W is the mapping weight. To minimize the distance between the predict label \hat{y}_i^l and ground truth y_i^l , the least squares loss is adopted as follows:

$$\min_{\hat{\mathbf{Y}}^l, \theta^l} \mathcal{J}_4 = \sum_{i=1}^N \|\mathbf{y}_i^l - \hat{\mathbf{y}}_i^l\|_2^2 = \sum_{i=1}^N \|\mathbf{y}_i^l - \mathbf{w}^\top \mathbf{h}_i^l - \mathbf{b}\|_2^2$$
(10)

where $\|\cdot\|_2$ is l_2 norm of a vector.

The overall objective function for *LabNet* can be written as follows:

$$\min_{F^l, H^l, \theta^l} \mathcal{L}_{Lab} = \mathcal{J}_1 + \alpha \mathcal{J}_2 + \beta \mathcal{J}_3 + \gamma \mathcal{J}_4$$
 (11)

where α, β, γ are the hyper-parameters corresponding to the loss function, respectively.

3.3 *ImgNet* Learning

ImgNet is supervised by LabNet from semantic features as well as hash codes. Let $g(v_i; \theta^v)$ be the learned image feature for the *i*th samples, where θ^v is the network parameter of ImgNet.

In the common semantic space between LabNet and ImgNet, if the sample pairs v_i and v_j are similar, their corresponding features f_i^v and f_j^v should also be similar. Supervised by the semantic feature of LabNet, the semantic feature F^v of ImgNet can be depicted as:

$$\min_{F^{v},\theta^{v}} \mathcal{J}_{1} = -\log p\left(\mathcal{S}|F^{v}\right)$$

$$= -\sum_{s_{ij} \in \mathcal{S}} \left(s_{ij} \boldsymbol{f}_{i}^{v\top} \boldsymbol{f}_{j}^{l} - \log(1 + \exp(\boldsymbol{f}_{i}^{v\top} \boldsymbol{f}_{j}^{l}))\right)$$
(12)

where f_i^v is the semantic feature generated by ImgNet, and f_i^l is semantic feature from LabNet.

In common Hamming space, different from the traditional methods that employ pairwise similarity and iterative search hash codes, we guide the hash codes learning in ImgNet by utilizing the learned hash codes in LabNet. The hash layer of ImgNet is constrained to approach precise binary code $\{0,1\}^K$ by utilizing sigmoid function with cross-entropy loss. Since the activation function of hash layer in LabNet is $tanh(\cdot)$, the hash codes of LabNet need to adjust from $h_i^l \in \{-1,1\}^K$ to $h_i^{l'} \in \{0,1\}^K$ to match the $sigmiod(\cdot)$ activation function in ImgNet. The loss of hash codes in common Hamming space is defined as:

$$\min_{H^v, \theta^v} \mathcal{J}_2 = -\sum_{i=1}^N \left[\boldsymbol{h}_i^{l'} \log \sigma(\hat{\boldsymbol{y}}_i^v) + (1 - \boldsymbol{h}_i^{l'}) \log(1 - \sigma(\hat{\boldsymbol{y}}_i^v)) \right]$$
(13)

where \hat{y}_{i}^{v} is the output of *ImgNet*.

Therefore, the whole objective function of *ImgNet* is denoted as follow:

$$\min_{F^v, H^v, \theta^v} \mathcal{L}_{\text{Img}} = \mathcal{J}_1 + \eta \mathcal{J}_2$$
 (14)

where η is the hyper-parameter to balance the two loss function terms.

3.4 Training Strategy

LabNet takes advantage of all label information to generate semantic features and hash codes. However, the learned semantic features and hash codes in LabNet may not match well with the corresponding semantic features and hash codes to be learned in ImgNet at the beginning. Therefore, we should exploit the strategy of alternative training to reconstruct the optimal semantic features and hash codes in semantic space and Hamming space, respectively.

Specifically, we first randomly initialize LabNet and train it until $\mathcal{L}_{\mathrm{lab}}$ reaches convergence. Then, utilizing the obtained semantic features and hash codes in LabNet, we supervise the ImgNet training in semantic space and Hamming space, respectively. Next, we initialize the semantic features and hash codes of LabNet with the resulting semantic feature and hash codes in ImgNet generated from the second step. Finally, repeating such training procedure for LabNet and ImgNet until convergence.

Algorithm 1 outlines the whole leaning algorithm in detail. It is noted that we learn all network parameters by utilizing stochastic gradient descent (SGD) with a back-propagation (BP) algorithm, which is also widely used in existing deep learning methods.

Algorithm 1 The learning algorithm for our DSEH

```
Input: Image set X, Label set L
Output: Parameters \theta^v of ImgNet, Optimal code matrix B
    Initialize network parameters \theta^l, \theta^v.
    hyper-parameters: \alpha, \beta, \gamma, and \eta.
    learning rate: \mu.
    mini-batch size: N^{l} = 32, N^{v} = 128.
     \  \, \text{maximum iteration number: } t^l,\!t^v.
     repeat
          for t^l iteration do
                 Update \theta^l by BP algorithm:
                 \theta^l \leftarrow \theta^l - \mu \cdot \nabla_{\theta^l} \frac{1}{n} \left( \mathcal{L}_{\text{lab}} \right)
          Update the parameter \boldsymbol{h}_{i}^{l} by \boldsymbol{h}_{i}^{l} = sign(\boldsymbol{h}_{i}^{l})

Update the parameter \boldsymbol{h}_{i}^{l'} by adjusting \boldsymbol{h}_{i}^{l} \in \{-1,1\}^{K} to \in \{0,1\}^{K}
          for t^v iteration do
                Update \theta^v by BP algorithm:

\theta^v \leftarrow \theta^v - \mu \cdot \nabla_{\theta^v} \frac{1}{n} (\mathcal{L}_{img})
          Update the parameter m{h}_i^v, m{h}_i^l by m{h}_i^v = sign(\hat{m{y}}_i^v), m{h}_i^l = sign(\hat{m{y}}_i^v) Update the parameter B by B = H^v
    until convergence
```

4 Experiments

4.1 Datasets and Settings

The experiments are conducted on three benchmark image retrieval datasets: NUS-WIDE [Chua et al., 2009], ImageNet [Russakovsky et al., 2015], and MS-COCO [Lin et al., 2014].

- NUS-WIDE dataset is a multi-label image dataset, which contains 269, 648 images with 81 ground truth concepts. We follow similar experimental protocols as DPSH [Li et al., 2015] and use the subset of 195, 834 images that are associated with the 21 most frequent concepts, where each concept contains at least 5,000 images. We randomly select 100 images per class as the query set, and 500 images per class as the training set.
- *ImageNet* dataset is a benchmark image dataset for Large Scale Visual Recognition Challenge (ILSVRC 2015), containing over 1.2M images. It is a single-label dataset, where each image is labeled by one of 1,000 categories. We randomly select 100 categories, and randomly select 50 images per class as the query set, 100 images per class as the training set.
- *MS-COCO* dataset is an image recognition, segmentation and caption dataset which contains 82, 783 training images and 40, 504 validation images. It is a multilabel dataset labeled by 80 categories. After pruning images without category information, we obtain 122, 218 images and randomly sample 5,000 images as queries, 10,000 images as training points.

We evaluate the retrieval quality using three evaluation metrics: Mean Average Precision (MAP), Precision-Recall curves, and Precision curves with respect to the number of top returned results. With the same training and test set, all methods were tested under the same conditions. Given a query, the ground truth is defined as: if a result shares at least one common concept with the query, it is relevant; otherwise it is irrelevant.

We compare our method with ten classical or stateof-art hashing methods, including unsupervised methods

Method	NUS-WIDE				ImageNet				MS-COCO			
	16 bits	32 bits	48 bits	64 bits	16 bits	32 bits	48 bits	64 bits	16 bits	32 bits	48 bits	64 bits
DSEH	0.7119	0.7312	0.7372	0.7422	0.5278	0.6137	0.6397	0.6548	0.5897	0.6048	0.6133	0.6188
HashNet	0.7007	0.7275	0.7301	0.7374	0.3260	0.4563	0.5018	0.5270	0.5600	0.5850	0.5989	0.6056
DHN	0.6512	0.6611	0.6675	0.6741	0.1838	0.2344	0.2375	0.2564	0.5353	0.5456	0.5486	0.5555
DPSH	0.6902	0.7049	0.7130	0.7158	0.2730	0.2841	0.3111	0.3242	0.5618	0.5774	0.5857	0.5901
CNNH	0.6573	0.6601	0.6716	0.6781	0.2488	0.3047	0.3263	0.3387	0.5115	0.5232	0.5283	0.5328
SDH	0.6488	0.6703	0.6811	0.6857	0.3687	0.4292	0.4446	0.4600	0.5312	0.5632	0.5634	0.5741
ITQ-CCA	0.6125	0.6472	0.6655	0.6766	0.2312	0.4061	0.4316	0.4568	0.5418	0.5658	0.5704	0.5715
KSH	0.6404	0.6636	0.6689	0.6731	0.3064	0.3874	0.4006	0.4168	0.5496	0.5574	0.5628	0.5688
ITQ	0.5715	0.5876	0.5910	0.5985	0.1668	0.2452	0.2929	0.3184	0.4834	0.4993	0.5111	0.5153
SH	0.4459	0.4504	0.4342	0.4244	0.1194	0.1776	0.2143	0.2335	0.4494	0.4400	0.4397	0.4316
LSH	0.4624	0.4431	0.4433	0.4816	0.0278	0.0526	0.0720	0.0966	0.3718	0.3807	0.3945	0.4119

Table 1: Mean Average Precision(MAP) of Hamming Ranking on three benchmark datasets.

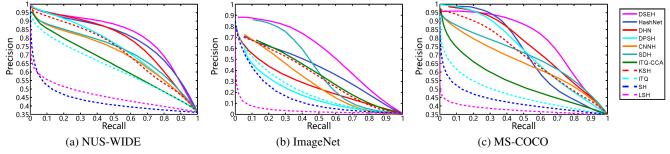


Figure 3: Precision-recall curves @ 32bits of our method and comparison methods on three benchmark datasets.

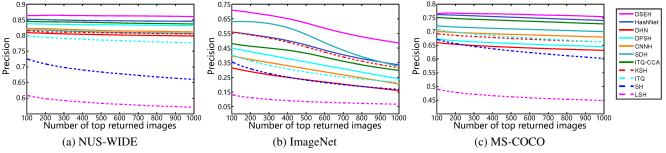


Figure 4: Precision w.r.t. top returned samples curves @ 32bits of our method and comparison methods on three benchmark datasets.

LSH [Gionis et al., 1999], SH [Weiss et al., 2009], ITQ [Gong et al., 2013], supervised shallow methods KSH [Liu et al., 2012], ITQ-CCA [Gong et al., 2013], SDH [Shen et al., 2015], and deep supervised methods CNNH [Xia et al., 2014], DPSH [Li et al., 2015], DHN [Zhu et al., 2016], HashNet [Cao et al., 2017].

For fair comparison, we extract 4,096-dimensional deep features by CNN-F [Chatfield et~al., 2014] model which is retrained on ImageNet dataset. We construct ImgNet to reserve first seven layers same with those in CNN-F followed fc8 with 512 nodes for semantic layer and K nodes for hash layer, i.e., $(I \rightarrow CNNF \rightarrow 512 \rightarrow K)$. LabNet is initialized randomly and constructed as $(L \rightarrow 4096 \rightarrow 512 \rightarrow K \rightarrow c)$, which contains c nodes for total class labels.

Since the semantic layer and hash layer are trained from scratch, we set its learning rate 10 times of the ones for the other layers. The learning rate is chosen from 10^{-2} to 10^{-6} with a validation set. The batch size of *LabNet* and *ImgNet* are set to 32 and 128 respectively. Since the semantic corre-

lation of ImageNet is sparse, we set the values in similarity matrix as $\mathcal{S} \in \{0,5\}$. For the hyper-parameters in LabNet, we conduct cross-validation to search α and γ from 10^{-3} to 10^2 , and search β from 10^{-6} to 10^{-1} . We find that the optimal result can be obtained when $\alpha = \gamma = 1$, and $\beta = 0.005$. Then we search from 10^{-3} to 10^2 and discover $\eta = 1$ is the best for ImgNet. It is noted that the parameter searching operations are performed with the searching step set to 5. Our model is implemented on **TensorFlow** [Abadi et al., 2016] on a server with two NVIDIA TITAN X GPUs.

4.2 Results and Discussions

Table 1 shows the results of different hashing methods on three benchmark datasets when the code length is 16, 32, 48, and 64 bits respectively. Fig. 3 and Fig. 4 show the Precision-Recall curves and Precision curves respectively for different methods on the code length of 32 bits.

On two multi-label datasets NUS-WIDE and MS-COCO, DSEH substantially outperforms all the compared baseline methods. Besides, almost all deep hashing methods outper-

Method		NUS-WIDE			ImageNet		MS-COCO			
	n_h	map_l	map_i	n_h	map_l	map_i	n_h	map_l	map_i	
DSEH	2008	0.9664	0.7312	100	1.0000	0.6137	1907	0.8276	0.6048	
DSEH-S	1959	0.9633	0.7208	100	1.0000	0.5988	1933	0.8260	0.5907	
DSEH-SS	1164	0.9322	0.7013	98	0.9825	0.5681	1220	0.7452	0.5237	
DSEH-L	1036	0.9607	0.7251	100	1.0000	0.6070	802	0.8199	0.5915	
DSEH-A	1684	0.9558	0.7234	100	1.0000	0.5576	1574	0.8134	0.5850	

Table 2: The results of ablation study @ 32bits of our DSEH.

form the traditional hashing baselines, which highlights the benefit of feature learning by deep networks that more discriminative representation can be obtained. Compared with other deep methods which utilize similarity pairs, DSEH achieves a substantial increase in average MAP at different code lengths. All the results shown in Table 1, Fig. 3 and Fig. 4 illustrate the superiority of our method. One reason may be that instead of utilizing similarity pairs information roughly, DESH exploring label information to generate semantic feature is very effective to generate more sufficient semantic information and thus produce more discriminative hash codes. Another reason is that sufficient semantic information obtained from LabNet can be retained completely and thus supervise ImgNet effectively when training ImgNet with the supervised information on the semantic level and hash codes level.

On ImageNet dataset which is annotated with single label. DHN, DPSH, and CNNH achieve under-performing results compared with the shallow baseline SDH, which demonstrates that network learning capacity can be dropped on single-label dataset because of the imbalance of pairs similarity. CNNH generates undiscriminating hash codes only under the supervision of pairwise similarity matrix. By adjusting the weight of similarity correlation, HashNet outperforms other baselines, which shows that adjusting weight can only alleviate influence of the data imbalance. The proposed DSEH significantly outperforms all other baselines. Compared with the state-of-the-art HashNet, we achieve about 34.50% increase in average MAP at different code lengths on this imbalanced dataset. It means that the proposed semantic feature learning and supervision to hashing learning can solve the issue of data imbalance in single-label dataset and thus hash codes can be generated more discriminative.

4.3 Empirical Analysis

Two different experiment settings are designed additionally to analyse the proposed method.

Visualization of Semantic Features: We visualize the semantic features generated by *LabNet* and *ImgNet* on NUS-WIDE at 32 bits in Fig. 5 (for convenience, 100 points are sampled and encapsulated by PCA [Wold *et al.*, 1987]). We observe that the semantic features of *LabNet* are abundant, indicating that the semantic information of labels is effectively exploited. Furthermore, the semantic features of *ImgNet* are similar to those in *LabNet*, inferring that *ImgNet* is well supervised in the common semantic space.

Ablation Study: We investigate the variants of DSEH on the three datasets. **DSEH-S** denotes that *ImgNet* without supervision on semantic layer from *LabNet*. **DSEH-SS** refers to that both *LabNet* and *ImgNet* without semantic supervision.

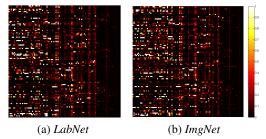


Figure 5: The visualization of semantic features.

DSEH-L denotes that *LabNet* drops direct label supervision. **DSEH-A** refers to that *LabNet* and *ImgNet* are trained only once without alternating manner.

Tabel 2 shows the average results of 10 runs of DSEH variants, where n_h is the total number of hash codes generated from $LabNet, map_l$ is the MAP of retrieving labels with hash codes generated by LabNet, and map_i is the MAP of retrieving images with the hash codes generated by ImgNet. DSEH outperforms all of its variants, which shows the effectiveness of each module. DSEH-SS achieves the worst performance, the main reason of which is that semantic supervision plays a very important role in the proposed framework. It is noted that the higher n_h is, the more diverse hash codes can be generated. DSEH-L reduces n_h dramatically, illustrating that more semantic information can be maintained by adding label supervision to the proposed method.

5 Conclusion

In this paper, we proposed a novel deep hashing method, namely DSEH, for image retrieval, which consists of *Lab-Net* and *ImgNet*. The *LabNet* is explored to discover abundant semantic correlation and generate accurate hash codes. Meanwhile, the *ImgNet* is jointly constrained with the supervision information from common semantic space and common Hamming space for generating similarity-preserving yet discriminative hash codes. Extensive experiments conducted on three widely-used datasets demonstrate that our proposed method significantly outperforms many state-of-the-art hashing approaches, including both traditional and deep learning-based ones.

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