Time		1 km	[ in		1	te.	11		15 bar	10 ka	v	m k	,	1	ber 17	a ar
ICTK=1			<u> </u>		<u> </u>	<u> </u>	<u> </u>	<u></u>	<u> </u>		<u>''''''</u> ''''	<u></u>	·	<del>,,,,,,,,,,,,,</del>	tec 27	
														<u> </u>		
a[3:0]=4	XXX		6	<u></u>		2	15	X6	χo		X2			X4		
	XXX		11	χ7		-3	X-4	<b>)</b> -6	<b>X</b> 2	<b>X</b> 0	<b>X</b> 3		-4	<b>X</b> -6		
	XXX		7	3		2	4		<b>X</b> 2	(10	(11	X		<b>)</b> 10		
	XXX		-7	(-4		-2	<b>X</b> 5	X4	<b>X</b> -2	(-4	-1	X	5	4		
a_q[3:0]=2	XXX		6			(2		<b>)</b> 6		X1		X	1			
b_q[3:0]=-4	XXX		1			-3		<b>X</b> -6		<b>X</b> 0		X	-4			
c_q[3:0]=6	XXX		7			2		)\4		10		Ý	5			
d_q[3:0]=5	XXX		-7			-2				)-4		===i	i			
i[31:0]=10	XXX	ln .	Xi I	<b>Y</b> 2		/3	<b>Y</b> 4	V:	Vs.	Ŷ7	Ys	<del></del>		<b>X</b> 10		
	XXX	*	Λ-	^ <del></del>	-48	<u> </u>	V-00	X-148 X-158	X-122	X-146 X-		X-87 X	-132 <b>/</b> -134		Y-193	
	XXX		0			(-48		X-98		Y-122	102		-167 A 151		1273	
				V 10		-40	V 00	V-20	V 100	N-122	V 1/2			V 100		
expected_out[15:0]=-129	0			<b>X</b> -48			<b>X</b> -98		-122		<b>X</b> -167	_		<b>X</b> -129		
control=0							L									