Flexible Applications with the SIA-series

The SIA-series are small and agile 7-axis robots providing "human-like" flexibility of movement and fast acceleration. They distinguish themselves through slim and lightweight design. They offer high payload and big working ranges. These agile and versatile robots open up a wide range of industrial applications: ideal for assembly, injection moulding, inspection, machine tending and a host of other operations.

These all-round robots can be driven by the high performance DX100 controller as well as the compact FS100 controller.

- Flexible applications · Compact design allows
 - maximum performance



MOTOMAN SIA-series

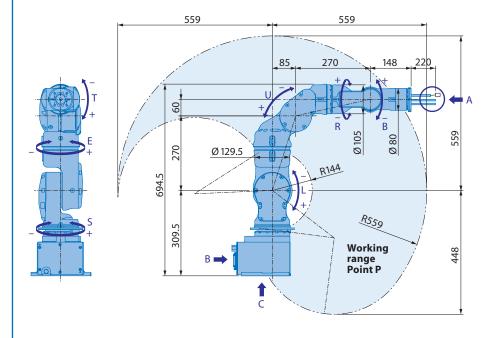


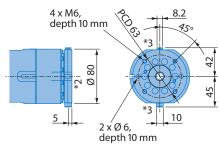




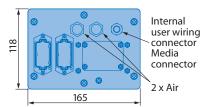




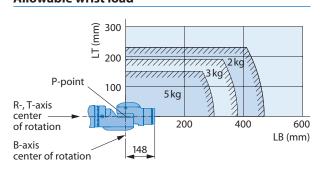




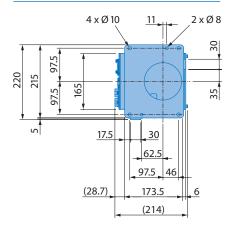
View B



Allowable wrist load



View C



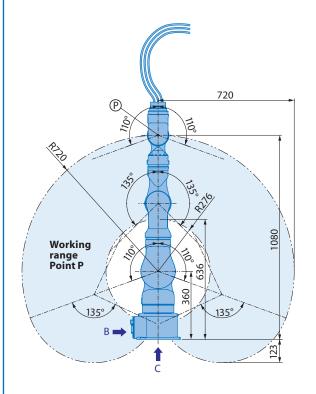
Mounting options: Floor, wall, ceiling

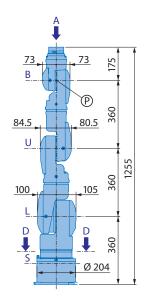


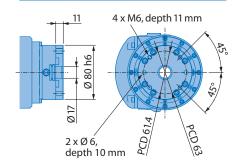
All dimensions in mm | Technical data may be subject to change without previous notice | Please request detailed drawings at robotics@yaskawa.eu.com – YR-SIA05D-A00, B-07-2012, A-No. 157198

Specifications SIA5F

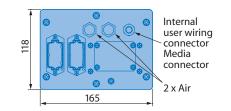
Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [Nm]	Allowable moment of inertia [kg·m²]	Controlled axes Max. payload [kg]	7 5
S	±180	200	-	-	Repeat. pos. accuracy [mm]	±0.6
L	±110	200	-	-	Max.reach [mm]	R = 559
θ	±170	200	-	-	Temperature [°C]	0.4 1.40
U	-90/+115	200	-	-	remperature [*C]	0 to +40
R	±180	200	14.7	0.45	Humidity [%]	20 – 80
В	±110	230	14.7	0.45	Weight [kg]	30
Т	±180	350	7.35	0.11	Power supply, average [KVA]	1.0



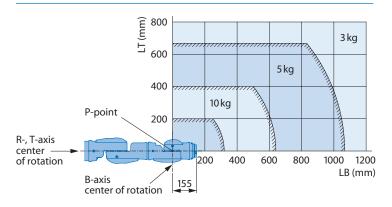




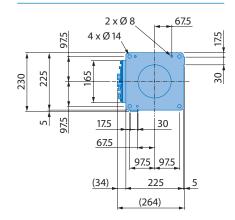
View B



Allowable wrist load



View C



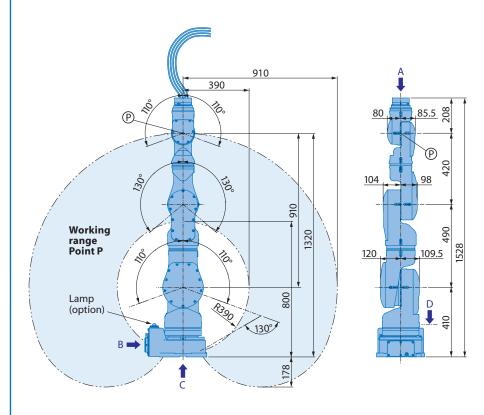
Mounting options: Floor, wall, ceiling

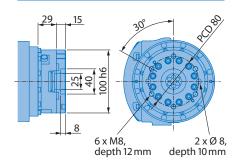


All dimensions in mm | Technical data may be subject to change without previous notice | Please request detailed drawings at robotics@yaskawa.eu.com – YR-SIA010D-A11, B-07-2012, A-No. 157198

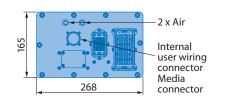
Specifications SIA10D, SIA10F

Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [Nm]	Allowable moment of inertia $[kg \cdot m^2]$	Controlled axes Max. payload [kg]	7 10
S	±180	170	-	-	Repeat. pos. accuracy [mm]	±0.6
L	±110	170	-	-	Max.reach [mm]	R = 720
θ	±170	170	-	-	Temperature [°C]	0 to +40
U	±135	170	-	-		0 10 +40
R	±180	200	31.4	1.0	Humidity [%]	20 – 80
В	±110	200	31.4	1.0	Weight [kg]	60
Т	±180	400	19.6	0.4	Power supply, average [KVA]	1.0

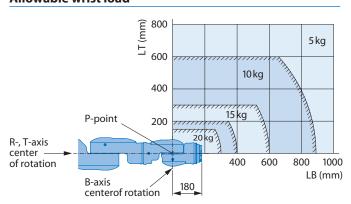




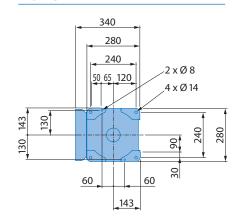
View B



Allowable wrist load



View C



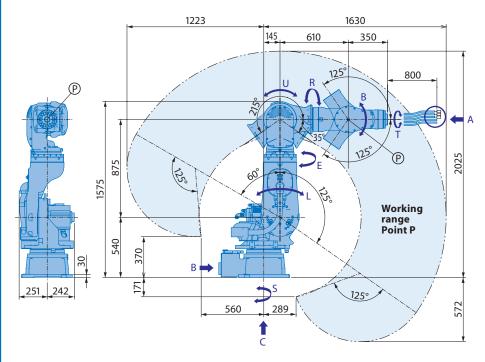
Mounting options: Floor, wall, ceiling

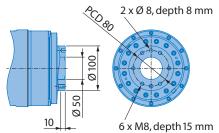


All dimensions in mm | Technical data may be subject to change without previous notice | Please request detailed drawings at robotics@yaskawa.eu.com – YR-SIA020D-A11, B-07-2012, A-No. 157198

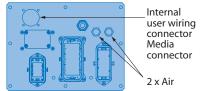
Specifications SIA20D, SIA20F

Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [Nm]	Allowable moment of inertia $[kg \cdot m^2]$	Controlled axes Max. payload [kg]	7 20
S	±180	130	-	-	Repeat. pos. accuracy [mm]	±0.1
L	±110	130	-	-	Max.reach [mm]	R = 910
θ	±170	170	-	-	Temperature [°C]	0 to +40
U	±130	170	-	-	remperature [*C]	0 10 +40
R	±180	200	58.8	4.0	Humidity [%]	20 – 80
В	±110	200	58.8	4.0	Weight [kg]	120
Т	±180	400	29.4	2.0	Power supply, average [KVA]	2.2

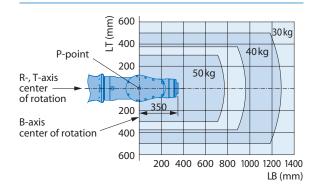




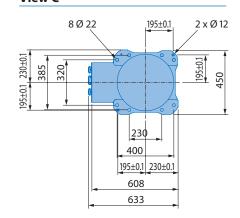
View B



Allowable wrist load



View C



Mounting options: Floor, wall, ceiling



All dimensions in mm | Technical data may be subject to change without previous notice | Please request detailed drawings at robotics@yaskawa.eu.com – YR-SIA050D-A00, B-07-2012, A-No. 157198

Specifications SIA50D

Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [Nm]	Allowable moment of inertia $[kg \cdot m^2]$	Controlled axes Max. payload [kg]	7 50
S	±180	170	-	-	Repeat. pos. accuracy [mm]	±0.1
L	-60/+125	130	-	-	Max.reach [mm]	R = 1485
θ	±170	130	-	-	Temperature [°C]	0 to +40
U	-35/+225	130	-	-	remperature [*C]	0 10 +40
R	±170	130	377	29.6	Humidity [%]	20 – 80
В	±125	130	377	29.6	Weight [kg]	640
Т	±180	200	14	12.5	Power supply, average [KVA]	5.0

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