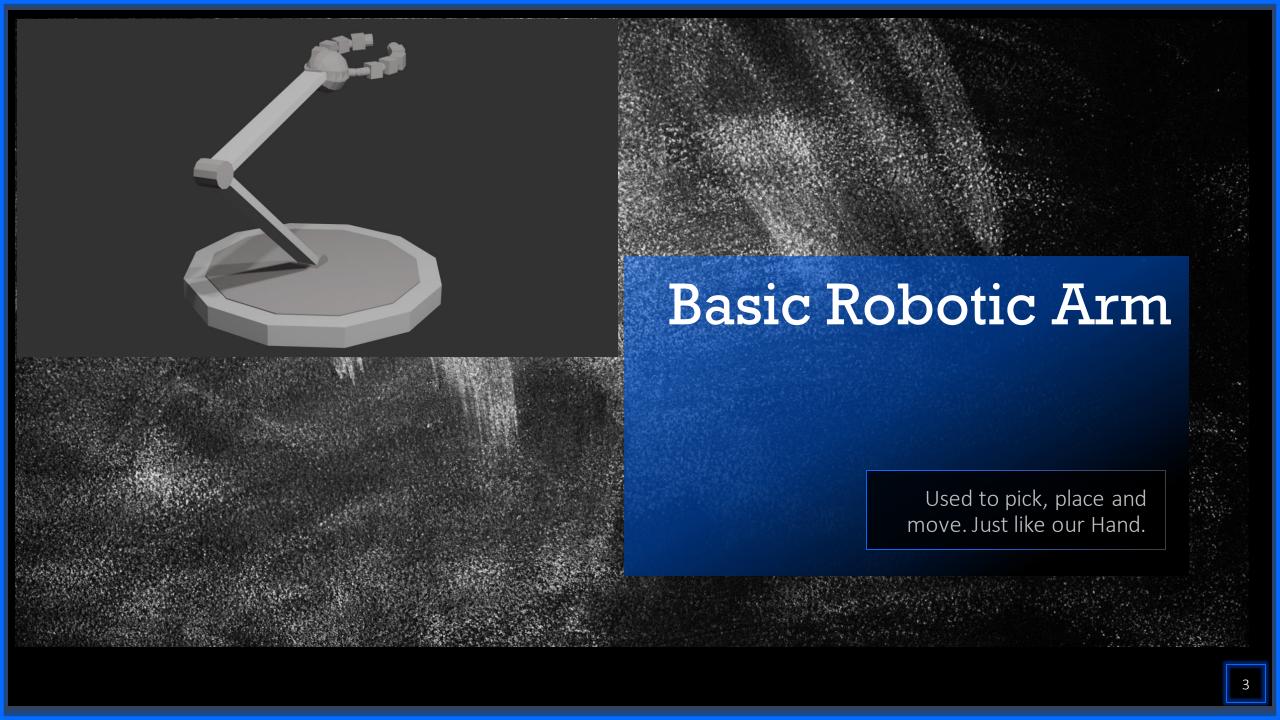
Handy Hands

By – Team Dyknoww

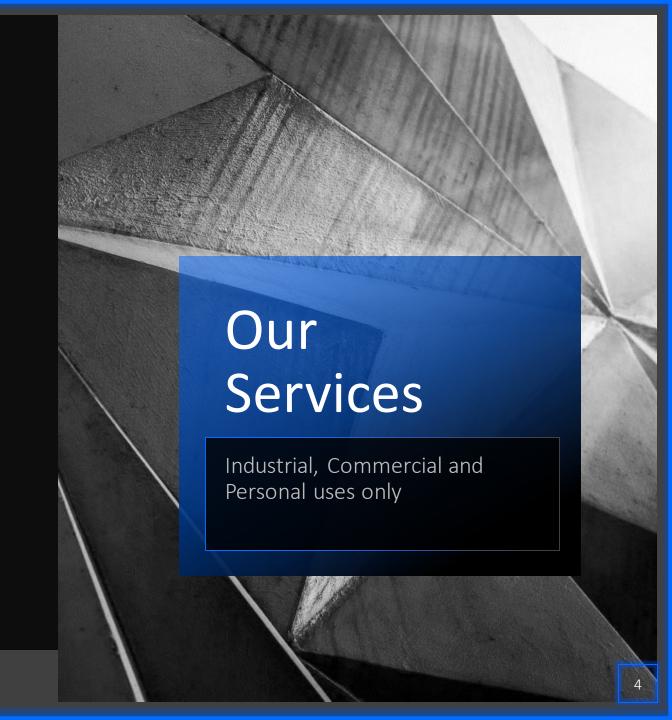
For Electrothon'20

An intermix of IoT and automation to build a new multipurpose device containing hardware and software to solve problems.



Industrial:

Use for high performance multitasks where a lot of synchronous robots are required.

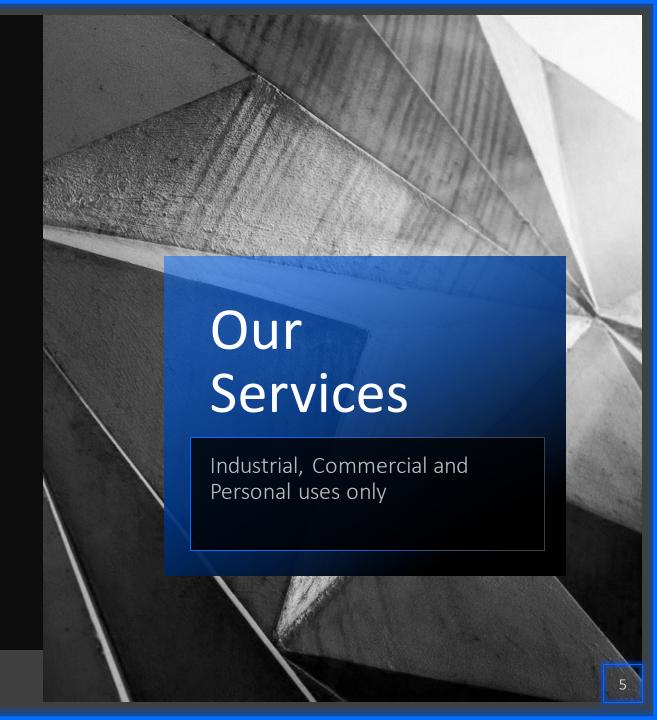


Commercial:

Use for performing specific tasks that are predefined in the app provided or by using OpenCV

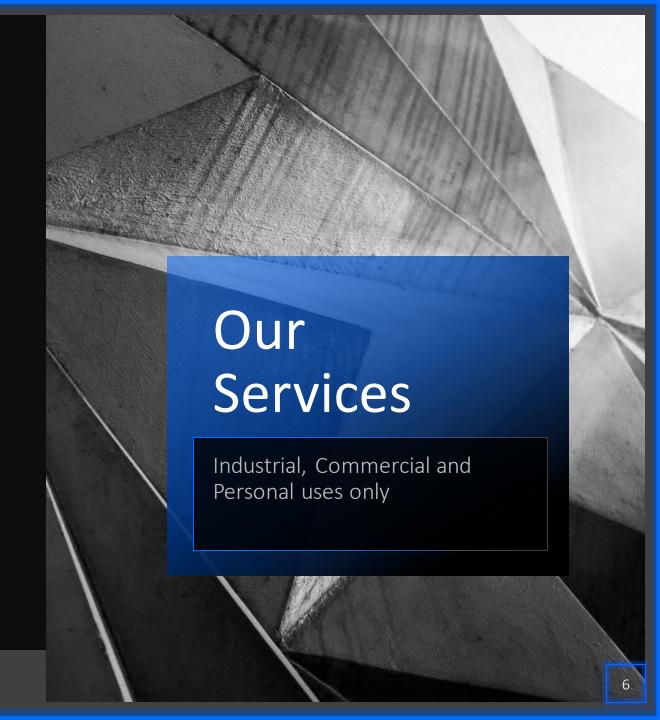
Tasks it can be used for:

- 1. Cam control
- 2. Holding stuff in proper place
- 3. Medical Purpose



Personal:

Use this manually and/or by voice Just like the robot of Iron-Man



Working but not only limited to:

Currently using our software to control the robotics hand but can be used to control any kind of hardware like: cars, drones, etc.

Things different in Software

- Complete new way of controlling high number of robotics
- Controlling stuff using IoT in hierarchy fashion
- Multi places to control a single

Things different in Hardware

- In robotic arm:
- Different type of claw to reduce processing and electronics usage
- Stability using Accelerometer so that claw stay in position and does not move at all

SM IoT

0.00 🔞 46 79% О 0.00 🔞 4 79% О 0.20 🔞 46 79% О 11:47:00 11:46:00 11:46:09 **SMIoT** Smayank.com BUTTON **BUTTON** {"placing component"} BUTTON BUTTON App created to make connecting BUTTON **BUTTON** to IoT device and interact with it. Data sent should be a number but not greater than "9999". BUTTON BUTTON This app also contains a feedback system use it through "Log". the data in the Logs you can use it BUTTON **BUTTON** to get data from your IoT device or send data compleatly different :-) BUTTON LOG **EDIT** LOG **EDIT** LOG **EDIT**

Zulip Bot

Levels of bots:

