[1] test here

test

[2]

[1]   Z. Ren, L. Wang, and L. Bi, "Robust GICP-based 3D LiDAR SLAM for underground mining environment," *Sensors*, vol. 19, no. 13, p. 2915, 2019.

[2]   V. Ress, W. Zhang, D. Skuddis, N. Haala, and U. Soergel, "SLAM for Indoor Mapping of Wide Area Construction Environments." arXiv, Apr. 2024. doi: 10.48550/arXiv.2404.17215.