

$$\frac{\partial H}{\partial u} = 0 \quad ; \quad \frac{\partial H}{\partial p} = \dot{x}(t)$$

$$\frac{\partial H}{\partial x} = -\dot{p}(t) \quad ; \quad p(t_f) = \frac{\partial \lambda}{\partial x}$$

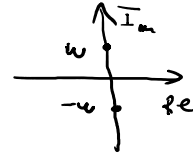
$$\dot{x}(t) = f(x(t), u(t), t) \quad u(t) = ?$$

$$J(u) = \lambda(\quad) + \int_{t_0}^{t_f} \mathcal{L}(x(t), u(t)) dt$$

$$H(x, u, t) = \mathcal{L}(\quad) + p^T(t) \cdot f(x(t), u(t), t)$$

$$H_p(s) = \frac{k}{s^2 + \omega^2}$$

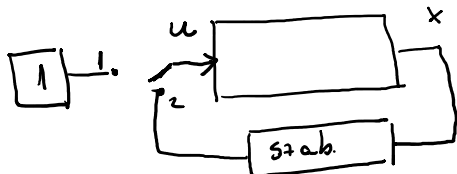
$$\rightarrow \lambda_{1,2} = \pm \omega j$$



$$|u(t)| \leq 1$$

$$J(u) = \int_{t_0}^{t_f} 1 dt = t_f - t_0$$

$$\boxed{\forall x_0 \rightarrow 0}$$



$$x_1 \rightarrow y$$

$$x_2 \rightarrow y$$

$$\begin{pmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{pmatrix} = \begin{pmatrix} 0 & \omega \\ -\omega & 0 \end{pmatrix} \cdot \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} u(t)$$

$$H(x, u, p, t) = 1 + (p_1(t) \ p_2(t)) \cdot \begin{pmatrix} \omega \cdot x_2(t) \\ -\omega \cdot x_1(t) + u(t) \end{pmatrix} =$$

$$= \boxed{1 + p_1(t) \cdot \omega \cdot x_2(t) - \omega \cdot p_2(t) \cdot x_1(t) + p_2(t) \cdot u(t)}$$

$$\frac{\partial H}{\partial u} = 0 \Rightarrow p_2(t) = 0 \rightarrow |u(t)| \rightarrow \{+1, -1\} \quad u^* = \begin{pmatrix} +1 \\ -1 \end{pmatrix}$$

$$u(t) = -\text{sign}(p_2(t))$$

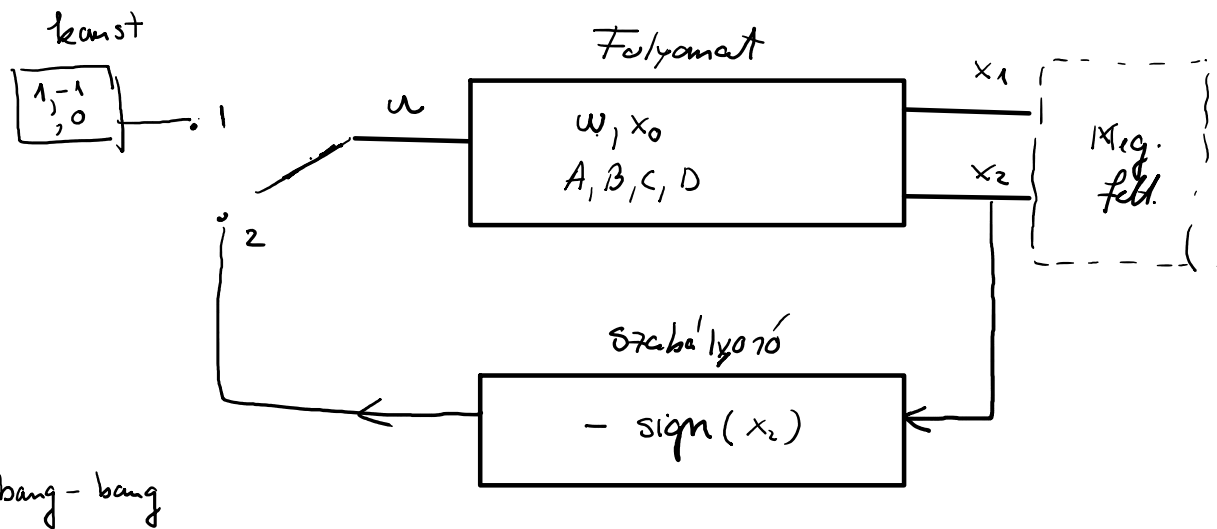
$$\frac{\partial H}{\partial x_1} = -\dot{p}_1(t) \Rightarrow \begin{cases} -\dot{p}_1(t) = -\omega \cdot p_2(t) \\ -\dot{p}_2(t) = \omega \cdot p_1(t) \end{cases} \Rightarrow \begin{pmatrix} \dot{p}_1(t) \\ \dot{p}_2(t) \end{pmatrix} = \begin{pmatrix} 0 & \omega \\ -\omega & 0 \end{pmatrix} \cdot \begin{pmatrix} p_1(t) \\ p_2(t) \end{pmatrix}$$

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$$\boxed{u(t) = -\text{sign}(x_2(t))}$$

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$x_1(t), x_2(t), u(t), x_1(x_2)$ Scope, XY Graph

$$\begin{cases} y_1 = x_1 \\ y_2 = x_2 \end{cases} \Rightarrow \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \end{pmatrix} u$$

$$|x_1| < \varepsilon \ \& \ |x_2| \leq \varepsilon \rightarrow \text{STOP}$$