- Two internal Timers/Counters
 - □ 16-bit timer/counter
- ☐ Timer uses system clock as source of input pulses
- □Counter uses external input pulses from port 3 (T0,T1)
- □ If associated interrupt is enabled, when count overflow an

interrupt is generated

Registers

- □TH0, TL0 : timer/counter register of timer 0
- □TH1, TL1: timer/counter register of timer 1
- □TMOD : Mode Select register
- □TCON: Control Register

TMOD and TCON Registers

	Timer/Counter 0	M1
2		C/T#
∞		GATE#
4	Timer/Counter 1	M0
2		M1
9		C/T#
7		GATE#

M0

TMOD

ITO
IE0
IT1
IE1
TRO
TF0
TR1
TF1

TCON

Operation Modes

Mode 0

- 013-bit counter, an interrupt is generated when counter overflows
- It takes 8192 input pulses to generate the next interrupt

Mode 1

16-bit counter, similar to mode 0, but take 65536 input pulses

Operation Modes (cont.)

Mode 2

- 8-bit reload
- TLi operates as timer/counter
- THi store a number and reload to TLi when overflows

Mode 3

- OTimer 1 is inactive, hold count value
- TL0 and TH0 operate as two separate 8-bit timer/counter
- TL0 control by timer 0 control bits
- TH0 operate as timer driven by system clock, prescaled by 12 and cause timer 1 interrupt overflows

Mode 0, like mode 1, except that it's 13-bit timer/counter Setup the timer 0, mode 1 -- 16-bit timer

```
timer_init:

mov TMOD, #1

setb TR0

mov TH0, #H_count

ret
```

In ISR, count value must be restored in subroutine mov TH0, #H_count mov TL0, #L_count call something timer0_isr:

Setup the timer 0, mode 2 -- 8-bit timer auto-reload

timer_init:
mov TMOD, #2
setb TR0
mov TH0, #count
ret

Mode 2, value is reload automatically from THx call something timer0_isr: reti

Setup the timer, mode 3

```
timer_init:

mov TMOD, #3

mov TH0, #Timer1_count

mov TL0, #Timer0_count

setb TR0

setb TR1

ret
```

timer0_isr: mov TL0, #Timer0_count call something0 reti

Timer mode 3

Mode 3, likes mode 1, but it is:

□ 8-bit counter

□TL0 is used for timer0□TH0 is used for timer1□TH1 & TL1 can be used for serial or other application

8051 Serial Port

SCON Register (cont.)

□SM1 & SM0 Serial Mode (bit 6 & 7)

Operating modes

Operating modes

□ Mode 0 8-bit shift register, f/12

1Mbit with 12Mhz Oscillator Frequency

□ Mode 1 8-bit UART, variable baud rate

0187.5K and 375K with 12MHz Oscillator Frequency □ Mode 2 9-bit UART, f/64 or f/32

□ Mode 3 9-bit UART, variable baud rate

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Baud Rate Variable Baud Rate

384 x (256 - TH1) SMOD Baud Rate =

TH-SMOD **Baud Rate**

62.5K 12.000 1 FFF 19.2K 11.059 1 FDI 9.6K 11.059 0 FDI 4.8K 11.059 0 FAF 1.2K 11.059 0 FAF 1.2K 11.059 0 FAF

8051 Serial Port

Initialize Serial Port Subroutine

TMOD, #20h; set timer 1 for auto reload TCON, #41h; run counter 1 edge trig SCON, #50h; 8-bit data mode 1 Set baud rate to 9600 for 11.0592 Crystal TH1, #0FDh; 9600 baud M₀V M₀V M₀V MOV

Sending and Receiving Subroutines

jnb RI, getchr mov A, SBUF clr RI getchr: TI, txloop mov SBUF, A quí sndchr: txloop:

<u>ē</u>

ret