

Week 12 Practice Problem Set - Laplace Transforms

Practice the questions in the following problem set and **submit only Qn No. 1a and 2a from Part 1 and Qn No. 2 from Part 2 as a single scanned pdf along with z-Transforms in Moodle.**

Part 1 Questions:

- Determine the Laplace Transform and the associated region of convergence and pole zero plot for each of the following functions of time:
 - $x_1(t) = e^{2t}u(t) + e^{-3t}u(t)$
 - $x_2(t) = |t|e^{-2|t|}$
- Determine the function of time $x(t)$, for each of the Laplace Transforms and their associated region of convergence.
 - $\frac{s^2-s+1}{(s+1)^2}, \operatorname{Re}\{s\} > -1$
 - $\frac{s+1}{s^2+5s+6}, -3 < \operatorname{Re}\{s\} < -2$
- Consider the signal $x(t) = e^{-5t}u(t) + e^{-\beta t}u(t)$ and denote its Laplace Transform by $X(s)$. What are the constraints placed on the real and imaginary parts of β if the region of convergence of $X(s)$ is $\operatorname{Re}\{s\} > -3$?

Part 2

- A causal LTI system S with impulse response $h(t)$ has its input $x(t)$ and output $y(t)$ related through a linear constant coefficient differential equation of the form,

$$\frac{d^3 y(t)}{dt^3} + (1 + \alpha) \frac{d^2 y(t)}{dt^2} + \alpha(1 + \alpha) \frac{dy(t)}{dt} + \alpha^2 y(t) = x(t)$$

- If $g(t) = \frac{dh(t)}{dt} + h(t)$, how many poles does $G(s)$ have?
 - For what real parameter α is S guaranteed to be stable?
- Consider the RL circuit shown below:

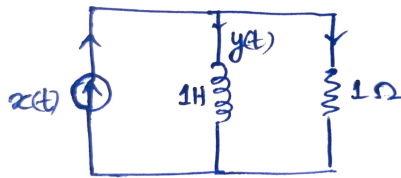


Figure 1:

- Determine the zero state response of the circuit when input current is $x(t) = e^{-2t}u(t)$.

- (b) Determine the zero-input response of the circuit for $t > 0^-$, given that $y(0^-) = 1$.
 - (c) Determine the output of the circuit when the input current is $x(t) = e^{-2t}u(t)$ and the initial condition is same as the one specified in part (b)
3. Consider an LTI system with input $x(t) = e^{-t}u(t)$ and impulse response $h(t) = e^{-2t}u(t)$.
- (a) Determine the Laplace transforms of $x(t)$ and $h(t)$. Further, using convolution property, determine the LT $Y(s)$ of the output $y(t)$.
 - (b) From $Y(s)$ obtained in part (a), determine $y(t)$.