

### Ex. 3.8

We will examine the QR decomposition of  $X$  and notice what remains when we put it in terms of  $Q_2$ .

$X = QR$ , Now if  $\hat{Z}_i = \frac{Z_i}{\|Z_i\|}$  (as described by alg 3.1)

We have:  $Q = [\hat{Z}_0, \hat{Z}_1, \dots, \hat{Z}_p]$  (dim:  $N \times (P+1)$ )

and by def of  $D$  and  $\Gamma$ :

$$R = \begin{bmatrix} \langle \hat{Z}_0, 1 \rangle & \langle \hat{Z}_0, x_1 \rangle & \dots & \langle \hat{Z}_0, x_p \rangle \\ 0 & & & \\ \vdots & & & \\ 0 & & R_2 & \end{bmatrix}$$

We will call the first row  $R_1$ , a  $1 \times (P+1)$  vector.

Then we are left with  $\bar{O}_p$  a  $P \times 1$  vector of 0's and  $R_2$ , the  $P \times P$  remainder of  $R$ .

Solving  $R_1$  using:

$$\langle \hat{Z}_0, 1 \rangle = \frac{N}{\sqrt{N}}$$

$$\text{and } \langle \hat{Z}_0, x_i \rangle = \frac{\sum x_i}{N}$$

Note: This is the sum of the  $N$  elements of the vector  $x_i$

$$\Rightarrow R_1 = \frac{1}{\sqrt{N}} [N, \sum x_1, \sum x_2, \dots, \sum x_p]$$

Thus we can decompose  $QR$ :

$$X = QR = \hat{Z}_0 R_1 + Q_2 [\bar{O}_p, R_2]$$

$$\hat{Z}_0 R_1 = \begin{bmatrix} 1 & \bar{x}_1 & \bar{x}_p \\ 1 & \bar{x}_1 & \bar{x}_p \\ \vdots & \vdots & \vdots \\ 1 & \bar{x}_1 & \bar{x}_p \end{bmatrix} \quad (N \times (P+1))$$



$$X - \hat{Z}_0 R_1 = [\bar{O}_N, Q_2 R_2]$$

$(N \times P+1) \qquad \qquad (N \times P+1)$

$$\Rightarrow [\bar{O}_N, \tilde{X}] = [\bar{O}_N, Q_2 R_2]$$

So  $\tilde{X} = Q_2 R_2 \Rightarrow Q_2$  spans the column space of  $\tilde{X}$

And by definition of SVD for  $\tilde{X} = U D V^T$ , we know that  $U$  also spans the column space of  $\tilde{X}$ .

Under what circumstances is  $Q_2 = U$ ?

Suppose  $\tilde{X}$  is orthogonal, then:

$$\tilde{X} = Z_2 D_2^{-1} D_2 \Gamma_2 = Q_2 R_2$$

Here we find:

$$Z_2 = [X_1 - \bar{X}_1, \dots, X_P - \bar{X}_P]$$

$$D_2 = \text{diag}(\|X_1 - \bar{X}_1\|, \dots, \|X_P - \bar{X}_P\|)$$

$$\Gamma_2 = I_P$$

$$\Rightarrow Q_2 = [\hat{X}_1, \dots, \hat{X}_P] \quad \text{where} \quad \hat{X}_i = \frac{X_i - \bar{X}_i}{\|X_i - \bar{X}_i\|}$$

Now we simply notice that  $Q_2 D_2 \Gamma_2$  is a valid SVD of  $\tilde{X}$  where  $Q_2 = U$ ,  $D_2 = D$  and  $\Gamma_2 = V^T$ .

And since we know that the SVD is unique up to a sign flip then we can conclude that if  $\tilde{X}$  is orthogonal then  $Q_2 = U$  up to a sign flip.