	Ex 3.11
	We will (conveniently) skip over some of the
	tricky matrix differenciation here by themes making
	use of the books step from 3.38 to 3.34.
	2.9.
	IF RSS(B) = tr [(y-XB)T(y-XB)] (*)
	then $X^T(Y-XB)=0$
	and $B = (X^TX)^{-1}X^TY$
	THE RESIDENCE OF THE STATE OF T
	Now we wish to estimate B when
	$Rss(B, \Sigma) = tr \Gamma(y - xB) \Sigma^{-1}(y - xB)^{T}$
	(using tr(ATB) = tr(ABT))
	Z-1
(A), to 3	Now, since Σ^{-1} is Positive definite and Symmetric
AUX Pa	We can rewrite it as $\Sigma^{-1} = 55^{\circ}$ Where 5
	is also Positive definite and Symetric.
(4,3)+3	- OCC I F (CON COT (V P)T]
th dest by 1 of 2	=> RSS = tr[(y-XB)SST(y-XB)]
	= tr [(ys-xBS) ST(yT-BTXT)]
	$= tr \left[(ys - XBS)(S^{T}Y^{T} - S^{T}B^{T}X^{T}) \right]$ $= tr \left[(ys - XBS)((ys)^{T} - (XBB)^{T}) \right]$
	= tr [(ys-XBs)(ys-XBs)]
	= tr [(ys-XBS) (ys-XBS)]
	Now using (*)
	$X^{T}(ys - x\hat{B}s) = 0$
	XTYS = XTX BS
	$(X^TX)^{-1}X^TYS = \hat{I}\hat{S}S$
	$(X^T X)^{-1} X^T Y = \hat{B}$ as required