| | Ex 3.24 |
|---|--|
| 2 | |
| | We will use the fact that the angle or between two vectors a, b is given by: |
| | Vectors a, b is given by: |
| | -1/a.b) |
| | |
| | |
| | Noticing that UK is an NXI Vector, we wish to man Calculate the angle between each Predictor Xj, iEAK |
| | man Calculate the angle between each Predictor Xj, JEAK |
| | and the Vector Un. Using (*) this is given by: |
| | |
| | $\alpha = \cos^{-1}\left(\frac{X_1 \cdot u_k}{ X_1 \cdot u_k }\right)$ |
| | |
| | $= \cos^{-1}\left(\frac{X_{i}^{T} \cdot U_{i}}{U_{i}}\right) \text{since} X_{i} = 1 \text{(unit norm)}$ |
| | Un |
| | |
| | > Thus if XiT. UK is constant ViEAK then the |
| | cingle of is also constant. |
| | |
| | XAR UK = XAR XAR JR (by definition) |
| | |
| | = XT XAK (XAK XAK) XAK TK |
| | |
| | = XAKTK |
| | |
| | and Since each Predictor X; in the active Set Ax |
| | has equal correlation with the current residual [k |
| | by definition in algorithm 3.2, we can conclude |
| | that the LAR direction Un Makes an equal angle |
| | With each of the Predictors in Ax. |
| | |
| | |
| | |