

9-16.

①. 1. $(0,0)$ 是唯-平衡点.

2. $A^T P + P A = -4I$

$\Rightarrow P = \begin{bmatrix} 5 & 1 \\ 1 & 1 \end{bmatrix} > 0$

| 又 \because 线性系统

\therefore 系统在 $(0,0)$ 是大范围渐近稳定.

②

1. $(0,0)$ 平衡点.

2. $V(x) = \frac{1}{2}(x_1^2 + x_2^2)$

$\dot{V} = x_1 \dot{x}_1 + x_2 \dot{x}_2$

$= (x_1^2 + x_2^2)^2 - (x_1^2 + x_2^2)$

Let $x_1^2 + x_2^2 = y$

$= y^2 - y$

$= (y - \frac{1}{2})^2 - \frac{1}{4}$

if $\dot{V} < 0$

$\Rightarrow y - \frac{1}{2} < \frac{1}{2}$

$y < 1$

$x_1^2 + x_2^2 < 1$ 时 $\dot{V} < 0$

\therefore 对于 $(0,0)$ 点, $x_1^2 + x_2^2 < 1$ 时
渐近稳定.

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