

P1-4.1

$$(a) \vec{S} = \vec{E} \times \vec{H} = \hat{r} \frac{wk^2 q^2 \ell^2}{16\pi^2 \epsilon_0 r^2} \sin^2 \theta \cos^2(kr - \omega t)$$

$$\langle \vec{S} \rangle = \frac{1}{2\pi} \int_0^{2\pi} d(\omega t) \vec{E} \times \vec{H} = \hat{r} \frac{wk^2 q^2 \ell^2}{32\pi^2 \epsilon_0 r^2} \sin^2 \theta$$

$$(b) P = \oint \vec{S} \cdot \hat{n} dS = \int_0^\pi d\theta \sin\theta \int_0^{2\pi} d\phi \frac{wk^2 q^2 \ell^2}{32\pi^2 \epsilon_0 r^2} \sin^2 \theta = \frac{wk^2 q^2 \ell^2}{12\pi \epsilon_0}$$

$$(c) R_{rad} = \frac{2P}{I_0} = \frac{2}{wq\ell} \cdot \frac{wk^2 q^2 \ell^2}{12\pi \epsilon_0} = \frac{k^2 \ell^2}{6\pi \epsilon_0 w}$$

$$(d) \theta = \frac{\pi}{2} \quad E_0 = -\frac{k^2 q \ell}{4\pi \epsilon_0 r} \quad \therefore q\ell = -\frac{4\pi \epsilon_0 r}{k^2} E_0$$

$$P = \frac{2\pi}{3\eta_0} (E_0 r)^2 = \frac{2\pi}{3\eta_0} (25 \times 10^{-3} \times 15 \times 10^3)^2 = 781.25 \text{ W}$$

P1-6.1

$$\oint_{\partial S} (\vec{\omega} \times \vec{E}) d\vec{s} = \oint_{\partial S} \left( -\frac{\partial \vec{B}}{\partial t} \right) d\vec{s}$$

$$\Rightarrow \oint_{\partial S} d\vec{t} \cdot \vec{E} = -\frac{\partial \vec{B}}{\partial t} \cdot \hat{n} d\omega$$

$$\Rightarrow \oint_{\partial S} (\hat{n} \times \vec{E}) \cdot (\vec{E}_1 - \vec{E}_2) = -\frac{\partial \vec{B}}{\partial t} \cdot \hat{n} d\omega$$

$$\Rightarrow (\hat{n} \times \vec{E}) \cdot (\vec{E}_1 - \vec{E}_2) = -\frac{\partial \vec{B}}{\partial t} \cdot \hat{n} d\omega$$

$$\Rightarrow \oint_{\partial S} (\hat{n} \times (\vec{E}_1 - \vec{E}_2)) = \oint_{\partial S} \left( -\frac{\partial \vec{B}}{\partial t} \right) d\omega$$

$$\therefore d\omega \rightarrow 0 \quad \therefore \hat{n} \times (\vec{E}_1 - \vec{E}_2) = -\lim_{d\omega \rightarrow 0} \frac{\partial \vec{B}}{\partial t} \cdot \hat{n} d\omega = 0$$

$$\oint_{\partial S} (\vec{\omega} \times \vec{H}) = \oint_{\partial S} \left( \frac{\partial \vec{D}}{\partial t} + \vec{J} \right)$$

$$\text{同理可得} \quad \hat{n} \times (\vec{H}_1 - \vec{H}_2) = \lim_{d\omega \rightarrow 0} \left( \frac{\partial \vec{D}}{\partial t} + \vec{J} \right) \cdot \hat{n} d\omega = \lim_{d\omega \rightarrow 0} \vec{J} \cdot \hat{n} d\omega \quad \left. \begin{array}{l} \text{导线} \Rightarrow = 0 \\ \text{面电流} \Rightarrow = \vec{J}_s \end{array} \right\}$$

P1-6.2

$$\iiint dV \vec{\omega} \times \vec{H} \approx A \hat{z} \times (\vec{H}_2 z_0 - \vec{H}_1 z_0)$$

$$= A \Delta z \frac{\partial \vec{D}}{\partial t} + A \Delta z \vec{J}$$

$$\Delta z \rightarrow 0 \quad \therefore \Delta z \frac{\partial \vec{D}}{\partial t} \rightarrow 0 \quad \vec{J} \text{ 无界} \quad \Delta z \vec{J} = \vec{J}_s$$

$$\therefore \iiint dV \vec{\omega} \times \vec{H} \approx A \cdot \vec{J}_s$$

P1-6.3

$$\iiint dV (\vec{\omega} \cdot \vec{D}) = \iiint dV \rho$$

$$\oint_{\partial S} d\vec{s} \cdot \vec{D} = \iiint dV \rho$$

$$\lim_{\Delta S \rightarrow 0} \hat{n} \Delta S \cdot (\vec{D}_1 - \vec{D}_2) = \lim_{\Delta S \rightarrow 0} \Delta S \rho$$

$$\therefore \hat{n} \cdot (\vec{D}_1 - \vec{D}_2) = \lim_{\Delta S \rightarrow 0} \rho \Delta S = \rho_s \quad \text{体电荷密度}$$