





Math Foundations Team

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Introduction



- ► Till now we have discussed about Taylor/Maclaurian series, Partial Derivatives and Gradients.
- Now we are interested in Higher order Derivatives.
- Multivariate Taylor Series and its uses in the expansion of a function with multivariables.

Higher-Order Derivatives



Consider a function $f: \mathbb{R}^2 \to \mathbb{R}$

Notations for Higher-Order Partial Derivatives:

 $\frac{\partial^2 f}{\partial x^2}$: Second Partial Derivative of x w.r.t. x

 $\frac{\partial^n f}{\partial x^n}$: n^{th} Partial Derivative of x w.r.t. x

 $\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right)$: is the partial derivative obtained by first partial differentiating with respect to x and then with respect to y.

 $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} (\frac{\partial f}{\partial y})$: is the partial derivative obtained by first partial differentiating by y and then x.

Hessian Matrix



The Hessian is the collection of all second-order partial derivatives. If f(x, y) is a twice (continuously) differentiable function, then $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$ i.e., the order of differentiation does not matter, and the corresponding Hessian matrix

$$\mathbf{H} = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix}$$

is symmetric. The Hessian is denoted as $\nabla^2_{x,y} f(x,y)$

Linearization and Multivariate Taylor Series



The gradient ∇f of a function f is often used for a locally linear approximation of f around x_0 :

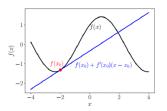
$$f(x) \approx f(x_0) + (\nabla_x f)(x_0)(x - x_0) \tag{1}$$

Here $(\nabla_x f)(x_0)$ is the gradient of f with respect to x, evaluated at x_0 . Figure illustrates the linear approximation of a function f at an input x_0 . The original function is approximated by a straight line.

Linearization and Multivariate Taylor Series...



This approximation is locally accurate, but the farther we move away from x_0 the worse the approximation gets. Equation (1) is a special case of a multivariate Taylor series expansion of f at x_0 , where we consider only the first two terms. We discuss the more general case in the following, which will allow for better approximations.



Linear approximation of a function. The original function f is linearized at $x_0 = -2$ using a first-order Taylor series expansion.

Multivariate Taylor Series



Consider a function $f: \mathbb{R}^D \to \mathbb{R}, x \to f(x)$,

$$x \in \mathbb{R}^D$$

that is smooth at x_0 . When we define the difference vector $\delta := x - x_0$ the multivariate Taylor series of f at (x_0) is defined as multivariate Taylor series

$$f(x) = \sum_{k=0}^{\infty} \frac{D_x^k f(x_0)}{k!} \delta^k$$
 (2)

where $D_x^k f(x_0)$ is the k^{th} (total) derivative of f with respect to x, evaluated at x_0 .

Taylor Polynomial



The Taylor polynomial of degree n of Taylor polynomial f at x_0 contains the first n+1 components of the series in (2) and is defined as

$$T_n(x) = \sum_{k=0}^n \frac{D_x^k f(x_0)}{k!} \delta^k$$
 (3)

In (2) and (3), we used the slightly sloppy notation of δ^k , which is not defined for vectors

$$x \in \mathbb{R}^D$$
,

D>1, and k>1. Note that both $D_x^k f$ and δ^k are k^{th} order tensors, i.e., k-dimensional arrays.

Taylor Polynomial...



k times

kth-order tensor $\delta^k \in \mathbb{R}^{\widetilde{D \times D \times ... \times D}}$ is obtained as a k-fold outer product, denoted by \otimes , of the vector $\delta \in \mathbb{R}^D$. For example,

$$\boldsymbol{\delta}^2 := \boldsymbol{\delta} \otimes \boldsymbol{\delta} = \boldsymbol{\delta} \boldsymbol{\delta}^\top \,, \quad \boldsymbol{\delta}^2[i,j] = \delta[i]\delta[j]$$

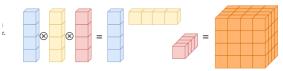
$$\boldsymbol{\delta}^3 := \boldsymbol{\delta} \otimes \boldsymbol{\delta} \otimes \boldsymbol{\delta}, \quad \boldsymbol{\delta}^3[i,j,k] = \delta[i]\delta[j]\delta[k].$$

Taylor Polynomial...





(a) Given a vector $\delta \in \mathbb{R}^4$, we obtain the outer product $\delta^2 := \delta \otimes \delta = \delta \delta^\top \in \mathbb{R}^{4 \times 4}$ as a matrix.



(b) An outer product $\delta^3:=\delta\otimes\delta\otimes\delta\in\mathbb{R}^{4\times4\times4}$ results in a third-order tensor ("three-dimensional matrix"), i.e., an array with three indexes.

$$D_{\boldsymbol{x}}^k f(\boldsymbol{x}_0) \boldsymbol{\delta}^k = \sum_{i_1=1}^D \cdots \sum_{i_k=1}^D D_{\boldsymbol{x}}^k f(\boldsymbol{x}_0)[i_1, \dots, i_k] \delta[i_1] \cdots \delta[i_k]$$

Taylor Polynomial...



In general, we obtain the terms in the Taylor series, where $D_x^k f(x_0) \delta^k$ contains k^{th} order polynomials. Now that we defined the Taylor series for vector fields, let us explicitly write down the first terms $D_x^k f(x_0) \delta^k$ of the Taylor series expansion for

$$\begin{split} k &= 0, \dots, 3 \text{ and } \boldsymbol{\delta} := \boldsymbol{x} - \boldsymbol{x}_0 : \\ k &= 0 : D_x^0 f(\boldsymbol{x}_0) \boldsymbol{\delta}^0 = f(\boldsymbol{x}_0) \in \mathbb{R} \\ k &= 1 : D_x^1 f(\boldsymbol{x}_0) \boldsymbol{\delta}^1 = \underbrace{\nabla_{\boldsymbol{x}} f(\boldsymbol{x}_0)}_{1 \times D} \underbrace{\boldsymbol{\delta}}_{D \times 1} = \sum_{i=1}^D \nabla_{\boldsymbol{x}} f(\boldsymbol{x}_0)[i] \boldsymbol{\delta}[i] \in \mathbb{R} \\ k &= 2 : D_x^2 f(\boldsymbol{x}_0) \boldsymbol{\delta}^2 = \operatorname{tr} \big(\underbrace{\boldsymbol{H}(\boldsymbol{x}_0)}_{D \times D} \underbrace{\boldsymbol{\delta}}_{D \times 1} \underbrace{\boldsymbol{\delta}}_{1 \times D}^\top \big) = \boldsymbol{\delta}^\top \boldsymbol{H}(\boldsymbol{x}_0) \boldsymbol{\delta} \\ &= \sum_{i=1}^D \sum_{j=1}^D \boldsymbol{H}[i,j] \boldsymbol{\delta}[i] \boldsymbol{\delta}[j] \in \mathbb{R} \\ k &= 3 : D_x^3 f(\boldsymbol{x}_0) \boldsymbol{\delta}^3 = \sum_{i=1}^D \sum_{j=1}^D \sum_{j=1}^D D_x^3 f(\boldsymbol{x}_0)[i,j,k] \boldsymbol{\delta}[i] \boldsymbol{\delta}[j] \boldsymbol{\delta}[k] \in \mathbb{R} \end{split}$$

Here, $H(x_0)$ is the Hessian of f evaluated at x_0 .



Consider the function $f(x, y) = x^2 + 2xy + y^3$.

We want to compute the Taylor series expansion of f at $(x_0, y_0) = (1, 2)$.

Before we start, let us discuss what to expect: The function in f(x,y) is a polynomial of degree 3. We are looking for a Taylor series expansion,which itself is a linear combination of polynomials. Therefore, we do not expect the Taylor series expansion to contain terms of fourth or higher order to express a third-order polynomial. This means that it should be sufficient to determine the first four terms of $f(x) = \sum_{k=0}^{\infty} \frac{D_x^k f(x_0)}{k!} \delta^k$ for an exact alternative representation of f(x,y). To determine the Taylor series expansion, we start with the constant term and the first-order derivatives, which are given by f(1,2) = 13



$$\frac{\partial f}{\partial x} = 2x + 2y \implies \frac{\partial f}{\partial x}(1,2) = 6$$
$$\frac{\partial f}{\partial y} = 2x + 3y^2 \implies \frac{\partial f}{\partial y}(1,2) = 14.$$

Therefore, we obtain

$$D^1_{x,y}f(1,2) = \nabla_{x,y}f(1,2) = \begin{bmatrix} \frac{\partial f}{\partial x}(1,2) & \frac{\partial f}{\partial y}(1,2) \end{bmatrix} = \begin{bmatrix} 6 & 14 \end{bmatrix} \in \mathbb{R}^{1 \times 2}$$

such that

$$\frac{D_{x,y}^1 f(1,2)}{1!} \delta = \begin{bmatrix} 6 & 14 \end{bmatrix} \begin{bmatrix} x-1 \\ y-2 \end{bmatrix} = 6(x-1) + 14(y-2).$$

Therefore, we obtain

$$D^1_{x,y}f(1,2) = \nabla_{x,y}f(1,2) = \begin{bmatrix} \frac{\partial f}{\partial x}(1,2) & \frac{\partial f}{\partial y}(1,2) \end{bmatrix} = \begin{bmatrix} 6 & 14 \end{bmatrix} \in \mathbb{R}^{1 \times 2}$$



When we collect the second-order partial derivatives, we obtain the Hessian

$$\boldsymbol{H} = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 6y \end{bmatrix} ,$$

such that

$$H(1,2) = \begin{bmatrix} 2 & 2 \\ 2 & 12 \end{bmatrix} \in \mathbb{R}^{2 \times 2}$$
.

Therefore, the next term of the Taylor-series expansion is given

$$\begin{split} \frac{D_{x,y}^2 f(1,2)}{2!} \pmb{\delta}^2 &= \frac{1}{2} \pmb{\delta}^\top \pmb{H}(1,2) \pmb{\delta} \\ &= \frac{1}{2} \begin{bmatrix} x-1 & y-2 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 2 & 12 \end{bmatrix} \begin{bmatrix} x-1 \\ y-2 \end{bmatrix} \\ &= (x-1)^2 + 2(x-1)(y-2) + 6(y-2)^2 \,. \end{split}$$



The third-order derivatives are obtained as

$$D_{x,y}^{3}f = \begin{bmatrix} \frac{\partial \mathbf{H}}{\partial x} & \frac{\partial \mathbf{H}}{\partial y} \end{bmatrix} \in \mathbb{R}^{2 \times 2 \times 2},$$

$$D_{x,y}^{3}f[:,:,1] = \frac{\partial \mathbf{H}}{\partial x} = \begin{bmatrix} \frac{\partial^{3}f}{\partial x^{3}} & \frac{\partial^{3}f}{\partial x^{2}\partial y} \\ \frac{\partial^{3}f}{\partial x\partial y\partial x} & \frac{\partial^{3}f}{\partial x\partial y^{2}} \end{bmatrix},$$

$$D_{x,y}^{3}f[:,:,2] = \frac{\partial \mathbf{H}}{\partial y} = \begin{bmatrix} \frac{\partial^{3}f}{\partial y\partial x^{2}} & \frac{\partial^{3}f}{\partial y\partial x\partial y} \\ \frac{\partial^{3}f}{\partial y^{2}\partial x} & \frac{\partial^{3}f}{\partial y^{3}} \end{bmatrix}.$$



Since most second-order partial derivatives in the Hessian, are constant, the only nonzero third-order partial derivative is $\frac{\partial^3 f}{\partial v^3} = 6 \implies \frac{\partial^3 f}{\partial v^3}(1,2) = 6$ Higher-order derivatives and the mixed derivatives of degree 3 (e.g., $\frac{\partial^3 f}{\partial x^2 \partial y}$) vanish, such that

$$D_{x,y}^3 f[:,:,1] = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \quad D_{x,y}^3 f[:,:,2] = \begin{bmatrix} 0 & 0 \\ 0 & 6 \end{bmatrix}$$

and

$$\frac{D_{x,y}^3 f(1,2)}{3!} \delta^3 = (y-2)^3,$$



which collects all cubic terms of the Taylor series. Overall, the (exact) Taylor series expansion of f at $(x_0, y_0) = (1, 2)$ is

$$\begin{split} f(x) &= f(1,2) + D_{x,y}^{1} f(1,2) \delta + \frac{D_{x,y}^{2} f(1,2)}{2!} \delta^{2} + \frac{D_{x,y}^{3} f(1,2)}{3!} \delta^{3} \\ &= f(1,2) + \frac{\partial f(1,2)}{\partial x} (x-1) + \frac{\partial f(1,2)}{\partial y} (y-2) \\ &+ \frac{1}{2!} \left(\frac{\partial^{2} f(1,2)}{\partial x^{2}} (x-1)^{2} + \frac{\partial^{2} f(1,2)}{\partial y^{2}} (y-2)^{2} \right. \\ &+ 2 \frac{\partial^{2} f(1,2)}{\partial x \partial y} (x-1) (y-2) \right) + \frac{1}{6} \frac{\partial^{3} f(1,2)}{\partial y^{3}} (y-2)^{3} \\ &= 13 + 6(x-1) + 14(y-2) \\ &+ (x-1)^{2} + 6(y-2)^{2} + 2(x-1)(y-2) + (y-2)^{3} \,. \end{split}$$