

Alternating Current Mindmap.

AC Current:-

→ Direction of current changes alternatively.

$$i = i_0 \sin \omega t \quad V = V_0 \sin \omega t$$

$$i_{rms} = \frac{i_0}{\sqrt{2}} \quad V_{rms} = \frac{V_0}{\sqrt{2}}$$

$$i_{avg} = \frac{2i_0}{\pi} \quad V_{avg} = \frac{2V_0}{\pi}$$

L-C-R Circuit:-

$$V_0 = I_0 \sqrt{(X_L - X_C)^2 + R^2}$$

$$Z = \sqrt{(X_L - X_C)^2 + R^2}$$

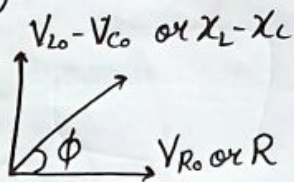
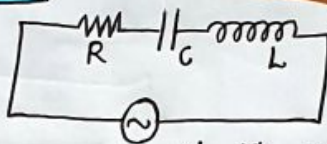
$$V_{rms} = I_{rms} Z$$

$$\langle P \rangle = i_{rms} V_{rms} \cos \phi$$

$$= \frac{i_0}{\sqrt{2}} \frac{V_0}{\sqrt{2}} \cos \phi$$

$$\text{and } \cos \phi = \frac{R}{Z}$$

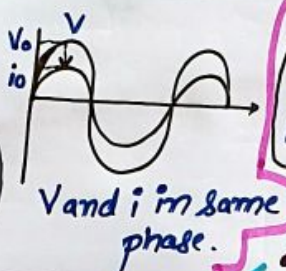
$$\tan \phi = \frac{X_L - X_C}{R}$$



R-Circuit:-

$$i_0 = \frac{V_0}{R}, \quad i_{rms} = \frac{V_{rms}}{R}$$

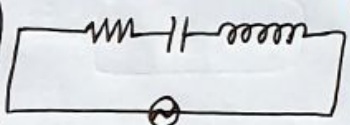
$$i_{rms} = \frac{i_0}{\sqrt{2}}, \quad V_{rms} = \frac{V_0}{\sqrt{2}}$$



Resonance in L-C-R:-

$$V = V_0 \sin(\omega t + \phi)$$

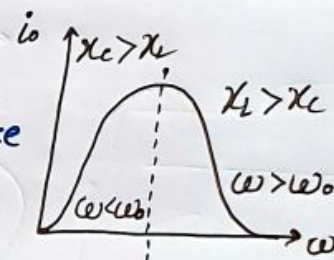
$$i_0 = \frac{V_0}{Z} = \frac{V_0}{\sqrt{(X_L - X_C)^2 + R^2}}$$



• Resonant frequency

$$f_0 = \frac{1}{2\pi\sqrt{LC}}$$

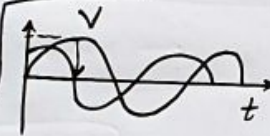
- At resonance
- $i_0 = \text{max}$
- $X_L = X_C$
- $Z = R$
- $\cos \phi = 1, \omega_0 = \frac{1}{\sqrt{LC}}$



C-Circuit:-

$$V = V_0 \sin \omega t \quad i = i_0 \sin(\omega t + \frac{\pi}{2})$$

$$i_0 = \frac{V_0}{X_C} = \frac{V_0}{\frac{1}{\omega C}} = \omega C V_0$$



$$\langle P \rangle = 0$$

→ Current leads voltage by $\pi/2$.

L-Circuit:-

$$V = V_0 \sin \omega t \quad i = i_0 \sin(\omega t - \frac{\pi}{2})$$

$$i_0 = \frac{V_0}{X_L} = \frac{V_0}{\omega L}$$



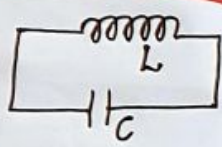
$$\langle P \rangle = 0$$

→ Voltage leads current by $\pi/2$.

LC Oscillation

$$q = q_0 \cos \omega t$$

$$I = -\frac{dq}{dt}$$



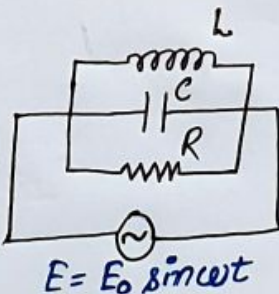
$$\omega = \frac{1}{\sqrt{LC}}$$

$$E = \frac{q^2}{2C} + \frac{1}{2} L I^2$$

Parallel L-C-R:-

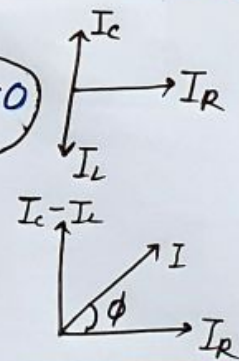
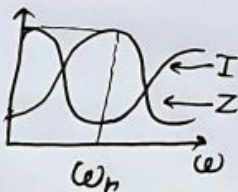
$$I = \sqrt{(I_C - I_L)^2 + (I_R)^2}$$

$$\frac{1}{Z} = \sqrt{\left[\frac{1}{X_C} - \frac{1}{X_L}\right]^2 + \left[\frac{1}{R}\right]^2}$$



At resonance

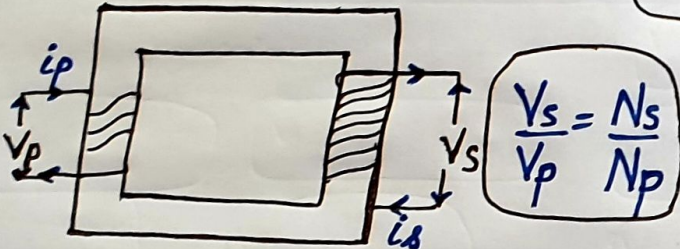
$$\omega_r = \frac{1}{\sqrt{LC}} \text{ and } \phi = 0$$



Transformers: →

→ used to change an alternating voltage from one to another.

$$V_s = -N_s \frac{d\phi}{dt}$$



$$V_p I_p = V_s I_s$$

→ $N_s > N_p$ → step up

$$\frac{I_s}{I_p} = \frac{V_p}{V_s} = \frac{N_p}{N_s}$$

→ $N_p > N_s$ → step down

→ No loss in flux and energy → Ideal

$$\eta = \frac{P_{out}}{P_{in}} \times 100$$

Quality Factor

$$Q = \frac{\omega_0}{\text{Bandwidth}}$$

$$Q = \frac{\omega_0 L}{R}$$

Efficiency Of Motor

$$\eta = \frac{P_{out}}{P_{in}} = \frac{E}{V}$$



NEET
SLAYER