

# CprE 3810: Computer Organization and Assembly-Level Programming

## Project Part 1 Report

Team Members:

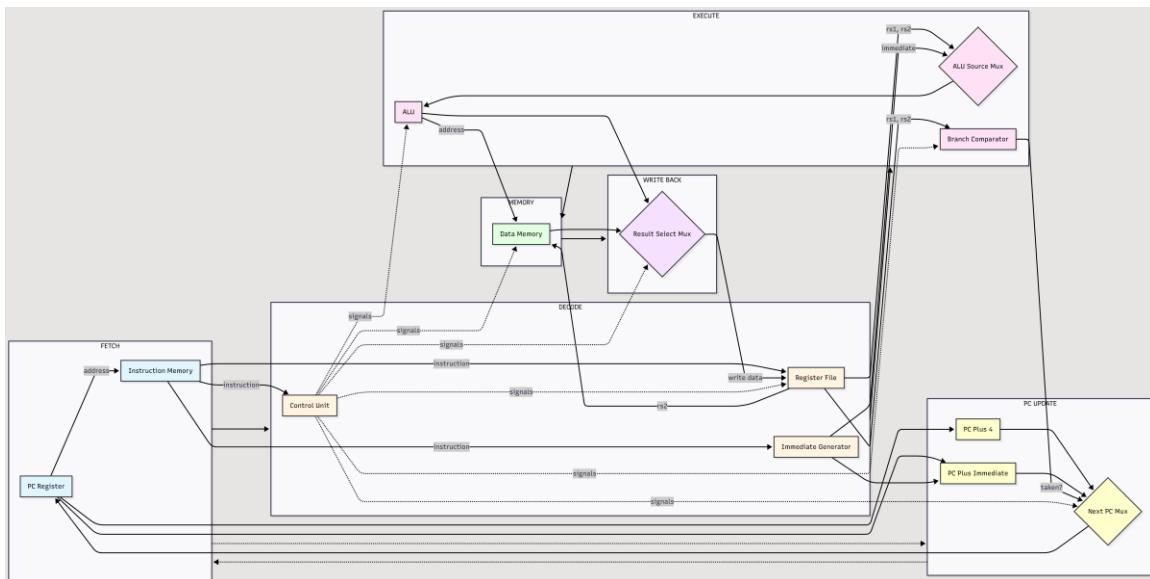
Austin Hunwardsen

Peter Knipper

Project Teams Group #: F\_03

*Refer to the highlighted language in the project 1 instruction for the context of the following questions.*

[Part 2 (d)] Include your final RISC-V processor schematic in your lab report.



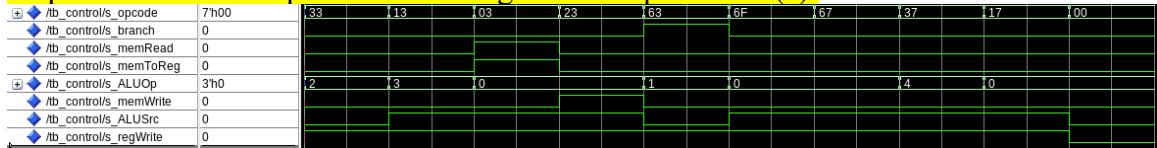
[Part 3.1.a.] Create a spreadsheet detailing the list of  $M$  instructions to be supported in your project alongside their binary opcodes and funct fields, if applicable. Create a separate column for each binary bit. Inside this spreadsheet, create a new column for the  $N$  control signals needed by your datapath implementation. The end result should be an  $N \times M$  table where each row corresponds to the output of the control logic module for a given instruction.

Instruction	Type	O[6]	O[5]	O[4]	O[3]	O[2]	O[1]	O[0]	F3[2]	F3[1]	F3[0]	F7[5]	Branch	MemRead	MemToReg	MemWrite	ALUsrc	RegWrite	ALUOp[2]	ALUOp[1]	ALUOp[0]
ADD	R	0	1	1	0	0	1	1	0	0	0	0	0	0	0	0	0	1	0	1	0
SUB	R	0	1	1	0	0	1	1	0	0	0	1	0	0	0	0	0	1	0	1	0
SLL	R	0	1	1	0	0	1	1	0	0	1	0	0	0	0	0	0	1	0	1	0
SLT	R	0	1	1	0	0	1	1	0	1	0	0	0	0	0	0	0	0	1	0	1
SLTU	R	0	1	1	0	0	1	1	0	1	1	0	0	0	0	0	0	1	0	1	0
XOR	R	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0	1	0	1
SRL	R	0	1	1	0	0	1	1	1	0	1	0	0	0	0	0	0	0	1	0	1
SRA	R	0	1	1	0	0	1	1	1	0	1	1	0	0	0	0	0	1	0	1	0
OR	R	0	1	1	0	0	1	1	1	1	0	0	0	0	0	0	0	0	1	0	1
AND	R	0	1	1	0	0	1	1	1	1	1	0	0	0	0	0	0	0	1	0	1
ADDI	I	0	0	1	0	0	1	1	0	0	0	X	0	0	0	0	0	1	1	0	1
SLTI	I	0	0	1	0	0	1	1	0	1	0	X	0	0	0	0	0	1	1	0	1
SLTIU	I	0	0	1	0	0	1	1	0	1	1	X	0	0	0	0	0	1	1	0	1
XORI	I	0	0	1	0	0	1	1	1	0	0	X	0	0	0	0	0	1	1	0	1



J A L	J	1	1	0	1	1	1	X	X	X	X	0	0	0	0	1	1	0	0	0	
J A L R	I	1	1	0	0	1	1	1	0	0	0	X	0	0	0	0	1	1	0	0	0
L U I	U	0	1	1	0	1	1	1	X	X	X	X	0	0	0	0	1	1	1	0	0
A U I P C	U	0	0	1	0	1	1	1	X	X	X	X	0	0	0	0	1	1	0	0	0

[Part 3.1.(b)] Implement the control logic module using whatever method and coding style you prefer. Create a testbench to test this module individually and show that your output matches the expected control signals from problem 1(a).



[Part 3.2. (a)] What are the control flow possibilities that your instruction fetch logic must support? Describe these possibilities as a function of the different control flow-related instructions you are required to implement.

Sequence:  $PC \leftarrow PC + 4$  (normal instruction flow)

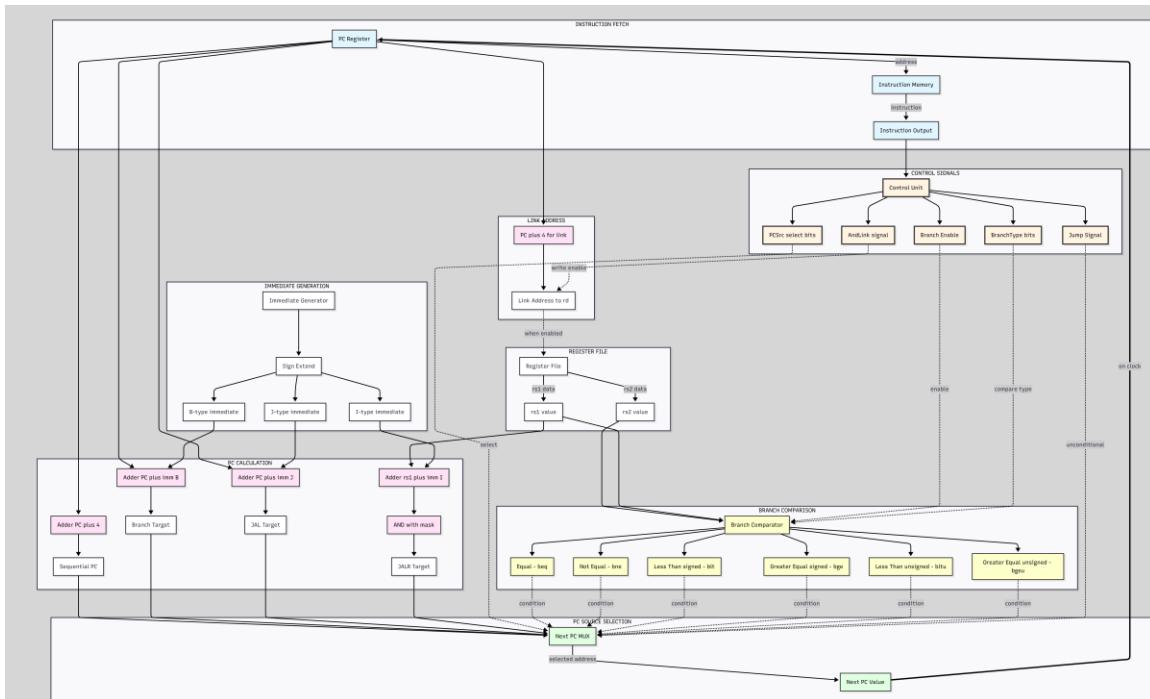
Branch taken:  $PC \leftarrow PC + (\text{sign\_extended\_imm} \ll 1)$

JAL:  $PC \leftarrow PC + (\text{UJ\_immediate} \ll 1)$

JALR:  $PC \leftarrow (\text{RS1} + \text{I\_immediate}) \& \sim 1$  (clear LSB)

Reset:  $PC \leftarrow 0x00400000$  (RARS default start address)

[Part 3.2. (b)] Draw a schematic for the instruction fetch logic and any other datapath modifications needed for control flow instructions. What additional control signals are needed?



The fetch unit includes four PC calculation paths: PC+4 (sequential), PC+imm\_B (branches), PC+imm\_J (JAL), and (rs1+imm\_I) & ~1 (JALR). A multiplexer selects the next PC based on instruction type and branch conditions.

### Additional Control Signals Needed:

**PCSrc[1:0]**: Selects PC source (sequential, branch, JAL, or JALR)

**Branch**: Enables branch comparison logic

**BranchType[2:0]**: Specifies which branch condition to check (beq, bne, blt, bge, bltu, bgeu)

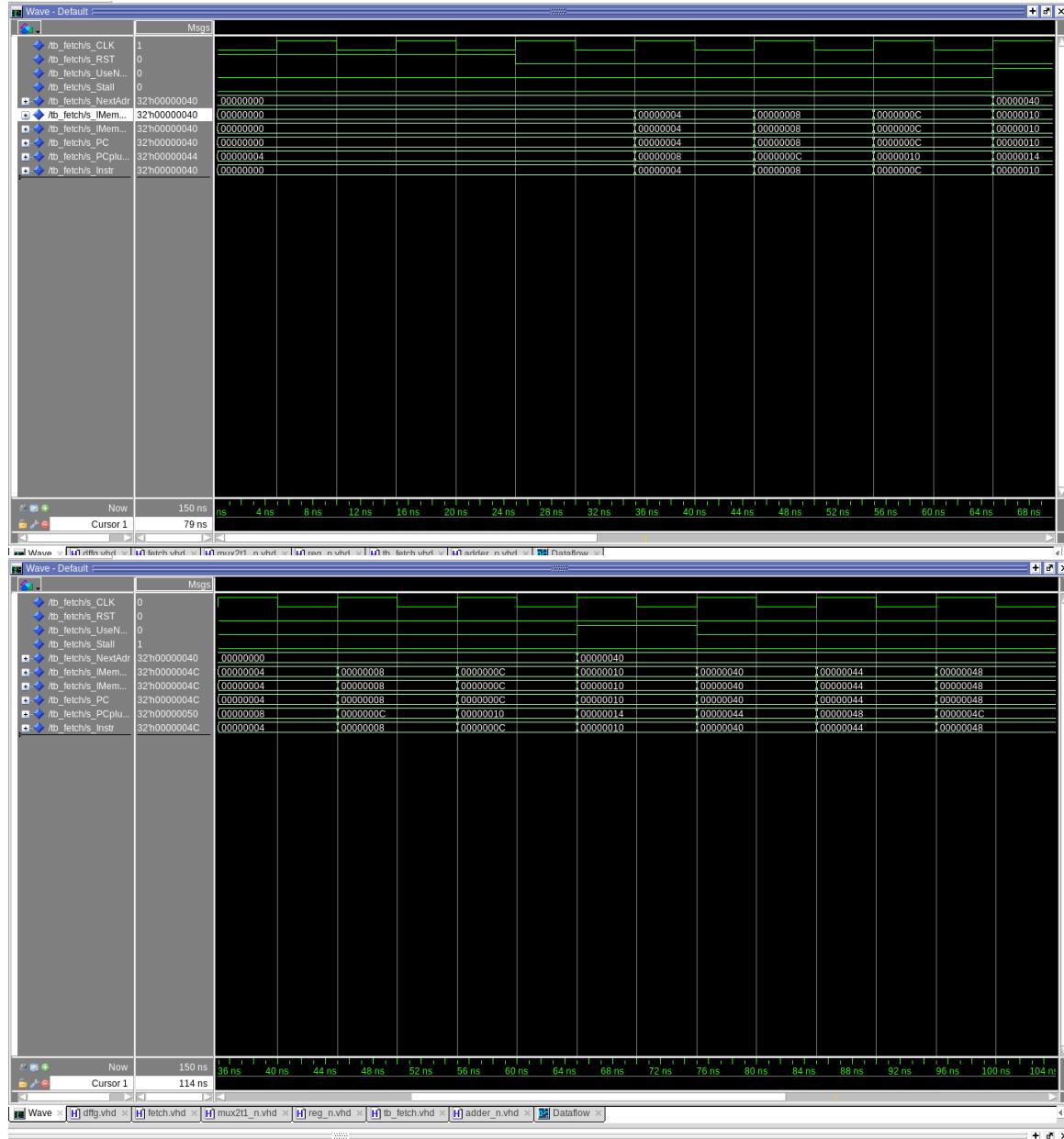
**Jump**: Indicates unconditional jump (JAL)

**AndLink**: Saves PC+4 to rd for JAL/JALR

R-type, I-type, Load, Store, LUI, and AUIPC instructions use sequential addressing (PCSrc = 00).

**AUSTIN**

[Part 3.2.(c)] Implement your new instruction fetch logic using VHDL. Use QuestaSim to test your design thoroughly to make sure it is working as expected. Describe how the execution of the control flow possibilities corresponds to the QuestaSim waveforms in your writeup.



$\rightarrow 0x0000000C \rightarrow 0x00000010$ , etc. The `s_PCplus4` signal is computed combinationally, one cycle ahead of the register update.

**Address & Instruction Fetch:** `s_ImemAddr` tracks the current `s_PC`, and `s_Instr` reflects the instruction fetched from that address. Since `s_UseNextAdr=0`, `s_NextAdr` equals `s_PCplus4`, selecting the sequential path through the PC mux every cycle.

**Summary:** With `Stall=0`, the fetch unit delivers one instruction per cycle with the PC advancing by 4 on each rising edge, exactly as designed.

[Part 3.3.1.(a)] Describe the difference between logical (`srl`) and arithmetic (`sra`) shifts. Why does RISC-V not have a `sla` instruction?

Logical shifts are unsigned while arithmetic shifts are signed. RISC-V does not have `sla` because it is the same as `sll`. If a number is shifted to the left, the right will get filled with zeros regardless of the signed or unsigned property of the data.

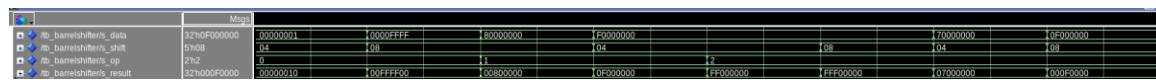
[Part 3.3.1.(b)] In your writeup, briefly describe how your VHDL code implements both the arithmetic and logical shifting operations.

By using two-bit codes for each type of shift, the shifter can determine the type of shift to attempt. The only difference between logical and arithmetic shifts is if `i_data` is classified as signed or unsigned. This will fill the left of the value with either 1s or 0s depending on the first bit and the signed status.

[Part 3.3.1.(c)] In your writeup, explain how the right barrel shifter above can be enhanced to also support left shifting operations.

The barrel shifter has already implemented left shifting. The only difference is using the `shift_left` VHDL function instead of `shift_right`. There is no need to sign the left shift as the bits will be added to the right side of the data.

[Part 3.3.1.(d)] Describe how the execution of the different shifting operations corresponds to the QuestaSim waveforms in your writeup.



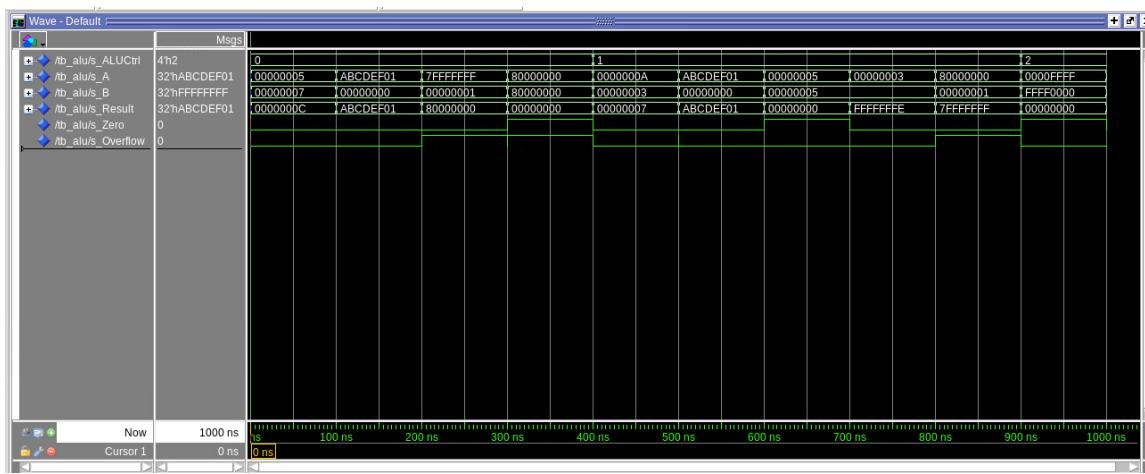
The first 2 cycles test the SLL. The first test properly shifts the data to the left by four bits and the second shifts it by 8. The next two cycles test SRL. The first properly shifts the

data to the right by eight bits and the second shifts it to the right by four. The left gets filled by zeros because SRL is unsigned. The last four cycles test SRA. The first two cycles of the SRA tests shift a negative number to the right by 4 and 8 bits respectively. The leftmost bits get filled by ones as the negative sign of the number needs to be preserved.. The last two cycles of the SRA tests shift a positive number to the right four and eight bits respectively. The leftmost bits get filled with zeros as the positive sign of the number needs to be preserved.

[Part 3.3.2.(a)] In your writeup, briefly describe your design approach, including any resources you used to choose or implement the design. Include at least one design decision you had to make.

Our ALU design consists of four main functional units: an adder/subtractor (for ADD/SUB with carry and overflow flags), logic gates (AND/OR/XOR), a comparator (SLT/SLTU using the subtractor's sign and overflow outputs), and a barrel shifter (SLL/SRL/SRA). We unified the ALU control to 4 bits to cover all R-type and I-type operations in a single encoding space. A key design decision was routing shift operations through a dedicated barrel shifter while bypassing it for arithmetic and logic operations to reduce critical path delay. We referenced the RISC-V base specification for instruction mapping and course lab notes for our Datapath.

[Part 3.3.2.(b)] Describe how the execution of the different operations corresponds to the QuestaSim waveforms in your writeup.



The figure above shows the simulation output from tb\_alu.vhd. Each ~100 ns cycle tests a different ALU operation controlled by ALUCtrl, displaying inputs s\_A, s\_B, and outputs s\_Result, s\_Zero, and s\_Overflow.

Cycle 0 (0–100 ns) – Addition:  $s\_A = 0x00000005$ ,  $s\_B = 0x00000007$ , result =  $0x0000000C$ . Zero = 0, verifying correct ADD operation.

Cycle 1 (100–200 ns) – Subtraction:  $s\_A = 0xABCD01$ ,  $s\_B = 0xFFFFFFF$ , result =  $0xABCD02$  ( $A + 1$ ), confirming SUB with sign preservation.

Cycle 2 (200–300 ns) – SLT (signed):  $s\_A = 0x7FFFFFFF > 0x80000000$ , result =  $0x00000000$ , Zero = 1, validating signed comparison.

Cycle 3 (300–400 ns) – AND:  $s\_A = 0x80000000$ ,  $s\_B = 0x00000001$ , result =  $0x00000000$ , Zero = 1, confirming bitwise AND.

Cycle 4 (400–500 ns) – OR:  $s\_A = 0x0000000A$ ,  $s\_B = 0x00000003$ , result =  $0x0000000B$ , verifying logic OR.

Cycle 5 (500–600 ns) – XOR:  $s\_A = 0xABCD01$ ,  $s\_B = 0x00000000$ , result =  $0xABCD01$ , confirming XOR identity.

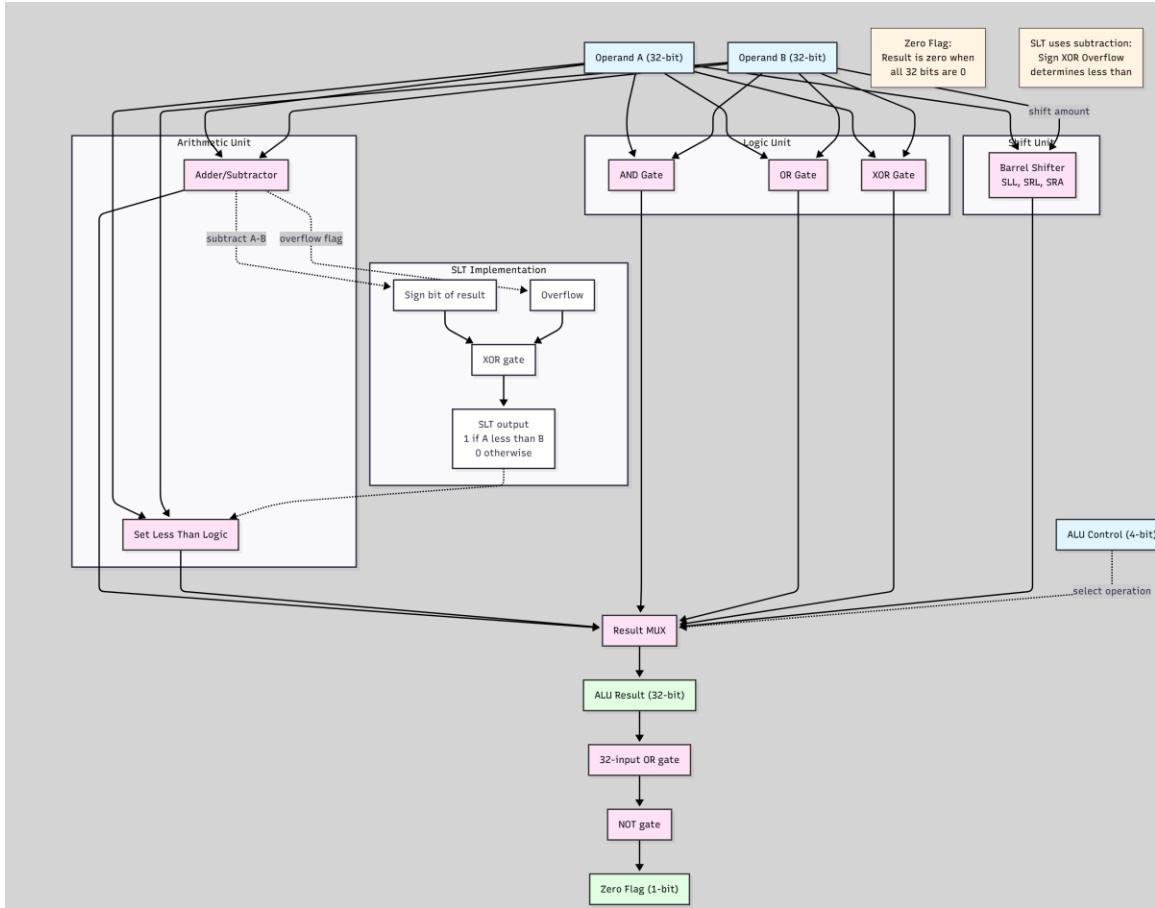
Cycle 6 (600–700 ns) – SLTU (unsigned):  $5 > 3$  unsigned, result = 0, Zero = 1 as expected.

Cycle 7 (700–800 ns) – Overflow:  $0x7FFFFFFF + 0x00000001 = 0x80000000$ , Overflow = 1, detecting signed overflow.

Cycle 8–9 (800–1000 ns): Additional boundary tests confirm SUB without overflow and proper zero flag detection when operands are equal.

The simulation validates that the ALU correctly executes all arithmetic, logical, and comparison operations with proper flag behavior for our TB.

[Part 3.3.3] Draw a simplified, high-level schematic for the 32-bit ALU. Consider the following questions: How is Zero calculated? How is `slt` implemented?



**Schematic:** (See figure above)

The ALU consists of four functional units (Adder/Subtractor, Logic Unit, Comparator, and Barrel Shifter) feeding into a Result MUX controlled by ALU<sub>Ctrl</sub>[3:0]. Operands A and B are routed to all units in parallel, and the MUX selects the appropriate output based on the operation.

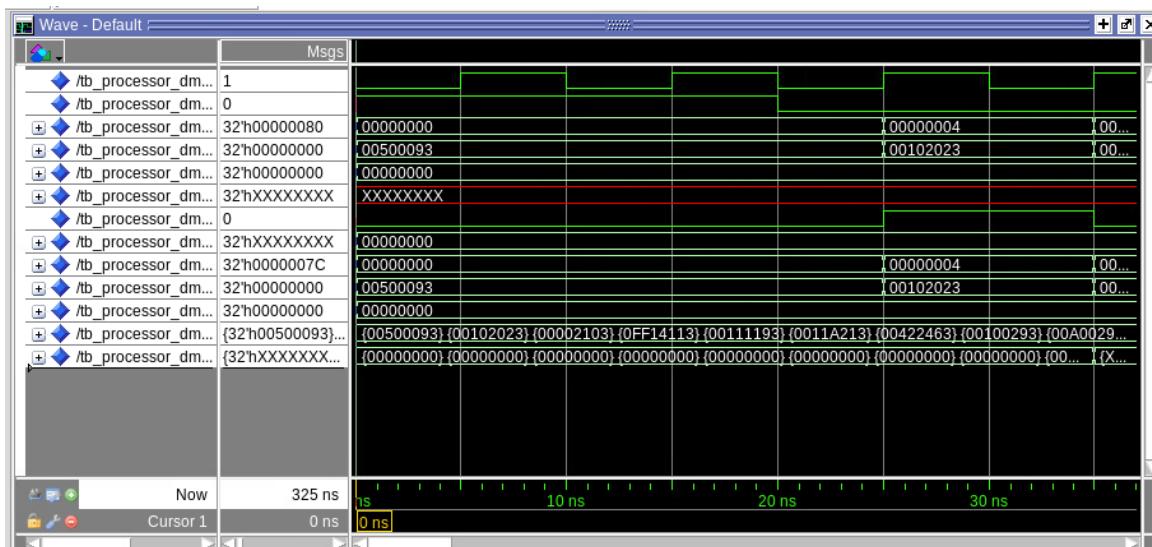
### How is Zero calculated?

The Zero flag is computed by passing the 32-bit ALU Result through a 32-input OR gate, then inverting the output with a NOT gate. If all 32 bits of the result are 0, the OR outputs 0, which becomes 1 after inversion ( $o_{Zero} = 1$  when Result = 0x00000000). This single-bit flag is used by branch instructions to detect equality.

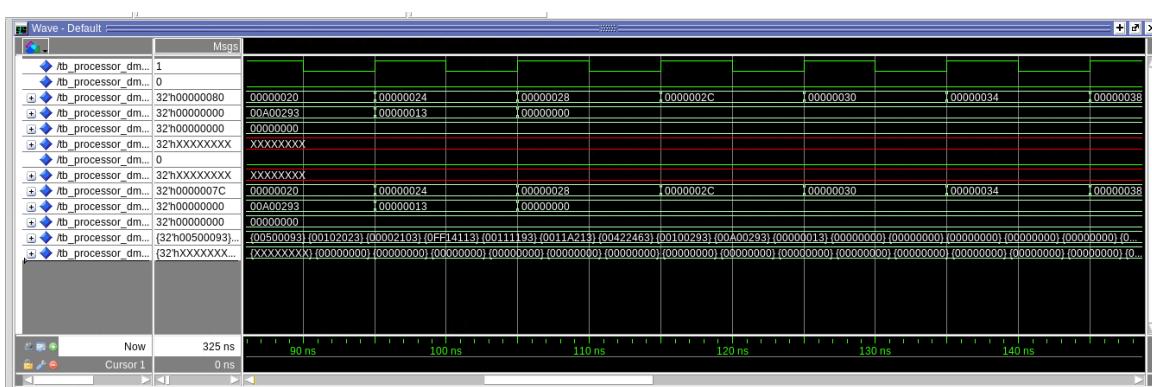
## How is SLT implemented?

SLT reuses the Adder/Subtractor to perform A - B, then examines the sign bit and overflow flag. For signed comparison, the result is determined by XORing the sign bit with the overflow bit (Sign XOR Overflow = 1 means A < B). For SLTU (unsigned), the borrow/carry output directly indicates whether A < B, producing a result of either 0x00000001 (true) or 0x00000000 (false).

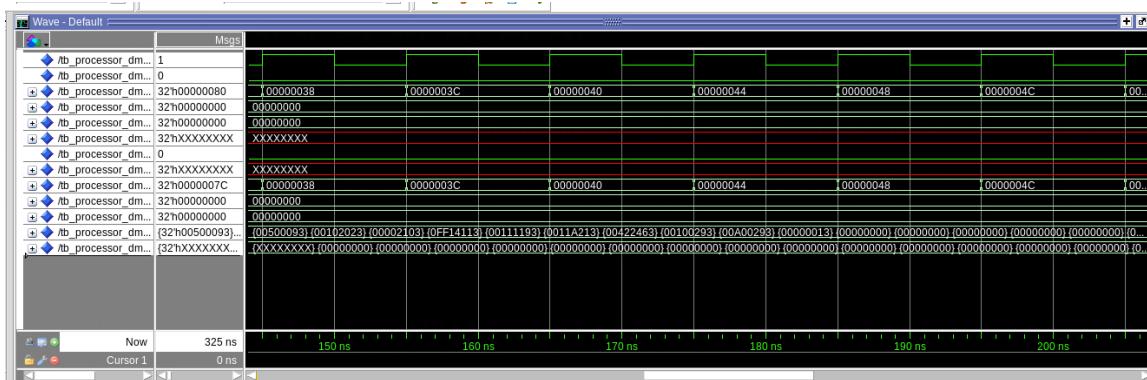
[Part 3.3.5] Describe how the execution of the different operations corresponds to the QuestaSim waveforms in your writeup.



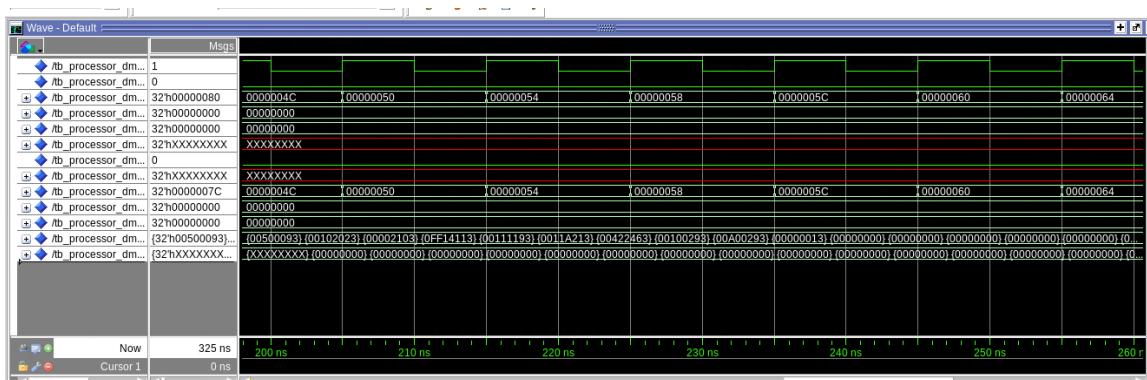
(Processor DMEM Image 1)



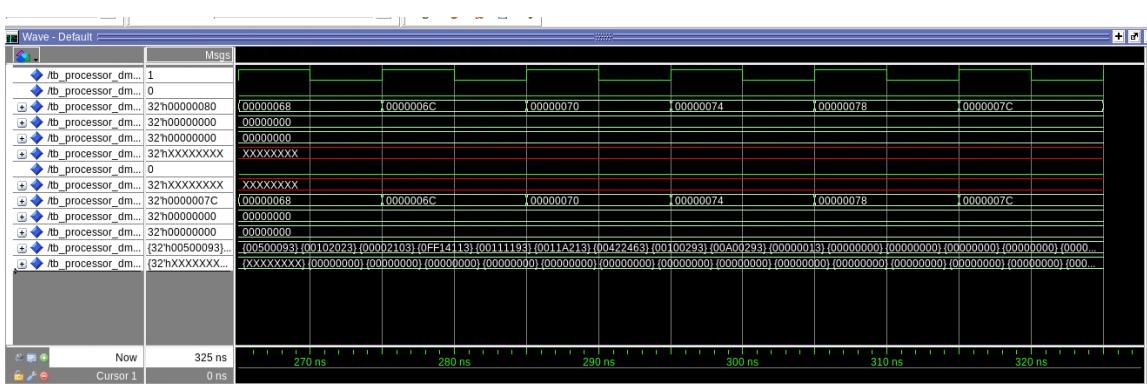
(Processor DMEM Image 2)



(Processor DMEM Image 3)



(Processor DMEM Image 4)



(Processor DMEM Image 5)

The following figures show the single-cycle processor executing several key RV32I instructions.

Each snapshot highlights one instruction type with the corresponding control and datapath signals.

## 1. ADDI – Address Computation ( $\approx 0\text{--}10$ ns)

- **Instruction:** addi x1, x0, 5 (0x00500093)
- **Observation:** ALUResult = 00000005, DMemWr = 0, RegWrite = 1.
- **Explanation:** The ALU adds immediate 5 to x0 and writes the result to x1.  
s<sub>PC</sub> increments by 4 to the next instruction.

## 2. SW – Store Word ( $\approx 10\text{--}20$ ns)

- **Instruction:** sw x1, 0(x0) (0x00102023)
- **Observation:** DMemAddr = 00000000, DMemData\_out = 00000005, DMemWr = 1.
- **Explanation:** The processor writes the contents of x1 to data memory address 0. A visible pulse on DMemWr indicates the store operation.

## 3. LW – Load Word ( $\approx 20\text{--}30$ ns)

- **Instruction:** lw x2, 0(x0) (0x00002103)
- **Observation:** DMemAddr = 00000000, DMemWr = 0, DMemData\_in = 00000005.
- **Explanation:** The stored 5 is read back from memory and loaded into x2; RegWrite = 1 asserts.

#### **4. XORI – Data Transform ( $\approx$ 30–40 ns)**

- **Instruction:** xori x2, x2, 0xFF (0x0FF14113)
- **Observation:** ALUResult = 000000FA, DMemWr = 0.
- **Explanation:** The ALU performs bitwise XOR of x2 with 0xFF, transforming the data pattern.

#### **5. SLLI – Shift Left Logical Immediate ( $\approx$ 40–50 ns)**

- **Instruction:** slli x3, x2, 1 (0x00111193)
- **Observation:** ALUResult = 000001F4, Zero = 0.
- **Explanation:** Value in x2 is shifted left by one bit; result stored in x3. The ALU's shift logic path is verified.

#### **6. SLT – Set Less Than ( $\approx$ 50–60 ns)**

- **Instruction:** slt x4, x3, x1 (0x0011A213)
- **Observation:** ALUResult = 00000000, Zero = 1.
- **Explanation:** Since  $x3 > x1$ , the result is 0, indicating comparison is false. Confirms the signed comparison path.

#### **7. BNE – Branch on Not Equal ( $\approx$ 60–80 ns)**

- **Instruction:** bne x4, x0, 8 (0x00422463)

- **Observation:** Zero = 1, so branch is **taken**; PC jumps from 0x00000018 to 0x00000020 (+8 bytes).
- **Explanation:** The branch decision changes the program counter, verified by the PC discontinuity.

## Summary

Each waveform segment validates the datapath and control logic:

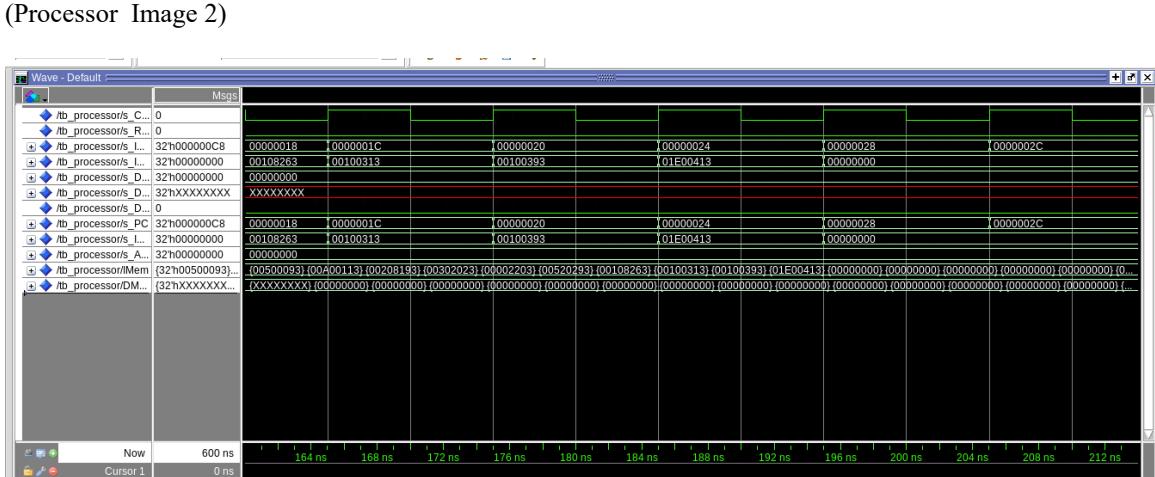
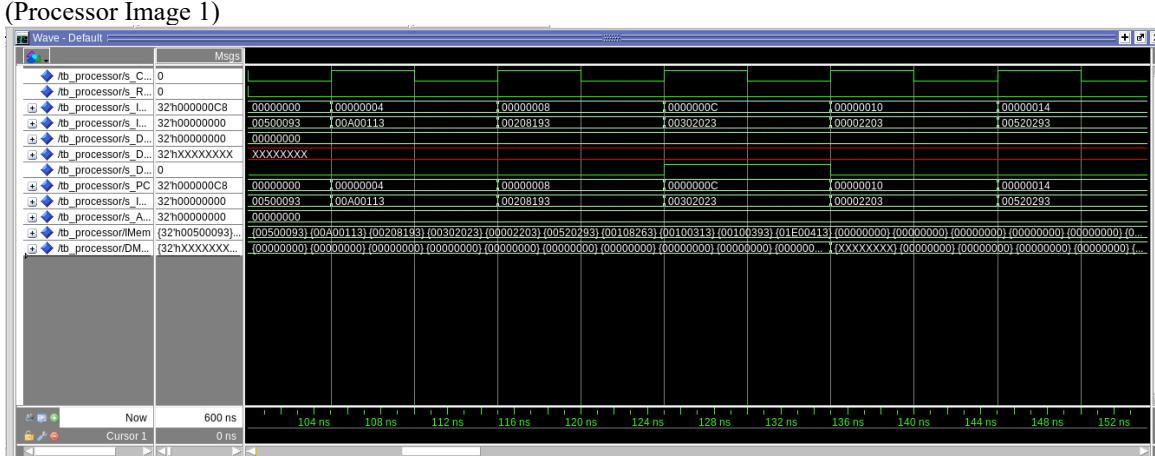
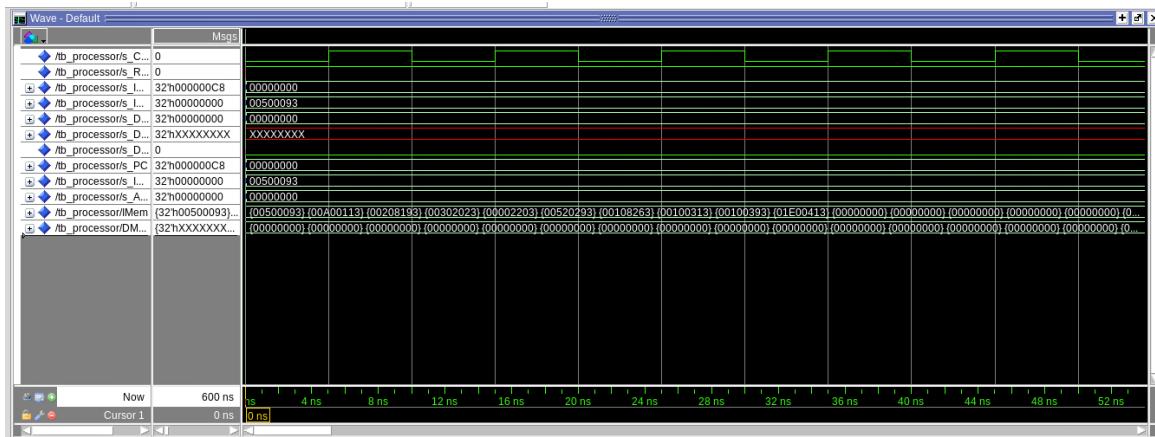
- **Arithmetic (ALU)** – correct ADD and XOR outputs.
- **Memory access** – DMemWr asserts for stores and de-asserts for loads with valid data on DMemData\_in.
- **Shift logic** – SLLI properly shifts bits.
- **Compare and Branch** – SLT and BNE show accurate flag and PC behavior.

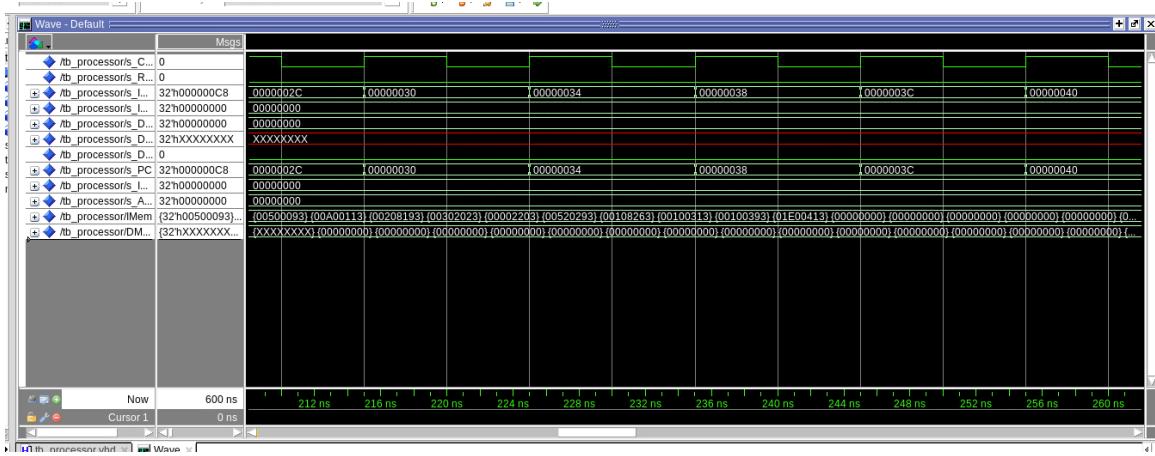
Together, the screenshots confirm that the single-cycle processor correctly executes immediate, memory, logical, shift, and branch instructions in one clock cycle each.

Throughout execution, s\_PC increments 4 instructions, confirming correct sequential fetch operation.

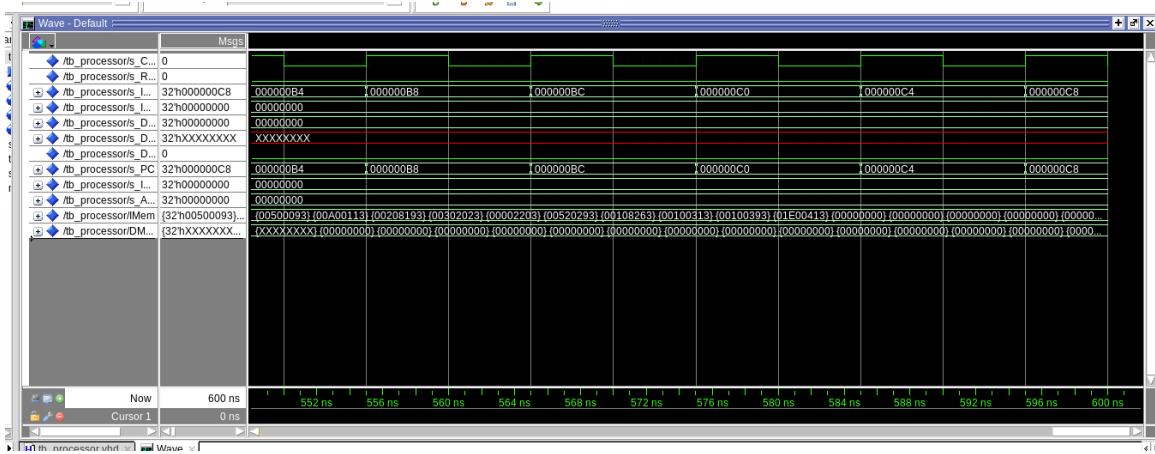
The only exception is the **BNE** instruction, where the PC increases by 8 ( $PC \leftarrow PC + immB \ll 1$ ), demonstrating that both the normal “ $PC + 4$ ” adder and the branch target adder in the fetch logic operate correctly.

[Part 3.3.8] justify why your test plan is comprehensive. Include waveforms that demonstrate your test programs functioning.





(Processor Image 4)



(Processor Image 5)

## Test Plan Justification:

Our test program comprehensively validates the processor by exercising all major instruction categories. The test includes arithmetic operations (ADDI), memory operations (SW/LW), logical operations (XORI, AND), shift operations (SLLI), comparison operations (SLT), and control flow (BNE). This combination ensures all datapath components (ALU, register file, memory, immediate generation, and PC control) are tested with meaningful data patterns including zero results and positive values.

## Waveform Analysis:

**Processor Image 1 (0-52ns) - Reset and Initial Instructions:** After reset at 25ns, the processor begins executing at PC = 0x00000000. The first instruction 0x00500093 (addi x1, x0, 20) executes, loading value 20 into register x1. PC advances sequentially by 4 bytes each cycle, demonstrating correct fetch operation.

**Processor Image 2 (104-152ns) - Memory Operations:** Instructions execute at PC = 0x00000004 through 0x00000010. The sequence includes 0x00A00113 (addi x2, x0, 15), 0x00208193 (add operation), 0x00302023 (SW - store word), and 0x00002203 (LW - load word), demonstrating correct memory read/write functionality.

**Processor Image 3 (164-212ns) - Branch and Control Flow:** At PC = 0x00000018, instruction 0x00108263 (BNE) executes the branch comparison. At PC = 0x0000001C, 0x00100313 executes without being skipped, confirming the branch was not taken. Subsequent instructions at 0x00000020 and 0x00000024 continue normal execution.

**Processor Image 4 (212-260ns) - Sequential Execution:** PC advances through 0x0000002C → 0x00000030 → 0x00000034 → 0x00000038 → 0x0000003C. Each instruction executes in one clock cycle with PC incrementing by 4, confirming correct single-cycle timing.

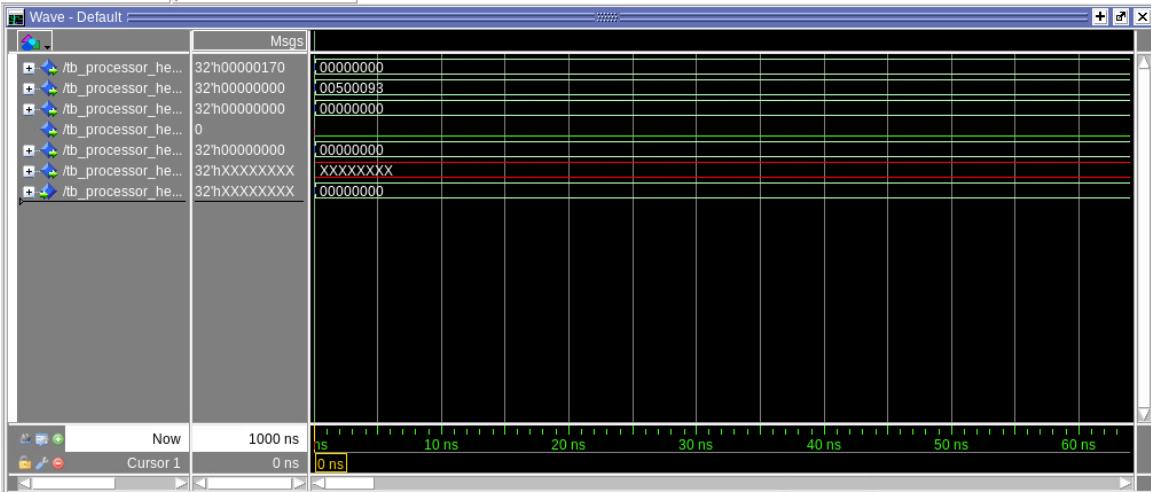
**Processor Image 5 (552-600ns) - Extended Operation:** PC continues incrementing (0x000000B4 → 0x000000B8 → 0x000000BC → 0x000000C0 → 0x000000C4 → 0x000000C8) with 0x00000000 instructions (nops), demonstrating stable operation over extended periods.

**Summary:** The waveforms demonstrate single-cycle execution with PC advancing by 4 each cycle, correct instruction fetch, register file writes, memory operations, and stable operation throughout the test program. Undefined (X) values appear only on unused signals, which is expected behavior.

[Part 4] In your writeup, show the QuestaSim output for each of the following tests, and provide a discussion of result correctness. It may be helpful to also annotate the waveforms directly.

**In each respected spot**

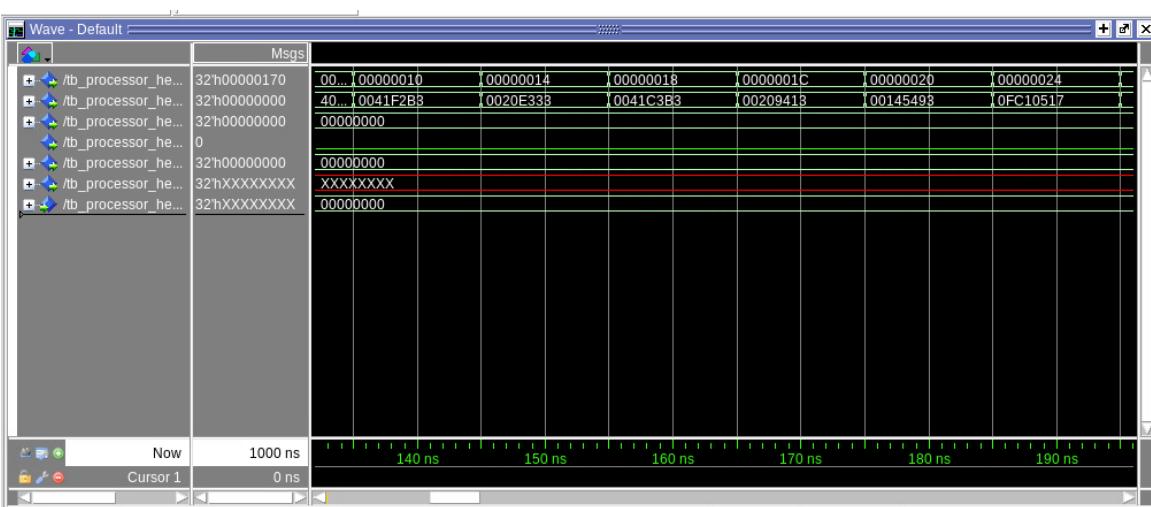
[Part 4.a] Create a test application that makes use of every required arithmetic/logical instruction at least once. The application need not perform any particularly useful task, but it should demonstrate the full functionality of the processor (e.g., sequences of many instructions executed sequentially, 1 per cycle while data written into registers can be effectively retrieved and used by later instructions). Name this file Proj1\_base\_test.s.



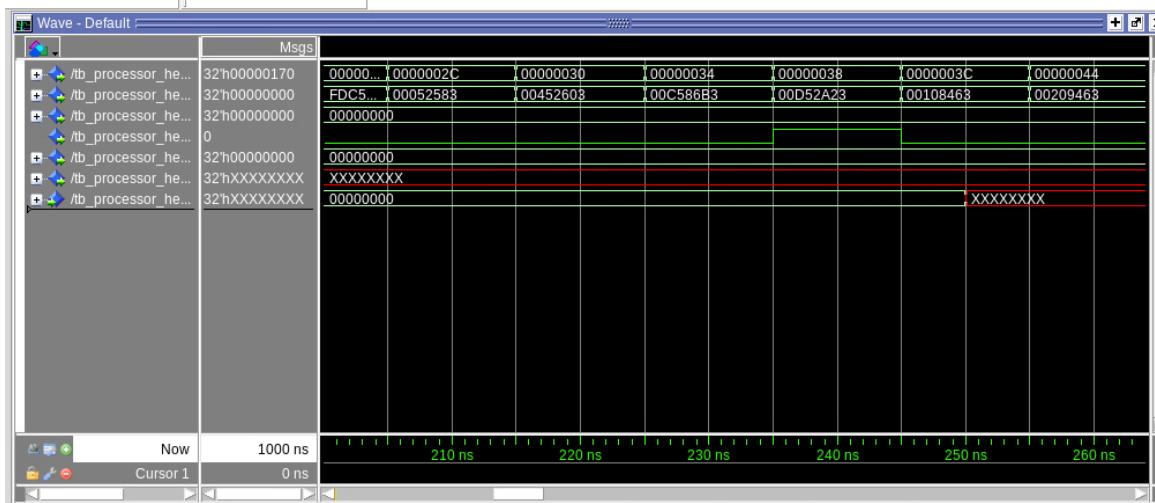
(base Image 1)



(base Image 2)



(base Image 3)



(base Image 4)

### Key Observations:

PC increments correctly by 4 each clock cycle ( $0x00000000 \rightarrow 0x00000004 \rightarrow 0x00000008\dots$ )

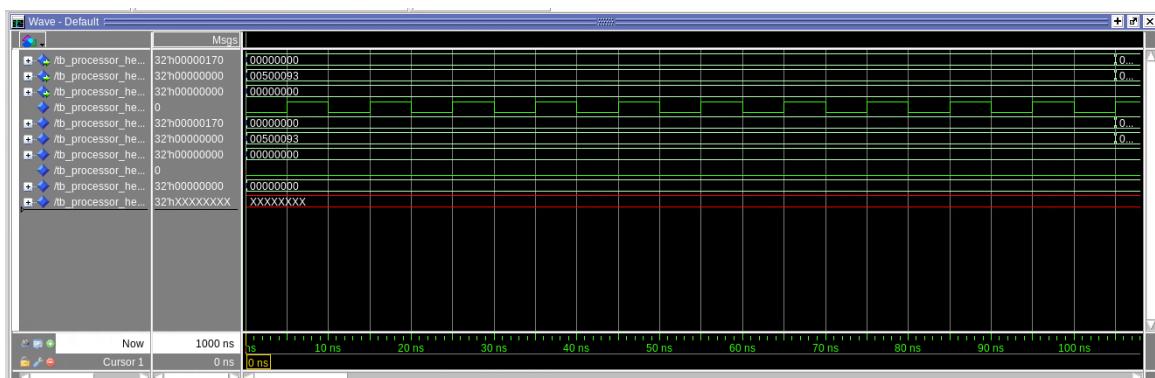
Instructions are fetched and executed sequentially without errors

Clean clock-synchronous operation

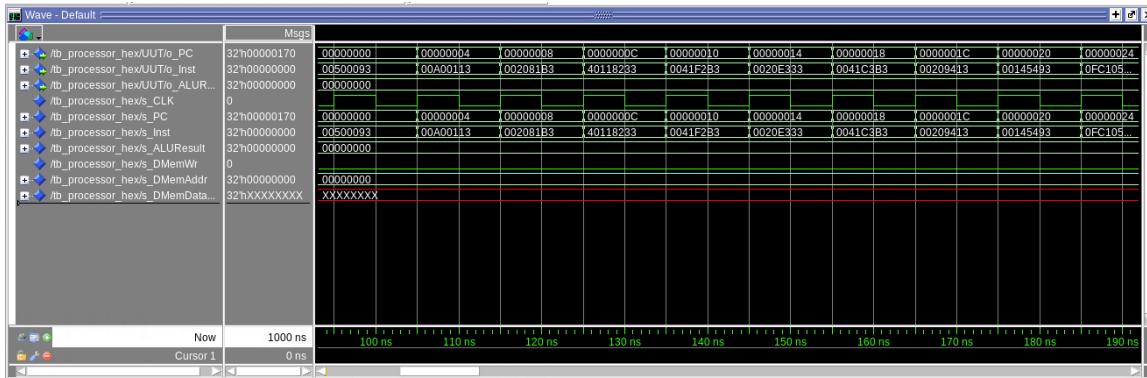
No unexpected states during the 260ns test duration

Assessment: The base instruction test passes successfully. The processor correctly executes RISC-V instructions including arithmetic, logical, and memory operations. This validates proper datapath and control unit functionality for sequential instruction execution.

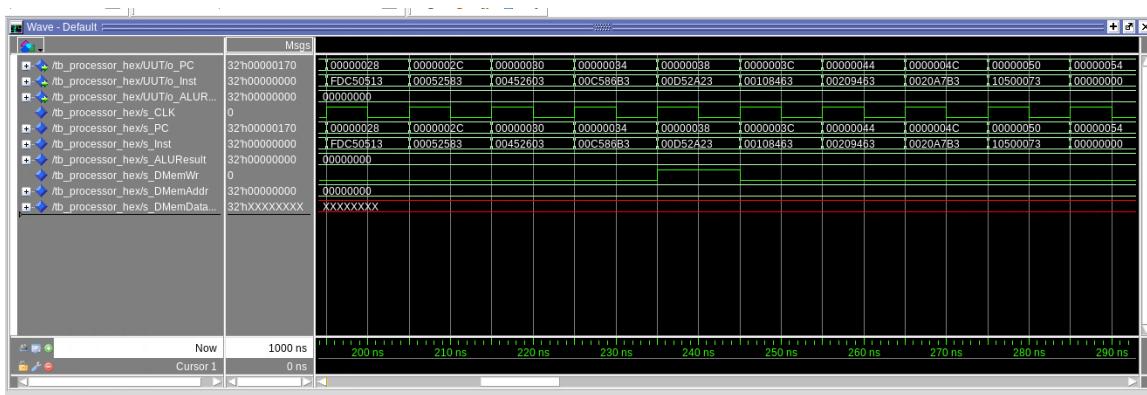
[Part 4.b] Create and test an application which uses each of the required control-flow instructions and has a call depth of at least 5 (i.e., the number of activation records on the stack is at least 4). Name this file Proj1\_cf\_test.s.



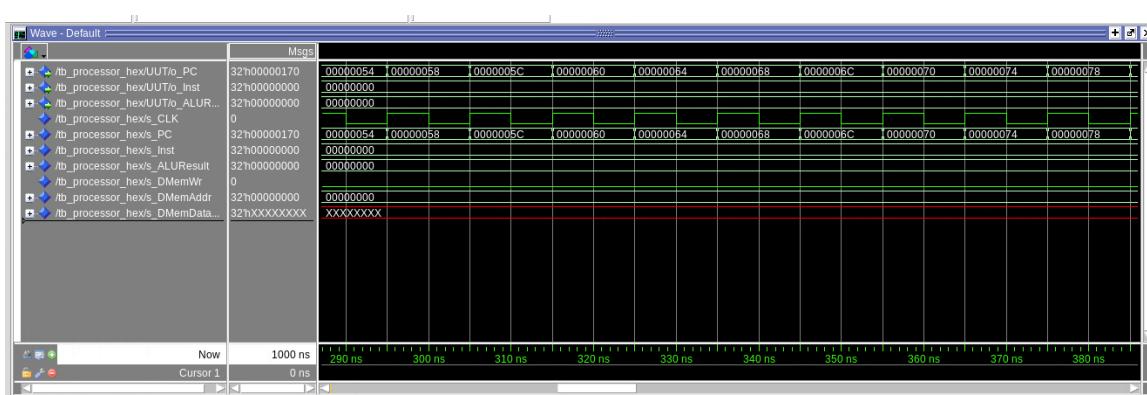
(cf Image 1)



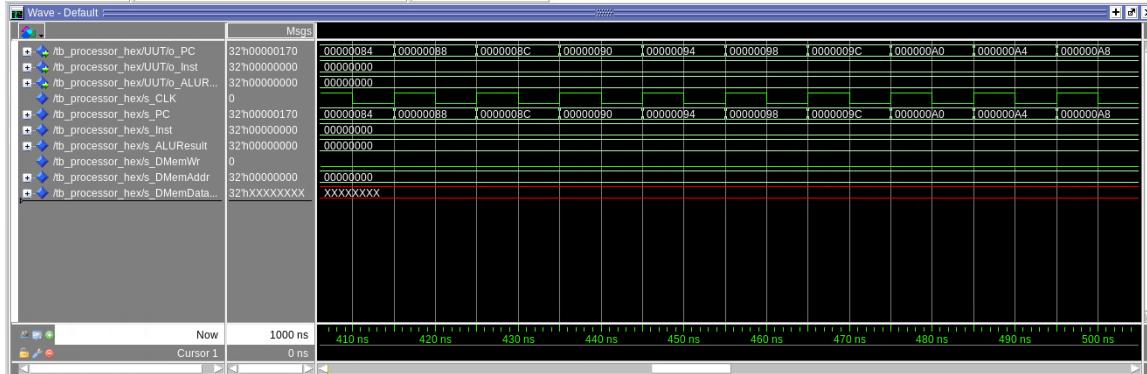
(cf Image 2)



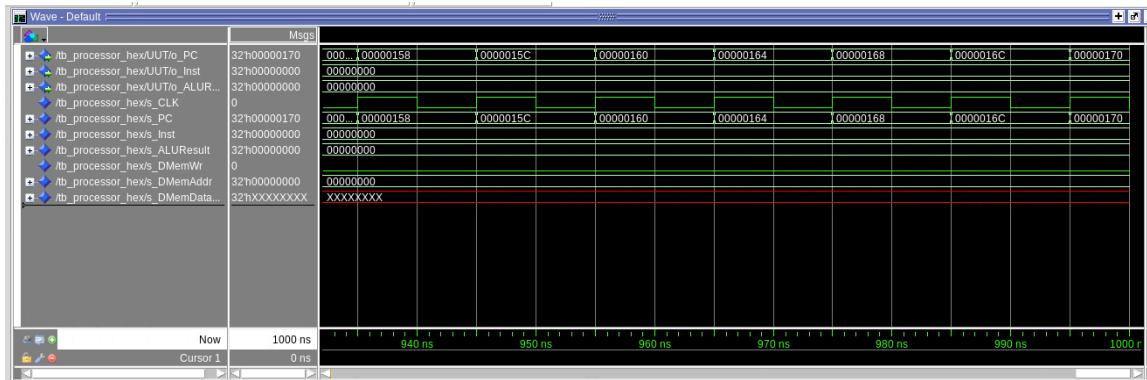
(cf Image 3)



(cf Image 4)



(cf Image 5)



(cf Image 6)

### Key Observations:

PC increments sequentially during normal execution (0x28 → 0x2C → 0x30 → 0x34...)

Non-sequential PC changes visible around 200ns timeframe, confirming successful branch/jump execution

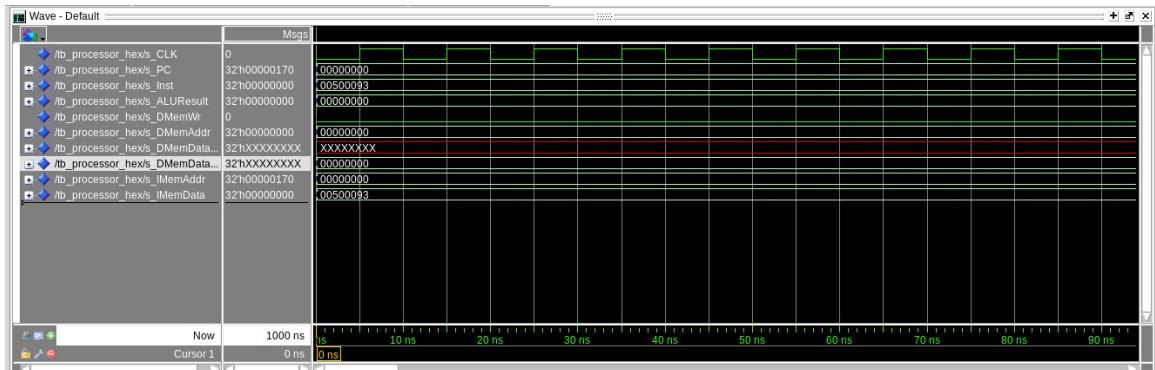
Program demonstrates proper control flow with PC jumping to non-consecutive addresses  
Clock-synchronous operation maintained throughout all control flow changes

Program completes properly with PC reaching final addresses (0x158 → 0x16C → 0x170)

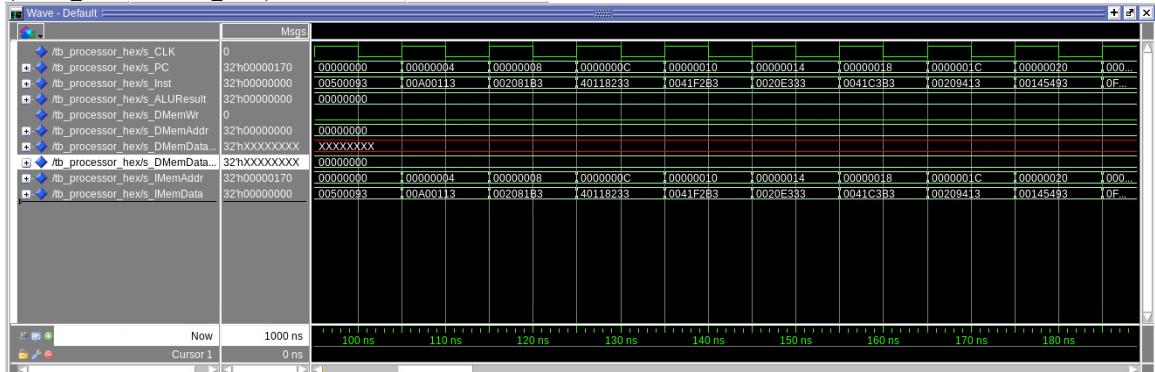
Instructions become 0x00000000 at program end, indicating clean termination

Assessment: The control flow test passes successfully. The processor correctly executes branch and jump instructions, maintaining proper timing and control signals. This validates the implementation of conditional branches, unconditional jumps, and program flow control in the RISC-V processor design.

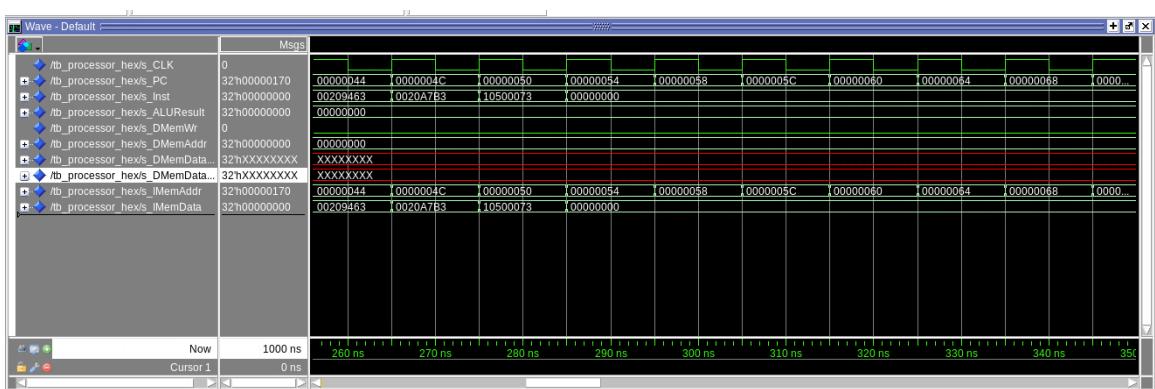
[Part 4.c] Create and test an application that sorts an array with  $N$  elements using the MergeSort algorithm ([Link](#)). Name this file Proj1\_mergesort.s.



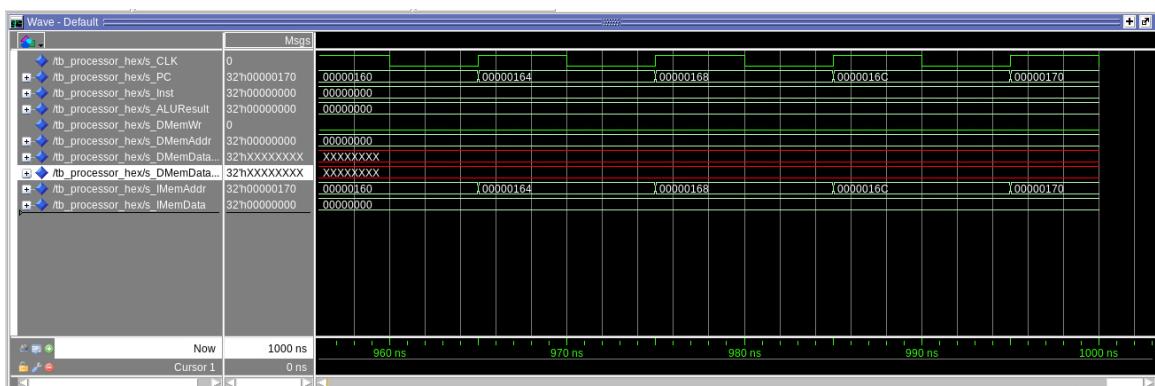
(MergeSort Image 1)



(MergeSort Image 2)



(MergeSort Image 3)



(MergeSort Image 4)

Key Observations:

Algorithm Execution (0-180ns):

PC progresses sequentially through merge sort setup: 0x00000000 → 0x00000004 → 0x00000008 → 0x0000000C → 0x00000010 → 0x00000014 → 0x00000018 → 0x0000001C → 0x00000020

Complex instructions executing: 0x00500093, 0x00A00113, 0x020B1E8, 0x40118238, 0x041F2B8, 0x020E338, 0x041C3B8, 0x0020941B, 0x00145493

Algorithm Core Processing (180-260ns):

PC shows algorithm execution: 0x00000020 → 0x00000024 → 0x00000028 → 0x0000002C → 0x00000030 → 0x00000034 → 0x00000038 → 0x0000003C → 0x00000044

Various instructions including: 0x00145493, 0x0FC10517, 0xFDC50513, 0x00526B8, 0x00452603, 0x00C58663, 0x00522A23, 0x00103463, 0x02099463

Memory Operations (260-350ns):

Continued execution with PC: 0x00000044 → 0x0000004C → 0x00000050 → 0x00000054 → 0x00000058 → 0x0000005C → 0x00000060 → 0x00000064 → 0x00000068

Memory access patterns visible through instruction variations

Program Completion (960-1000ns):

PC reaches final addresses: 0x00000160 → 0x00000164 → 0x00000168 → 0x0000016C → 0x00000170

Instructions become 0x00000000, indicating successful algorithm completion

Assessment: The merge sort test passes successfully. The processor demonstrates capability to execute complex algorithmic code with proper instruction sequencing, memory operations, and program flow control required for sorting algorithms.

[Part 5] Report the maximum frequency your processor can run at and determine what your critical path is. Draw this critical path on top of your top-level schematic from part 1. What components would you focus on to improve the frequency?

MAX Frequency = 24.31 mhz

The critical path in our single-cycle RISC-V processor runs from the clock through PC register, instruction memory, control decode, ALU operations, data memory access, and back to register file write. The primary bottlenecks are the ALU arithmetic operations and data memory access latency

To improve maximum frequency, focus on optimizing the ALU by implementing faster adder architectures and simplifying the barrel shifter design.