

Interstellar Medium 2020

Lecture 12: Shocks and the 3-phase ISM



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Course Contents

1. Introduction and ecology of the interstellar medium
2. Physical conditions and radiative processes
3. The atomic interstellar medium
4. Ionization and recombination
5. HII regions
6. Collisional excitation and nebular diagnostics
7. Molecules and their spectra
8. Molecular clouds
9. Thermal balance
10. Interstellar dust
11. Molecular clouds and their properties
12. Shocks, supernova remnants and the 3-phase ISM

Today's lecture

- Shock waves: principles
- Shocks in molecular clouds
- Supernova remnants
- 3-phase Interstellar Medium

Corresponding textbook material: Draine, Ch. 35, 36 & 39

Shock waves

- A shock wave is a pressure-driven compressive disturbance propagating faster than “signal speed”: a **hydrodynamic surprise**.
- Shock waves produce an **irreversible change** in the state of the gas (or fluid).

Sound speed and Mach number

- Sound speed: $c_s^2 = \frac{dP}{d\rho}$
- $c_s \approx \sqrt{\frac{kT}{m}} \approx 1 \text{ km s}^{-1}$ for $T \sim 100 \text{ K}$
- Mach number: $M \equiv$ ratio of velocity w.r.t. sound speed:
 $M \equiv v/c_s$
- When speaking of a “strong” shock, this refers to the velocity of the disturbance: a strong shock is a fast shock.

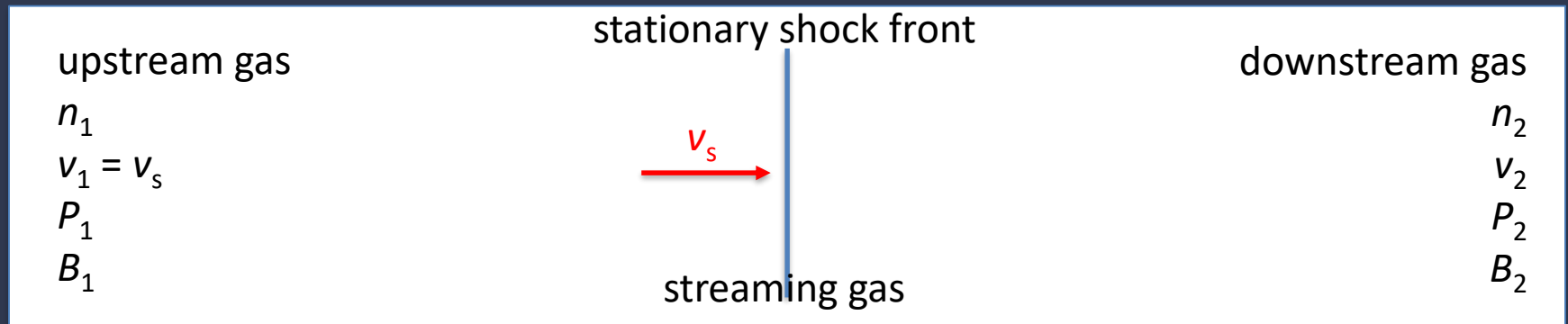
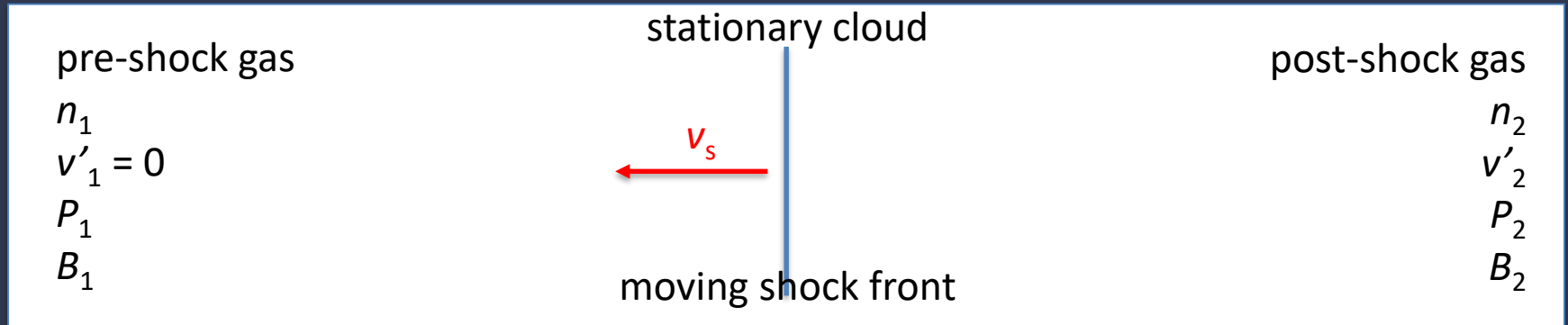
“Signal speed” in the Interstellar Medium

- In the absence of magnetic fields, information travels with sound speed:
 - $M < 1$ subsonic
 - $M > 1$ supersonic \Rightarrow shocks
- If magnetic field is present, disturbances will travel along B at Alfvén speed v_A :
$$v_A^2 = \frac{B^2}{4\pi\rho}$$
- Interstellar magnetic field (empirical):
$$B = 1 \mu\text{G} \cdot \sqrt{n_H}$$
for $10 < n_H < 10^6 \text{ cm}^{-3}$

Shock waves in the ISM occur in...

- cloud-cloud collisions
- expansion of HII regions
- fast stellar winds (“interstellar bubbles”)
- supernova blast waves
- accretion and outflows during star formation
- spiral shocks in Galactic disks
- supersonic turbulence

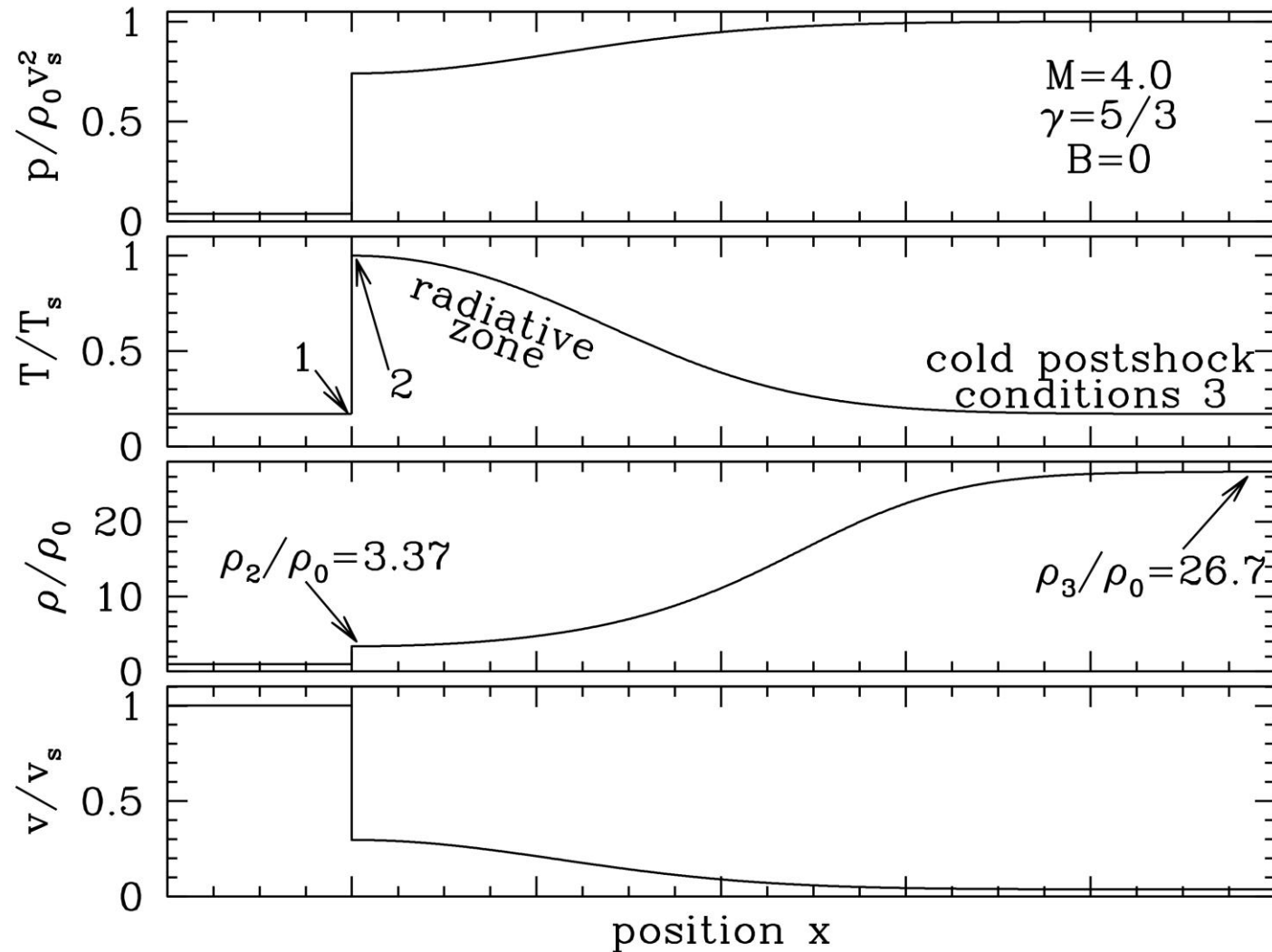
Cloud frame and shock frame



Shock jump conditions

- Adopt frame in which shock is stationary
- Consider plane-parallel shock: gas properties depend only on distance from shock front
- In shock transition zone: transform part of the bulk kinetic energy into heat \Rightarrow irreversible change (entropy increases)
- Immediately pre-shock and post-shock conditions are connected by the (Rankine-Hugoniot) jump conditions

Structure of a radiative shock



(Draine, Fig. 36.1)

Rankine-Hugoniot jump conditions

Following Draine, write u for velocity and subscripts 1 and 2 for pre-shock and post-shock conditions (and $u_1 = v_s$)

- Mass conservation: $\rho_1 u_1 = \rho_2 u_2$

- Momentum conservation: $\rho_1 u_1^2 + p_1 + \frac{B_1^2}{8\pi} = \rho_2 u_2^2 + p_2 + \frac{B_2^2}{8\pi}$

- Energy conservation:

$$\frac{1}{2}\rho_1 u_1^3 + \frac{\gamma}{\gamma - 1} u_1 p_1 + \frac{u_1 B_1^2}{8\pi} = \frac{1}{2}\rho_2 u_2^3 + \frac{\gamma}{\gamma - 1} u_2 p_2 + \frac{u_2 B_2^2}{8\pi}$$

- Magnetic flux conservation: $u_1 B_1 = u_2 B_2$

- NB: also must adopt a magnetic field configuration (here assumed parallel to shock front)

Solving the R-H jump conditions

- 4 equations with 4 unknowns (u_2, n_2, p_2, B_2)
- Solution $u_1 = u_2, n_1 = n_2$, etc. always exists. What is the requirement for the existence of a second solution?
- This requirement can be shown to be (see Draine, Sect. 36.2.5)

$$v_s > V_{\text{ms}} = \sqrt{c_s^2 + v_A^2} \quad \text{where } V_{\text{ms}} \text{ is the magnetosonic speed}$$

- This is the requirement for the existence of a shock.

Key results for strong shocks ($M \gg 1$)

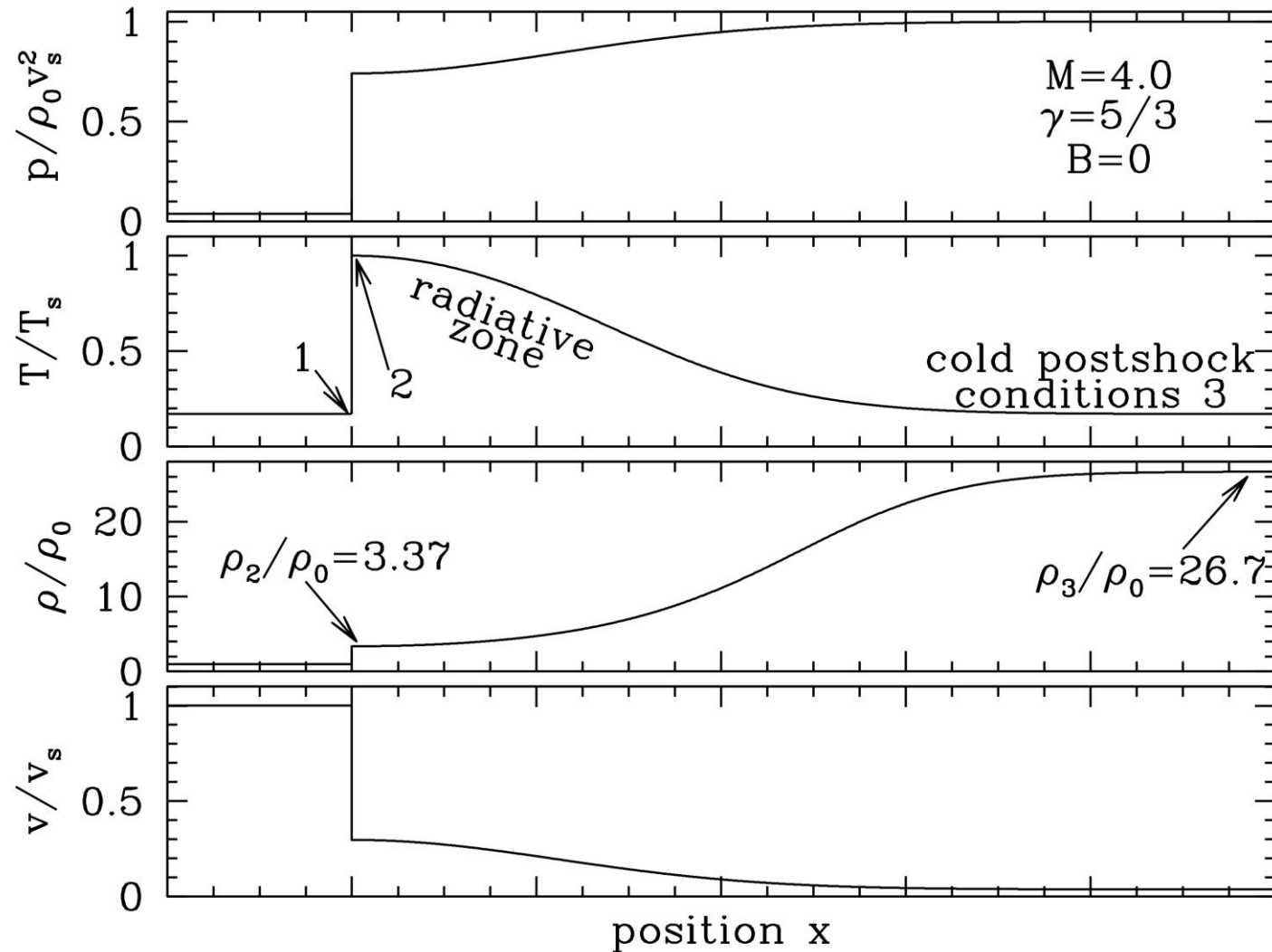
- Immediately post-shock, the maximum compression (density increase) is only a factor 4 (no cooling \Rightarrow post-shock pressure is high)
- Immediately post-shock: $T_2 = \frac{3}{16} \mu v_s^2$ (μ is average particle mass)

so $T_2 = 2890 \text{ K} \frac{\mu}{1.273 m_{\text{H}}} \left(\frac{v_s}{10 \text{ km s}^{-1}} \right)^2$ (neutral atomic gas)

$$T_2 = 1.38 \cdot 10^7 \text{ K} \frac{\mu}{0.609 m_{\text{H}}} \left(\frac{v_s}{1000 \text{ km s}^{-1}} \right)^2 \quad (\text{ionized gas})$$

- After cooling, much higher compression possible

Structure of a radiative shock



(Draine, Fig. 36.1)

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- Shock waves: principles
- Shocks in molecular clouds
- Supernova remnants
- 3-phase Interstellar Medium

Shocks in molecular clouds

So far we considered only single-fluid shocks; normally interstellar gas consists of 2 fluids:

- neutral particles
- ions and electrons

These fluids are not 100% coupled, and will respond differently to the presence of a magnetic field.

For $B \neq 0$, disturbances travel by MHD waves; perpendicular to B the propagation speed is the magnetosonic speed:

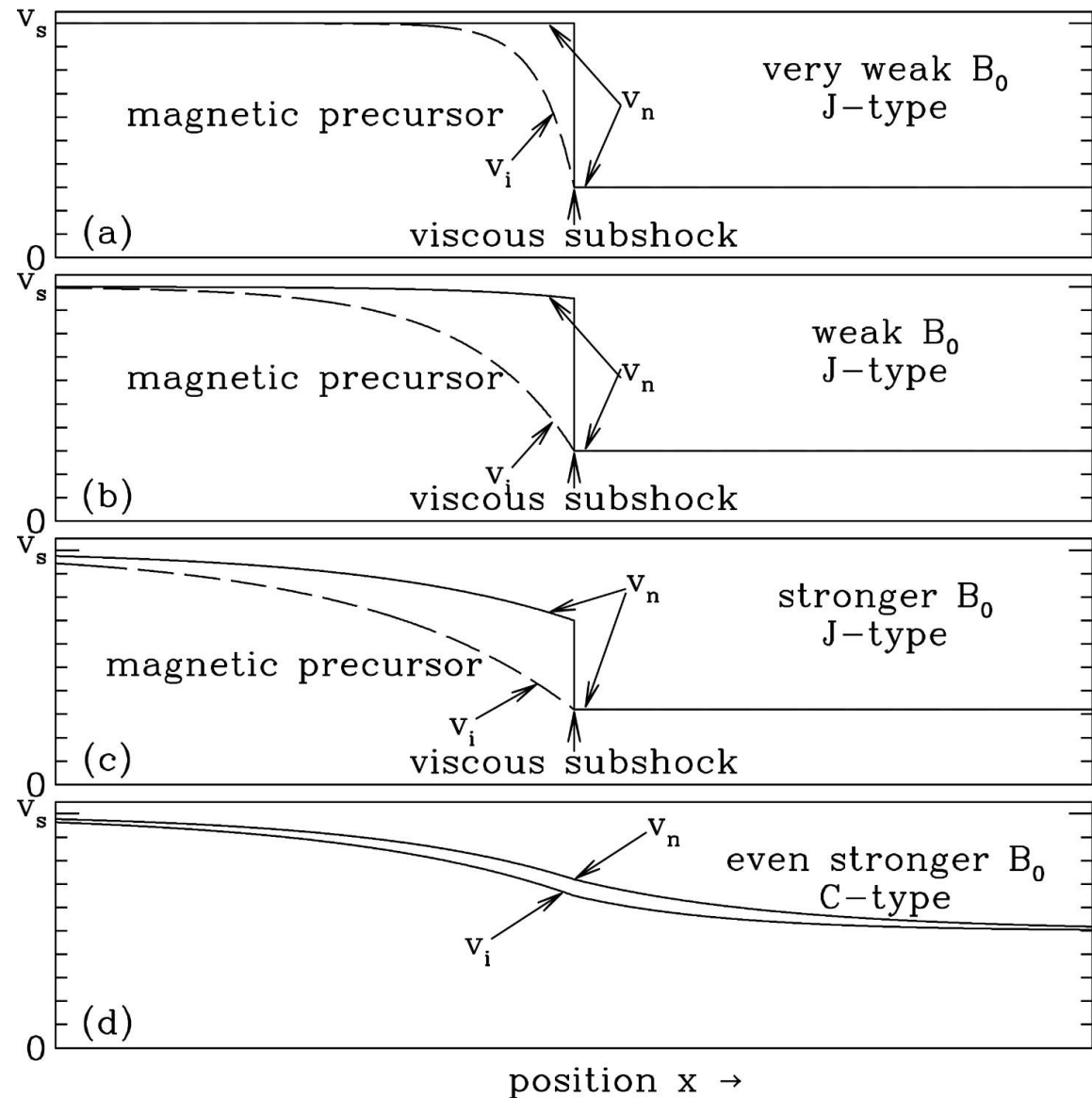
$$V_{\text{ms}} = \sqrt{c_s^2 + v_A^2}$$

Normally $v_A \gg c_s$, so $V_{\text{MS}} \approx v_A$

C-type and J-type shocks

- In many cases: $c_s < v_s < v_A$
- In this case, the ion-electron fluid is not actually shocked but subject to a submagnetosonic disturbance (not a jump but continuous)
- This sends information ahead of the shock front to “inform” pre-shock gas that compression is coming: magnetic precursor
- Resulting transition can be smooth and continuous \Rightarrow C-type shock
- In case of jump: J-type shock

Schematic structure of J- and C-shocks



(Draine, Fig. 36.3)

J-shocks vs. C-shocks

J (“jump”)-shocks: $v_s \geq 50$ km/s; fractional ionization high

1. Shock abrupt
2. Neutrals and ions tied into single fluid
3. T high: $T \approx 20 (v_s / \text{km s}^{-1})^2$
4. Molecules destroyed (but reform in cooling post-shock gas)

C (“continuous”)-shocks: $v_s \leq 50$ km/s; fractional ionization low

1. Gas variables (T, ρ, v) change continuously
2. Ions ahead of neutrals; drag modifies neutral flow
3. $T_i \neq T_n$; both much lower than in J-shocks
4. Gas heated but molecules (mostly) not destroyed
5. Can be important gas heating mechanism (dissipation of supersonic turbulence)

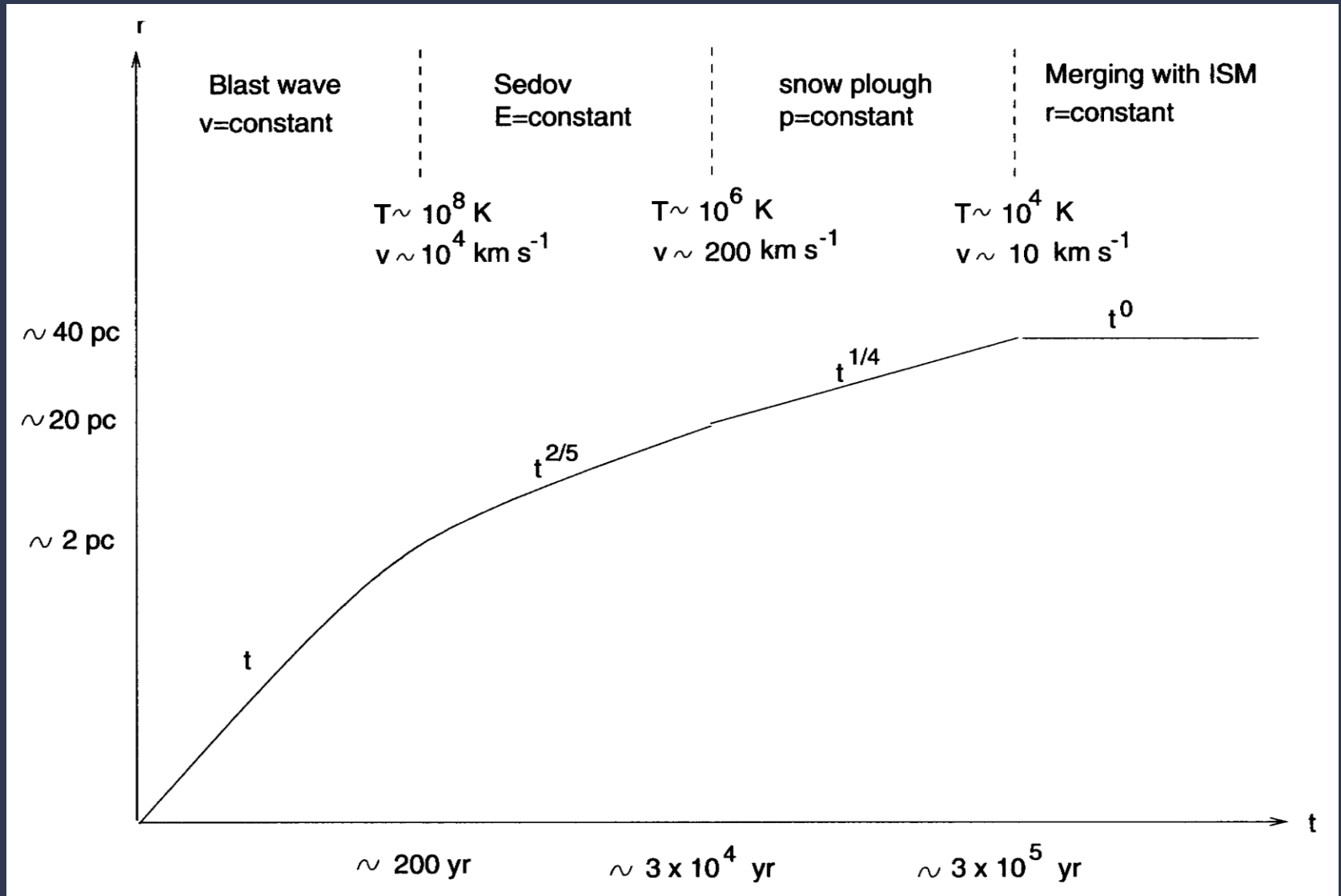
Today's lecture

- Shock waves: principles
- Shocks in molecular clouds
- **Supernova remnants**
- 3-phase Interstellar Medium

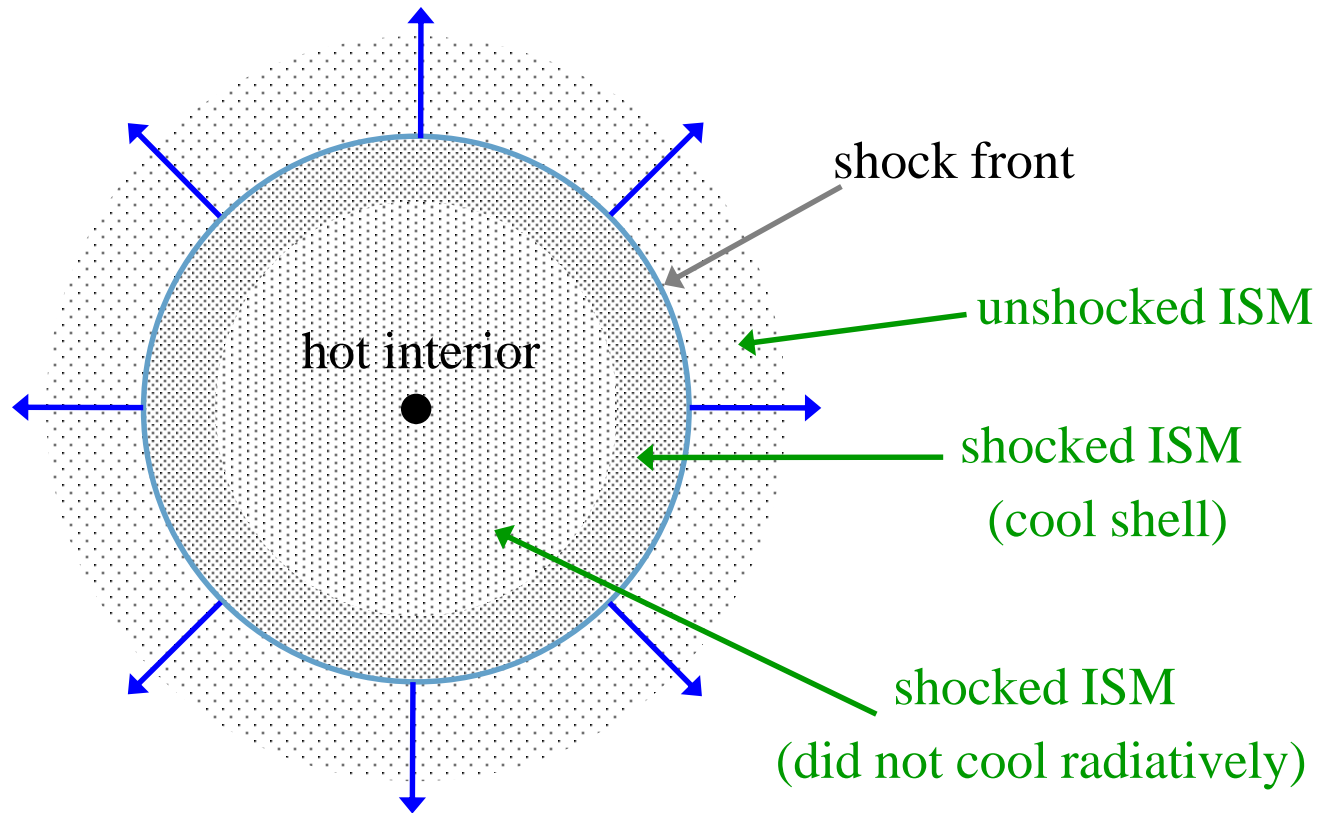
Supernova remnant evolution and shocks

- Early phase ($M_{\text{swept-up}} < M_{\text{ejecta}}$): free expansion, $R_s = v_s t$
- Sedov-Taylor phase ($M_{\text{swept-up}} > M_{\text{ejecta}}$ and $t < t_{\text{cool}}$): non-radiative shock, slower expansion
- “Snowplow” phase ($t > t_{\text{cool}}$): radiative shock, even slower expansion
- Merging phase: v_s drops below velocity dispersion of ambient ISM

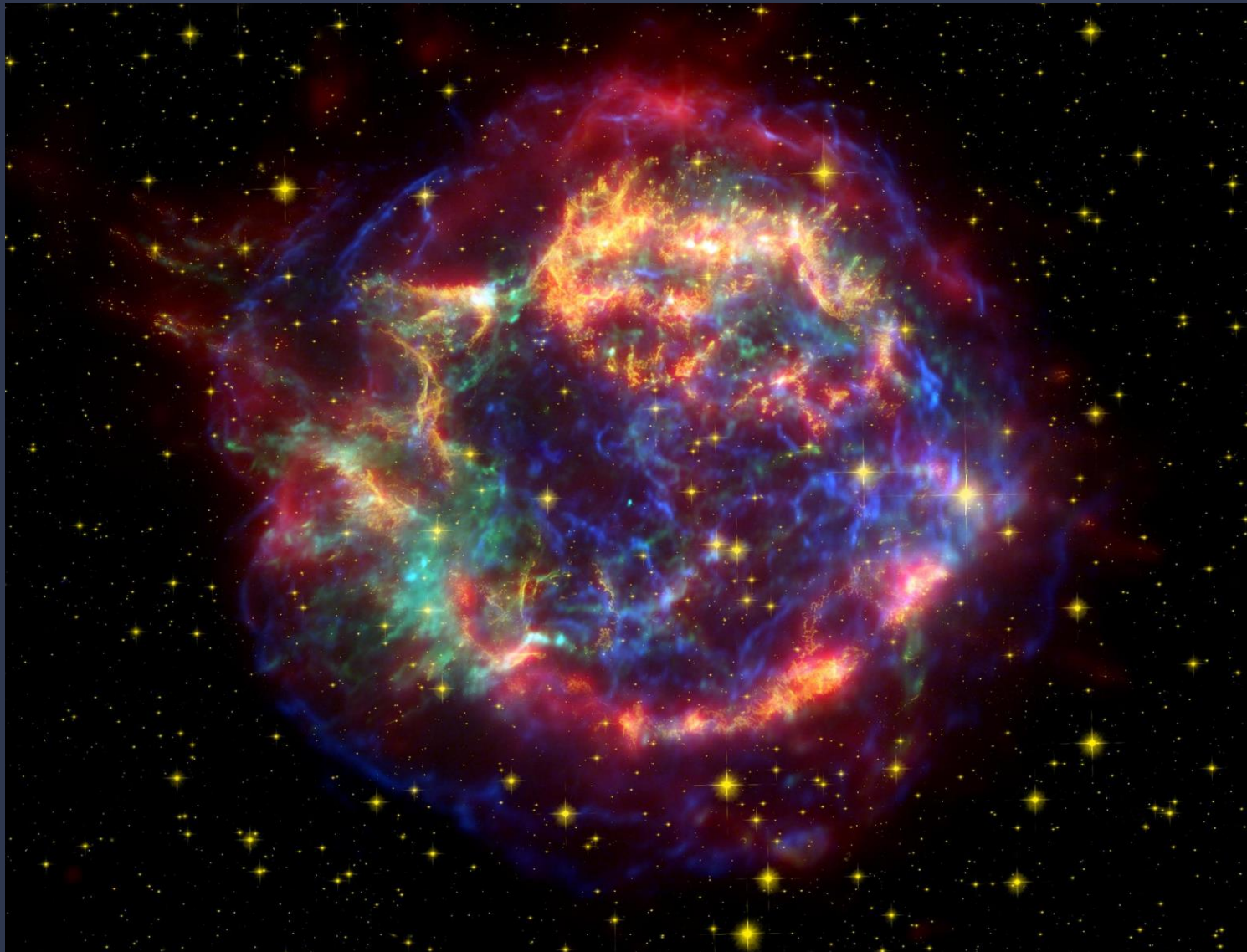
Supernova Remnant evolution



Supernova Remnant structure



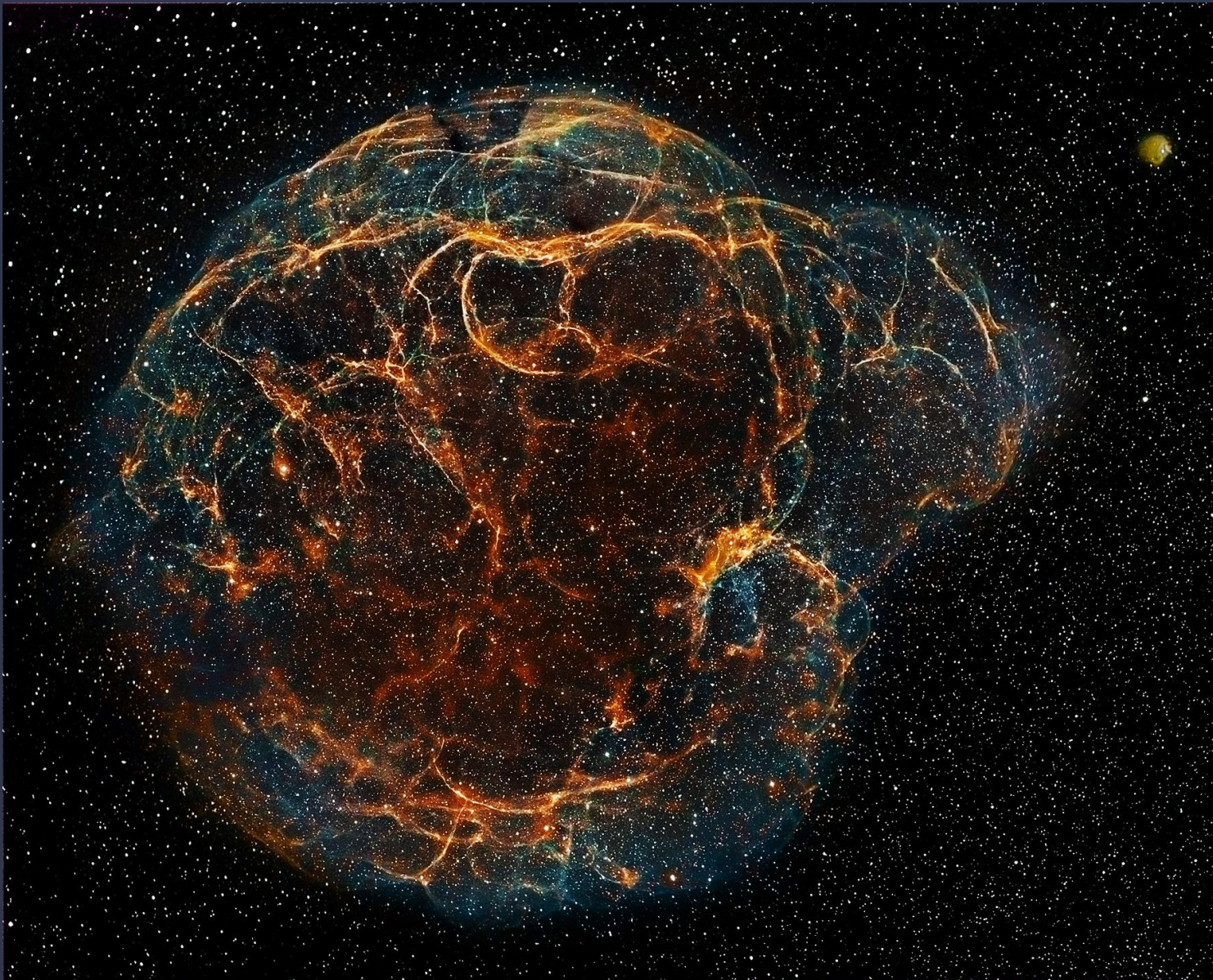
Young supernova remnant



Cas A, ~1680:
in Sedov-taylor
phase

red: infrared
yellow: optical
Blue: X-rays

Old supernova remnant



Simeis 147:
at end of
Snowplough
phase

red: [SII]
yellow: H α
blue: [OIII]
(credit: Emil
Ivanov}

Today's lecture

- Shock waves: principles
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Need for a 3-phase ISM model

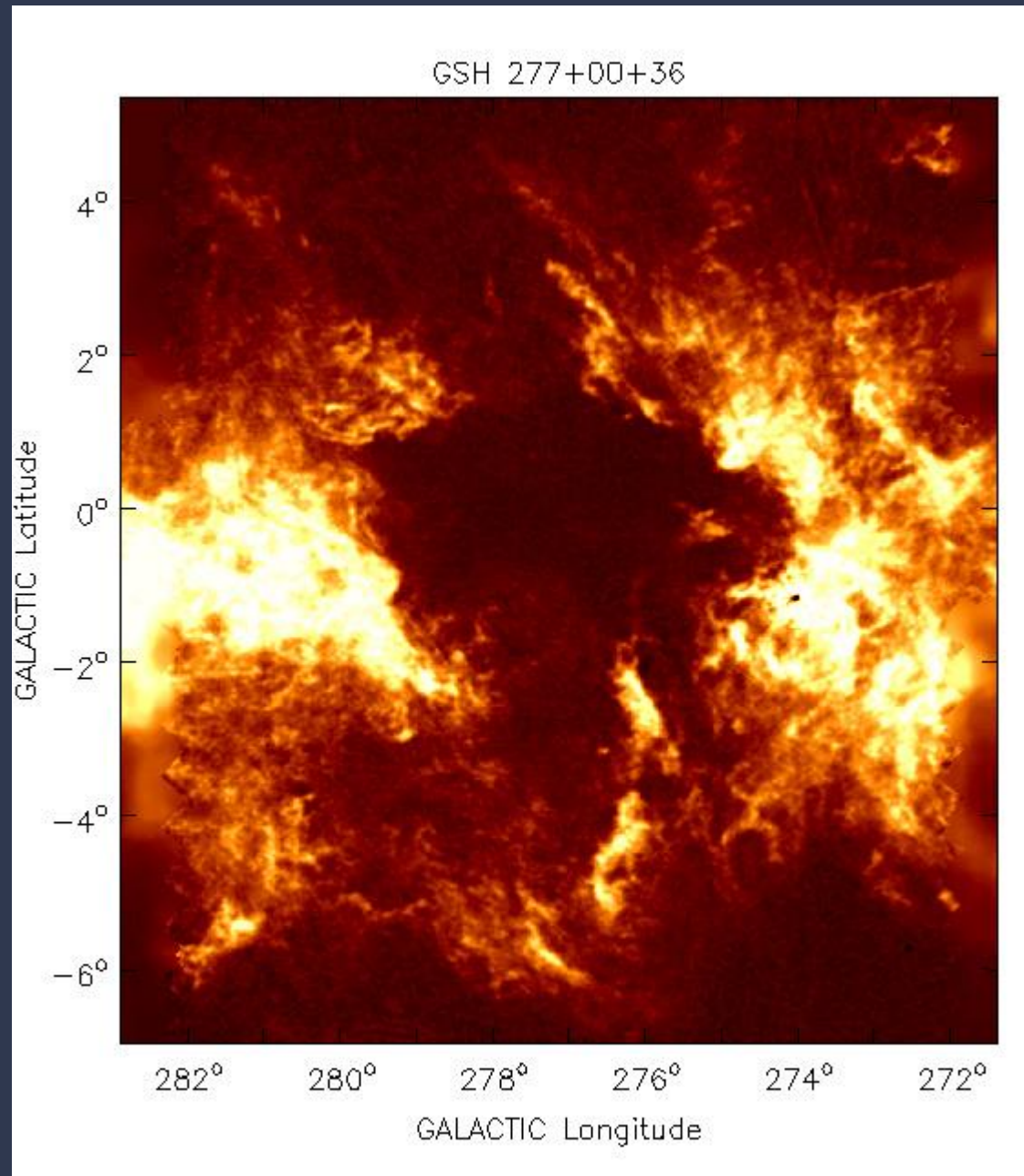
- 2-phase model accounts for only WNM & CNM (parts of which can become ionized or molecular); how do we account for the HIM?
- With Milky Way Supernova rate, lifetimes and sizes, neutral medium will be destroyed on timescales $< 10^6$ yr.
- Vertical scale height of CNM/WNM can only be explained if the medium is turbulent, $\sim 7 \text{ km s}^{-1} \rightarrow$ something must be stirring up the ISM continuously

All three point to a role for supernova remnants.

SNRs in the 3-phase model

- Overlapping SNRs create a “tunnel” system of hot ionized gas threading the HI clouds, much like the “holes” in a “swiss cheese”: the HIM.
- SNR evolves in isolation until it intersects a tunnel and connects to the HIM; then pressure drops suddenly as SNR “vents” to tunnel system and contributes to pressure of the HIM.

Supershells in HI 21cm – bubbles blown by SNRs



Physical principles of the 3-phase model

McKee & Ostriker 1977

1. Pressure balance

- Pressure is from supersonic turbulence, maintained by SNRs
- Can be used to determine P_{ISM} giving the correct result within factor of 2!

2. Mass balance

- Balanced mass exchange between phases

3. Energy balance

- most SN energy leaves system as radiation. This is satisfied if SNRs enter radiative phase before they overlap (which they do)
- A small fraction of SN energy remains as kinetic energy of shells at time of SNR overlap. This energy maintains random motions of clouds.

The 3-phase model: successes

- Predicts pressure of the ISM correctly “ab initio”
- Observed soft X-ray background in rough agreement with $T \approx 5 \times 10^5$ K expected for cooling SNR gas = HIM
- Predicted cloud velocity dispersion $\approx 7 \text{ km s}^{-1}$ agrees with observations

The classical 3-phase model: problems

- Does not predict enough WNM
- Required porosity is larger than observed

But additional effects to be considered:

- Clustering of supernovae
- Blowout into the halo
- Inhomogeneous ISM
- Magnetic field

Multiphase structure in the Large Magellanic Cloud

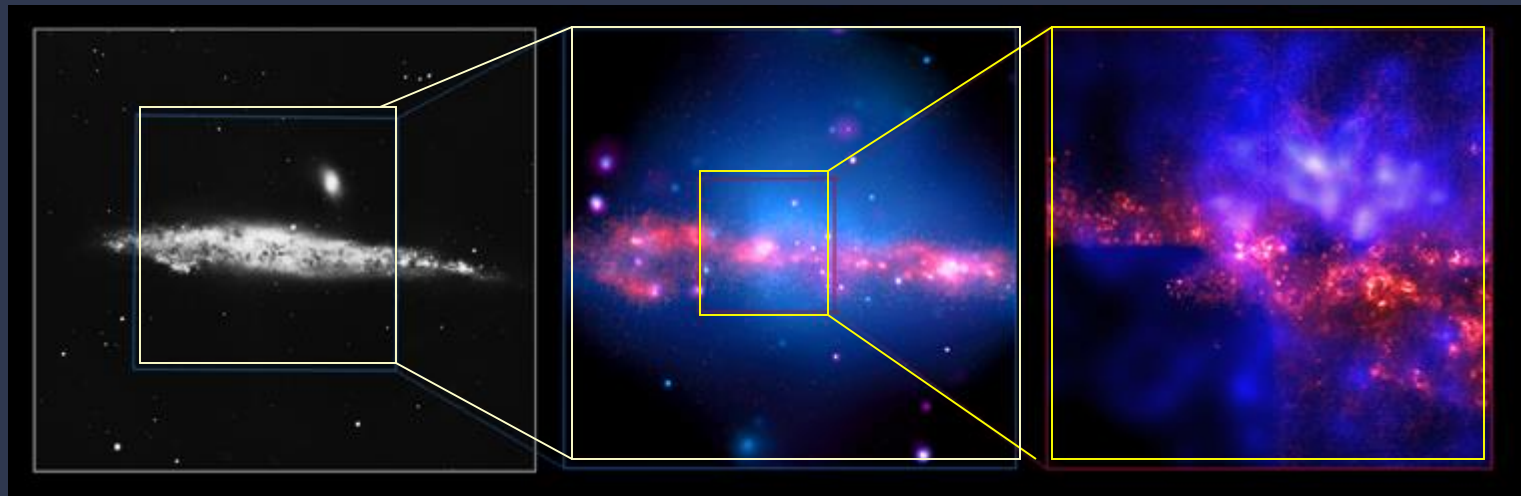


Blue: X-rays (HIM)

Orange: dust emission
(mostly CNM)

Blowout into the halo (“superwind”)

NGC4631



optical

red = $H\alpha$

blue: X-ray

Outlook, hot topics, further study...

- Star (and planet) formation
- Origin (and universality) of the Initial Mass Function
- Role of ISM regulating star formation on Galaxy-wide scales
- ISM in ultraluminous galaxies
- ISM and Active Galactic Nuclei
- ISM in high- z galaxies (where 50% of baryonic mass is gas)
- ISM in low-metallicity galaxies (including at very high z)
- Formation of the first stars
- etc, etc, etc...