

The Medium Access Control Sublayer

Sachin Gajjar

sachin.gajjar@nirmauni.ac.in

Reading Material for this topic

- Computer Networks, Fourth Edition by Andrew S Tanenbaum
 - Chapter 4, Topic 4.1, 4.2.1, 4.2.2, 4.2.6

Network categories:

1. Those using point-to-point channels
2. Those using broadcast channels
 - In broadcast network, key issue is to determine who gets to use channel when there is competition for it.
 - Broadcast channels = multiaccess channels
 - Eg. conference call – chaos in who goes next
 - Eg. Face to face meeting – raise hands when you want to speak
 - protocols used to determine who goes next on a multiaccess channel belong to a sublayer of data link layer called MAC (Medium Access Control) sublayer

Static Channel Allocation in LANs and MANs

- Static channel – FDM
- N users BW divided into N equal size portion
- All users may not access channel – a waste
- More than N users want to communicate some may be denied due to lack of BW
- OK for small fixed no. users with heavy load
- When users more and traffic bursty – not ok
- computer systems peak : mean traffic = 1000:1
- Channel idle for most of time
- Same for TDM – user may not use allotted time

Dynamic Channel Allocation in LANs and MANs

- Key assumptions
- **Station Model**
- Consists of N independent stations, each generates frames for transmission.
- Once a frame has been generated, station is blocked and does nothing until the frame has been successfully transmitted

- **Single Channel Assumption**
- Single channel is available for all communication
- All stations can transmit on it and all can receive from it.
- Hardware at all stations are equivalent,
- Protocol software may assign priorities to them.

- **Collision Assumption.**
- If 2 frames are transmitted simultaneously, they overlap in time and resulting signal is garbled.
- This event is called a collision.
- All stations can detect collisions.
- A collided frame must be transmitted again later.
- There are no errors other than those generated by collisions.

- Carrier = electrical signal on cable
- **Continuous Time.** Frame transmission can begin at any instant. No master clock dividing time into discrete intervals.
- **Slotted Time.** Time is divided into discrete intervals (slots). Frame transmissions always begin at start of a slot. A slot may contain 0, 1, or more frames, corresponding to an idle slot, a successful transmission, or a collision, respectively.
- **Carrier Sense.** Stations can tell if channel is in use before trying to use it. If channel is sensed as busy, no station will attempt to use it until it goes idle.
- **No Carrier Sense.** Stations cannot sense channel before trying to use it. They just go ahead and transmit. Only later can they determine whether transmission was successful.

Multiple Access Protocols

- ALOHA
- In 1970s, Norman Abramson, University of Hawaii devised method to solve channel allocation problem.
- Work used ground-based radio broadcasting
- Basic idea is applicable to any system in which uncoordinated users are competing for use of a single shared channel.
- Two versions of ALOHA here: pure and slotted.

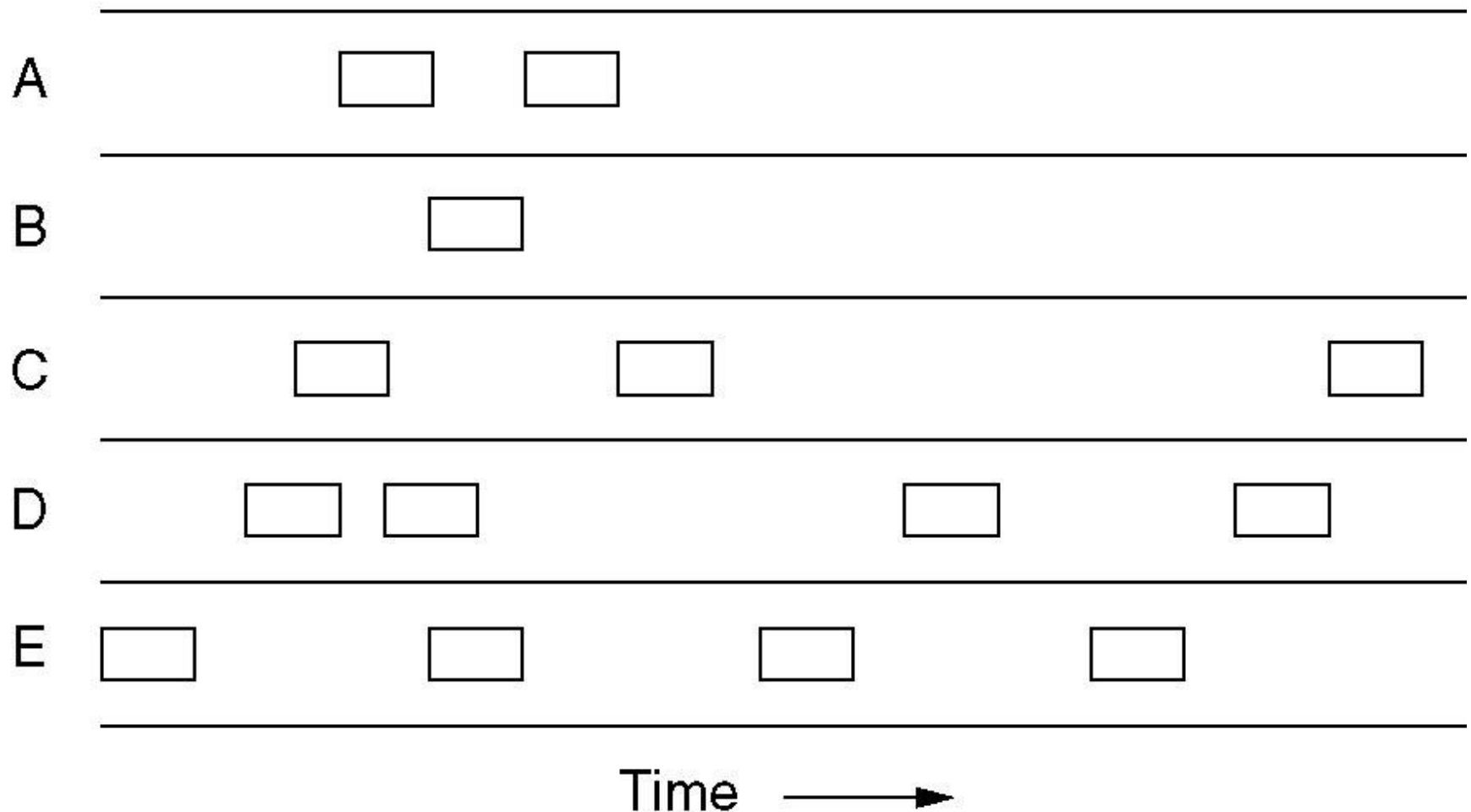
Pure ALOHA

- Let users transmit whenever they have data to be sent.
- There will be collisions, colliding frames will be damaged.
- Due to feedback property of broadcasting, sender can always find out whether its frame was destroyed by listening to channel
- If listening while transmitting is not possible for some reason, acknowledgements are needed.
- If frame was destroyed, sender just waits a random amount of time and sends it again.
- Waiting time must be random or same frames will collide over and over, in lockstep.

Frame generation in an ALOHA system

- Frames of same length

User

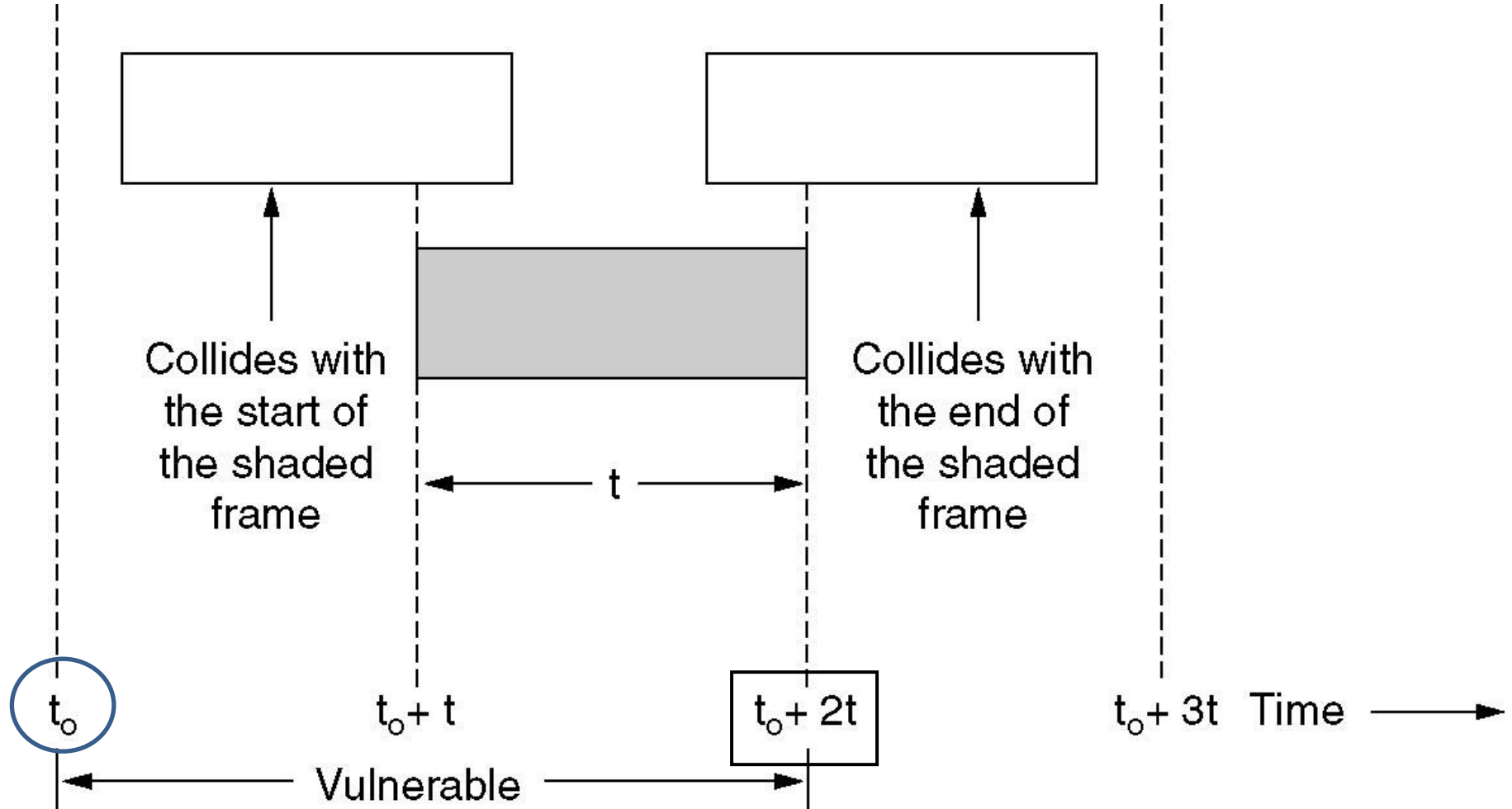


Efficiency of an ALOHA channel

- Frame time = amount of time needed to transmit standard, fixed-length frame
- Frame time = Frame length/bit rate
- Infinite number of users generates new frames according to Poisson's distribution with average N frames per frame time
- If $N > 1$, users generating frames at a higher rate than channel can handle and most frames will suffer a collision
- To reduce collision we would expect $0 < N < 1$

- In addition to new frames, stations also generate retransmissions of frames that previously suffered collisions.
- Let there be k transmission attempts (including retransmissions) per frame time.
- The probability of k transmissions per frame time is also Poisson.
- Let the mean of these transmissions be G per frame time.
- Clearly, $G \geq N$ (old (duplicate) and new frames will be more than new frames)
- At low load ($N \approx 0$), few collisions, few retransmissions, so $G \approx N$.
- At high load there will be many collisions, so $G > N$
- For all loads, Throughput per frame time = $S = G \times \text{Probability that a frame doesn't suffer collision} = GP_0$
- We find P_0

Vulnerable time for the shaded frame



- What is the condition for shaded frame to arrive undamaged without collision? (for finding P_0)

- t = time required to send a frame
- If any other user has generated a frame between time t_0 and $t_0 + t$, end of that frame will collide with beginning of shaded one
- any other frame started between $t_0 + t$ and $t_0 + 2t$, beginning of that frame will collide with end of shaded frame
- Vulnerable period = $t_0 + 2t - t_0 = 2t$

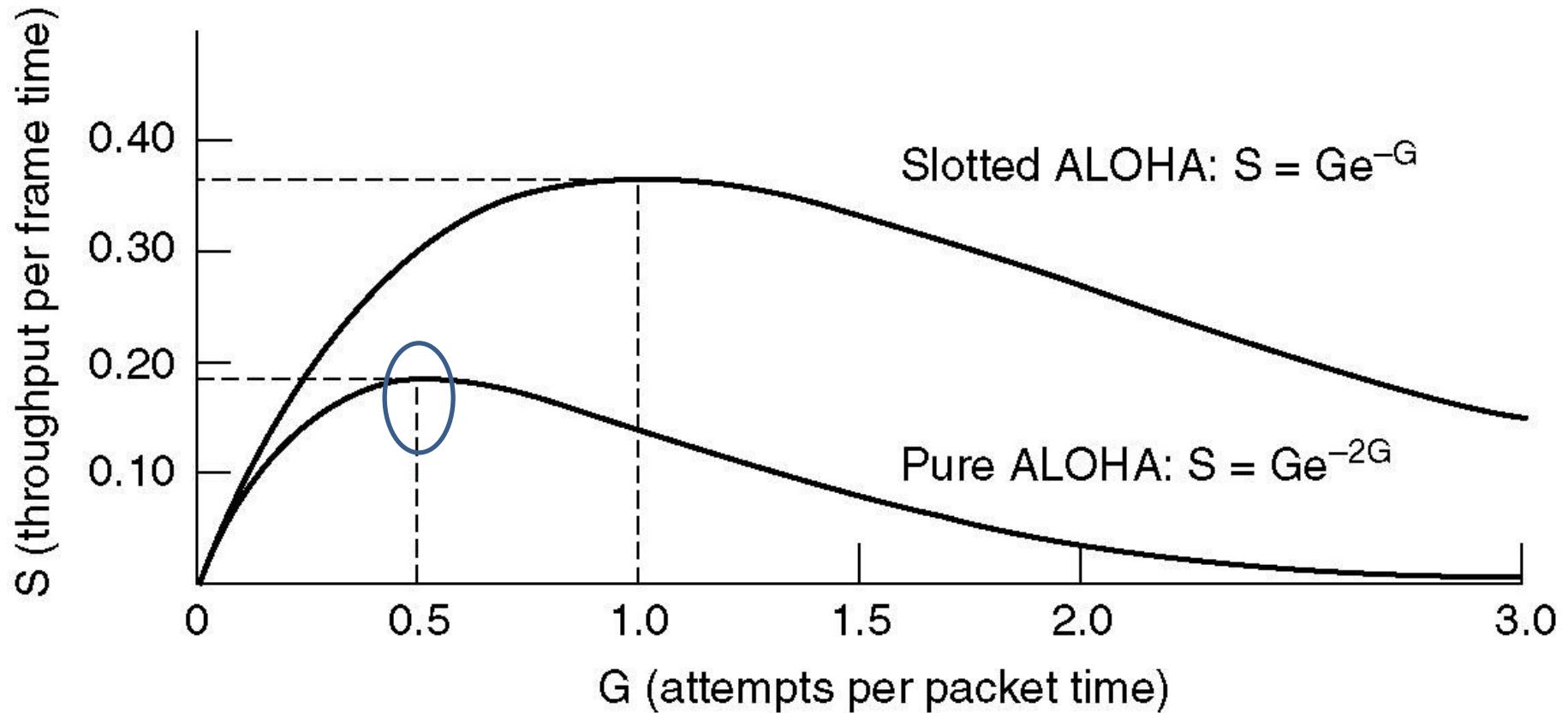
Generalized Poisson Distribution for frame generation

- Probability that k frames are generated during time t is given by Poisson distribution
- $P[k] = [G^k e^{-G}] / k!$
- Probability of generating zero frames i.e. $k = 0$ (when 0 frame generated no collision and so no frame damaged)
- $P[k] = [G^0 e^{-G}] / 0!$
- $P[k] = e^{-G}$ (i.e. $0! = 1$)

Poisson Distribution for frame generation during vulnerable period

- If interval is two frame time long ($2t$, vulnerable period), mean number of frames generated will be $2G$ ($t \rightarrow G$ frames, $2t \rightarrow 2G$ frames)
- Probability of generating zero frames i.e. $k = 0$ during $2t$ (no collision and so no frame damaged when 0 frame generated)
- $P_0 = [(2G)^0 e^{-2G}] / 0!$
- $P_0 = e^{-2G}$
- Using $S = GP_0$,
- Throughput per frame time = $S = G e^{-2G}$

Offered traffic (G) and throughput (S)



Pure ALOHA

- maximum throughput (S) occurs at $G = 0.5$,

$$S = G e^{-2G}$$

$$S = 0.5 \times e^{-2 \times 0.5}$$

$$= 0.5 \times e^{-1}$$

$$= 0.184$$

$$= 18.4\%$$

- $e = \text{constant} = 2.71828$
- We get efficiency of 18 percent in Pure Aloha

Example

A pure ALOHA network transmits 200-bit frames on a shared channel of 200 kbps. What is the requirement to make this frame collision-free?

Solution

*Average frame transmission time $t = \text{frame length} / \text{bit rate}$
 $= 200 \text{ bits} / 200 \text{ kbps} = 1 \text{ ms}.$*

Vulnerable time $= 2t = 2 \times 1 \text{ ms} = 2 \text{ ms}.$

This means no station should send later than 1 ms before this station starts transmission and no station should start sending during one 1-ms period that this station is sending.

Example

A pure ALOHA network transmits 200-bit frames on a shared channel of 200 kbps. What is the throughput in terms of number of frames/percentage if system (all stations together) produces

***a.** 1000 frames per second **b.** 500 frames per second*

Solution

The frame transmission time = 200 (frame length)/200 kbps (bit rate)=1 ms.

***a.** If system creates 1000 frames per second, this is 1 frame per millisecond. The load offered by system i.e G is 1. Thus $S = G \times e^{-2G}$ or $S = 1 \times e^{-2 \times 1} = 1/(2.71828)^2 = 0.135$ (13.5 percent). From 100 frames 13.5 will not collide, how many from 1000 frames will be successfully transmitted without collision. Throughput = $1000 \times 13.5/100 = 135$ frames. Only 135 frames out of 1000 will probably survive.*

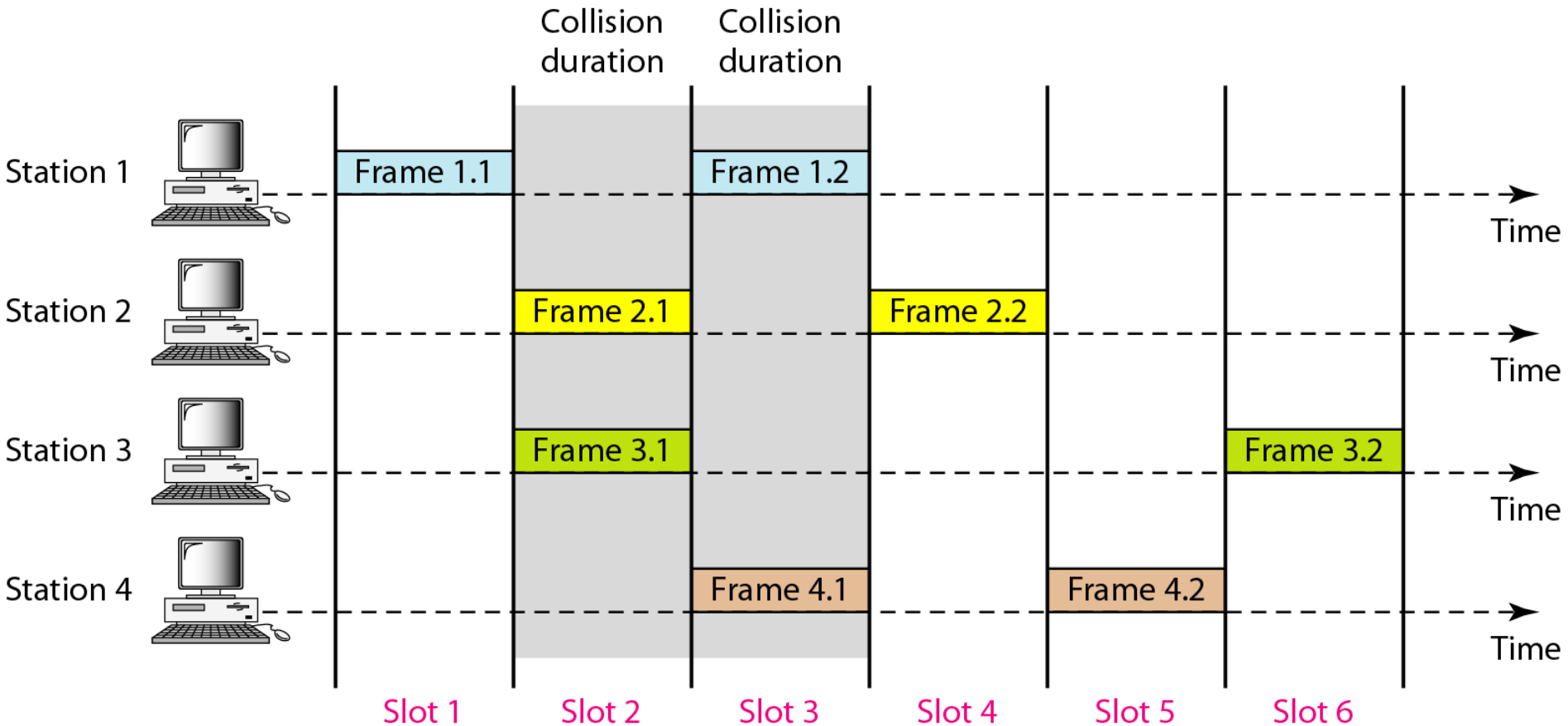
Example 12.3 (continued)

- b. If system creates 500 frames per second, this is $(1/2)$ frame per millisecond. The load is $(1/2)$. In this case $S = G \times e^{-2G}$ or $S = 0.184$ (18.4 percent). This means that the throughput is $500 \times 0.184 = 92$ and that only 92 frames out of 500 will probably survive. Note that this is the maximum throughput case, percentage-wise.*
- c. If the system creates 250 frames per second, this is $(1/4)$ frame per millisecond. The load is $(1/4)$. In this case $S = G \times e^{-2G}$ or $S = 0.152$ (15.2 percent). This means that the throughput is $250 \times 0.152 = 38$. Only 38 frames out of 250 will probably survive.*

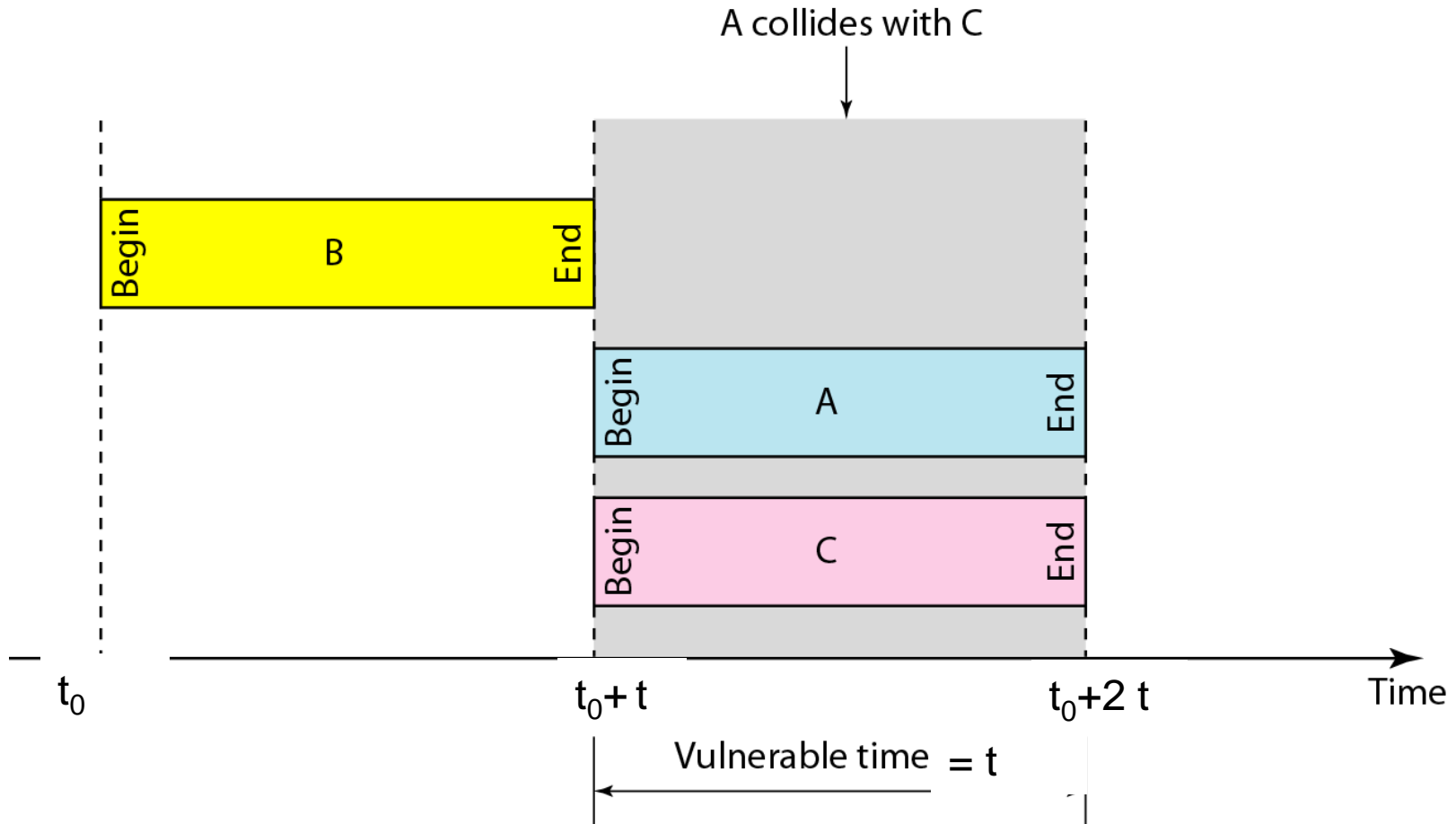
Slotted ALOHA

- In 1972, Roberts published a method for doubling efficiency of an ALOHA system
- Divide time into discrete intervals, each interval corresponding to one frame
- All users are to agree on slot boundaries.
- For synchronization one special station transmit a signal at the start of each interval, like a clock.
- User is not permitted to send whenever he wants
- it is required to wait for beginning of the next slot
- If misses to start at start of slot wait for begin of next slot

Frames in a slotted ALOHA network

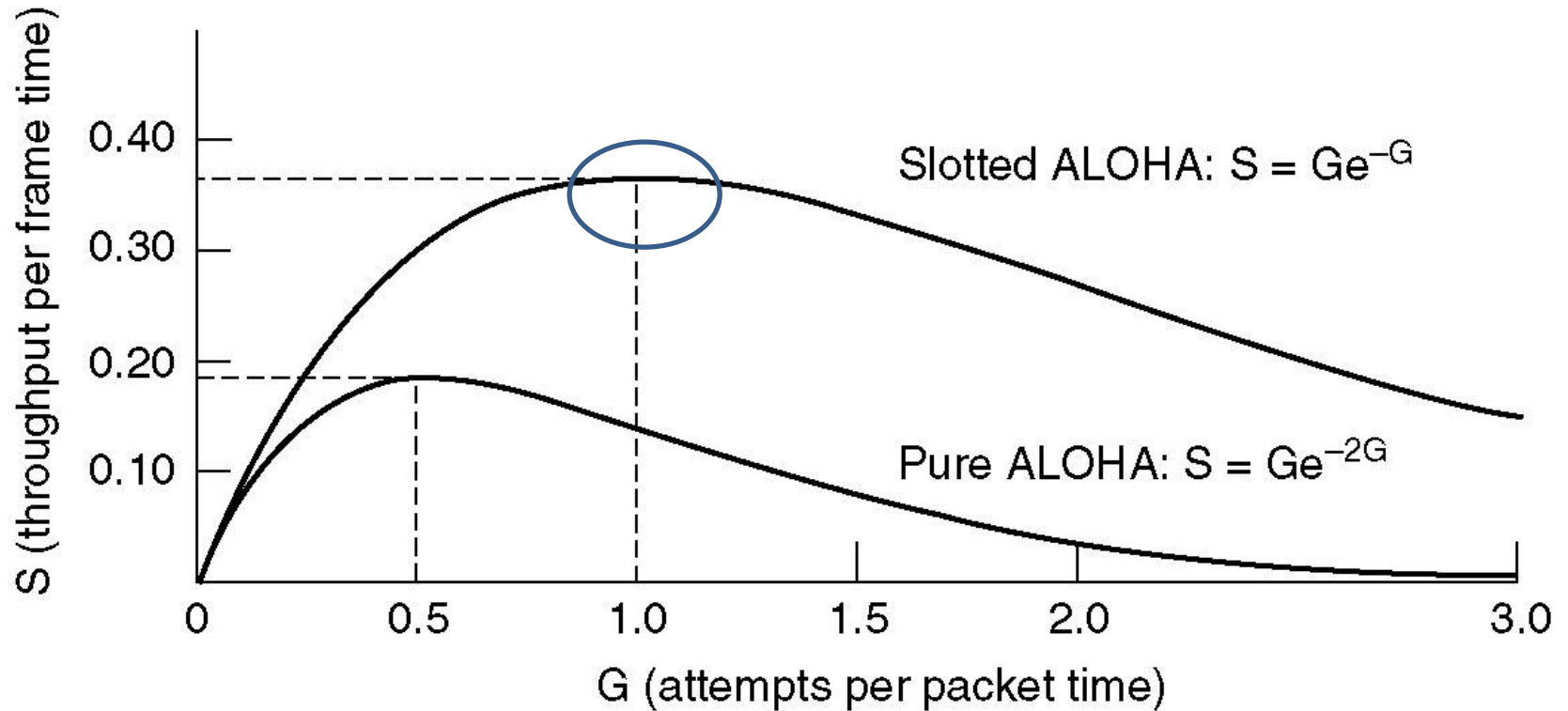


Vulnerable time for slotted ALOHA protocol



- If interval is one frame time long (t , vulnerable period), mean number of frames generated will be G (transmission attempts)
- Probability of generating zero frames i.e. $k=0$ during t (when 0 frame generated no collision and so no frame damaged)
- $P_0 = [(G)^0 e^{-G}] / 0!$
- $P_0 = e^{-G}$
- Using $S = GP_0$,
- $S = G e^{-G}$

offered traffic (G) and throughput (S)



Slotted ALOHA

- maximum throughput (S) occurs at $G = 1$,

$$S = G e^{-G}$$

$$S = 1/e^{-1}$$

- $e = \text{constant} = 2.71828$

$$S = 1/2.71828 = 0.3678$$

- We get efficiency of 37 percent in Slotted Aloha, twice that of pure ALOHA.

Carrier Sense Multiple Access Protocols

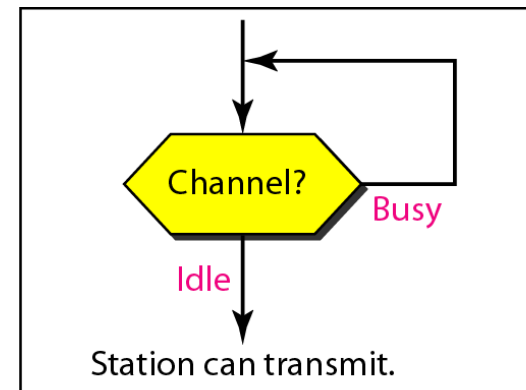
- In LAN, it is possible for stations to detect what other stations are doing, and adapt their behavior accordingly.
- Protocols in which stations listen for a carrier (i.e., a transmission) and act accordingly are called carrier sense protocols.
- CSMA is based on the principle "sense before transmit" or "listen before talk"

Persistence Methods

- What should a station do if channel is busy?
- What should a station do if channel is idle?
- Three methods have been devised to answer these questions: 1-persistent method, nonpersistent method, p-persistent method.

1-Persistent CSMA

- When a station has data to send, it first listens to channel to see if anyone else is transmitting
- If channel is busy, station continuously senses it waiting for it to become idle
- When station detects an idle channel, it transmits a frame (with probability 1)
- If a collision occurs, station waits a random amount of time and starts all over again.
- Has highest chance of collision because two or more stations may find channel idle and send their frames immediately

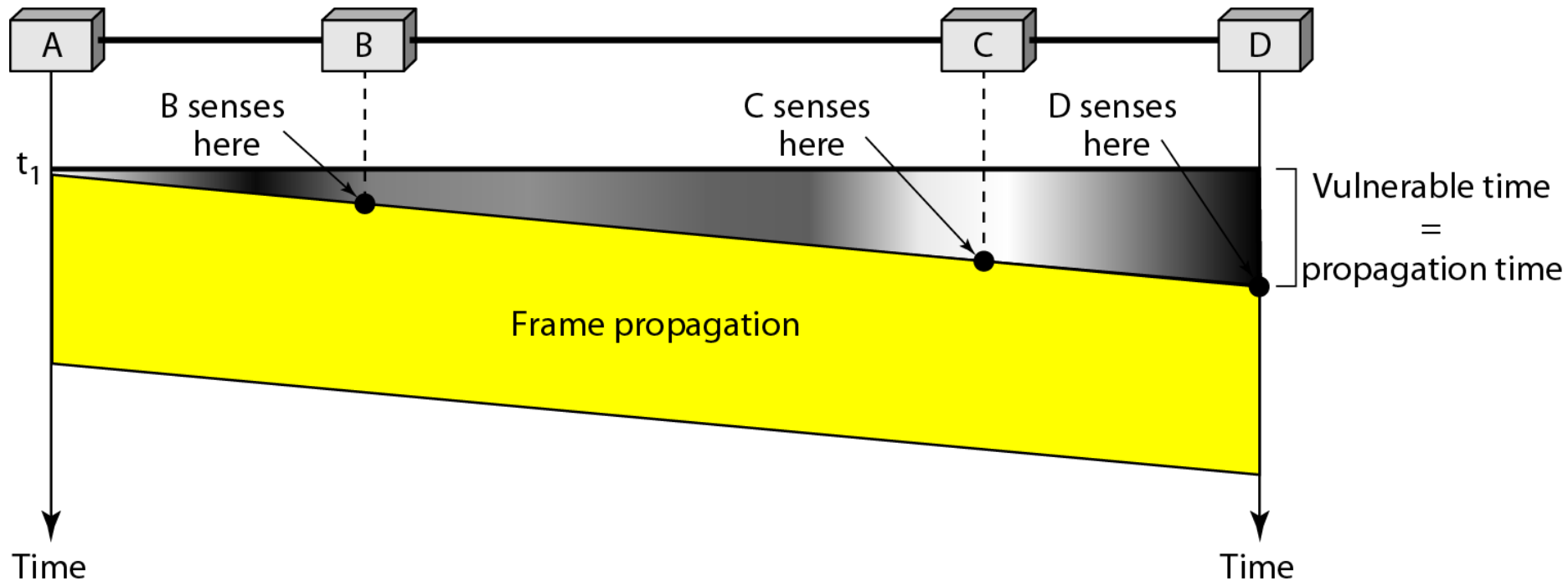


a. 1-persistent

Role of propagation delay in CSMA

- propagation delay has an important effect on performance CSMA
- just after a station begins sending, another station becomes ready to send and sense the channel.
- If first station's signal has not yet reached second one, latter will sense an idle channel and will also begin sending, resulting in a collision.
- longer propagation delay, more important this effect becomes, and worse the performance of the protocol
- Even if propagation delay is zero, two stations become ready in middle of a third station's transmission, both will wait until transmission ends and then both will begin transmitting exactly simultaneously, resulting in a collision

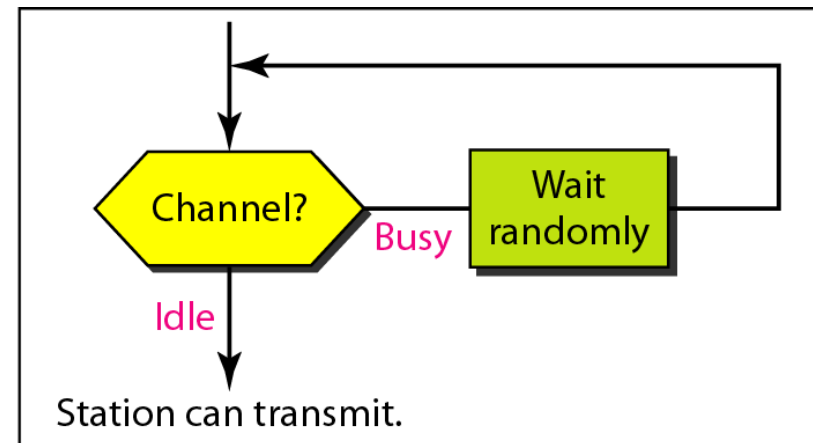
Vulnerable time in CSMA = Propagation time



longer propagation delay, more important this effect becomes, and worse is the performance of the protocol

nonpersistent CSMA

- attempt is made to be less greedy
- Before sending, a station senses the channel.
- If no one else is sending, the station begins doing so itself.
- However, if channel is already in use, station does not continually sense it for purpose of seizing it immediately upon detecting end of previous transmission.
- Instead, it waits a random period of time and then repeats the algorithm.
- Consequently, this algorithm leads to better channel utilization but longer delays than 1-persistent CSMA

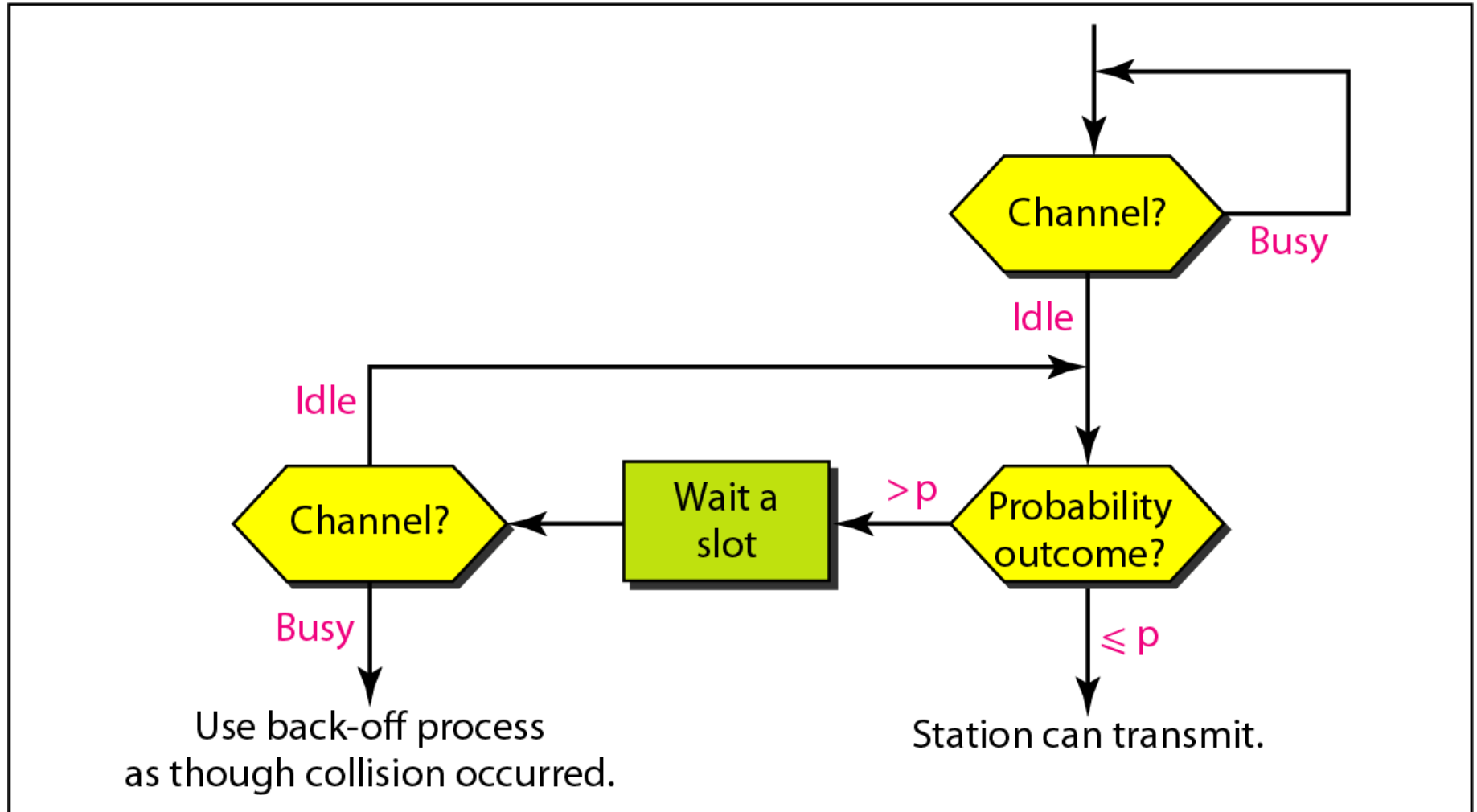


b. Nonpersistent

p-persistent CSMA

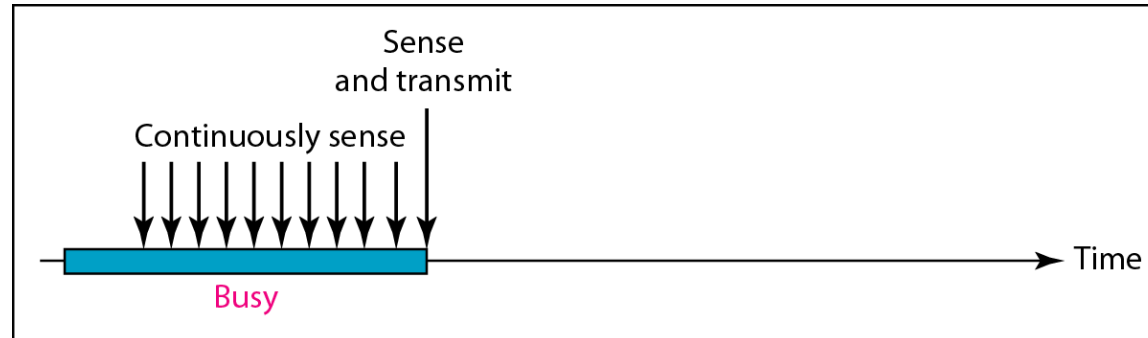
- Used if channel has time slots with a slot duration \geq maximum propagation time
- When a station becomes ready to send, it senses the channel.
- If station finds channel idle it follows these steps:
 1. With probability p , the station sends its frame.
 2. With probability $q = 1 - p$, the station waits for the beginning of the next time slot and checks the line again.
 - a. If the line is idle, it goes to step 1.
 - b. If the line is busy, it acts as though a collision has occurred and uses the back-off procedure.
- If station initially senses the channel busy, it waits until the next slot and applies the above algorithm.

Flow diagram of p-persistence method

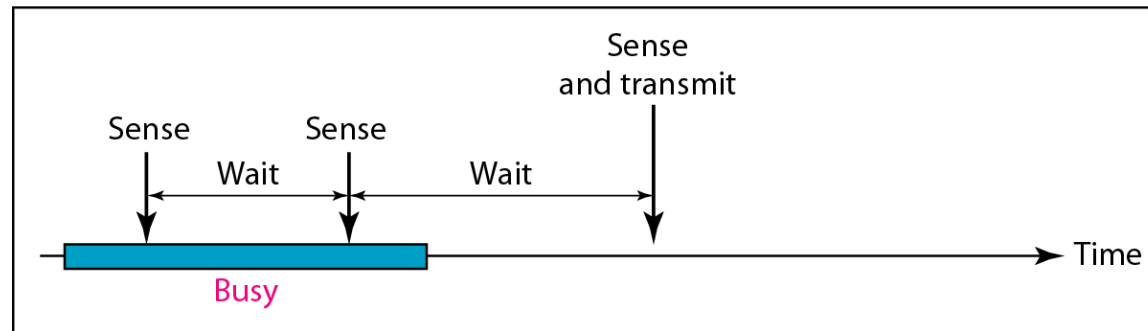


c. p-persistent

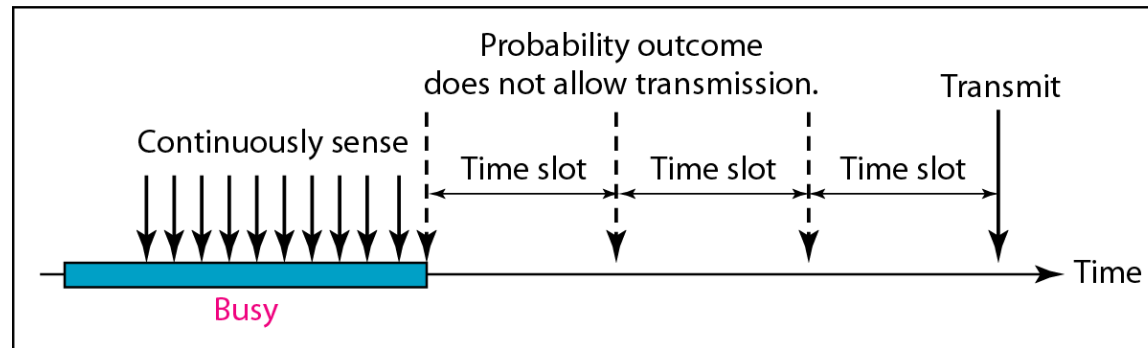
Behavior of three persistence methods



a. 1-persistent

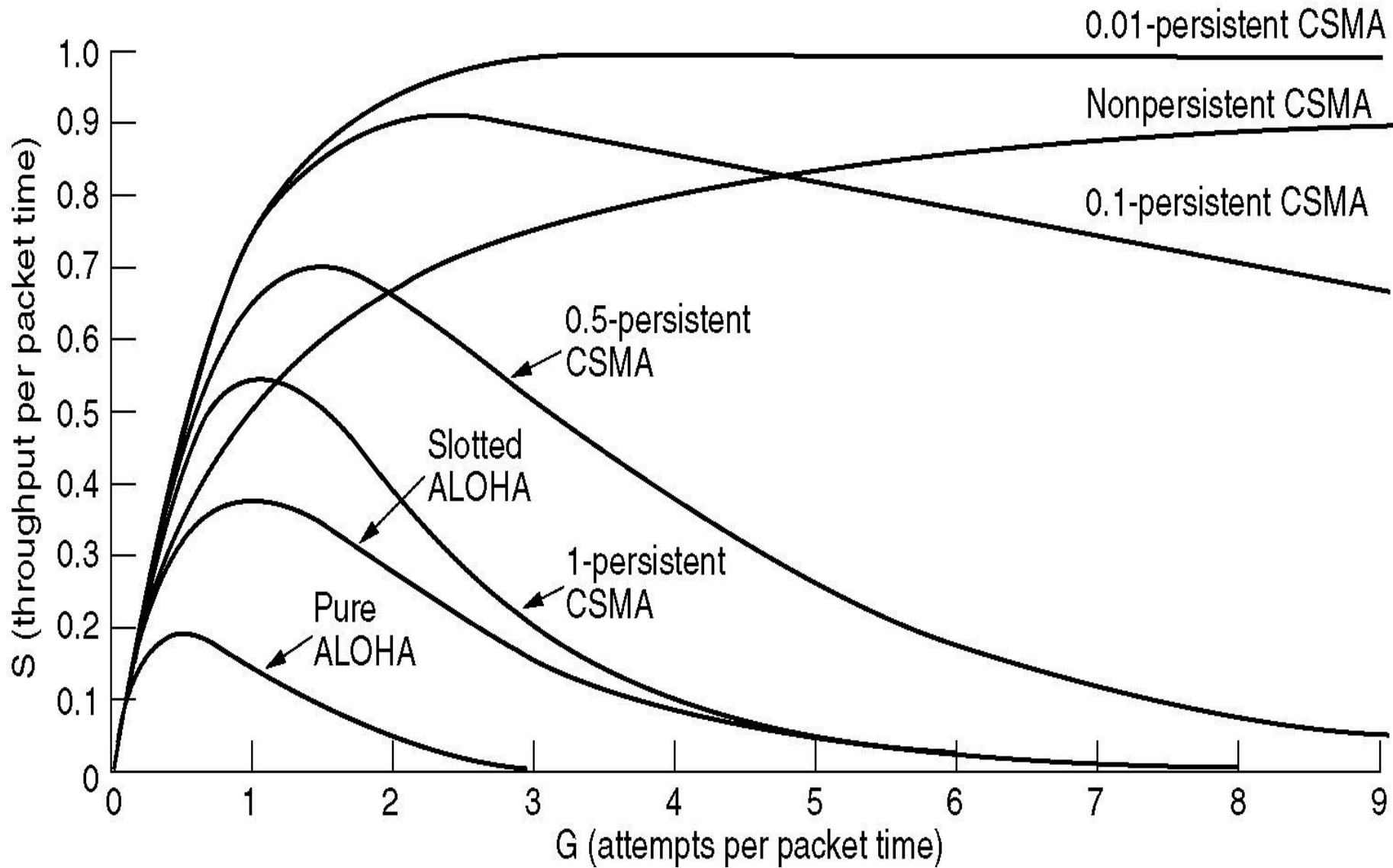


b. Nonpersistent



c. p-persistent

computed throughput versus offered traffic



CSMA with Collision Detection

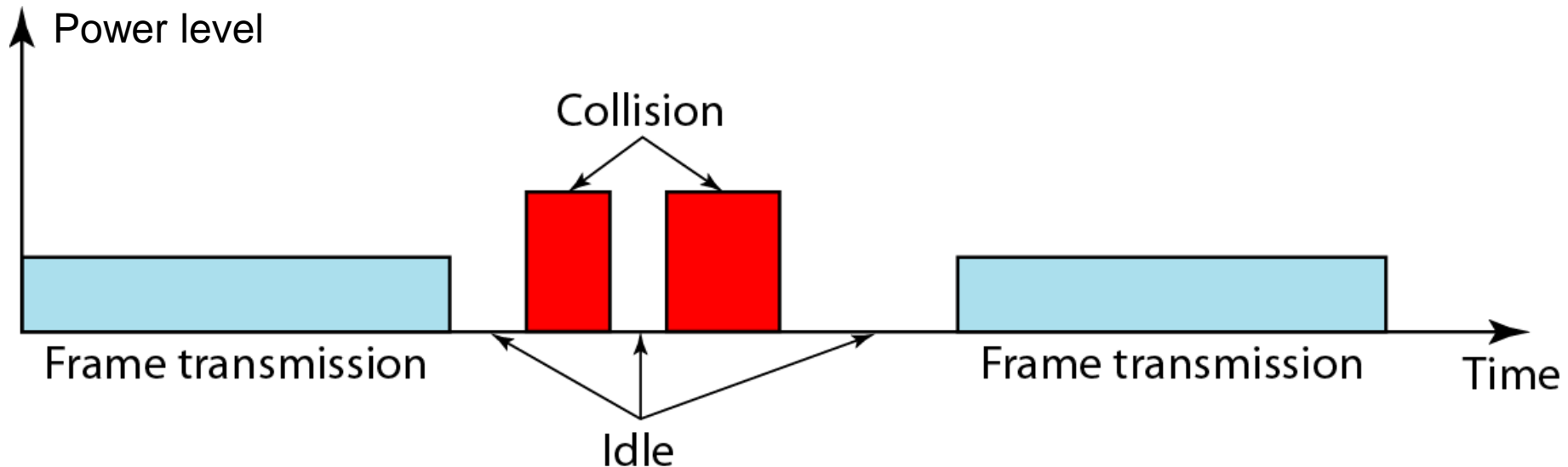
- Augmentation to handle collision
- station monitors channel after it sends a frame to see if transmission was successful
- If so, the station is finished.
- If, there is a collision, the frame is sent again.
- stations to abort their transmissions as soon as they detect a collision
- widely used on LANs in the MAC sublayer.
- Ethernet LAN uses it

Collision Detection

- station's hardware must listen to the channel while it is transmitting.
- If what it reads back is different from what it is putting out, it knows that a collision is occurring.
- Signal encoding must allow collisions to be detected (e.g., a collision of two 0-volt signals cannot be detected, 1 = 5 V, 0=0 V is better).
- a sending station must continually monitor the channel, listening for noise bursts that might indicate a collision.

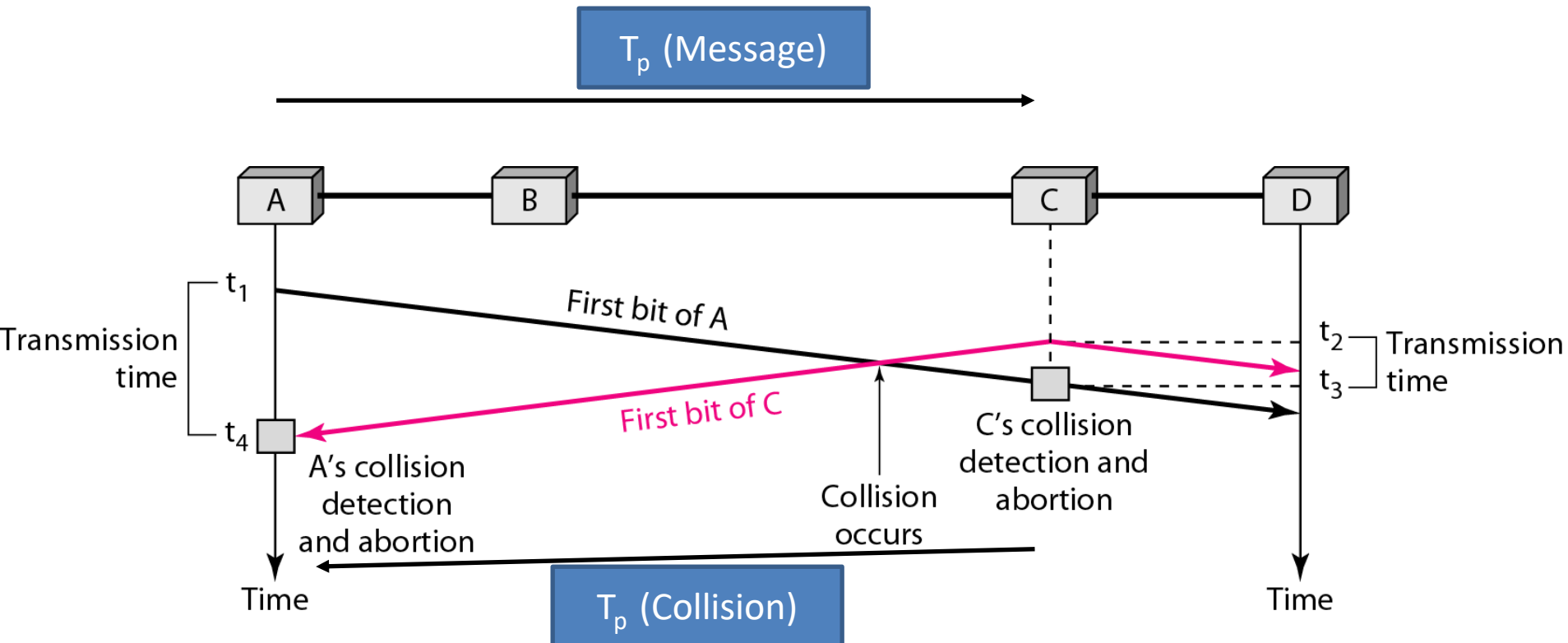
Collision Detection

- Collisions can be detected by looking at power or pulse width of received signal and comparing it to transmitted signal
- After station detects a collision, it aborts its transmission, waits a random period of time, and then tries again



Minimum Frame Size

- If two stations involved in a collision are maximum distance apart, signal from first takes time T_p (propagation time) to reach second
- Effect of collision takes another time T_p to reach the first
- So requirement is that first station must still be transmitting after $2T_p$ (i.e. active to know collision has occurred)



Example

A network using CSMA/CD has a bandwidth of 10 Mbps. If maximum propagation time (including the delays in the devices) is $25.6 \mu\text{s}$, what is minimum size of frame?

Solution

- *The frame transmission time is $T_{fr} = 2 \times T_p = 51.2 \mu\text{s}$.*
- *This means, in worst case, a station needs to transmit for a period of $51.2 \mu\text{s}$ to detect collision.*
- *Transmission time=Message size/BW*
- *Minimum size of frame = $10 \text{ Mbps} \times 51.2 \mu\text{s} = 512 \text{ bits or } 64 \text{ bytes}$*
- *This is frame size of Ethernet*

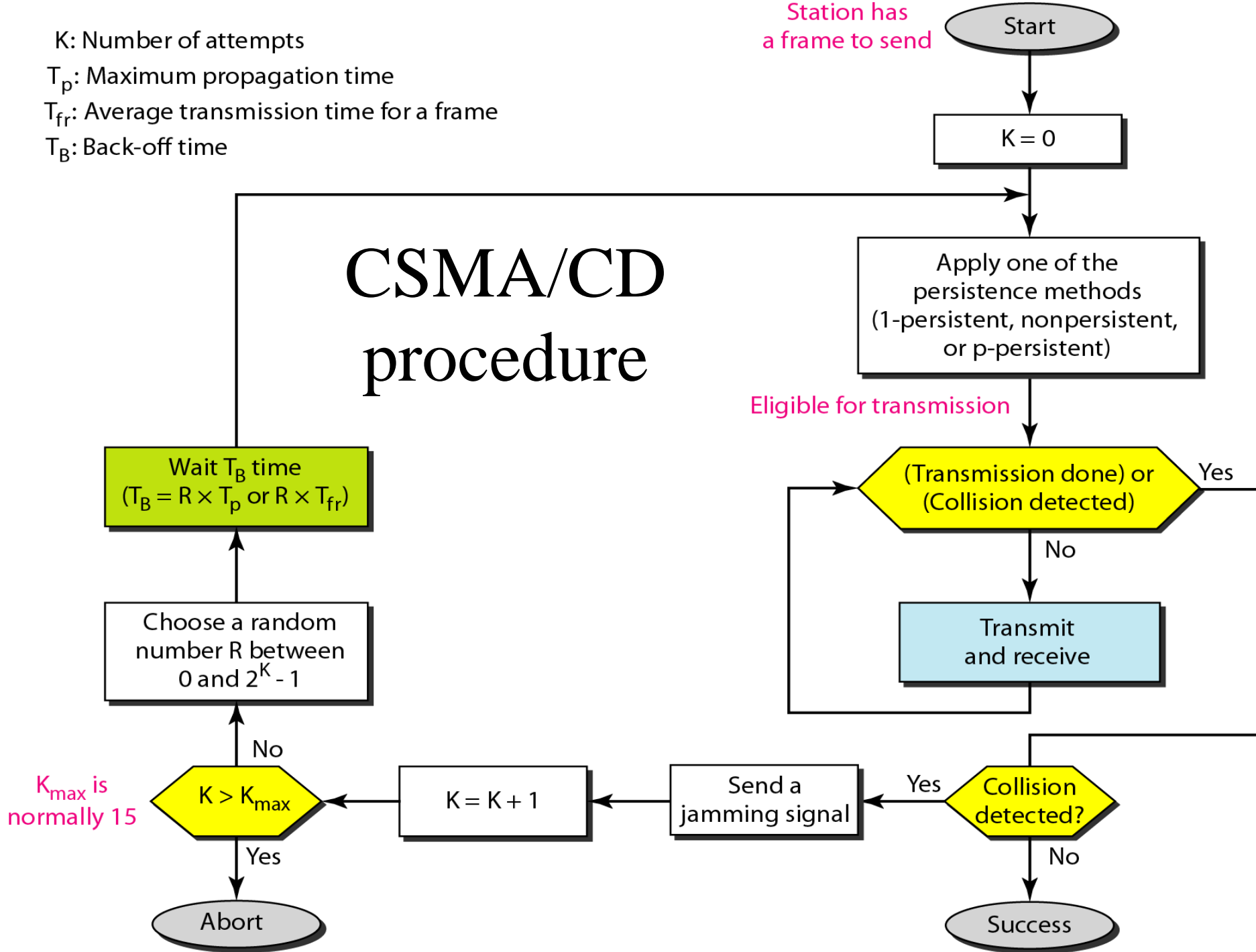
K : Number of attempts

T_p : Maximum propagation time

T_{fr} : Average transmission time for a frame

T_B : Back-off time

CSMA/CD procedure



Thank You!