

Electrical and Electronic Measurements:

Sources of Error

1

Errors in Electrical Measurements

- Systematic error \Rightarrow every times you measure
e.g. loading or insertion of the measurement
instrument
- Meter error \Rightarrow scaling (inaccurate marking),
pointer bending, friction, no calibration
- Random error \Rightarrow temperature effect, noises
(unwanted signals)
- Reading error \Rightarrow parallax, read a wrong scale
- Recording error \Rightarrow for many measured values

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Background

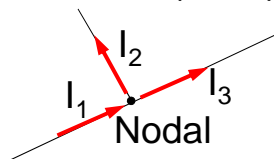
- Electric charge, $e^- = 1.6 \times 10^{-19}$ Coulombs
- Current, $I = dq/dt$ Coulomb/sec = Amps
- Voltage, the difference in electrical potential between two points (Joules/Coulomb)
- Power, $P = IV$ Watts
- Energy, $E = Pt$ Units (kW·hr)
- Ohm's Law, $V = IR$

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Background (Cont'd)

- Kirchhoff's Current Law (KCL)

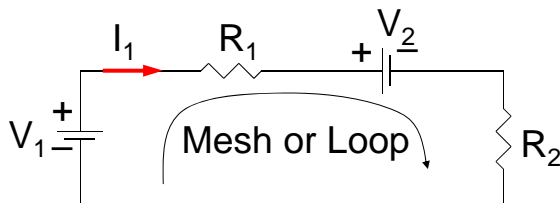
$$I_1 - I_2 - I_3 = 0$$



A *loop* is any closed path in a circuit, in which no node is encountered more than once.

- Kirchhoff's Voltage Law (KVL)

$$-V_1 + I_1 R_1 + V_2 + I_2 R_2 = 0$$

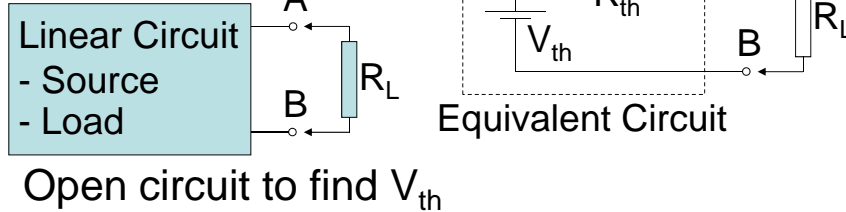


A *mesh* is a loop that has no other loops inside of it.

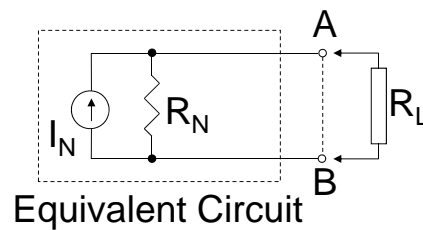
A *supermesh* occurs when a current source is contained between two essential meshes.⁴

Background (Cont'd)

- Thévenin's Theorem



- Norton's Theorem
- Short circuit to find I_N

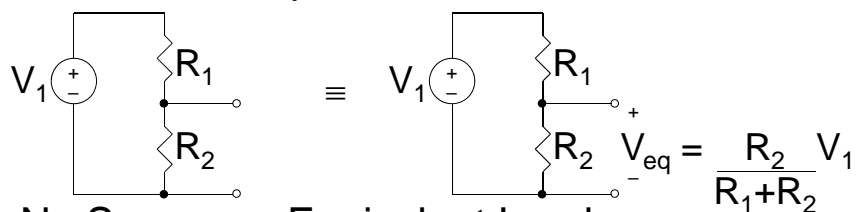


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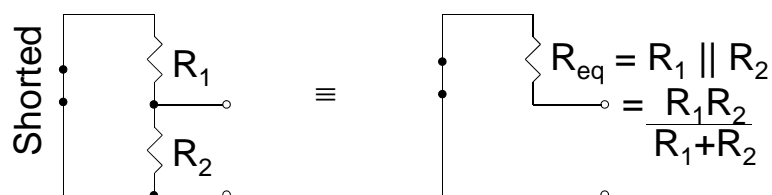
Background (Cont'd)

Example

No Load \Rightarrow Equivalent Source



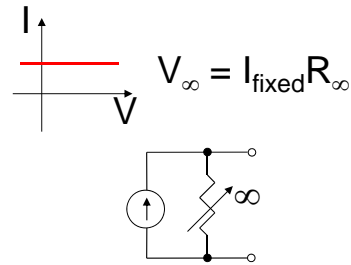
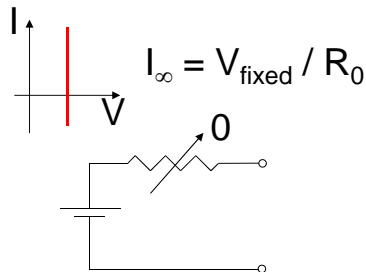
No Source \Rightarrow Equivalent Load



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Background (Cont'd)

- Ideal Voltage Source Vs. Ideal Current Source



- Superposition Theorem (for linear resistive network containing several sources)

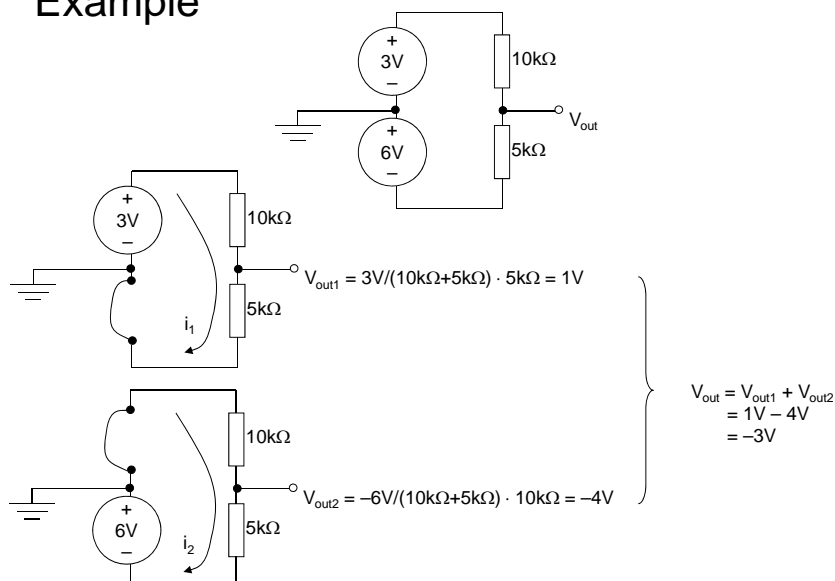
Voltage source $\text{---} \oplus \text{---} \Rightarrow$ Short Circuit $\text{---} 0 \text{ V} \text{---}$

Current source $\text{---} \rightarrow \text{---} \Rightarrow$ Open Circuit $\text{---} 0 \text{ A} \text{---}$

Vector summation of the individual voltage or current caused by each separate source 7

Background (Cont'd)

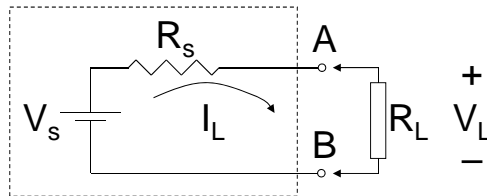
Example



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Background (Cont'd)

- The Maximum Power Transfer Theorem



If V_s and R_s are fixed, when $I_L \uparrow$ then $V_L \downarrow$

Maximum power is at $R_L = R_s$

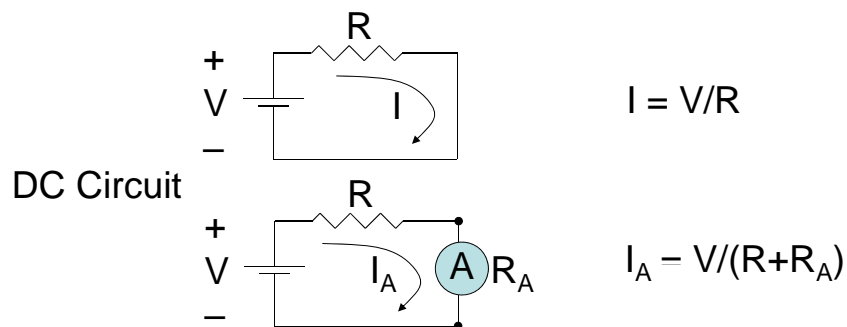
Therefore $V_L = V_s / 2$ and $I_L = V_s / 2R_L$

$$P_L = (I_L)^2 R_L = (V_s / 2R_L)^2 R_L = V_s^2 / 4R_L$$

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Ammeter Loading

For current measurement, open circuit to put an ammeter.



While this impact is inevitable, it can be minimized through good meter design.

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Ammeter Loading (Cont'd)

$$\begin{aligned}\text{Loading error, } I_A - I &= V/(R+R_A) - V/R \\ &= \frac{VR - V(R+R_A)}{R(R+R_A)} \\ &= \frac{-VR_A}{R(R+R_A)}\end{aligned}$$

$$\begin{aligned}\% \text{ Loading Error} &= (I_A - I)/I \times 100\% \\ &= \frac{-R_A}{R+R_A} \times 100\%\end{aligned}$$

It means if $R_A \uparrow$ then error \uparrow

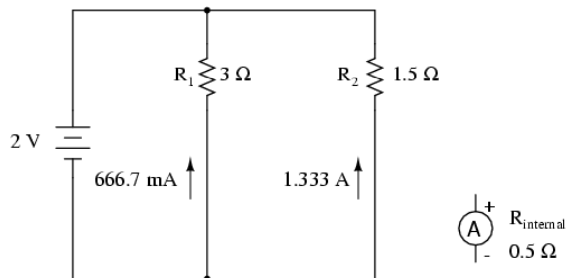
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Ammeter Loading (Cont'd)

The ideal ammeter has zero internal resistance, so as to drop as little voltage as possible as electrons flow through it.

Example

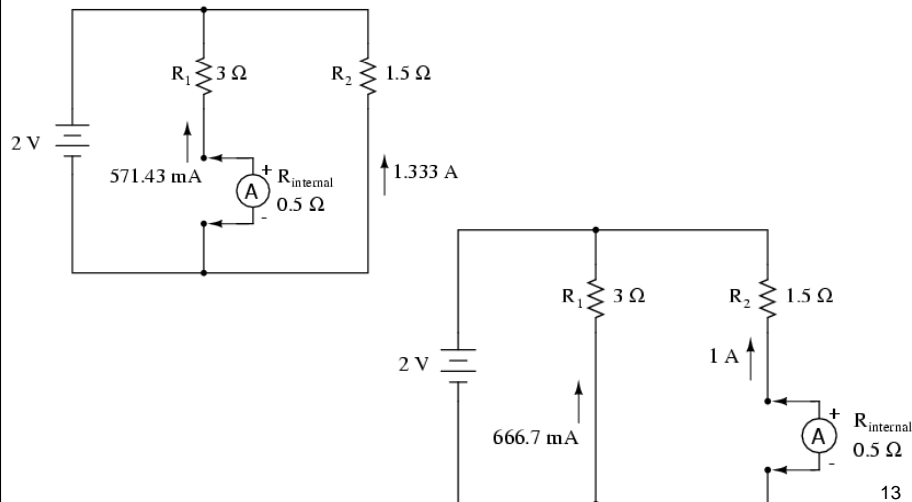
without the ammeter,



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Ammeter Loading (Cont'd)

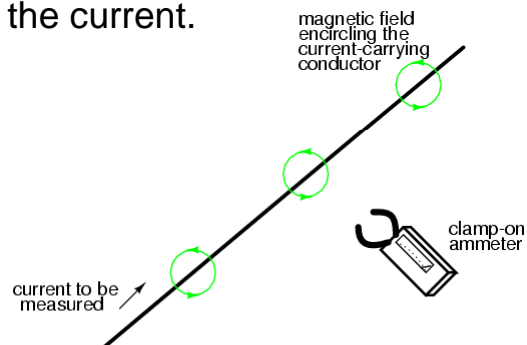
with the ammeter,



Ammeter Loading (Cont'd)

One ingenious way to reduce the impact that a current-measuring device has on a circuit is to use the circuit wire as part of the ammeter movement itself.

All current-carrying wires produce a magnetic field, the strength of which is in direct proportion to the strength of the current.

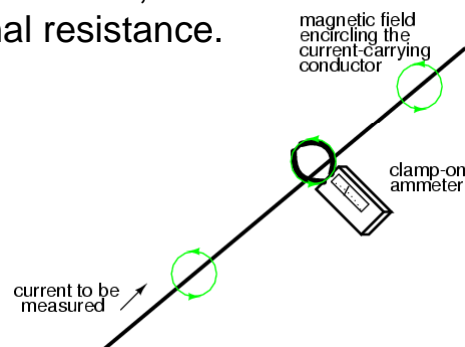


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Ammeter Loading (Cont'd)

By building an instrument that measures the strength of that magnetic field, a no-contact ammeter can be produced.

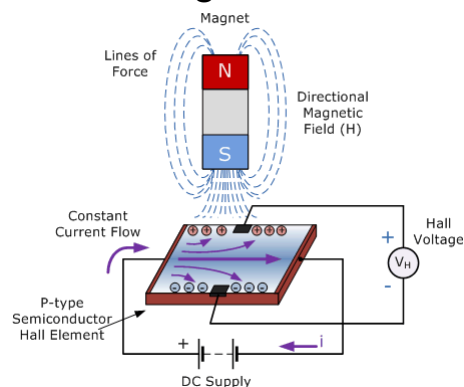
Such a meter is able to measure the current through a conductor without even having to make physical contact with the circuit, much less break continuity or insert additional resistance.



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Ammeter Loading (Cont'd)

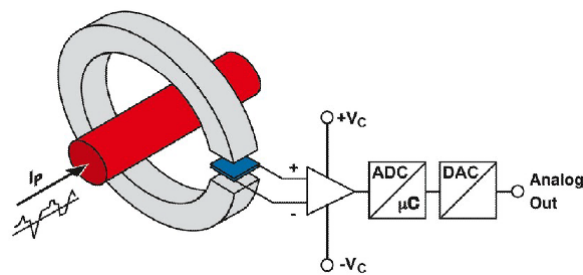
More modern designs of clamp-on ammeters utilize a small magnetic field detector device called a Hall-effect sensor to accurately determine field strength.



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Ammeter Loading (Cont'd)

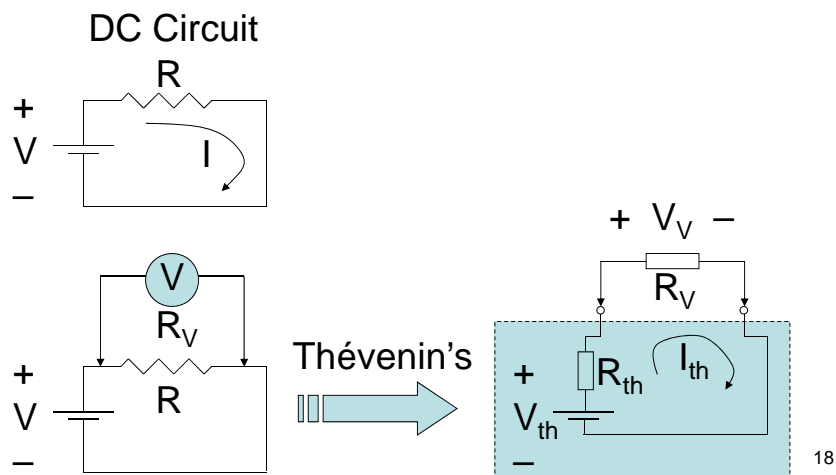
Some clamp-on meters contain electronic amplifier circuitry to generate a small voltage proportional to the current in the wire between the jaws, that small voltage connected to a voltmeter for convenient readout by a technician.



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Voltmeter Loading

For voltage measurement, voltmeter is placed in parallel with the circuit element.



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Voltmeter Loading (Cont'd)

$$I_{th} = V_{th} / (R_{th} + R_V)$$

$$V_V = I_{th} R_V = V_{th} R_V / (R_{th} + R_V)$$

$$\text{Error} = V_V - V_{th}$$

$$= \left(\frac{R_V}{R_{th} + R_V} - 1 \right) V_{th}$$

$$\% \text{ Error} = (V_V - V_{th}) / V_{th} \times 100\%$$

$$= \frac{-R_{th}}{R_{th} + R_V} \times 100\%$$

It means if $R_V \uparrow$ then error \downarrow

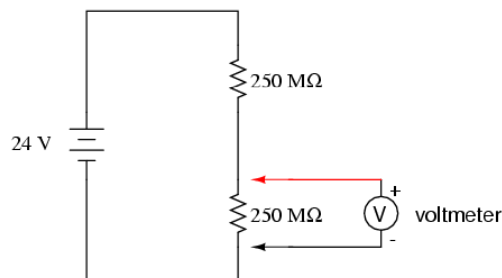
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Voltmeter Loading (Cont'd)

The ideal voltmeter has infinite resistance, so that it draws no current from the circuit under test.

Example

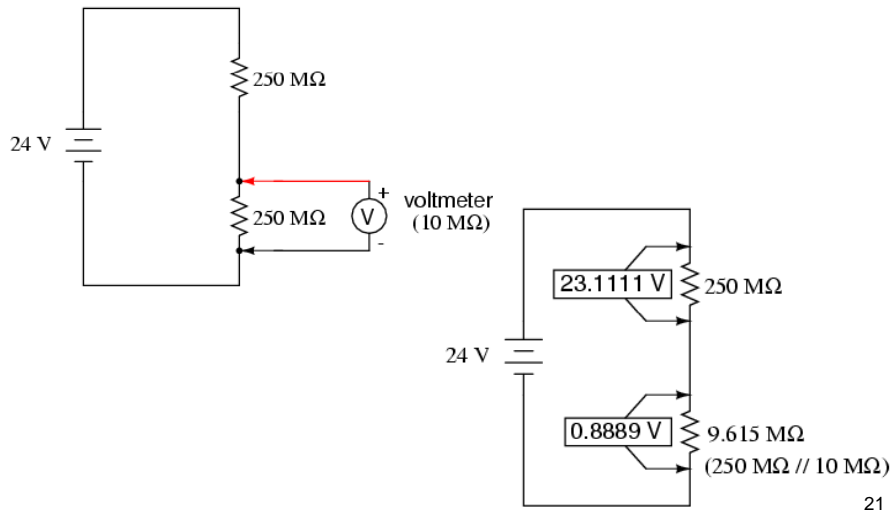
without the voltmeter,



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Voltmeter Loading (Cont'd)

with the voltmeter,



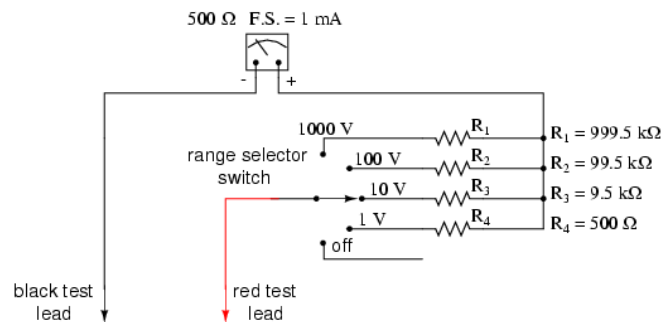
Voltmeter Sensitivity

- Voltmeters with electromechanical movements are typically given ratings in “ohms per volt” of range to designate the amount of circuit impact created by the current draw of the movement.
- Digital voltmeters, on the other hand, often exhibit a constant resistance across their test leads regardless of range setting, and as such are usually rated simply in ohms of input resistance, rather than “ohms per volt” sensitivity.
- Since most digital voltmeter have 50 times more impedance than analog voltmeters, digital meters are more accurate when measuring voltage.

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Voltmeter Sensitivity (Cont'd)

Ex On the 1000 volt scale,
the total resistance is $1\text{ M}\Omega$ ($999.5\text{ k}\Omega + 500\Omega$),
giving $1,000,000\ \Omega$ per 1,000 volts of range,
or $1\text{ k}\Omega/\text{V}$ (1,000 ohms per volt).



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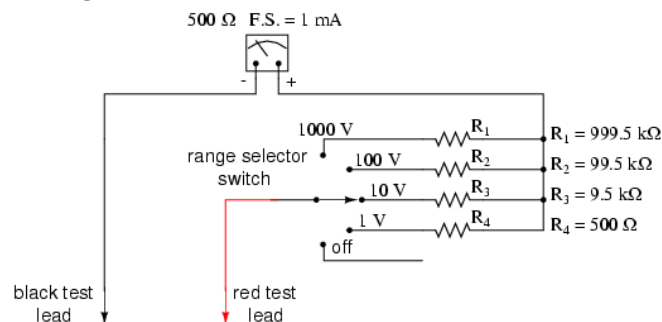
Voltmeter Sensitivity (Cont'd)

This ohms-per-volt “sensitivity” rating remains constant for any ranges of this meter:

100-V range, $100\text{ k}\Omega/100\text{ V} = 1\text{ k}\Omega/\text{V}$ sensitivity

10-V range, $10\text{ k}\Omega/10\text{ V} = 1\text{ k}\Omega/\text{V}$ sensitivity

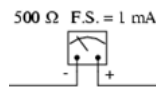
1-V range, $1\text{ k}\Omega/1\text{ V} = 1\text{ k}\Omega/\text{V}$ sensitivity



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Voltmeter Sensitivity (Cont'd)

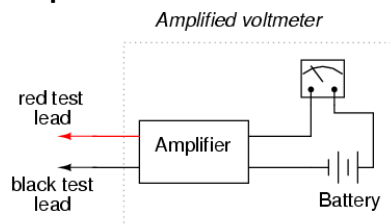
- “Ohms per volt” is the mathematical reciprocal of “volts per ohm,” which is defined by Ohm’s Law.
- The ohms-per-volt rating of any meter is determined by a single factor: the full-scale current of the movement, in this case 1 mA.



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Voltmeter Sensitivity (Cont'd)

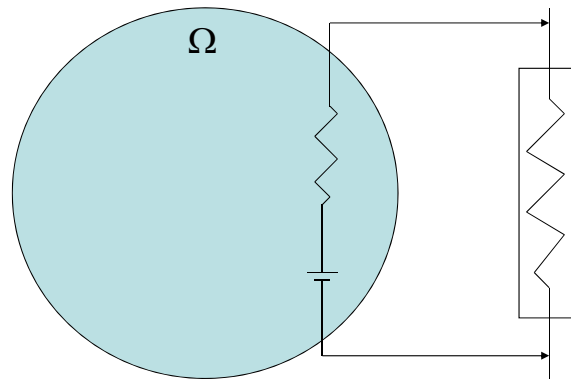
- To minimize the loading of a voltmeter on any circuit, the designer must seek to minimize the current draw of its movement.
- To electronically boost the current sent to the movement, so that very little current needs to be drawn from the circuit under test, an electronic amplifier is used.



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Ohmmeter Loading

Using a circuit within the instrument
(self-powered)



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Analog Ammeters & Voltmeters

- The users have to read the meter manual to find the basic accuracy specifications.
- Moving-coil-based analog meters are characterized by their full-scale deflection (f.s.d.) and effective resistance of the meters (few Ω - $k\Omega$)
- Typical meters produce a f.s.d. current of $50\ \mu\text{A}$ - $1\ \text{mA}$ (this is not the ranges of the meters)



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Percentage of FSD

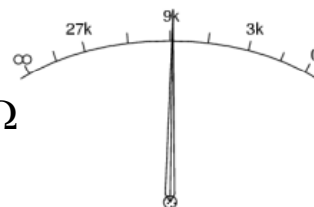
- The accuracy of analog ammeters and voltmeters are quoted as a percentage of the full-scale deflection of pointer on the linear scale for all reading on the selected range.
- e.g. an ammeter having accuracy $\pm 2\%$ f.s.d. within the range 0-10 A,
Relative error $\Rightarrow \pm 2\%$ of 10 A
Absolute error $\Rightarrow \pm 0.2$ A
- When a measured value is close to full scale, or at least above $2/3$ of full scale, the published accuracy is meaningful.



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Percentage of Midscale

- Moving-coil-based ohmmeters is characterized by their midscale deflection of the pointer on nonlinear scale.
- What figure lies exactly between infinity and zero?
- e.g. $\pm 3\%$ of midscale
Relative error $\Rightarrow \pm 3\%$ of 9 k Ω
Absolute error $\Rightarrow \pm 0.27$ k Ω



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Percentage of DMM Reading

- In the case of digital instruments, the accuracy is generally quoted as \pm the percentage of the reading ± 1 digit.
- e.g. $\pm 0.5\%$ Reading ± 1 Digit
when you read a voltage 1.2 V with a digit of 0.01 V (depending on the range selected)
$$\begin{aligned}\text{error} &= \pm 0.5\% \text{ of } 1.2 \text{ V} \pm 0.01 \text{ V} \\ &= \pm 0.016 \text{ V} \quad \Rightarrow \text{absolute error} \\ &= \pm 1.3\% \text{ of reading} \Rightarrow \text{relative error}\end{aligned}$$

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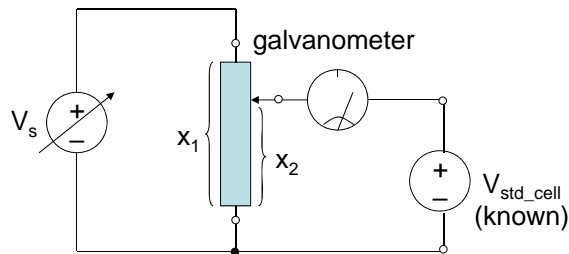
Potential Meter

- Before the moving coil meter, potentiometer was used in measuring the voltage in a circuit
- Calculated from a fraction of a known voltage (on resistive slide wire)
- Based on voltage divider (linearly)
- By means of a galvanometer (no deflection or null-balance)



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Calibration of Potentiometer



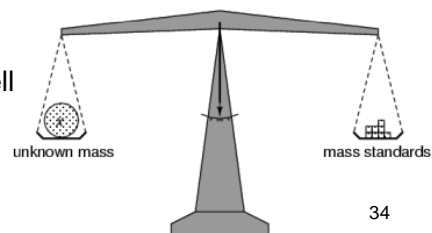
- The end of a uniform resistance wire is at x_1
- The sliding contact or wiper is then adjusted to x_2
- The standard electrochemical cell whose E.M.F. is known (e.g. 1.0183 volts for Weston cell)

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Calibration of Potentiometer (Cont'd)

- Adjust supply voltage V_s until the galvanometer shows zero or detect null (voltage on R_2 equals to the standard cell voltage or no current flows through the galvanometer)

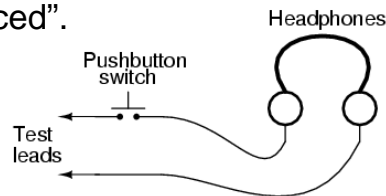
$$\begin{aligned} \bullet \quad x_2/x_1 V_s &= V_{std_cell} \\ V_s &= x_1/x_2 V_{std_cell} \end{aligned}$$



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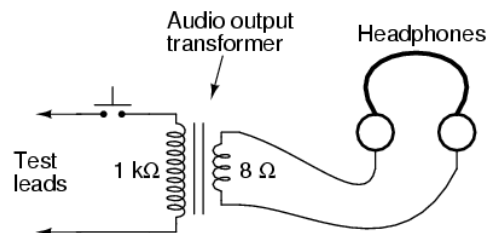
Calibration of Potentiometer (Cont'd)

- An extremely simple type of null detector, instead of the galvanometer, is a set of audio headphones, the speakers within acting as a kind of meter movement.
- When a DC voltage is initially applied to a speaker, the resulting current through it will move the speaker cone and produce an audible “click.”
- Another “click” sound will be heard when the DC source is disconnected.
- The technician would repeatedly press and release the pushbutton switch, listening for silence to indicate that the circuit was “balanced”.

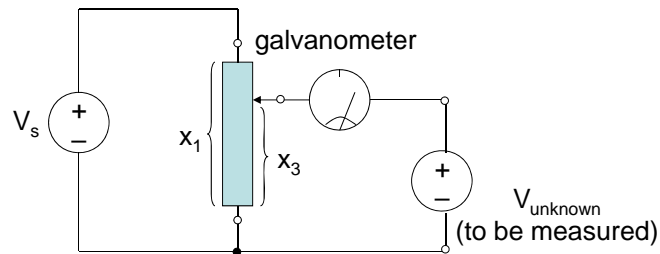


Calibration of Potentiometer (Cont'd)

- The headphone's sensitivity may be greatly increased by connecting it to a device called a transformer.
- A step-down transformer converts low-current pulses, created by closing and opening the pushbutton switch while connected to a small voltage source, into higher-current pulses to more efficiently drive the speaker cones inside the headphones ($N_p/N_s = I_s/I_p$).



Measuring of Potentiometer



- Slide the wiper (change x_3) until the galvanometer shows zero again
- $$V_{\text{unknown}} = \frac{x_3}{x_1} V_s$$
$$= \frac{x_3}{x_2} V_{\text{std_cell}}$$

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Rheostat

- Variable resistor with two terminals

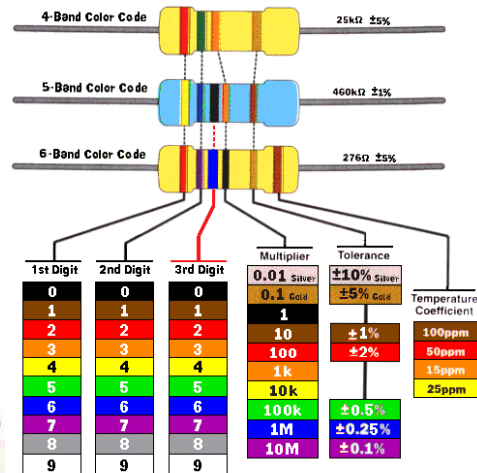
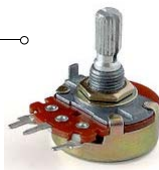
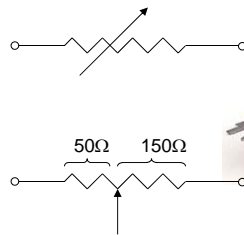


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Loading for a Potentiometer

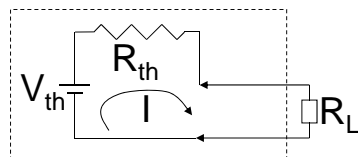
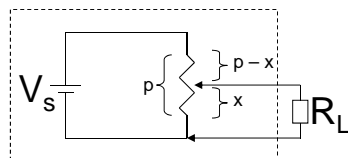
Resistor

- Fixed
- Adjustable Potentiometer

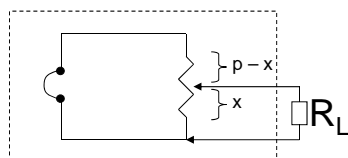


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Loading of a Potentiometer (Cont'd)



Thévenin's



Superposition

Voltage Divider

$$V_{th} = (x / p) V_s$$

$$\frac{1}{R_{th}} = \frac{1}{(x/p)R_p} + \frac{1}{((p-x)/p)R_p}$$

$$R_{th} = (x/p)R_p(1 - x/p)$$

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Loading of a Potentiometer (Cont'd)

$$\begin{aligned}
 V_{th} &= I (R_{th} + R_L) \\
 (x/p)V_s &= I [(x/p)(1 - x/p)R_p + R_L] \\
 I &= \frac{(x/p)V_s}{(x/p)(1 - x/p)R_p + R_L} \\
 V_L = IR_L &= \frac{(x/p)V_s R_L}{(x/p)(1 - x/p)R_p + R_L} \\
 &= \frac{(x/p)V_s}{(R_p/R_L)(x/p)(1 - x/p) + 1}
 \end{aligned}$$

It means the relationship between V_L and x is nonlinear!

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Loading of a Potentiometer (Cont'd)

Error,

$$\begin{aligned}
 V_{th} - V_L &= (x/p)V_s \left(1 - \frac{1}{(R_p/R_L)(x/p)(1 - x/p) + 1} \right) \\
 &= (x/p)V_s \left(\frac{(R_p/R_L)(x/p)(1 - x/p)}{(R_p/R_L)(x/p)(1 - x/p) + 1} \right)
 \end{aligned}$$

If $R_L \gg R_p$ then $R_p/R_L \approx 0$

Error $\approx (x/p)V_s(R_p/R_L)(x/p)(1 - x/p)$

$\approx V_s(R_p/R_L)[(x/p)^2 - (x/p)^3]$, $R_L \uparrow$ error \downarrow

% Error $\approx (R_p/R_L)[(x/p) - (x/p)^2] \times 100\%$

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Loading of a Potentiometer (Cont'd)

$$\text{Let } d(\text{Error})/dx = V_s(R_p/R_L)[2x/p^2 - 3x^2/p^3] = 0$$

$$\text{We get } 2x/p^2 = 3x^2/p^3$$

$$x/p = 2/3 \quad \text{for the maximum}$$

Therefore,

$$\text{the max error} = V_s(R_p/R_L)[(2/3)^2 - (2/3)^3]$$

$$\approx 0.148 V_s(R_p/R_L)$$

and the max % error $\approx 22.2 (R_p/R_L) \%$

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References

- <https://www.allaboutcircuits.com/textbook/direct-current/chpt-8/voltmeter-impact-measured-circuit/>

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