

Robot Arm (Provider) HTTP/JSON

System Description

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1 Overview

This document describes the Robot Arm Provider system.

The arm is both a provider and a consumer, but since it never works on its own it's labeled as a provider. The goal of the arm is to load or unload a piece of product to/from the tray. It will get data from the two Detectors.

2 Services

The Detector systems produces and consumes the following services:

2.1 Consumed Services

2.1.1 [Service Registry](#)

This service is consumed to make sure that the system becomes accessible to other systems.

2.1.2 [Authorization](#)

Used alongside ServiceRegistry to register the services into the cloud.

2.1.3 [Orchestration](#)

This service is used to get the information for the consumption of an application system.

2.1.4 [Get Detection](#)

Data from one the Detector, used to know if the load/unload process can be safely executed. The request and consumption of this is called by the process of the service that this system produces.

2.2 Produced Services

2.2.1 [Load/Unload](#)

This service is produced when requested. It has an input parameter that determines if it needs to load or unload. It will try to load/unload a piece to/from the tray, and send data about the success/failure of this operation.



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3 References

This document alongside any other document linked to this project are based on template documents, that are the description of "Intercloud Contract Negotiation and Automation" system, by Emanuel Palm [emanuel.palm@ltu.se]. I just adapted the template to my system.



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4 Revision History

4.1 Amendments

No.	Date	Version	Subject of Amendments	Author
1				

4.2 Quality Assurance

No.	Date	Version	Approved by
1			