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# FORMAL VERIFICATION OF JUST-IN-TIME COMPILATION

AURÈLE BARRIÈRE

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Billions of people use JITs every day.

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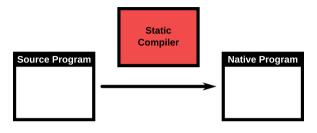
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## **Bugs in JITs**

These vulnerabilities rely on **bugs** in **Just-in-Time compilers** (JITs), and allow an attacker to execute malicious code.

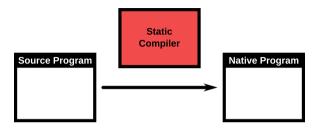


# Static compilation

Transforming a source program into an equivalent native program.

The resulting program can then be executed independently.

To trust this execution: trust both the source program and the compiler.

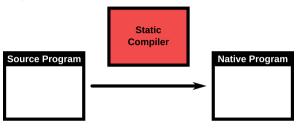


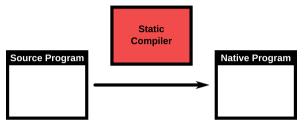
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## Despite testing, static compilers still contain bugs

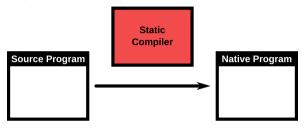
PLDI 2011: Hundreds of bugs found in GCC and LLVM [Yang et al. 2011].





## Program Semantics

We can formally define the behavior of a program, then prove the correctness of code transformations.

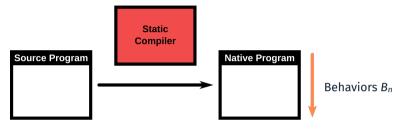


## **Program Semantics**

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#### Formally Verified Static Compilers

CompCert [Leroy 2006], CakeML [Kumar et al. 2014], VeLLVM [Zhao et al. 2012]. We can **prove** that a compiler **preserves** the behavior of the program it compiles.

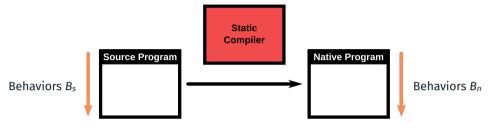


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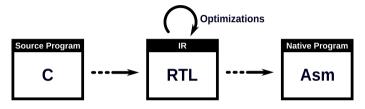
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#### Formally Verified Static Compilers

CompCert [Leroy 2006], CakeML [Kumar et al. 2014], VeLLVM [Zhao et al. 2012]. We can **prove** that a compiler **preserves** the behavior of the program it compiles.  $B_n \subseteq B_s$ 

From C to assembly (x86, ARM, PowerPC, RiscV). 9 Intermediate Representations (IRs).

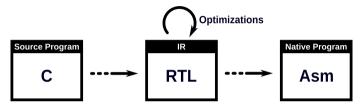


**Software-proof codesign**: developed in Coq, verified in Coq.

**Executable**: can be extracted as an OCaml program.

**Modular proof:** each transformation proved independently.

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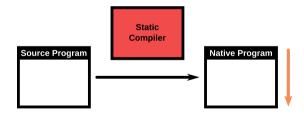
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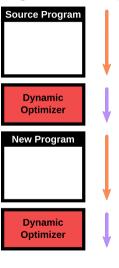
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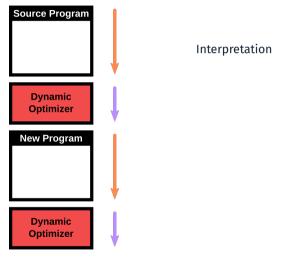
## Formal Verification brings substantial guarantees

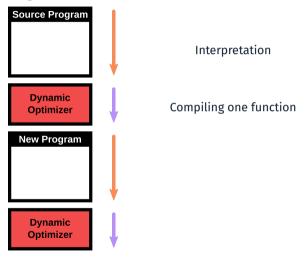
PLDI 2011: No bugs found in the formally verified part of CompCert [Yang et al. 2011].

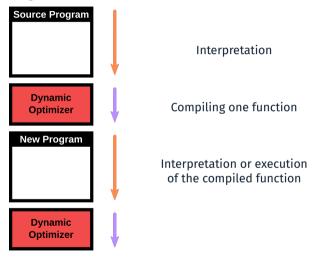
# WHAT ABOUT JUST-IN-TIME COMPILATION?

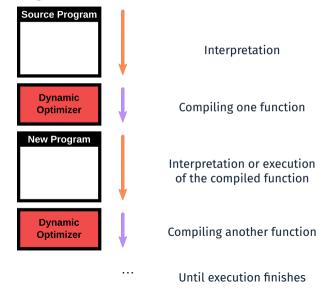






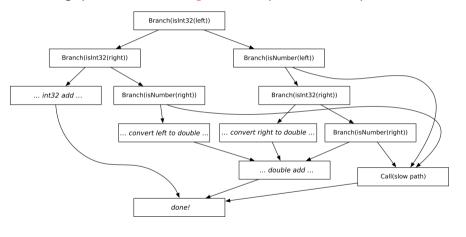




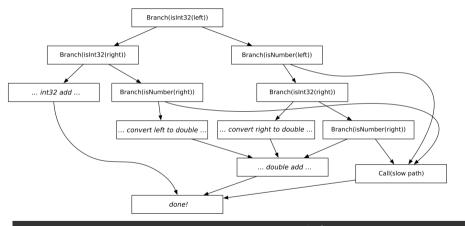


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Difficult to compile. Restricts optimizations. Executing operation left + right, an example from JavaScriptCore [WebKit 2020].



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## Type Speculation

If we can speculate on the types of left and right, the graph is reduced to a single node.

Execution Timeline

Interpretation of f

Execution Stack

Interpreter: f

Program

Function f():
 while (...):
 g()

Function g(): g1 g2

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#### Execution Timeline

Interpretation of f

Interpretation of g

Optimization of g

#### Execution Stack

Interpreter: f

Optimizing Compiler

#### **Program**

```
Function f():
  while (...):
   g()
```

```
Function g():
g1
g2
```

```
Function g_x86():
g1
Speculation (x is int32)
g2'
```

# Execution Timeline Interpretation of f Interpretation of g Optimization of g

Call to g x86

## Execution Stack

Interpreter: f

Native: g\_x86

#### **Program**

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Execution Timeline

Interpretation of f

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Optimization of g

Call to g x86

Deoptimization to g

Execution Stack

Interpreter: f

Native: g\_x86

Speculation fails

**Program** 

Function f(): while(...): g()

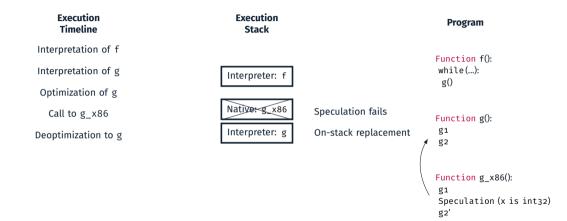
Function g():

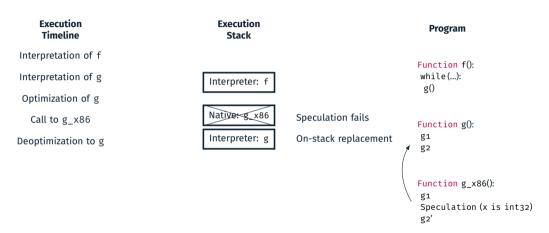
g1

g2

Function g x86(): g1

Speculation (x is int32) g2'





Deoptimization requires the JIT to synthesize interpreter stackframes in the middle of a function.

JIT-specific techniques like speculation, on-stack replacement are scarcely formalized.

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# Related Work in Formalizing JITs

- [Myreen 2010]: Verified non-optimizing x86 JIT.
- [Guo et al. 2011]: Soundness of trace optimizations in JITs.
- [Brown et al. 2020]: DSL to write verified range analyses in JITs.
- [Flückiger et al. 2018]: **Sourir**, an IR with speculation, with correctness proofs of speculative optimizations.

OUR GOAL 11 / 36

# In this thesis, we investigate the feasability of developing formally verified JITs.

**Dynamic Optimizations**: JITs interleave optimizations with the program execution.

Speculative Optimizations: JITs insert and manipulate speculations in their programs.

**Impure Components**: Some JITs components are difficult to write in Coq (e.g. executing native code).

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Our approach: integrate the CompCert backend and its proof to generate native code. Semantics for interleaving native code execution with other JIT components.

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In this presentation:

- A) Our JIT Design
- B) Dynamic Optimizations
- C) Speculative Optimizations

# DESIGNING A FORMALLY VERIFIED JIT IN COQ

#### CompCert Theorem

If we compile a program whose behaviors are free of errors, then any behavior of the compiled program is a behavior of the source program.

```
Theorem transf_c_program_is_refinement:

∀p tp, transf_c_program p = OK tp → (* compilation of p produced tp *)

(∀ beh,program_behaves (source_sem p) beh → not_wrong beh) → (* p has no wrong behaviors*)

(∀ beh,program_behaves (asm_sem tp) beh → program_behaves (source_sem p) beh).

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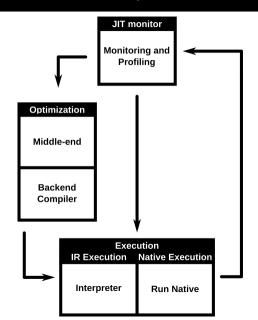
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#### **IIT Theorem**

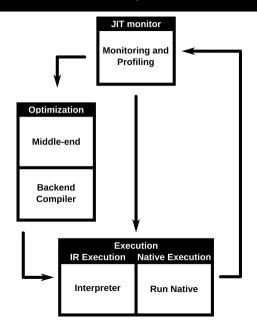
If the semantics (source\_sem) of the program is free of errors, then any behavior of the JIT on that program (jit\_sem) is a behavior of the program.

```
Theorem jit_behavior_refinement: \forall p, (\forall beh,program_behaves (source_sem p) beh \rightarrow not_wrong beh) \rightarrow (* p has no wrong behaviors*) (\forall beh,program_behaves (jit_sem p) beh \rightarrow program_behaves (source_sem p) beh). (* every behavior of the JIT executing p is a behavior of p *)
```



### JIT loop

The **monitor** chooses execution or optimization. **Profiling**: inspects execution and suggests speculations and optimizations.

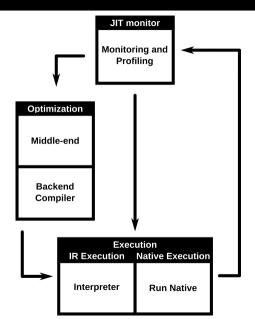


# Middle-end Optimizer

From the IR to the IR. Inserts speculation.

# **Backend Compiler**

Generates native code. Use the CompCert backend from RTL to x86.



# Interpreter

Interpret the IR code.

# Native Code Execution

Run the generated code.

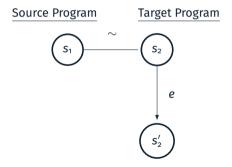
Returns to the monitor on function calls, function returns or deoptimizations.

# CORRECTNESS OF A JIT WITH DYNAMIC OPTIMIZATIONS

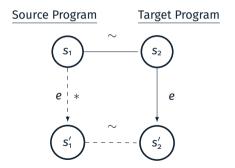
- lacktriangle design an invariant  $\sim$ , a relation between semantic states.
- show that each semantic step of the target program is matched with steps of the source program preserving the invariant and the observable events *e*.



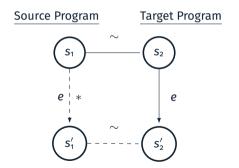
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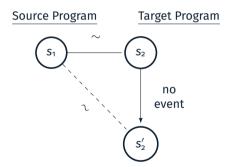


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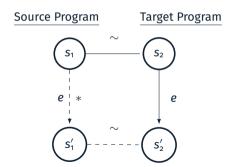


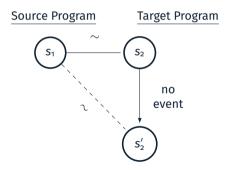
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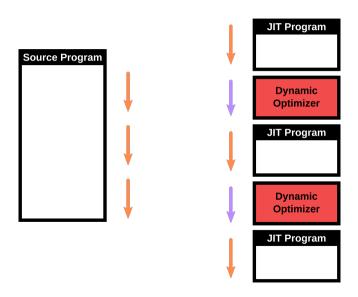


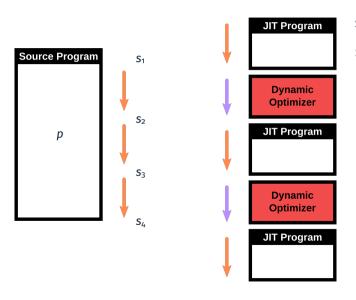
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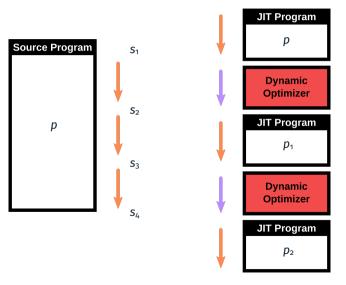


Simulations are composable.





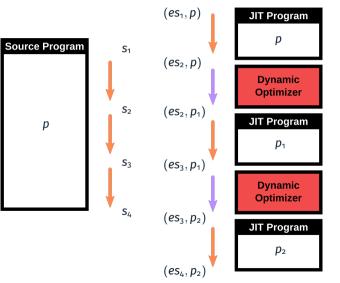
Fixed program p. Semantic states of p:  $s_1, s_2, s_3, s_4$ .



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#### **IIT Execution:**

Both the program and the execution state (e.g. interpreter state) are evolving.

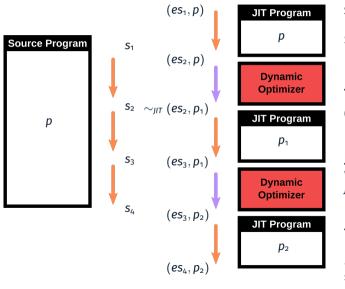


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Both the program and the execution state (e.g. interpreter state) are evolving.

**JIT Semantic states:** (es, jp) where es is an execution state, jp is the current JIT program.

#### To Prove a Simulation:

Find and preserve an invariant relation  $\sim_{JIT}$  between source states s and JIT states (es, jp).

At any point in the execution,

- the current execution state corresponds to a source semantic state,
- the current JIT program is equivalent to the source program p.

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# Defining the invariant

**Nested Simulations:** Our JIT simulation invariant contains another simulation (called *internal*).

s  $\sim_{\mathit{JIT}}$  (es,jp) when

- $\blacksquare$  there exists a simulation between p and jp, using an invariant  $\sim_{in}$
- lacksquare s  $\sim_{in}$  es.

The internal simulation changes as the JIT performs optimizations.

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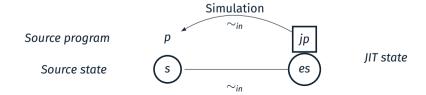
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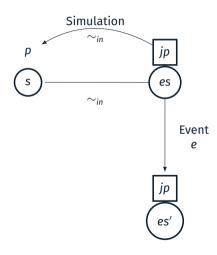
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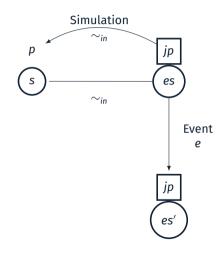
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  - lacktriangle there exists a simulation between p and p, using an invariant  $\sim_h$
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The internal simulation changes as the JIT performs optimizations.





We need to prove that there exists matching steps in the source semantics preserving the invariant and the observed behavior *e*.



Simulation  $\sim_{in}$ es Event **Event** е e ip es'

We use the internal simulation to exhibit source steps.

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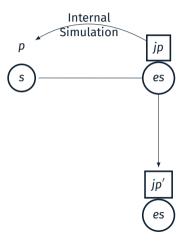
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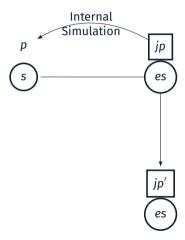
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The JIT program jp did not change, and is still simulated with p.

The JIT did an **optimization** step and updated its program *jp*.

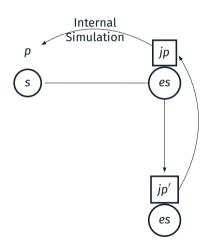


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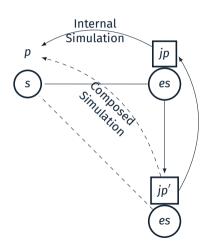


We prove the dynamic optimizer correct with a backward simulation.

Theorem optimizer\_correct:  $\forall$  jp jp', optimizer jp = jp'  $\rightarrow$  backward\_simulation jp jp'.

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We prove the dynamic optimizer correct with a backward simulation.

Theorem optimizer\_correct:  $\forall$  jp jp', optimizer jp = jp'  $\rightarrow$  backward\_simulation jp jp'.

We compose this new simulation with the existing internal one.

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# TO PROVE CORRECT A JIT WITH DYNAMIC OPTIMIZATIONS, IT SUFFICES TO PROVE ITS OPTIMIZER CORRECT WITH A BACKWARD SIMULATION.

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LIKE A STATIC COMPILER.

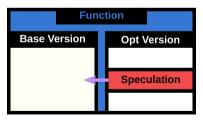
### FORMALLY VERIFIED SPECULATION

Speculative instructions should have precisely defined semantics.

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#### CoreIR, an Intermediate Representation for Speculation

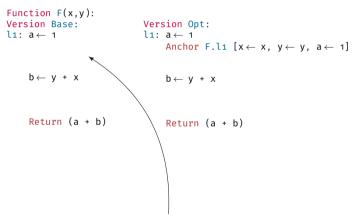
Two speculative instructions to represent two sides of speculation. Inspired by Sourir [Flückiger et al. 2018] and CompCert's RTL. Each function has a base version and an optional optimized one.



```
Function F(x,y): Version Base: l1: a \leftarrow 1 b \leftarrow y + x Return (a + b)
```

```
Function F(x,y):
Version Base:
l1: a \leftarrow 1
    Return (a + b)
```

Profiler: we might want to speculate here later



 Create an Opt version, with synchronization points Anchor

**Profiler**: we might want to speculate here later

```
Function F(x,y):
Version Base:
l1: a \leftarrow 1

b \leftarrow y + x

Return (a + b)

Version Opt:
l1: a \leftarrow 1

b \leftarrow y + x

b \leftarrow y + x

Return (a + b)
```

Create an Opt version, with synchronization points Anchor

**Profiler:** speculate that x is 9

```
Function F(x,y):

Version Base:

l1: a \leftarrow 1

Anchor F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

Assume (x = 9) F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

b \leftarrow y + x

Return (a + b)

Return (a + b)
```

- Create an Opt version, with synchronization points Anchor
- Insert speculation Assume

**Profiler**: speculate that x is 9

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b \leftarrow y + x

b \leftarrow y + 9

Return (a + b)

Return (1 + b)
```

- Create an Opt version, with synchronization points Anchor
- Insert speculation Assume
- Constant propagation

```
Function F(x,y):

Version Base:
l1: a \leftarrow 1

b \leftarrow y + x

Version Opt:
l1: a \leftarrow 1

Anchor F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

Assume (x=9) F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

Assume (y=7) F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

b \leftarrow y + 9

Return (a + b)

Return (1 + b)
```

- Create an Opt version, with synchronization points Anchor
- Insert speculation Assume
- Constant propagation
- Insert speculation

Profiler: speculate that y is 7

```
Function F(x,y):

Version Base:

l1: a \leftarrow 1

b \leftarrow y + x

Version Opt:

l1: a \leftarrow 1

Anchor F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

Assume (x=9) F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

Assume (y=7) F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

b \leftarrow 16

Return (a + b)

Return (17)
```

- Create an Opt version, with synchronization points Anchor
- Insert speculation
  Assume
- Constant propagation
- Insert speculation
- Constant propagation

```
Function F(x,y):

Version Base:

l1: a \leftarrow 1

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Assume (x=9) F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

Assume (y=7) F.l1 [x \leftarrow x, y \leftarrow y, a \leftarrow 1]

Return (a + b)

Return (17)
```

- Create an Opt version, with synchronization points Anchor
- Insert speculation
  Assume
- Constant propagation
- Insert speculation
- Constant propagation
- Dead code elimination

Expresses a synchronization between the original and optimized versions.

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Anchor F.1 [ $x \leftarrow y+1$ ] means that you can deoptimize to function F, label 1, putting y+1 in register x.

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Anchor F.l  $[x \leftarrow y+1]$  means that you **can** deoptimize to function F, label l, putting y+1 in register x.

#### The Assume instruction : Making Speculation Explicit

Insert speculation at any time next to an Anchor using an Assume.

Expresses a synchronization between the original and optimized versions.

Anchor F.l  $[x \leftarrow y+1]$  means that you **can** deoptimize to function F, label l, putting y+1 in register x.

#### The Assume instruction : Making Speculation Explicit

Insert speculation at any time next to an Anchor using an Assume.

Assume (y=3) F.l [x  $\leftarrow$  y+1] deoptimizes if y is not 3, skips to the next instruction otherwise.

Expresses a synchronization between the original and optimized versions.

Anchor F.1 [ $x \leftarrow y+1$ ] means that you can deoptimize to function F, label 1, putting y+1 in register x.

#### The Assume instruction: Making Speculation Explicit

Insert speculation at any time next to an Anchor using an Assume.

Assume (y=3) F.1 [x  $\leftarrow$  y+1] deoptimizes if y is not 3, skips to the next instruction otherwise.

#### **Non-deterministic Semantics**

The semantics of an Anchor are non-deterministic: either deoptimize to the original version or continue to the next instruction in the optimized version.

Assume is deterministic: deoptimizes when the speculation fails.

To prove each transformation, prove a backward simulation.

```
Theorem assume_insertion_correct: \forall p f guard lbl newp, insert_assume f guard lbl p = OK newp \rightarrow backward_simulation p newp.
```

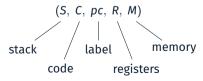
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```
Theorem assume_insertion_correct:

∀ p f guard lbl newp,
insert_assume f guard lbl p = OK newp →
backward_simulation p newp.
```

First, design an **invariant** relating semantic states of CorelR.

#### Semantic states of CoreIR:



```
Function G():
   Return F(4)

Function F(x):
Version Base:
l1:Return (x+16)

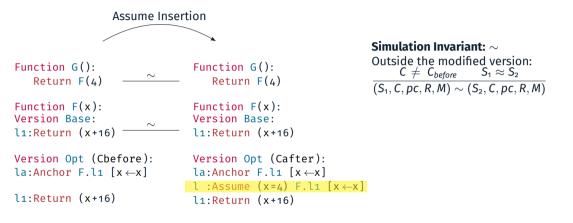
Version Opt (Cbefore):
la:Anchor F.l1 [x ←x]

l1:Return (x+16)
```

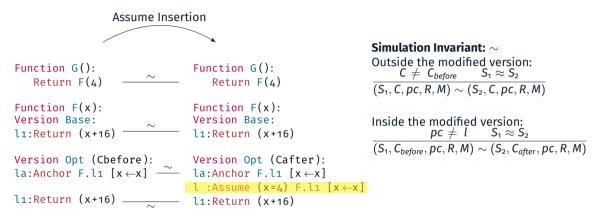
```
Assume Insertion
```

```
Function G():
                                Function G():
   Return F(4)
                                   Return F(4)
Function F(x):
                                Function F(x):
Version Base:
                                Version Base:
l1:Return (x+16)
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Version Opt (Cbefore):
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la:Anchor F.l1 [x \leftarrow x]
                                la:Anchor F.l1 [x \leftarrow x]
                                l :Assume (x=4) F.l1 [x \leftarrow x]
l1:Return (x+16)
                                l_1:Return (x+16)
```

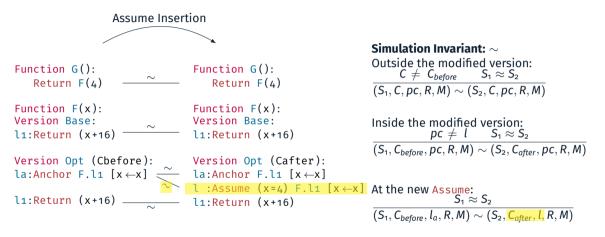
```
Assume Insertion
                                                                 Simulation Invariant: \sim
Function G():
                                Function G():
   Return F(4)
                                    Return F(4)
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l1:Return (x+16)
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```



 $S_1 \approx S_2$  when stackframes of  $C_{before}$  have been replaced with stackframes of  $C_{after}$ .



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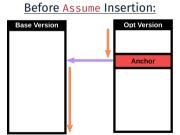
At the Assume, we reason by case analysis on the speculation:

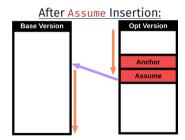
■ if it holds, we match this step to no deoptimization of the Anchor



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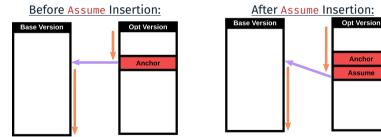
- if it holds, we match this step to no deoptimization of the Anchor
- if it fails, we match this step to deoptimization of the Anchor.





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- if it holds, we match this step to no deoptimization of the Anchor
- if it fails, we match this step to deoptimization of the Anchor.



Using the non-determinism of the Anchor, it is correct to insert a new Assume.

### NON-DETERMINISTIC SEMANTICS ARE ADEQUATE TO REPRESENT THE POSSIBILITY OF A DEOPTIMIZATION.

#### Backward Simulations: Handling Speculation

- Inserting Anchor instructions.
- Inserting Assume instructions using Anchors.
- Lowering : Removes Anchor instructions.

#### A Backward Simulation for Inlining

■ Inlining: When deoptimizing from an inlined function, we need to synthesize an additional stackframe to restore the environment.

#### **Proving Non-speculative Optimizations**

■ Constant Propagation : reusing the forward to backward methodology of CompCert.

#### Middle-end Correctness

Correct for any speculation and optimizations done by the middle-end.

```
Theorem middle_end_correct: \forall jp jp' optim_list, middle_end jp optim_list = jp' \rightarrow backward_simulation jp jp'.
```

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Theorem middle\_end\_correct:  $\forall$  jp jp' optim\_list, middle\_end jp optim\_list = jp'  $\rightarrow$  backward\_simulation jp jp'.

#### **Backend Correctness**

- Transform a CoreIR function into RTL programs, using custom calling conventions to interact with the JIT.
- Then, use the CompCert backend to generate x86 code.

```
Theorem backend_correct:
```

```
∀ jp' jp",
```

backend  $jp' = jp'' \rightarrow (* integrates CompCert backend *)$  backward simulation jp' jp''.

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```
Theorem backend_correct:

∀ jp' jp",

backend jp' = jp" → (* integrates CompCert backend *)
```

backward simulation jp' jp".

Using **nested** simulations:

```
Theorem jit_simulation:
    ∀ p, backward_simulation p (jit_sem p).
```

Which implies the JIT behavior preservation theorem.

A small set of *impure* primitives used in a JIT:

- store and load from the heap.
- push and pop from the stack.
- install, load and execute native code.

For primitives, write both C implementations and Coq specifications.

An encoding for programs using both Coq functions and Impure primitives:

```
Definition optimizer(f:function): free unit :=
   do f2 ← ret (middle_end f); (* written in Coq *)
   do f_x86 ← ret (backend f2); (* written in Coq, reusing CompCert *)
   Prim_Install_Code f_x86. (* impure primitive *)
```

CONTRIBUTIONS 34 / 36

## Solving the first two JIT challenges

POPL21: Formally Verified Speculation and Deoptimization in a JIT compiler. [Barrière et al. 2021]

- Dynamic Optimizations
- Speculations.

## Solving the remaining two JIT challenges

**POPL23:** Formally Verified Native Code Generation in an Effectful JIT or: Turning the CompCert Backend into a Formally Verified JIT Compiler. [Barrière et al. 2023]

- Impure Components
- Native code generation (reusing CompCert) and execution.

CONTRIBUTIONS 34 / 36

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- Impure Components
- Native code generation (reusing CompCert) and execution.

**Executable Coq develoment:** execute our JIT on CoreIR programs. Speedups when speculating or generating native code. https://github.com/Aurele-Barriere/JIThm CONCLUSION 35 / 36

# DESIGNED A GENERIC JIT ARCHITECTURE.

IDENTIFIED JIT-SPECIFIC VERIFICATION CHALLENGES AND PRESENTED COMPOSABLE CORRECTNESS ARGUMENTS.

A METHODOLOGY TO DEVELOP FORMALLY VERIFIED JITS, WITH A MECHANIZED VERIFIED AND EXECUTABLE COQ PROTOTYPE.

PERSPECTIVES 36 / 36

# Addressing our limitations

- Impure primitive verification: check the C implementations against their Coq specifications.
- Generating efficient code: the interfacing between native code and the JIT can be improved.

PERSPECTIVES 36 / 30

# Addressing our limitations

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#### A new playground to formalize/verify JIT features

- **Recompilation**: Recompiling from scratch a function that deoptimizes too often.
- **Contextual Dispatch**: Different versions of a function specialized for different call contexts. [Flückiger et al. 2020].
- On-Stack-Replacement as en entry: Jumping into native code from the interpreter.

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#### Towards Verified JITs for Realistic Languages

**WebAssembly**, a language for high-performance applications on web pages. On-going work on formally verified Coq interpreter and compiler for WebAssembly [Watt et al. 2021]. We could then reuse our techniques to develop a formally verified WebAssembly JIT.

#### RECAP - JIT-SPECIFIC VERIFICATION CHALLENGES

**Dynamic Optimizations**: JITs interleave optimizations with the program execution. Our approach: adapt the simulation proof methodology of CompCert.

**Speculative Optimizations**: JITs insert and manipulate speculations in their programs. Our approach: define semantics for speculative instructions, verify code transformations manipulating them.

**Impure Components**: Some JITs components are difficult to write in Coq (e.g. executing native code). Our approach: free monadic encoding of the JIT with a pure specification of some impure primitives.

**Static Compiler Reuse**: Verified JITs should reuse formally verified compilers.

Our approach: integrate the CompCert backend and its proof to generate native code.

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# **COREIR SYNTAX**

#### Operands:

$$op ::= r$$
 Register  $\mid v$  Value

#### Expressions:

$$\begin{array}{llll} e & \text{ $::=$ op + op \mid op - op \mid op * op } & \text{Arithmetic} \\ & & & |op < op \mid op = op & & \text{Relational} \\ & & & |op & & & \text{Register or value} \end{array}$$

#### Instructions:

#### Metadata:

$vm ::= (r \leftarrow e)^*$	Varmap
syn ::= f.lr vm	Stack frame
$deop ::= f.l \ vm \ syn^*$	Deopt metadata

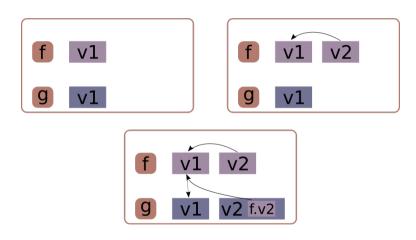
#### Programs:

$$V ::= l \mapsto i$$
 Code  
 $F ::= \{r^*, l, V, option V\}$  Function  
 $P ::= f \mapsto F$  Program

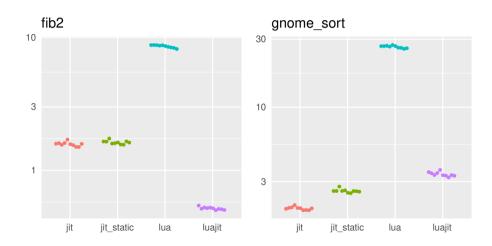
### **COREIR SPECULATIVE INSTRUCTIONS SEMANTICS**

$$V[l_{pc}] = \text{Anchor } f.l \ vm \ st^* \ l_{next}$$
 
$$\text{deopt\_regmap } vm \ R = R' \quad \text{synthesize\_frame } R \ st^* = S'$$
 
$$S \ V \ l_{pc} \ R \ M \rightarrow S \ V \ l_{next} \ R \ M$$
 
$$V[l_{pc}] = \text{Anchor } f.l \ vm \ st^* \ l_{next}$$
 
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$$S \ V \ l_{pc} \ R \ M \rightarrow (S'+S) \ (\text{base\_version}_P \ f) \ l \ R' \ M$$
 
$$Assume Pass = V[l_{pc}] = \text{Assume } e^* \ f.l \ vm \ st^* \ l_{next} \quad (e^*, R) \ \downarrow \ true$$
 
$$S \ V \ l_{pc} \ R \ M \rightarrow S \ V \ l_{next} \ R \ M$$
 
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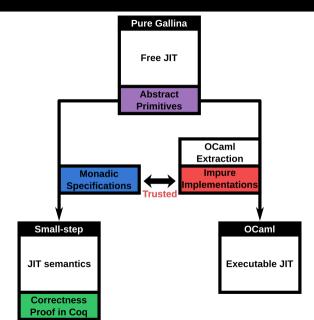
# INLINING SPECULATION - EXTRA STACKFRAME ON DEOPTIMIZATION



# **COREIR EXPERIMENTS**



# FREE MONADIC ENCODING



### STATE AND ERROR MONAD

A **pure** encoding of functions modifying and accessing a global state. Either the function fails. or it succeeds and returns the next global state. Found in CompCert.

```
Inductive sres (state:Type) (A:Type): Type :=
| SError:errmsg → sres state A
SOK: A \rightarrow state \rightarrow sres state A.
Definition state mon{state:Type} (A:Type): Type := state \rightarrow sres state A.
```

Monadic constructors:

```
Definition state ret{state:Type}{A:Type}(x:A): state mon A:=
fun (s:state) \Rightarrow SOK x s.
```

```
Definition state bind {state:Type} {A B:Type} (f: state mon A) (g:A → state mon B): state mon B :=
  fun(s:state) \Rightarrow
   match (f s) with
    | SError msg ⇒ SError msg
   | SOK a s' \Rightarrow g a s'
   end.
```

### Executable Impure JIT

This is fine to specify the primitives, but the executable JIT should execute **impure** code.

#### FREE MONAD DEFINITIONS - AN EXAMPLE

In that example, we want to write programs that can access a single global variable of type nat.

```
A list of primitives our programs can use:
```

```
Inductive primitive: Type → Type :=
| Get: primitive nat
| Put(x:nat): primitive unit.
```

#### We can then define the free monad:

```
Inductive free (T:Type): Type :=
  | pure (x: T): free T
  | impure {R}
     (prim: primitive R) (next: R → free T).
```

# Binding free monadic computations:

```
Fixpoint free_bind {X Y} (f: free X) (g: X →
free Y): free Y :=
  match f with
  | pure x ⇒ g x
  | impure R prim next ⇒
   impure prim (fun x ⇒ free_bind (next x) g)
  end.
```

We can now encode incomplete programs. Next, let's see two ways to complete them.

#### GIVING SEMANTICS TO OUR FREE MONAD - AN EXAMPLE

Given primitive implementations, we want to turn a free monadic function into an executable state monadic one. A **monadic specification** consists in one state monad for each primitive:

We can now define **semantics** for our free monadic encoding, replacing each primitive with its specification:

```
Fixpoint free_sem {A:Type} (f:free A) (i:monad_spec): state_mon A :=
    match f with
    | pure a ⇒ state_ret a
    | impure R prim cont ⇒
        state_bind (prim_spec prim i) (fun r:R ⇒ free_sem (cont r) i)
    end.
```

#### EXECUTING THE FREE MONAD - AN EXAMPLE

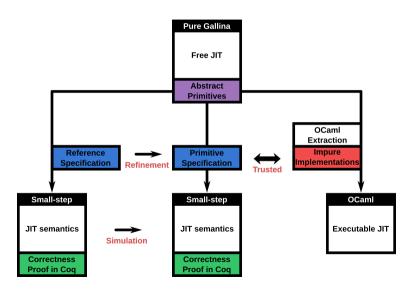
Finally, we extract the free monadic JIT to OCaml.

We can write a new way to execute a free monadic function, calling impure p

We can write a new way to **execute** a free monadic function, calling impure primitives when needed.

```
(* impure primitive implementations, using a global reference *)
let prim impl (p:'x primitive) : 'x =
match p with
  | Get -> !global
  | Put (n) -> global := n
(* from OCaml, we can also call C implementations *)
(* executing free monads *)
let rec exec (f:'A free) : 'A =
 match f with
  | Cog pure (a) -> a
  | Cog ferror (e) -> print error e; failwith "JIT crashed"
  | Coa impure (prim. cont) ->
    let x = prim_impl prim in
    exec (cont x)
```

# FREE MONADIC REFINEMENT



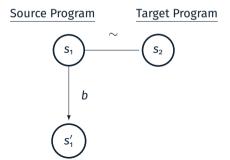
### Forward Simulation in CompCert:

- lacktriangle Design an invariant  $\sim$ , a relation between semantic states.
- Show that each semantic step of the source program is matched with steps of the target program preserving the invariant.

Source Program		Target Program
(S <sub>1</sub> )—	~	$ \left( S_{2}\right)$

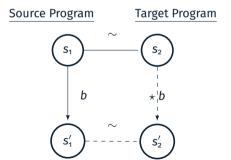
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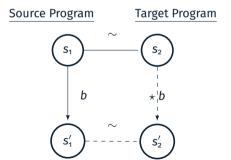
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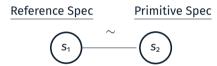
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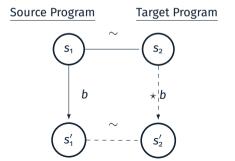
#### **Refinement:**

- Design an invariant  $\sim$ , a relation between monadic states.
- Show that each primitive execution of the first monadic specification is matched with a primitive execution of the second monadic specification preserving the invariant.



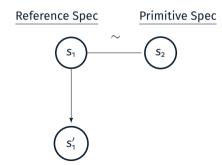
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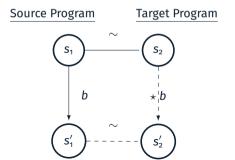
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- Design an invariant  $\sim$ , a relation between monadic states.
- Show that each primitive execution of the first monadic specification is matched with a primitive execution of the second monadic specification preserving the invariant.



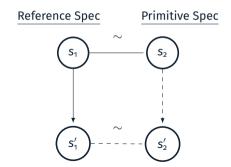
#### Forward Simulation in CompCert:

- lacktriangle Design an invariant  $\sim$ , a relation between semantic states.
- Show that each semantic step of the source program is matched with steps of the target program preserving the invariant.

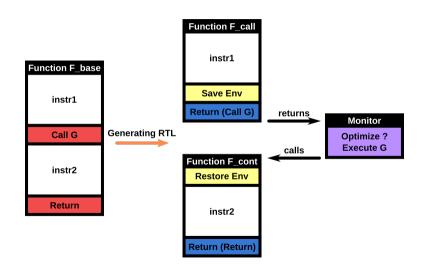


#### **Refinement:**

- Design an invariant  $\sim$ , a relation between monadic states.
- Show that each primitive execution of the first monadic specification is matched with a primitive execution of the second monadic specification preserving the invariant.



# **CUSTOM CALLING CONVENTIONS**



# GENERATING NATICE CODE USING PRIMITIVES - AN EXAMPLE

CoreIR Function	RTL Functions	Assembler Continuation Function
Function Fun1 (reg1): reg2 ← 4 + reg1 reg3 ← Call Fun7 (reg2) reg3 ← reg1 + reg3 Return reg3	\$1() {     x8 = "Pop"()     x9 = x8 + 4 (int)     // Save environment     x1 = "Push" (x8)     x1 = "Push" (Fun1, \$2)     x1 = "Push" (Fun7)     return RETCALL }  \$2() {     x10 = "Pop"()     // Restore environment     x8 = "Pop"()     x10 = x8 + x10     x1 = "Push" (x10)     return RETRET }	<pre># File generated by CompCert 3.8 \$2: leaq</pre>