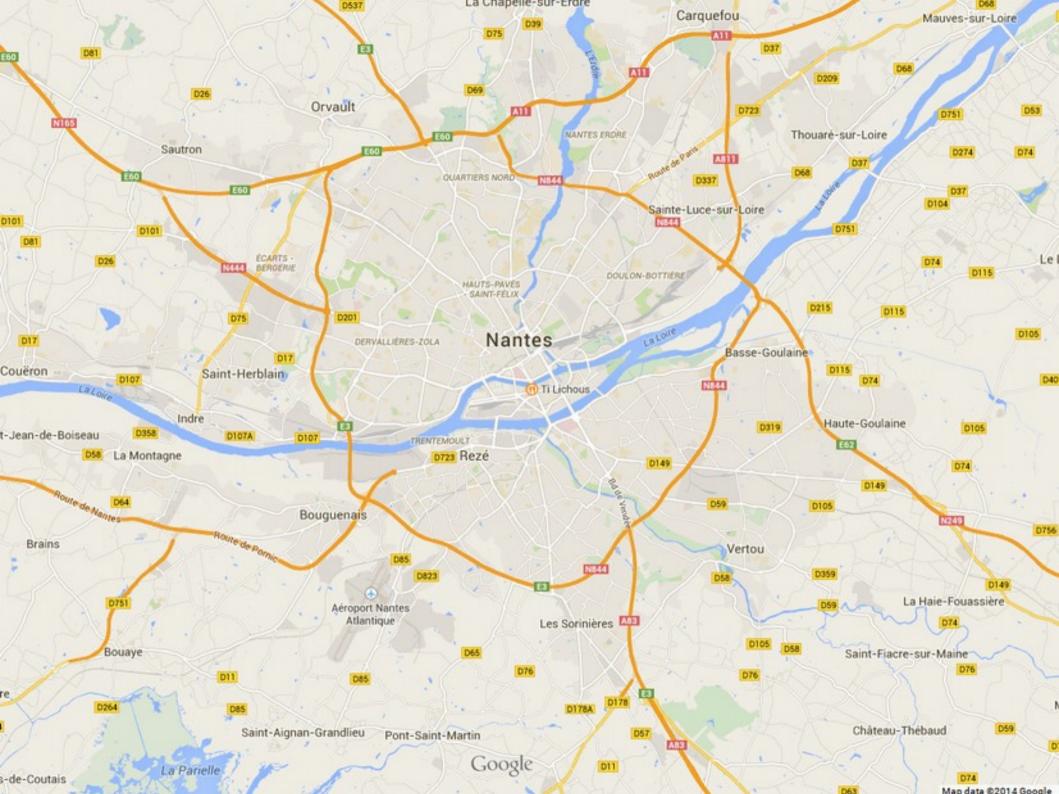
Scalable, Generic, and Adaptive Systems for Focused Crawling

Georges Gouriten* - georges@netiru.fr Silviu Maniu° Pierre Senellart*°

- * Télécom Paristech Institut Mines-Télécom LTCI CNRS
- Hong Kong University



densité







460 km 70 000 000 français

opportunité

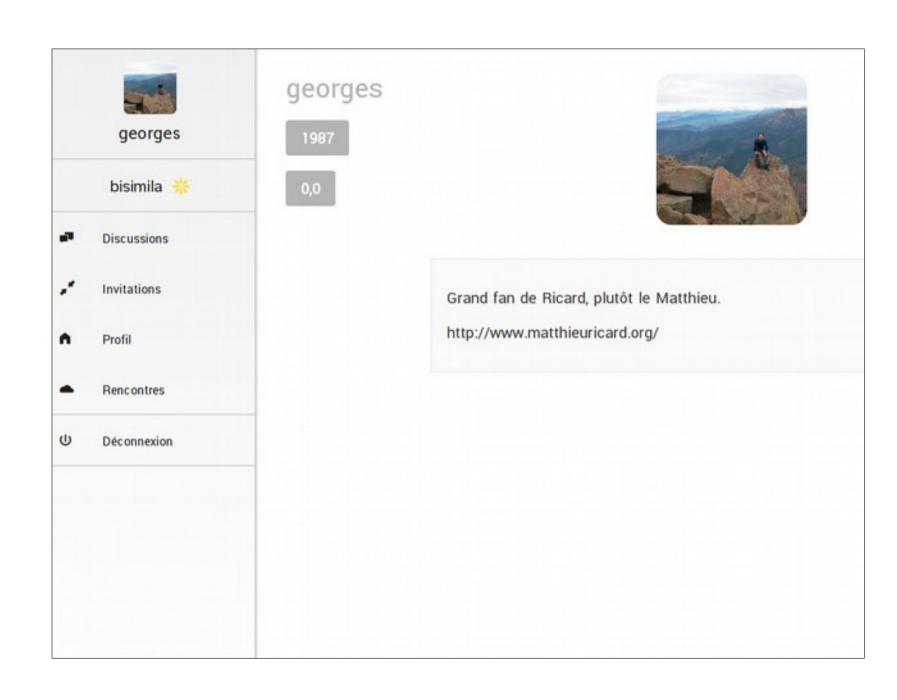




choix



La rencontre ouverte à tous



pour tous

sans pub

simple et sûr



bisimila.com

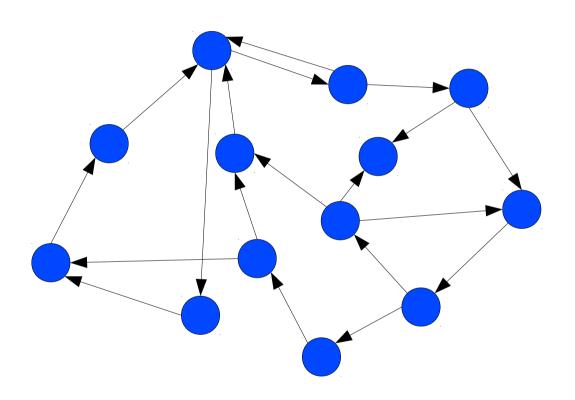
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What is focused crawling?

A directed graph



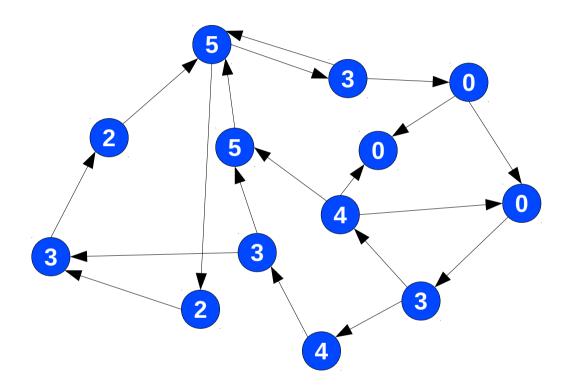
Web

Social network

P2P

etc.

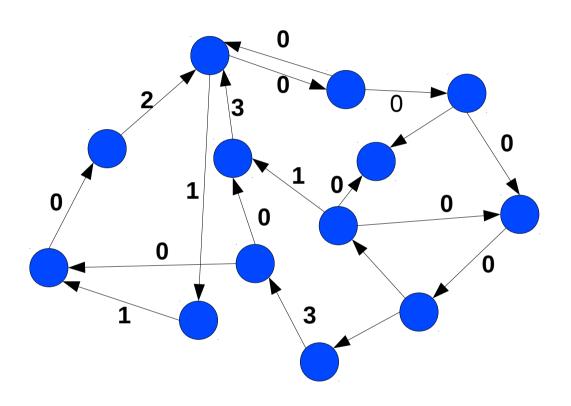
Weighted



Let *u* be a node,

 $\beta(u)$ = count of the word *Bhutan* in all the tweets of u

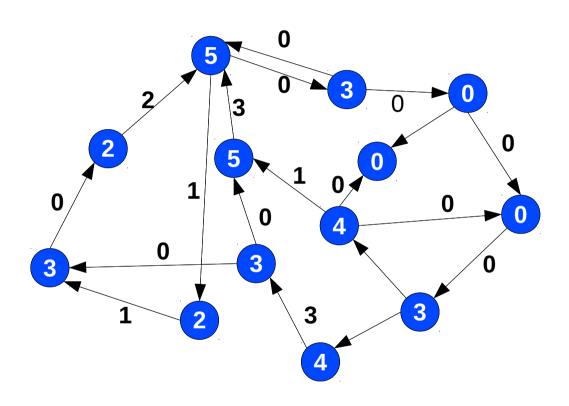
Even more weighted



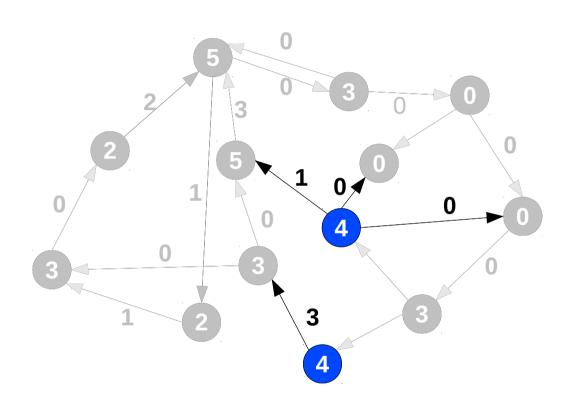
Let (u, v) be an edge,

 $\alpha(u)$ = count of the word *Bhutan* in all the tweets of u mentioning v

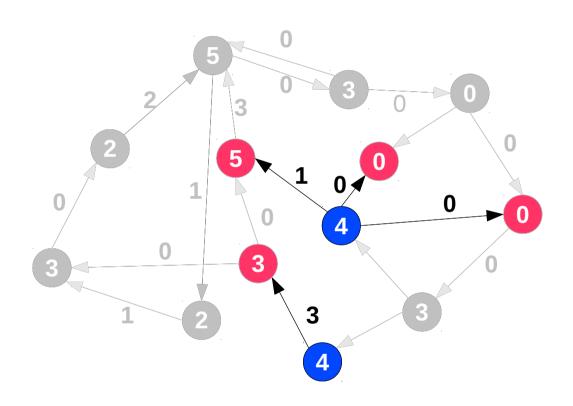
The total graph



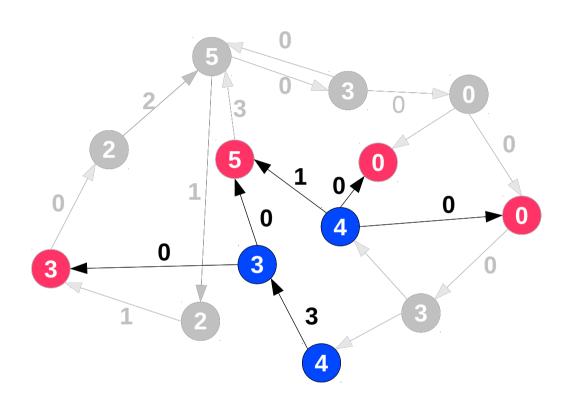
A seed list



The frontier



Crawling one node



A crawl sequence

Let V_0 be the seed list, a set of nodes, a *crawl sequence*, starting from V_0 , is

{ v_i , v_i in frontier($V_0 U \{v_0, v_1, ..., v_{i-1}\}$) }

Goal of a focused crawler

Produce crawl sequences with global scores (sum) as high as possible

A high-level algorithm

Estimate scores at the frontier

Pick a node from the frontier

Crawl the node

Supposing a perfect estimator

Finding an optimal crawl sequence offline: NP-hard

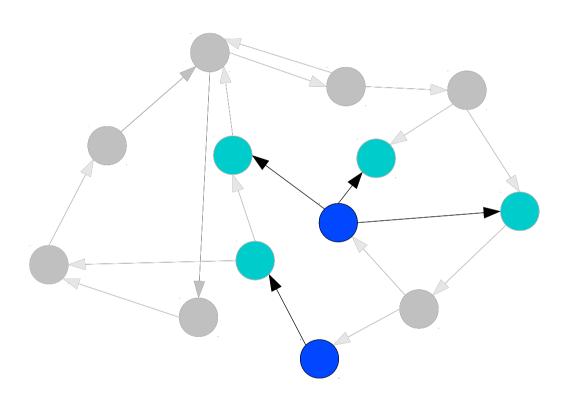
Greedy wins for a crawled graph > 1000 nodes

Refresh rate of 1 is better

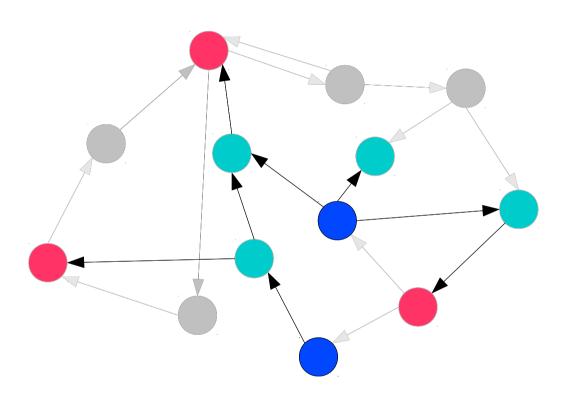
Estimation in practice

Different kinds of estimators

bfs



bfs



bfs

ESTIMATOR 1 (bfs). $\widetilde{\beta}(v) = \frac{1}{l(v)+1}$, where l(v) is the distance of v to V_0 .

nr

navigational rank

score propagation from the ancestors of a node

then to the children of a node

nr

$$NR_1(v)^{t+1} = d \times w(v) + (1-d) \times avg_{(v,u) \in E'} \frac{NR_1(u)^t}{d_i(u)}$$

$$NR_2(v)^{t+1} = d \times NR_1(v) + (1-d) \times avg_{(u,v) \in E'} \frac{NR_2(u)^t}{d_0(u)}.$$

ESTIMATOR 2 (nr).
$$\widetilde{\beta}(v) = NR_2(v)$$
.

opic

online page importance computation

~ online pageRank computation

opic

- 1. the node v with the highest cash is selected, and its history is updated with the current cash value H(v) = H(v) + C(v),
- 2. for each outgoing node u of v, the cash value is updated $C(u) = C(u) + \frac{C(v)}{d_{o(v)}}$,
- 3. the cash value of v is reset and the global counter incremented, by G = G + C(v) and C(v) = 0.

2.
$$> C(u) = C(u) + \frac{C(v)}{\sum_{(v,w)\in E'} \alpha(v,w) \times C(w)} \times \alpha(v,u) \times C(u)$$

ESTIMATOR 3 (opic).
$$\widetilde{\beta}(v) = \frac{H(v) + C(v)}{G+1}$$
.

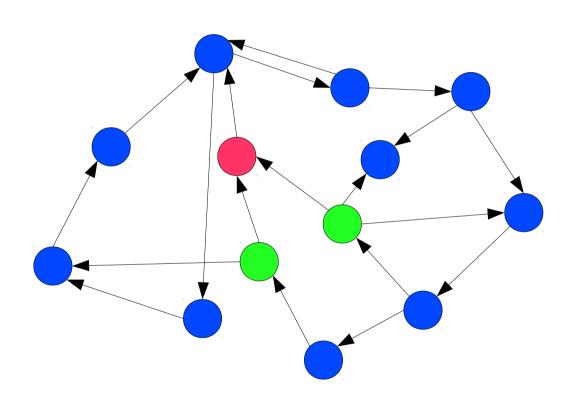
Open spaces in the state-of-the-art

nr has a quadratic complexity

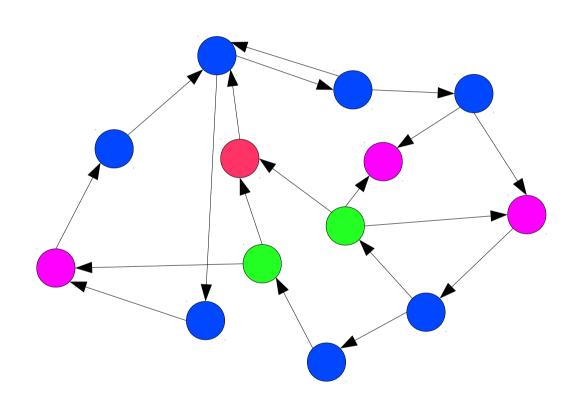
opic focus on popularity

the rest is about how to score

First-level neighboorhood •



Second-level neighboorhood •



deg, e, n, ne

deg: number of neighbors

e: sum of incoming edges

n: sum of incoming nodes

ne: sum of incoming (node*edge)s

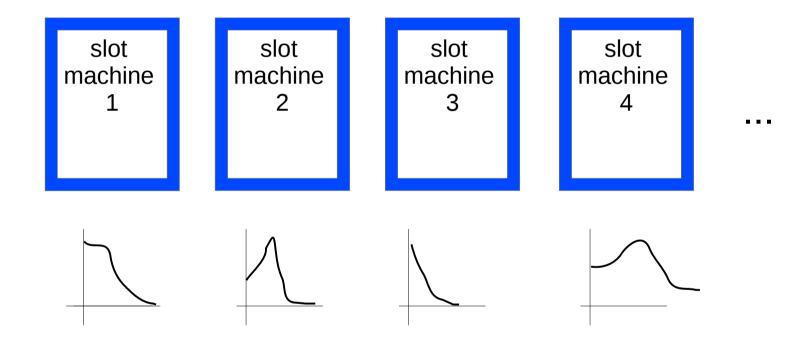
Neighborhood-based estimators

```
ESTIMATOR 4 (fl_n fl_e fl_ne sl_n sl_e sl_ne).
fl_deg: \widetilde{\beta}(v) = d_i(v) = |P(v)|
fl_n: \beta(v) = \sum_{u \in P(v)} \beta(u)
fl_e: \widehat{\beta}(v) = \sum_{u \in P(v)} \alpha(u, v)
fl_ne: \beta(v) = \sum_{u \in P(v)} \beta(u) \alpha(u, v)
sl_n: \widetilde{\beta}(v) = \sum_{u \in P(v)} \sum_{\substack{w \in V' \\ u \in P(w)}} \beta(w)
\mathtt{sl\_e:} \ \widetilde{\beta}(v) = \textstyle \sum_{u \in P(v)} \textstyle \sum_{\substack{w \in V' \\ u \in P(w)}} \alpha(u,w)
\mathtt{sl\_ne}: \ \widetilde{\beta}(v) = \sum_{u \in P(v)} \sum_{w \in V'} \beta(w) \alpha(u, w)
```

Linear regressions

```
ESTIMATOR 5 (lr_fl lr_sl).  lr_fl: \widetilde{\beta}(v) = trained\ linear\ combination\ of\ the\ fl_estimators.   lr_sl: \widetilde{\beta}(v) = trained\ linear\ combination\ of\ the\ fl_and\ sl_estimators.
```

Multi-armed bandits (1)



Multi-armed bandits (2)

Budget n, how to maximize the reward?

Balance exploration and exploitation

Applied to focused crawling

Slot machines: estimators

Reward: score of the top node

mab_ε

probability 1-ε: slot machine with the highest

average reward

probability ε: random slot machine

ESTIMATOR 6 (mab_ ε). $\widehat{\beta}(v) = output of an epsilon-greedy strategy.$

mab_ε-first

steps [0, Le x N]: random slot machine

steps [$\lfloor \epsilon \times N \rfloor + 1$, N]: slot machine with the highest average reward

ESTIMATOR 7 (mab_ ε -first). $\widetilde{\beta}(v) = output \ of \ an \ epsilon-first \ strategy.$

mab_var

Succession of ϵ -first strategies, with a reset every r steps, r varying with the context

ESTIMATOR 8 (mab_var). $\beta(v) = output \ of \ an \ epsilon-first$ with variable reset strategy.

Their running times

Expected running times

Twitter API for one week:

- **-** 3s
- 200,000 nodes

One domain website for one week:

- **-** 1s
- 600,000 nodes

Experimental framework (1)

Dataset	Nodes (million)	Non-zero nodes (%)	Edges (million)	Non-zero edges (%)
BRETAGNE	2.2	2.0	35.6	0.5
FRANCE	"	19.2	"	6.8
HAPPY	16.9	11.0	78.0	2.4
JAZZ	"	0.6	"	0.1
WEIRD	"	3.2	"	0.4

Experimental framework (2)

- Graph score
- 10 seed graphs
- 1 seed graph:
- 50 seeds picked randomly among non-zero β
- Arithmetic average of the crawl scores (sum)

- Global score
- Normalization with a baseline -- *relative score* Geometric average among the five graphs

Datasets and code are online

http://netiru.fr/research/14fc

To measure the running times

Same crawl sequence: the oracle

Storage in RAM (20G)

3.6 GHz

The running times (ms)

Dataset	Evaluator	100	1,000	10,000	100,000
FRANCE	nr	2,832.1	19,720.5	N/A	N/A
	opic	1.9	2.5	4.6	4.7
	ne_fl	0.2	0.1	0.1	0.1
	lr_fl	0.2	0.2	0.1	0.1
	mab_var_fl	0.6	0.3	0.2	0.2
	ne_sl	8.5	27.1	2.0	6.1
	lr_sl	8.5	27.2	2.0	6.1
Нарру	nr	45,965.7	105,209.3	N/A	N/A
	opic	1.8	1.6	1.9	2.5
	ne_fl	0.3	0.1	0.2	2.1
	lr_fl	0.5	0.1	0.2	2.1
	mab_var_fl	1.1	0.3	0.5	3.9
	ne_sl	111.1	24.5	63.3	240.5
	lr_sl	111.4	24.5	63.3	241.0

nr

$$NR_1(v)^{t+1} = d \times w(v) + (1-d) \times avg_{(v,u) \in E'} \frac{NR_1(u)^t}{d_i(u)}$$

$$NR_2(v)^{t+1} = d \times NR_1(v) + (1-d) \times avg_{(u,v) \in E'} \frac{NR_2(u)^t}{d_0(u)}.$$

ESTIMATOR 2 (nr).
$$\widetilde{\beta}(v) = NR_2(v)$$
.

Quadratic complexity, with large constant factors

Their precision

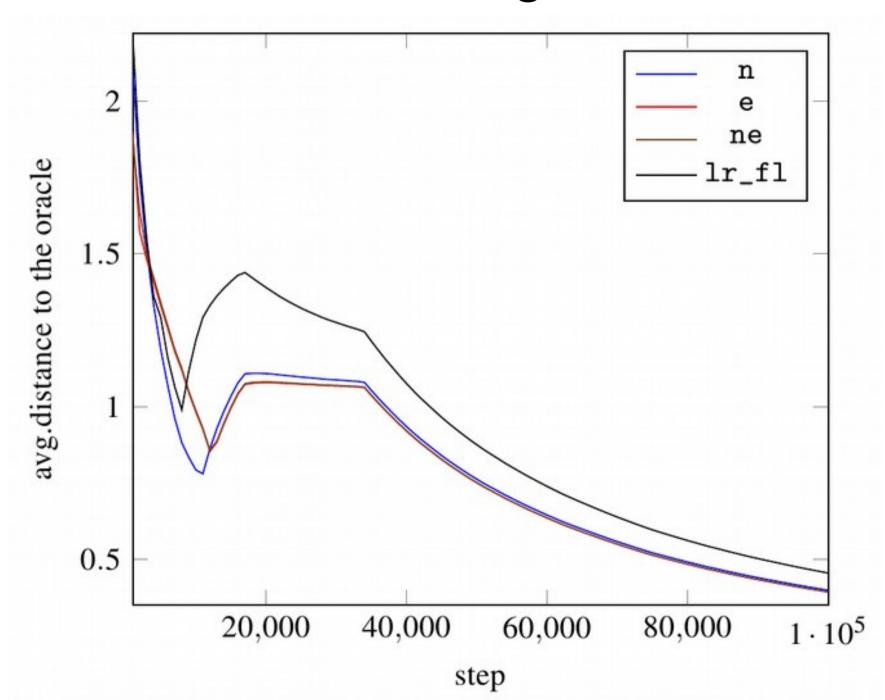
The precision

Same crawl sequence: the oracle

Precision: distance of the top node to the actual top node

Arithmetically averaged over a window of 1000 steps

For bretagne



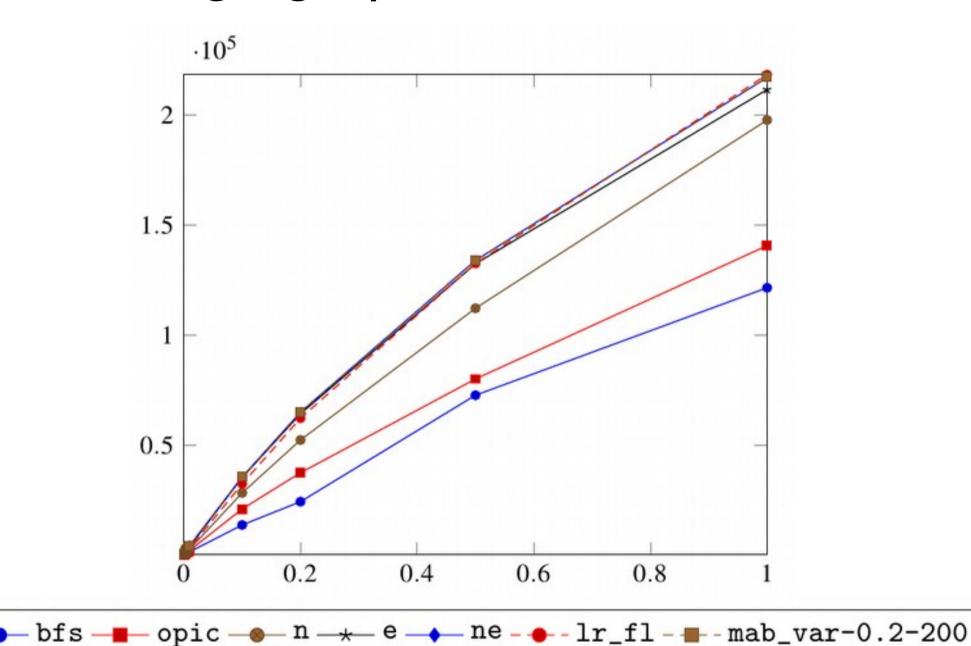
Their ability to lead crawls

Leading the crawl

Different crawl sequences:

defined by the top estimated nodes

Average graph scores for France



The multi armed-bandits

Type	100	1,000	10,000	100,000
ε	0.450	0.481	0.477	0.495
arepsilon-first	0.409	0.501	0.484	0.490
var-0.1-1000	0.383	0.439	0.420	0.494
var-0.2-200	0.427	0.413	0.461	0.458

All the estimators

Estimator	100	1,000	10,000	100,000
bfs	0.147	0.132	0.130	0.207
opic	0.283	0.184	0.205	0.287
n	0.358	0.280	0.362	0.467
е	0.594	0.560	0.457	0.377
ne	0.583	0.570	0.466	0.378
lr_fl	0.325	0.382	0.466	0.504
mab_var-0.2-200	0.427	0.413	0.461	0.458

Conclusion

What we learnt

Generic model

NP-hardness offline

Refresh rate of 1 Greedy

Neighborhood features
Linear regressions
Multi-armed bandit strategy

Future work

Approximation of the optimal score

Distributed crawl

Recrawling nodes

Further multi-armed bandits comparisons

Thank you.

georges@netiru.fr

Finding the optimal crawl sequences in a known graph

PTime many-one reduction from the LST-Graph problem

Problem remains hard if nodes, not edges, are weighted

A subtree rooted at r is seen as a crawl sequence starting from r

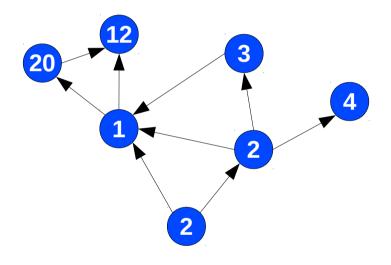
Free edges are added to the graph to allow free crawls from he seed to any potential root of a subtree

Rich friends will make you richer

The greedy strategy

Node picked = $argmax(\beta(v))$, v in frontier

Is not always optimal



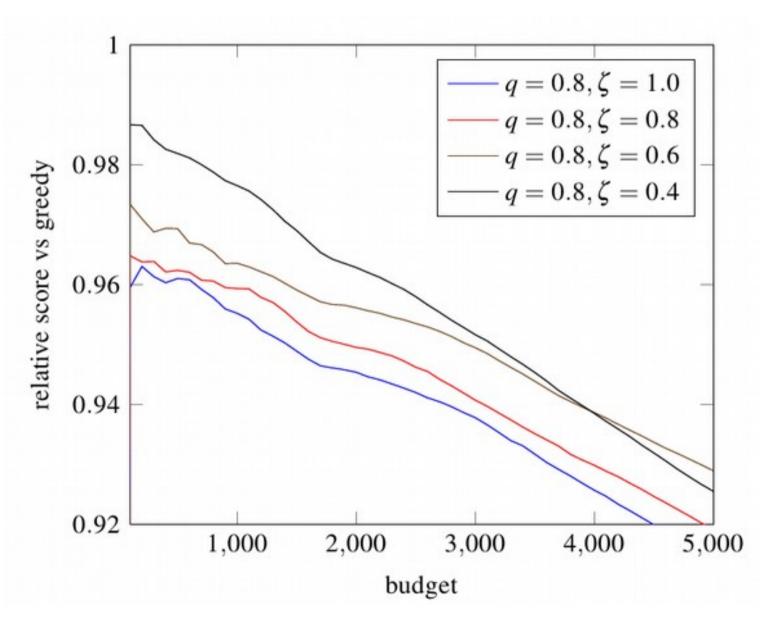
The altered greedy strategy

Node picked =

probability q: $argmax(\beta(v))$

probability 1-q: random v so that, $\max(\beta(u)) - \beta(v) \le \zeta \times \max(\beta(u))$

Altered greedy vs greedy for jazz



The refresh rate disadvantage

When estimation takes too long

```
input : seed subgraph G_0, budget n
   output: crawl sequence V with a score as high as possible
1 \ V \leftarrow ();
2 G' \leftarrow G_0;
3 budgetLeft ← n;
4 while budgetLeft > 0 do
       frontier \leftarrow extractFrontier(G');
5
       scoredFrontier \leftarrow
6
       estimator.scoreFrontier(G', frontier);
       r \leftarrow \text{getRefreshRate}();
7
       NodeSequence \leftarrow
8
       strategy.getNextNodes(scoredFrontier, r);
       V \leftarrow (V, \mathsf{NodeSequence});
9
       for u in NodeSequence do
10
           G' \leftarrow G' \cup \mathtt{crawlNode}(u);
11
       budgetLeft = budgetLeft - r
12
13 return V
```

The score degradation (%) at different steps

Refresh rate	100	1,000	10,000	100,000
2	0.4	2.2	3.9	6.4
8	1.3	6.5	12.8	18.3
32	6.6	6.5	17.5	24.3
128	38.8	10.7	19.9	29.5
1024	38.8	74.3	25.8	35.9