

Austin Lin

<https://austlin.github.io> | austinlin35@gmail.com | New London, CT 06320

Open to Relocation

SUMMARY

Engineer with experience in requirements verification, and utilizing Python and MATLAB for modeling, simulation and robotics.

TECHNICAL SKILLS

Languages: Python, C++, Java

Tools: MATLAB/Simulink, ROS2/Gazebo, SciPy, ZeroMQ, TCP/IP, Siemens NX, Git

EXPERIENCE

General Dynamics Electric Boat

Systems Engineer, New London CT

Sept 2024 - Present

- Programmed and deployed a tool to cut down a 4 hour manual process into a 30 minute calculation with improved accuracy. Utilized data from 3D models, finite element transient shock studies, statistical methods, and cost-constraint optimization in MATLAB.
- Led small team of engineers to implement class-wide design changes to improve safety and reliability in accordance with DoW requirements.
- Identify construction bottlenecks by coordinating closely with other disciplines (Design, Work Planning, Trades) and by providing engineering assistance to maintain quality and schedule.

L3Harris C5 Systems

Systems Engineering Intern, Camden, NJ

June 2023 – Aug 2023

- Demonstrate quality of product for the customer through performing System Operability Verification Tests for Marcom IVCS and Symphony.
- Used rack mounted Linux-based hardware to program various network/radio communication configurations.

UMD Spaces Systems Lab

Undergrad Researcher, College Park, MD

May 2022 – Aug 2022

- Delivered testing and modelling results to guide spacecraft design research with Benjamin Reed from Quantum Space and Dr. David Akin.
- Used Python to calculate robotic arm kinematics to test reachability of payloads for in-orbit servicing.
- Designed and fabricated a $\frac{1}{4}$ -scale physical robotic arm prototype. Produced and executed test procedure to validate python model results for 24+ spacecraft configurations.

PROJECTS

Robotics and Autonomous Systems

- Programmed robots to identify, grab, and hand off Legos to each other. Trained a YOLOv8 Computer vision model for object identification and ZeroMQ through TCP/IP for inter-robot communication.
- Implemented a maze solving algorithm into a robot, using LIDAR information and ROS2 for live localization and mapping.
- Developed hardware and software for a robot arm and controller. Programmed an Arduino microprocessor to communicate over serial bus to a computer that calculates and graphically shows arm kinematics.

Battery State of Charge Estimator Simulation

- Created an interactive model of a battery with Python/Shiny to explore how adding measurement noise and adjusting observer gain impacts state of charge estimator accuracy and convergence.

EDUCATION

University of Maryland, College Park, MD

Aug 2020 – Aug 2024

B.S. Mechanical Engineering, Minor in Robotics and Autonomous Systems

Scholars Public Leadership Program