

# Austin Lin

<https://austlin.github.io> | austinlin35@gmail.com | New London, CT 06320

Open to Relocation | Active US Secret Clearance

## SUMMARY

Engineer with experience in robotics, modeling and simulation using Python and MATLAB, and requirements verification.

## TECHNICAL SKILLS

**Languages:** Python, C++, Java

**Tools:** MATLAB/Simulink, ROS2/Gazebo, SciPy, ZeroMQ, TCP/IP, Siemens NX, Git

## EXPERIENCE

### General Dynamics Electric Boat

*Systems Engineer, New London CT*

Sept 2024 - Present

- Reviewed and signed off on electrical power systems updates to meet Columbia-class Ship Specifications.
- Identified latent electrical quality issues resulting from procedural gaps, and then developed and executed plan of corrective actions.
- Coordinated with Design, Planning, Structural, and Waterfront/Trades to maintain configuration management and reduce potential rework, in support of ongoing construction acceleration efforts.
- Hosted training meetings to familiarize engineers with using internal tools and ongoing long-term projects.

### L3Harris C5 Systems

*Systems Engineering Intern, Camden, NJ*

June 2023 – Aug 2023

- Demonstrated quality of product for the customer by performing System Operability Verification Tests for Marcom IVCS and Symphony.
- Used rack mounted Linux-based hardware to program various network/radio communication configurations.

### UMD Space Systems Lab

*Undergrad Researcher, College Park, MD*

May 2022 – Aug 2022

- Modeled spacecraft robotic arm kinematics with Python to test reachability of payloads for in-orbit servicing missions, with Benjamin Reed from Quantum Space and Dr. David Akin.
- Designed and fabricated a ¼-scale physical robotic arm prototype. Produced and executed test procedure to validate python model results for 24+ spacecraft configurations.
- Presented testing and Modelling results to Stakeholders.

## PROJECTS

### Robotics and Autonomous Systems

- Programmed robots to identify, grab, and hand off Legos to each other. Trained a YOLOv8 Computer vision model for object identification and ZeroMQ through TCP/IP for inter-robot communication.
- Implemented a maze solving algorithm into a robot, using LIDAR information and ROS2 for live localization and mapping.
- Developed hardware and software for a robot arm and controller. Used an Arduino microprocessor to send robot telemetry over a serial bus to a computer for graphically visualizing arm kinematics.

### Battery State of Charge Estimator Simulation

- Created an interactive model of a battery with Python/Shiny to explore how adding measurement noise and adjusting observer gain impacts state of charge estimator accuracy and convergence.

## EDUCATION

### University of Maryland, College Park, MD

Aug 2020 – Aug 2024

B.S. Mechanical Engineering, Minor in Robotics and Autonomous Systems

*Scholars Public Leadership Program*