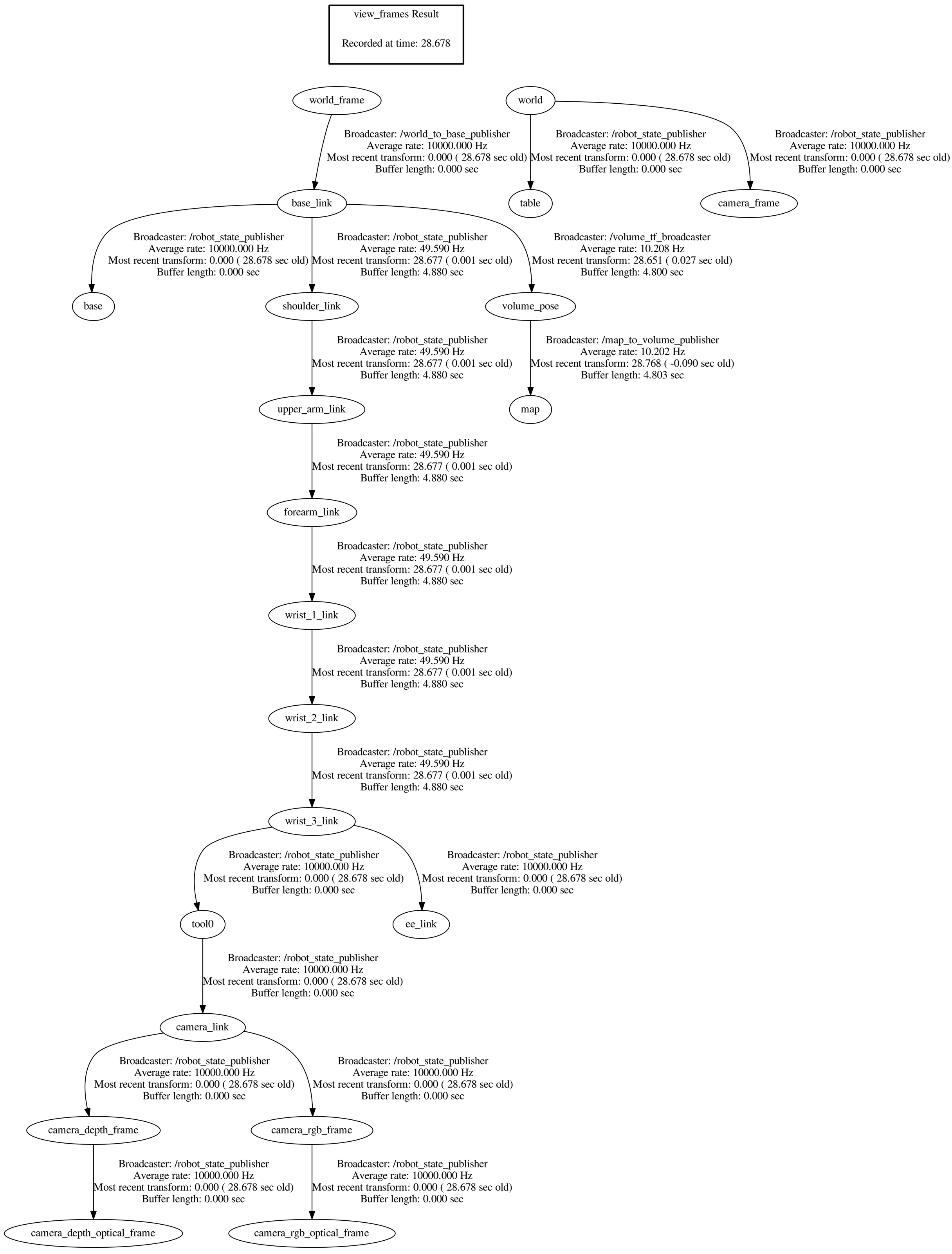
view_frames Result
Recorded at time: 28.678
world_frame
Broadcaster: /world_to_base_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
world
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
base_link
table
camera_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 49.590 Hz
Most recent transform: 28.677 (0.001 sec old)
Buffer length: 4.880 sec
Broadcaster: /volume_tf_broadcaster
Average rate: 10.208 Hz
Most recent transform: 28.651 (0.027 sec old)
Buffer length: 4.800 sec
base
shoulder_link
volume_pose
Broadcaster: /robot_state_publisher
Average rate: 49.590 Hz
Most recent transform: 28.677 (0.001 sec old)
Buffer length: 4.880 sec
Broadcaster: /map_to_volume_publisher
Average rate: 10.202 Hz
Most recent transform: 28.768 (-0.090 sec old)
Buffer length: 4.803 sec
upper_arm_link
map
Broadcaster: /robot_state_publisher
Average rate: 49.590 Hz
Most recent transform: 28.677 (0.001 sec old)
Buffer length: 4.880 sec
forearm_link
Broadcaster: /robot_state_publisher
Average rate: 49.590 Hz
Most recent transform: 28.677 (0.001 sec old)
Buffer length: 4.880 sec
wrist_1_link
Broadcaster: /robot_state_publisher
Average rate: 49.590 Hz
Most recent transform: 28.677 (0.001 sec old)
Buffer length: 4.880 sec
wrist_2_link
Broadcaster: /robot_state_publisher
Average rate: 49.590 Hz
Most recent transform: 28.677 (0.001 sec old)
Buffer length: 4.880 sec
wrist_3_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
tool0
ee_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
camera_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
camera_depth_frame
camera_rgb_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (28.678 sec old)
Buffer length: 0.000 sec
camera_depth_optical_frame
camera_rgb_optical_frame